

Subspace methods for line spectra



Per Mattsson

Systems and Control
Department of Information Technology
Uppsala University

2019-09-19

per.mattssonk@it.uu.se SysCon, IT, UU



Summary from last lecture

- Signal model for line spectra
- ► Estimating the spectrum ⇒ frequency estimation
- ► Nonlinear least squares
- ► Models of the covariance matrix and ARMA-type model
- ► Singular value decomposition (SVD)



Today

- ► A recap from L5
- Subspace methods for frequency estimation
 - ► High order Yule-Walker
 - MUSIC
 - ► Min-Norm
 - ESPRIT
- Makes use of the covariance structure



Line spectra

Signal model:

$$y(t) = \sum_{k=1}^{n} \alpha_k e^{i(\omega_k t + \varphi_k)} + e(t)$$



Line spectra

Signal model:

$$y(t) = \sum_{k=1}^{n} \alpha_k e^{i(\omega_k t + \varphi_k)} + e(t)$$

Theoretical ACS for line spectra

$$r(k) = E\{y(t)y^*(t-k)\} = \sum_{p=1}^{n} \alpha_p^2 e^{i\omega_p k} + \sigma^2 \delta_{k,0}$$



Line spectra

Signal model:

$$y(t) = \sum_{k=1}^{n} \alpha_k e^{i(\omega_k t + \varphi_k)} + e(t)$$

Theoretical ACS for line spectra

$$r(k) = E\{y(t)y^*(t-k)\} = \sum_{p=1}^{n} \alpha_p^2 e^{i\omega_p k} + \sigma^2 \delta_{k,0}$$

Theoretical spectrum

$$\phi(\omega) = 2\pi \sum_{p=1}^{n} \alpha_p^2 \delta(\omega - \omega_p) + \sigma^2$$



Problem

Determine $\{\omega_k\}_{k=1}^n$ from observations or samples $\{y(t)\}_{t=1}^N$



Problem

Determine $\{\omega_k\}_{k=1}^n$ from observations or samples $\{y(t)\}_{t=1}^N$

► The nonlinear least square method,

$$\min_{\omega,\alpha,\varphi} \sum_{k=1}^{N} \left| y(t) - \sum_{k=1}^{n} \alpha_k e^{i(\omega_k t + \varphi_k)} \right|^2$$



Problem

Determine $\{\omega_k\}_{k=1}^n$ from observations or samples $\{y(t)\}_{t=1}^N$

► The nonlinear least square method,

$$\min_{\omega,\alpha,\varphi} \sum_{k=1}^{N} \left| y(t) - \sum_{k=1}^{n} \alpha_k e^{i(\omega_k t + \varphi_k)} \right|^2$$

Excellent properties if the global minimum can be found.



Problem

Determine $\{\omega_k\}_{k=1}^n$ from observations or samples $\{y(t)\}_{t=1}^N$

► The nonlinear least square method,

$$\min_{\omega,\alpha,\varphi} \sum_{k=1}^{N} \left| y(t) - \sum_{k=1}^{n} \alpha_k e^{i(\omega_k t + \varphi_k)} \right|^2$$

- Excellent properties if the global minimum can be found.
- ► Hard (impossible) to use in general.



Problem

Determine $\{\omega_k\}_{k=1}^n$ from observations or samples $\{y(t)\}_{t=1}^N$

► The nonlinear least square method,

$$\min_{\omega,\alpha,\varphi} \sum_{k=1}^{N} \left| y(t) - \sum_{k=1}^{n} \alpha_k e^{i(\omega_k t + \varphi_k)} \right|^2$$

- Excellent properties if the global minimum can be found.
- ► Hard (impossible) to use in general.
- ► Today we will instead use subspace methods.



Singular value decomposition (SVD)

Definition

Factor a matrix $A \in \mathbb{C}^{m \times n}$ as

$$A = U\Sigma V^*$$

where $U \in \mathbb{C}^{m \times m}$ and $V \in \mathbb{C}^{n \times n}$ are unitary matrices, and $\Sigma \in \mathbb{R}^{m \times n}$ is diagonal with non-negative diagonal values σ_i (singular values) ordered in decreasing order

(See A.4 in the book for the details)

- Low-rank approximations
- Useful to find the best fit subspaces of A
- ► Projection onto subspace perpendicular distance
- ► LS fit vertical distance

SVD (2)

 $A \in \mathbb{C}^{m \times n}$ is of rank $r < \min(m, n)$ then

$$A = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix} = U_1 \Sigma_1 V_1^*$$

where $\Sigma_1 \in \mathbb{R}^{r \times r}$, then

- ▶ U_1 is an orthonormal basis in $\mathcal{R}(A)$
- ▶ U_2 is an orthonormal basis in $\mathcal{N}(A^*)$
- $ightharpoonup V_1$ is an orthonormal basis in $\mathcal{R}(A^*)$
- $ightharpoonup V_2$ is an orthonormal basis in $\mathcal{N}(A)$

