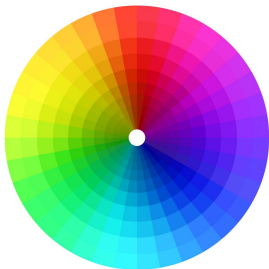




Order Selection



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Summary from last lecture

- ▶ Alternatives to NLS, based on ARMA and covariance model
- ▶ HOYW, MUSIC, Min-Norm, ESPRIT
- ▶ Subspace methods using EVD/SVD
- ▶ Complicated derivation but easy to use (and implement)
- ▶ Need to select user parameters and model order



Today

- ▶ How to choose the model order for parametric methods?
- ▶ Heuristic approaches
- ▶ Information criteria
- ▶ Intuitive ARMA order selection

Parametric signal models

$$y(t) = \sum_{k=1}^n \alpha_k e^{i(\omega_k t + \varphi_k)} + e(t)$$

$$A(z)y(t) = B(z)e(t)$$

$$A(z) = 1 + a_1 z^{-1} + \dots + a_n z^{-n}$$

$$B(z) = 1 + b_1 z^{-1} + \dots + b_m z^{-m}$$

- We can use these signal models and estimate spectra by estimating the parameters (real valued)

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Remaining problem

What is n and $m \in \mathbb{N}$?

- How to estimate the **discrete** parameters?

Definitions

Refer to n as the model order, or rather, the number of parameters, and N as the number of *real-valued* samples

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For $\{y(t)\}_{t=1}^{N_s}$ complex-valued samples from the line spectra model

$$y(t) = \sum_{k=1}^{n_c} \alpha_k e^{i(\omega_k t + \varphi_k)} + e(t)$$

we have

$$N = 2N_s$$

$$n = 3n_c + 1$$

that is, both real and imaginary part of the data, and three parameters per component plus the noise variance are unknown

Rule of thumb

General

It is always *possible* to get a better model fit if we increase the model order (“increase flexibility”).

- ▶ Infinite order is not better (or even possible)!
- ▶ Does not explain the underlying structure
- ▶ Fits to the random noise, giving random estimates (overfitting)

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Heuristic approach (Occam's razor)

We need to choose n high enough that the model gives a sufficient description of the data, while still keeping $n \ll N$ to get reliable (low variance) estimates.

In practice

Principle of parsimony idea

Increase the order as long as the error reduces **significantly**

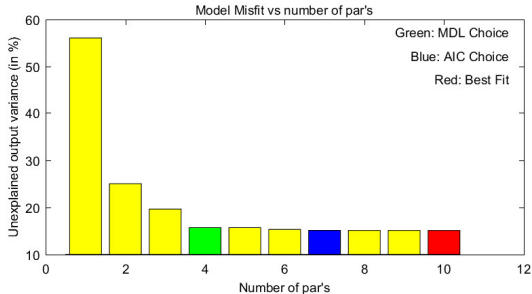
- ▶ Subjective but reasonable
- ▶ An even lower model order might still be enough for your purpose
- ▶ What is significant?

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- ▶ Somehow *automatically* estimate n from y
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- ▶ Reduces to NLS for Gaussian data

Gaussian likelihood example

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$$y = f(\gamma) + e$$

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$$\hat{\gamma} = \underset{\gamma}{\operatorname{argmin}} \|y - f(\gamma)\|^2 \quad \text{and} \quad \hat{\sigma}^2 = \frac{1}{N} \|y - f(\hat{\gamma})\|^2$$

Maximum a posteriori (MAP)

Hypothesis: H_n denotes that the model order is n

Bayes rule:

$$p(H_n|y) = \frac{p(y|H_n)p(H_n)}{p(y)}$$

where $p(H_n)$ is the *a priori* probability of H_n

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MAP

Find the most probable order, given the data, through

$$\max_{n \in [1, \bar{n}]} p(y|H_n)p(H_n)$$

$p(y)$ is just a normalization factor independent of n

A few different rules

Derived from statistical reasoning and information theory
(Maximum a posteriori or Kullback-Leibler information)

Four methods we will look at (listed by increasing “performance”)

- ▶ Akaike information criterion (AIC)
- ▶ Corrected Akaike information criterion (AIC_c)
- ▶ Generalized information criterion (GIC)
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See the book for derivations (beyond our scope).

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Several other criteria available too:

- ▶ Minimum description length (MDL)
- ▶ etc...

Statistical approach

Reasonable idea: Add a term to the fitting problem that depends on n , penalizing high order.