Moreover, $\mathcal{R}(A)$ and $\mathcal{N}(A^*)$ are orthogonal to each other and they span \mathbb{C}^m

 $(\mathcal{N}(A^*))$ is the orthogonal complement to $\mathcal{R}(A)$ and vice versa)





Start from ARMA-model:

$$A(z)y(t) = A(z)e(t), \quad A(z) = \prod_{k=1}^{n} (1 - e^{i\omega_k}z^{-1}).$$



Start from ARMA-model:

$$A(z)y(t) = A(z)e(t), \quad A(z) = \prod_{k=1}^{n} (1 - e^{i\omega_k}z^{-1}).$$

ightharpoonup Can't divide away A(z) due to poles on unit circle!



Start from ARMA-model:

$$A(z)y(t) = A(z)e(t), \quad A(z) = \prod_{k=1}^{n} (1 - e^{i\omega_k}z^{-1}).$$

- ightharpoonup Can't divide away A(z) due to poles on unit circle!
- ▶ Multiply both sides with some filter $\tilde{A}(z)$ to get

$$B(z)y(t) = B(z)e(t),$$

where $B(z) = A(z)\tilde{A}(z)$ has order L > n ("high order").



Start from ARMA-model:

$$A(z)y(t) = A(z)e(t), \quad A(z) = \prod_{k=1}^{n} (1 - e^{i\omega_k}z^{-1}).$$

- ightharpoonup Can't divide away A(z) due to poles on unit circle!
- lackbox Multiply both sides with some filter $\tilde{A}(z)$ to get

$$B(z)y(t) = B(z)e(t),$$

where $B(z) = A(z)\tilde{A}(z)$ has order L > n ("high order").

▶ B(z) will have n roots $\{e^{i\omega_k}\}_{k=1}^n$ on the unit circle corresponding to the frequencies, and L-n spurious roots.



Start from ARMA-model:

$$A(z)y(t) = A(z)e(t), \quad A(z) = \prod_{k=1}^{n} (1 - e^{i\omega_k}z^{-1}).$$

- lacktriangle Can't divide away A(z) due to poles on unit circle!
- ▶ Multiply both sides with some filter $\tilde{A}(z)$ to get

$$B(z)y(t) = B(z)e(t),$$

where $B(z) = A(z)\tilde{A}(z)$ has order L > n ("high order").

- ▶ B(z) will have n roots $\{e^{i\omega_k}\}_{k=1}^n$ on the unit circle corresponding to the frequencies, and L-n spurious roots.
- ▶ Idea: Estimate B(z) and take the n roots $\{r_k\}_{k=1}^n$ closest to the unit circle to get estimates $\hat{\omega}_k = \arg(r_k)$.



$$B(z)y(t) = B(z)e(t).$$

From before we know that

$$r(k) + \sum_{i=1}^{L} b_i r(k-i) = 0, k > L.$$



$$B(z)y(t) = B(z)e(t).$$

From before we know that

$$r(k) + \sum_{i=1}^{L} b_i r(k-i) = 0, k > L.$$

For $k = L + 1, \dots, L + M$ we get

$$\underbrace{\begin{bmatrix} r(L) & \cdots & r(1) \\ \vdots & \ddots & \vdots \\ r(L+M-1) & \cdots & r(M) \end{bmatrix}}_{\Omega} b = -\underbrace{\begin{bmatrix} r(L+1) \\ \vdots \\ r(L+M) \end{bmatrix}}_{\alpha}$$



$$B(z)y(t) = B(z)e(t).$$

From before we know that

$$r(k) + \sum_{i=1}^{L} b_i r(k-i) = 0, k > L.$$

For $k = L + 1, \dots, L + M$ we get

$$\underbrace{\begin{bmatrix} r(L) & \cdots & r(1) \\ \vdots & \ddots & \vdots \\ r(L+M-1) & \cdots & r(M) \end{bmatrix}}_{\Omega} b = -\underbrace{\begin{bmatrix} r(L+1) \\ \vdots \\ r(L+M) \end{bmatrix}}_{\Omega}$$

▶ Important property: $rank(\Omega) = n$.



$$B(z)y(t) = B(z)e(t).$$

From before we know that

$$r(k) + \sum_{i=1}^{L} b_i r(k-i) = 0, k > L.$$

ightharpoonup For $k = L + 1, \dots, L + M$ we get

$$\underbrace{\begin{bmatrix} r(L) & \cdots & r(1) \\ \vdots & \ddots & \vdots \\ r(L+M-1) & \cdots & r(M) \end{bmatrix}}_{b} b = - \underbrace{\begin{bmatrix} r(L+1) \\ \vdots \\ r(L+M) \end{bmatrix}}_{c}$$

- ▶ Important property: $rank(\Omega) = n$.
- When L > n this rank-condition gives extra information about the structure of Ω .



Form $\widehat{\Omega}$ and $\widehat{\rho}$ by replacing r(k) with $\widehat{r}(k)$ in Ω and ρ , $\widehat{\Omega}b \approx -\widehat{\rho}$. (1)



Form $\widehat{\Omega}$ and $\widehat{\rho}$ by replacing r(k) with $\widehat{r}(k)$ in Ω and ρ ,

$$\widehat{\Omega}b \approx -\widehat{\rho}.\tag{1}$$

Random errors in $\hat{r}(k)$, so we (almost surely) get a full-rank $\hat{\Omega}$, $\operatorname{rank}(\widehat{\Omega}) = \min(M, L) > n.$



Form $\widehat{\Omega}$ and $\widehat{\rho}$ by replacing r(k) with $\widehat{r}(k)$ in Ω and ρ ,

$$\widehat{\Omega}b \approx -\widehat{\rho}.$$
 (1)

- ▶ Random errors in $\hat{r}(k)$, so we (almost surely) get a full-rank $\hat{\Omega}$, $\operatorname{rank}(\widehat{\Omega}) = \min(M, L) > n.$
- ▶ Ill-conditioned: For reasonable large N, $\widehat{\Omega}$ will be close to a rank-n matrix. Hence, solving for b in (1) directly is numerically problematic.



Form $\widehat{\Omega}$ and $\widehat{\rho}$ by replacing r(k) with $\widehat{r}(k)$ in Ω and ρ ,

$$\widehat{\Omega}b \approx -\hat{\rho}.$$
 (1)

▶ Random errors in $\hat{r}(k)$, so we (almost surely) get a full-rank $\hat{\Omega}$. $\operatorname{rank}(\widehat{\Omega}) = \min(M, L) > n.$

- ▶ Ill-conditioned: For reasonable large N, $\widehat{\Omega}$ will be close to a rank-n matrix. Hence, solving for b in (1) directly is numerically problematic.
- ▶ Idea: First approximate $\widehat{\Omega}$ with a rank-n matrix $\widehat{\Omega}_n$.



Form $\widehat{\Omega}$ and $\widehat{\rho}$ by replacing r(k) with $\widehat{r}(k)$ in Ω and ρ ,

$$\widehat{\Omega}b \approx -\widehat{\rho}.\tag{1}$$

▶ Random errors in $\hat{r}(k)$, so we (almost surely) get a full-rank $\hat{\Omega}$.

$$\operatorname{rank}(\widehat{\Omega}) = \min(M, L) > n.$$

- ▶ Ill-conditioned: For reasonable large N, $\widehat{\Omega}$ will be close to a rank-n matrix. Hence, solving for b in (1) directly is numerically problematic.
- ▶ Idea: First approximate $\widehat{\Omega}$ with a rank-n matrix $\widehat{\Omega}_n$.
- $lackbox{}\widehat{\Omega}_n$ should be closer to the true Ω since we exploited

$$\operatorname{rank}(\Omega) = n.$$



Form $\widehat{\Omega}$ and $\widehat{\rho}$ by replacing r(k) with $\widehat{r}(k)$ in Ω and ρ ,

$$\widehat{\Omega}b \approx -\widehat{\rho}.\tag{1}$$

▶ Random errors in $\hat{r}(k)$, so we (almost surely) get a full-rank $\widehat{\Omega}$,

$${\sf rank}(\widehat{\Omega}) = \min(M,L) > n.$$

- ▶ Ill-conditioned: For reasonable large N, $\widehat{\Omega}$ will be close to a rank-n matrix. Hence, solving for b in (1) directly is numerically problematic.
- ▶ Idea: First approximate $\widehat{\Omega}$ with a rank-n matrix $\widehat{\Omega}_n$.
- $lackbox{} \widehat{\Omega}_n$ should be closer to the true Ω since we exploited

$$rank(\Omega) = n$$
.

Find \hat{b} by solving (LS)

$$\widehat{\Omega}_n \widehat{b} \approx -\widehat{\rho} \Longrightarrow \widehat{b} = -\widehat{\Omega}_n^{\dagger} \widehat{\rho}.$$



• Use SVD on $\widehat{\Omega}$,

$$\widehat{\Omega} = U\Sigma V^* = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix},$$

where Σ_1 contains the n largest singular values.