Family of selection rules

$$\underset{\theta_{n,n}}{\text{minimize}} \quad -2 \ln(p_n(y|\theta_n)) + \eta(n, N)n$$

where θ_n is used as a reminder that θ is of length n

The penalty coefficients $\eta(n, N)$ are given by

$$\text{AIC} : \eta(n, N) = 2$$

$$\text{AIC}_c : \eta(n, N) = 2 \frac{N}{N - n - 1}$$

$$\text{GIC} : \eta(n, N) = \nu \in [2, 6]$$

$$\text{BIC} : \eta(n, N) = \ln N$$

Penalty comparison

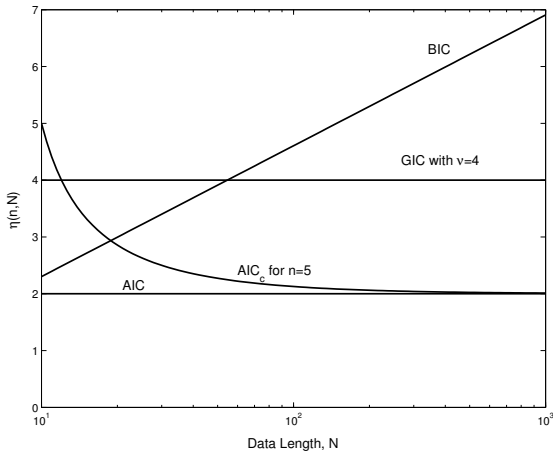


Figure C.1. Penalty coefficients of AIC, GIC with $\nu = 4$ ($\rho = 3$), AIC_c (for $n = 5$), and BIC, as functions of data length N .

Practical considerations

- ▶ Hard to solve

$$\min_{\theta_n, n} -2 \ln(p_n(y|\theta_n)) + \eta(n, N)n$$

- ▶ Assuming Gaussian noise, inserting the solution for fixed n

$$-2 \ln(p_n(y|\hat{\theta}_n)) = N \ln(2\pi) + N + N \ln(\hat{\sigma}_n^2),$$

where $\hat{\sigma}_n^2 = \frac{1}{N} \|y - f(\hat{\gamma}_n)\|^2$.

- ▶ **Solution:** Compute $\hat{\sigma}_n^2$ for many n , and choose the solution that minimize

$$N \ln(\hat{\sigma}_n^2) + \eta(n, N)n.$$

Example: Line spectra

For some fixed order n_c of the complex-valued signal model, and the estimated parameters for that order, we have

$$\hat{\sigma}_{n_c}^2 = \frac{1}{N_s} \sum_{t=1}^{N_s} \left| y(t) - \sum_{k=1}^{n_c} \hat{\alpha}_k e^{i(\hat{\omega}_k + \hat{\varphi}_k)} \right|^2$$

which can be computed for every order n_c

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We can then compute, e.g. the AIC, as

$$\text{AIC}(n_c) = 2N_s \ln(\hat{\sigma}_{n_c}^2) + 2(3n_c + 1)$$

and choose the order that minimizes the AIC

- ▶ We need to compute the error (MSE) for many model orders
- ▶ Then we can choose based on some information criteria

Considerations

- ▶ Automatic order selection is possible
- ▶ Now we have several criteria, how do we choose?
 - ▶ Pick your favorite
 - ▶ Look at all of them to make a final decision
 - ▶ Combine the information based approaches
- ▶ Computational burden can be a problem
- ▶ Methods can “fail”
- ▶ An informed guess can still be better
- ▶ Non-parametric approaches avoids this problem (almost)

ARMA order selection

Heuristic for ARMA (or linear systems)

Reduce order if you have pole/zero cancellation, i.e., if there are estimated poles and zeros that overlap (more or less) they may not influence the result.

$$y(t) = \frac{B(z)}{A(z)}e(t) = \frac{\tilde{B}(z)(1 - kz^{-1})}{\tilde{A}(z)(1 - kz^{-1})}e(t) = \frac{\tilde{B}(z)}{\tilde{A}(z)}e(t)$$

where \tilde{B} and \tilde{A} have lower order

- ▶ Model specific approach (but quite general)
- ▶ Easy to use
- ▶ Intuitive

Useful functions

Custom functions implemented:

- ▶ `armaorder(mvec,sig2,N,nu)`
- ▶ `sinorder(mvec,sig2,N,nu)`

Usage:

- ▶ `mvec`: vector of number of sinusoids (or complex exponentials for complex valued data)
- ▶ `sig2`: vector mean square errors (that is, estimate of σ^2) for model orders given in `mvec`
- ▶ `N`: number of real-valued data points
- ▶ `nu`: GIC parameter (usually $\nu \in [2, 6]$, default=4)
- ▶ output: the model orders that minimizes the AIC, AICc, GIC, and BIC criteria

Summary

- ▶ Out of a selection of models that are sufficient for the application, choose the simplest one
- ▶ In general: try to choose $n \ll N$
- ▶ Look at the increase in performance (decrease in error) as a function of n
- ▶ BIC, GIC, AIC_c, AIC can give automatic guidance
- ▶ Study your model and simplify (e.g. pole/zero cancellation)

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In the end, try several things to make yourself comfortable with a certain choice of n