▶ Use SVD on $\widehat{\Omega}$.

$$\widehat{\Omega} = U\Sigma V^* = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{vmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{vmatrix} \begin{vmatrix} V_1^* \\ V_2^* \end{vmatrix},$$

where Σ_1 contains the *n* largest singular values.

ightharpoonup Truncate (i.e. replace Σ_2 with 0) to get rank-n matrix

$$\widehat{\Omega}_n = U_1 \Sigma_1 V_1^* \approx \widehat{\Omega}.$$



• Use SVD on $\widehat{\Omega}$,

$$\widehat{\Omega} = U\Sigma V^* = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix},$$

where Σ_1 contains the n largest singular values.

▶ Truncate (i.e. replace Σ_2 with 0) to get rank-n matrix

$$\widehat{\Omega}_n = U_1 \Sigma_1 V_1^* \approx \widehat{\Omega}.$$

► Solve for \hat{b} ,

$$\hat{b} = -\widehat{\Omega}_n^{\dagger} \hat{\rho} =$$



▶ Use SVD on $\widehat{\Omega}$.

$$\widehat{\Omega} = U\Sigma V^* = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix},$$

where Σ_1 contains the *n* largest singular values.

ightharpoonup Truncate (i.e. replace Σ_2 with 0) to get rank-n matrix

$$\widehat{\Omega}_n = U_1 \Sigma_1 V_1^* \approx \widehat{\Omega}.$$

► Solve for \hat{b} .

$$\hat{b} = -\widehat{\Omega}_n^{\dagger} \hat{\rho} = -V_1 \Sigma_1^{-1} U_1^* \hat{\rho}.$$



• Use SVD on $\widehat{\Omega}$,

$$\widehat{\Omega} = U\Sigma V^* = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix},$$

where Σ_1 contains the n largest singular values.

▶ Truncate (i.e. replace Σ_2 with 0) to get rank-n matrix

$$\widehat{\Omega}_n = U_1 \Sigma_1 V_1^* \approx \widehat{\Omega}.$$

► Solve for \hat{b} ,

$$\hat{b} = -\widehat{\Omega}_n^{\dagger} \hat{\rho} = -V_1 \Sigma_1^{-1} U_1^* \hat{\rho}.$$

 $lackbox{}{} \{\hat{\omega}_k\}_{k=1}^n$ from the n roots of $\hat{B}(z)$ closest to the unit circle.



• Use SVD on $\widehat{\Omega}$,

$$\widehat{\Omega} = U\Sigma V^* = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix},$$

where Σ_1 contains the n largest singular values.

▶ Truncate (i.e. replace Σ_2 with 0) to get rank-n matrix

$$\widehat{\Omega}_n = U_1 \Sigma_1 V_1^* \approx \widehat{\Omega}.$$

► Solve for \hat{b} ,

$$\hat{b} = -\widehat{\Omega}_n^{\dagger} \hat{\rho} = -V_1 \Sigma_1^{-1} U_1^* \hat{\rho}.$$

- \blacktriangleright $\{\hat{\omega}_k\}_{k=1}^n$ from the n roots of $\hat{B}(z)$ closest to the unit circle.
- ▶ User parameters: $M \approx L$, and L + M a fraction of N.



▶ Use SVD on $\widehat{\Omega}$.

$$\widehat{\Omega} = U \Sigma V^* = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{bmatrix} \begin{bmatrix} V_1^* \\ V_2^* \end{bmatrix},$$

where Σ_1 contains the *n* largest singular values.

ightharpoonup Truncate (i.e. replace Σ_2 with 0) to get rank-n matrix

$$\widehat{\Omega}_n = U_1 \Sigma_1 V_1^* \approx \widehat{\Omega}.$$

ightharpoonup Solve for \hat{b} .

$$\hat{b} = -\widehat{\Omega}_n^{\dagger} \hat{\rho} = -V_1 \Sigma_1^{-1} U_1^* \hat{\rho}.$$

- $\{\hat{\omega}_k\}_{k=1}^n$ from the *n* roots of $\hat{B}(z)$ closest to the unit circle.
- ▶ User parameters: $M \approx L$, and L + M a fraction of N.
- ▶ Note: SVD can also give an idea about the size of n.



MUltiple SIgnal Classification (MUSIC)



The Covariance Matrix Equation

Let

$$a(\omega) = \begin{bmatrix} 1 & e^{-i\omega} & \cdots & e^{-i(m-1)\omega} \end{bmatrix}^{\top}$$
 for some $m > n$

$$A = \begin{bmatrix} a(\omega_1) & \cdots & a(\omega_n) \end{bmatrix} \in \mathbb{C}^{m \times n}$$

Let
$$ilde{y}(t) = egin{bmatrix} y(t) & \cdots & y(t-m+1) \end{bmatrix}^{ op}$$
, then

$$ilde{y}(t) = A ilde{x}(t) + ilde{e}(t)$$

$$\tilde{x}(t) = \begin{bmatrix} x_1(t) & \cdots & x_n(t) \end{bmatrix}^{\mathsf{T}}, \quad \tilde{e}(t) = \begin{bmatrix} e(t) & \cdots & e(t-m+1) \end{bmatrix}^{\mathsf{T}}$$

Covariance matrix: $R = E\{\tilde{y}(t)\tilde{y}^*(t)\} = APA^* + \sigma^2 I$, where

$$P = E\{\tilde{x}(t)\tilde{x}^*(t)\} = \begin{bmatrix} \alpha_1^2 & 0 \\ & \ddots \\ 0 & \alpha_n^2 \end{bmatrix}$$



▶ rank(A) = n (if $m \ge n$ and $\omega_k \ne \omega_p$ for $k \ne p$).



- rank(A) = n (if $m \ge n$ and $\omega_k \ne \omega_p$ for $k \ne p$).
- Hence,

$$\operatorname{rank}(APA^*)=n.$$



- rank(A) = n (if $m \ge n$ and $\omega_k \ne \omega_p$ for $k \ne p$).
- Hence,

$$\operatorname{rank}(APA^*) = n.$$

 $ightharpoonup APA^*$ has n strictly positive eigenvalues, and m-neigenvalues equal to 0,



- rank(A) = n (if $m \ge n$ and $\omega_k \ne \omega_n$ for $k \ne p$).
- Hence.

$$\operatorname{rank}(APA^*) = n.$$

▶ APA^* has n strictly positive eigenvalues, and m-neigenvalues equal to 0,

$$\tilde{\lambda}_1 \ge \tilde{\lambda}_2 \ge \dots \ge \tilde{\lambda}_n > 0, \quad \tilde{\lambda}_{n+1} = \dots = \tilde{\lambda}_m = 0.$$



- rank(A) = n (if $m \ge n$ and $\omega_k \ne \omega_n$ for $k \ne p$).
- Hence.

$$\operatorname{rank}(APA^*) = n.$$

▶ APA^* has n strictly positive eigenvalues, and m-neigenvalues equal to 0,

$$\tilde{\lambda}_1 \ge \tilde{\lambda}_2 \ge \dots \ge \tilde{\lambda}_n > 0, \quad \tilde{\lambda}_{n+1} = \dots = \tilde{\lambda}_m = 0.$$

► The eigenvalues λ_k of $R = APA^* + \sigma^2 I$ are thus given by

$$\lambda_k =$$



- rank(A) = n (if $m \ge n$ and $\omega_k \ne \omega_n$ for $k \ne p$).
- Hence.

$$\operatorname{rank}(APA^*) = n.$$

▶ APA^* has n strictly positive eigenvalues, and m-neigenvalues equal to 0,

$$\tilde{\lambda}_1 \ge \tilde{\lambda}_2 \ge \dots \ge \tilde{\lambda}_n > 0, \quad \tilde{\lambda}_{n+1} = \dots = \tilde{\lambda}_m = 0.$$

► The eigenvalues λ_k of $R = APA^* + \sigma^2 I$ are thus given by

$$\lambda_k = \tilde{\lambda}_k + \sigma^2 > 0, \quad k = 1, \dots, m,$$



- ▶ $\operatorname{rank}(A) = n$ (if $m \ge n$ and $\omega_k \ne \omega_p$ for $k \ne p$).
- ► Hence,

$$\mathsf{rank}(APA^*) = n.$$

▶ APA^* has n strictly positive eigenvalues, and m-n eigenvalues equal to 0,

$$\tilde{\lambda}_1 \ge \tilde{\lambda}_2 \ge \dots \ge \tilde{\lambda}_n > 0, \quad \tilde{\lambda}_{n+1} = \dots = \tilde{\lambda}_m = 0.$$

► The eigenvalues λ_k of $R = APA^* + \sigma^2 I$ are thus given by

$$\lambda_k = \tilde{\lambda}_k + \sigma^2 > 0, \quad k = 1, \dots, m,$$

and thus

$$rank(R) = m$$
.



Eigendecomposition of R

$$R = APA^* + \sigma^2 I \quad (m > n)$$

▶ Eigenvalues: $\lambda_1 \geq \lambda_2 \geq \ldots \geq \lambda_n > \lambda_{n+1} = \cdots = \lambda_m = \sigma^2$



Eigendecomposition of R

$$R = APA^* + \sigma^2 I \quad (m > n)$$

- \blacktriangleright Eigenvalues: $\lambda_1 > \lambda_2 > \ldots > \lambda_n > \lambda_{n+1} = \cdots = \lambda_m = \sigma^2$
- ightharpoonup Eigenvectors: $s_1, \ldots, s_n, g_1, \ldots, g_{m-n}$ orthonormal

$$S = \begin{bmatrix} s_1 & \cdots & s_n \end{bmatrix}$$
 corresponding to $\lambda_1, \dots, \lambda_n$ $G = \begin{bmatrix} g_1 & \cdots & g_{m-n} \end{bmatrix}$ corresponding to $\lambda_{n+1}, \dots, \lambda_m$



Eigendecomposition of R

$$R = APA^* + \sigma^2 I \quad (m > n)$$

- \blacktriangleright Eigenvalues: $\lambda_1 > \lambda_2 > \ldots > \lambda_n > \lambda_{n+1} = \cdots = \lambda_m = \sigma^2$
- ightharpoonup Eigenvectors: $s_1, \ldots, s_n, g_1, \ldots, g_{m-n}$ orthonormal

$$S = \begin{bmatrix} s_1 & \cdots & s_n \end{bmatrix}$$
 corresponding to $\lambda_1, \dots, \lambda_n$ $G = \begin{bmatrix} g_1 & \cdots & g_{m-n} \end{bmatrix}$ corresponding to $\lambda_{n+1}, \dots, \lambda_m$

Eigendecomposition:

$$R = \begin{bmatrix} S & G \end{bmatrix} \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \ddots \end{bmatrix} \begin{bmatrix} S^* \\ G^* \end{bmatrix}.$$



► Note that

RG =



Note that

$$RG = \sigma^2G =$$



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$

ightharpoonup Follows that $APA^*G=0$.



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$

▶ Follows that $APA^*G = 0$. Since AP has full rank we get

$$0 = A^*G =$$



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$

▶ Follows that $APA^*G = 0$. Since AP has full rank we get

$$0 = A^*G = \begin{bmatrix} a^*(\omega_1)G \\ \vdots \\ a^*(\omega_n)G \end{bmatrix}$$



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$

Follows that $APA^*G=0$. Since AP has full rank we get

$$0 = A^*G = \begin{vmatrix} a^*(\omega_1)G \\ \vdots \\ a^*(\omega_n)G \end{vmatrix} \implies a^*(\omega)G = 0 \text{ if } \omega = \omega_k.$$



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$

Follows that $APA^*G=0$. Since AP has full rank we get

$$0 = A^*G = \begin{bmatrix} a^*(\omega_1)G \\ \vdots \\ a^*(\omega_n)G \end{bmatrix} \implies a^*(\omega)G = 0 \text{ if } \omega = \omega_k.$$

ightharpoonup Result: For $\omega = \omega_k$ (the true frequencies)

$$a^*(\omega)GG^*a(\omega) = 0$$



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$

Follows that $APA^*G=0$. Since AP has full rank we get

$$0 = A^*G = \begin{bmatrix} a^*(\omega_1)G \\ \vdots \\ a^*(\omega_n)G \end{bmatrix} \implies a^*(\omega)G = 0 \text{ if } \omega = \omega_k.$$

ightharpoonup Result: For $\omega = \omega_k$ (the true frequencies)

$$a^*(\omega)GG^*a(\omega) = 0$$

It can be shown that the above holds if and only if $\omega = \omega_k$ for $k = 1, \ldots, n$.



Note that

$$RG = \sigma^2 G = APA^*G + \sigma^2 G$$

▶ Follows that $APA^*G = 0$. Since AP has full rank we get

$$0 = A^*G = \begin{bmatrix} a^*(\omega_1)G \\ \vdots \\ a^*(\omega_n)G \end{bmatrix} \implies a^*(\omega)G = 0 \text{ if } \omega = \omega_k.$$

ightharpoonup Result: For $\omega=\omega_k$ (the true frequencies)

$$a^*(\omega)GG^*a(\omega) = 0$$

- It can be shown that the above holds if and only if $\omega = \omega_k$ for $k = 1, \dots, n$.
- (Any $a(\tilde{\omega})$ that satisfy the equation belongs to $\mathcal{N}(G^*)$, which is a subspace of dimension n. At most n vectors on the form $a(\omega)$ can belong to this subspace, which by the above must be $\{a(\omega_k)\}_{k=1}^n$.

SysCon, IT, UU



MUSIC

Compute sample covariance matrix (hermitian positive definite)

$$\hat{R} = \frac{1}{N} \sum_{t=m}^{N} \tilde{y}(t) \tilde{y}^*(t)$$

and its eigendecomposition (here SVD) giving matrices \hat{S} and \hat{G}



MUSIC

Compute sample covariance matrix (hermitian positive definite)

$$\hat{R} = \frac{1}{N} \sum_{t=m}^{N} \tilde{y}(t) \tilde{y}^*(t)$$

and its eigendecomposition (here SVD) giving matrices \hat{S} and \hat{G}

Spectral MUSIC

Plot pseudo spectrum and determine frequencies from the n highest peaks

$$\frac{1}{a^*(\omega)\hat{G}\hat{G}^*a(\omega)} \quad \omega \in [-\pi, \pi]$$



MUSIC

Compute sample covariance matrix (hermitian positive definite)

$$\hat{R} = \frac{1}{N} \sum_{t=m}^{N} \tilde{y}(t) \tilde{y}^*(t)$$

and its eigendecomposition (here SVD) giving matrices \hat{S} and \hat{G}

Spectral MUSIC

Plot pseudo spectrum and determine frequencies from the nhighest peaks

$$\frac{1}{a^*(\omega)\hat{G}\hat{G}^*a(\omega)} \quad \omega \in [-\pi, \pi]$$

Root MUSIC

Determine frequencies from the angular positions of the n roots of

$$a^{\mathsf{T}}(z^{-1})\hat{G}\hat{G}^*a(z) = 0$$

closest to the unit circle



Min-Norm method



▶ Goal: Reduce computational burden, and reduce risk of false frequency estimates.



- Goal: Reduce computational burden, and reduce risk of false frequency estimates.
- Idea: From our previous discussion we can see that for any vector $g \in \mathcal{R}(G) = \mathcal{N}(A^*)$ we have

$$a^*(\omega)g = 0$$
, for $\omega = \omega_k$.



- Goal: Reduce computational burden, and reduce risk of false frequency estimates.
- ▶ Idea: From our previous discussion we can see that for any vector $q \in \mathcal{R}(G) = \mathcal{N}(A^*)$ we have

$$a^*(\omega)g = 0$$
, for $\omega = \omega_k$.

Computationally easier to solve this equation!



- Goal: Reduce computational burden, and reduce risk of false frequency estimates.
- ▶ Idea: From our previous discussion we can see that for any vector $q \in \mathcal{R}(G) = \mathcal{N}(A^*)$ we have

$$a^*(\omega)g = 0$$
, for $\omega = \omega_k$.

- Computationally easier to solve this equation!
- ▶ Which vector to use? Are strong empirical evidence that the vector

$$g = \begin{bmatrix} 1 \\ \tilde{g} \end{bmatrix} \in \mathcal{R}(G)$$

with minimum Euclidean norm have good properties (accuracy, and reduced risk of spurious ω -estimates).



Min-Norm

Find

$$\begin{bmatrix} 1 \\ \hat{g} \end{bmatrix} \in \mathcal{R}(\hat{G})$$

with minimum Euclidean norm (see textbook).



Min-Norm

Find

$$\begin{bmatrix} 1 \\ \hat{g} \end{bmatrix} \in \mathcal{R}(\hat{G})$$

with minimum Euclidean norm (see textbook).

Spectral Min-Norm

Plot pseudo spectrum and determine frequencies from the \boldsymbol{n}

highest peaks

$$\frac{1}{a^*(\omega) \begin{bmatrix} 1 \\ \hat{g} \end{bmatrix}}$$



Min-Norm

Find

$$\begin{bmatrix} 1 \\ \hat{g} \end{bmatrix} \in \mathcal{R}(\hat{G})$$

with minimum Euclidean norm (see textbook).

Spectral Min-Norm

Plot pseudo spectrum and determine frequencies from the n highest peaks $\begin{tabular}{l} 1 \end{tabular}$

$$\frac{1}{a^*(\omega) \begin{bmatrix} 1 \\ \hat{g} \end{bmatrix}}$$

Root Min-Norm

Determine frequencies from the angular positions of the n roots of

$$a^{\mathsf{T}}(z^{-1}) \begin{bmatrix} 1 \\ \hat{g} \end{bmatrix} = 0$$

closest to the unit circle



Estimation of Signal Parameters by Rotational Invariance Techniques (ESPRIT)

esprit (noun) - vivacious cleverness or wit

21/26 per.mattssonk@it.uu.se SysCon, IT, UU



Theory of ESPRIT

 \blacktriangleright Let A_1 be A with last row removed, and A_2 be A with first row removed



Theory of ESPRIT

Let A_1 be A with last row removed, and A_2 be A with first row removed, i.e.,

$$A_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} A, \quad A_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} A, \quad (m-1 \times n)$$



▶ Let A_1 be A with last row removed, and A_2 be A with first row removed, i.e.,

$$A_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} A, \quad A_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} A, \quad (m-1 \times n)$$

▶ then,

$$A_2 = A_1 D, \quad D = \begin{bmatrix} e^{-i\omega_1} & 0 \\ & \ddots & \\ 0 & e^{-i\omega_n} \end{bmatrix}.$$



▶ Let A_1 be A with last row removed, and A_2 be A with first row removed, i.e.,

$$A_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} A, \quad A_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} A, \quad (m-1 \times n)$$

▶ then,

$$A_2 = A_1 D, \quad D = \begin{bmatrix} e^{-i\omega_1} & 0 \\ & \ddots & \\ 0 & e^{-i\omega_n} \end{bmatrix}.$$

► In the same way let

$$S_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} S$$
, $S_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} S$.

▶ There exist nonsingular C such that S = AC.



▶ Let A_1 be A with last row removed, and A_2 be A with first row removed, i.e.,

$$A_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} A, \quad A_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} A, \quad (m-1 \times n)$$

▶ then,

$$A_2 = A_1 D, \quad D = \begin{bmatrix} e^{-i\omega_1} & 0 \\ & \ddots & \\ 0 & e^{-i\omega_n} \end{bmatrix}.$$

► In the same way let

$$S_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} S$$
, $S_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} S$.

ightharpoonup There exist nonsingular C such that S=AC. Hence,

$$S_2 =$$



▶ Let A_1 be A with last row removed, and A_2 be A with first row removed, i.e.,

$$A_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} A, \quad A_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} A, \quad (m-1 \times n)$$

▶ then,

$$A_2 = A_1 D, \quad D = \begin{bmatrix} e^{-i\omega_1} & 0 \\ & \ddots & \\ 0 & e^{-i\omega_n} \end{bmatrix}.$$

► In the same way let

$$S_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} S$$
, $S_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} S$.

ightharpoonup There exist nonsingular C such that S=AC. Hence,

$$S_2 = A_2C =$$



▶ Let A_1 be A with last row removed, and A_2 be A with first row removed, i.e.,

$$A_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} A, \quad A_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} A, \quad (m-1 \times n)$$

▶ then,

$$A_2 = A_1 D, \quad D = \begin{bmatrix} e^{-i\omega_1} & 0 \\ & \ddots & \\ 0 & e^{-i\omega_n} \end{bmatrix}.$$

► In the same way let

$$S_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} S$$
, $S_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} S$.

ightharpoonup There exist nonsingular C such that S=AC. Hence,

$$S_2 = A_2C = A_1DC =$$



▶ Let A_1 be A with last row removed, and A_2 be A with first row removed, i.e.,

$$A_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} A, \quad A_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} A, \quad (m-1 \times n)$$

▶ then,

$$A_2 = A_1 D, \quad D = \begin{bmatrix} e^{-i\omega_1} & 0 \\ & \ddots & \\ 0 & e^{-i\omega_n} \end{bmatrix}.$$

► In the same way let

$$S_1 = \begin{bmatrix} I_{m-1} & 0 \end{bmatrix} S$$
, $S_2 = \begin{bmatrix} 0 & I_{m-1} \end{bmatrix} S$.

▶ There exist nonsingular C such that S = AC. Hence,

$$S_2 = A_2 C = A_1 DC = S_1 \underbrace{C^{-1} DC}_{1}.$$



► We have

$$S_2 = S_1 \phi, \quad \text{where } \phi = C^{-1} DC.$$



► We have

$$S_2 = S_1 \phi, \quad \text{where } \phi = C^{-1} DC.$$

Eigenvalues of ϕ : ϕ is similar to $D \Rightarrow$



We have

$$S_2 = S_1 \phi$$
, where $\phi = C^{-1}DC$.

Eigenvalues of ϕ : ϕ is similar to $D \Rightarrow \text{The eigenvalues}$ of ϕ are the same as the eigenvalues of D, i.e., $\{e^{-i\omega_k}\}_{k=1}^n$.



We have

$$S_2 = S_1 \phi$$
, where $\phi = C^{-1}DC$.

- **Eigenvalues** of ϕ : ϕ is similar to $D \Rightarrow \text{The eigenvalues}$ of ϕ are the same as the eigenvalues of D, i.e., $\{e^{-i\omega_k}\}_{k=1}^n$.
- $ightharpoonup S_1$ and S_2 have full rank, so ϕ is uniquely given by

$$\phi = (S_1^* S_1)^{-1} S_1^* S_2.$$



We have

$$S_2 = S_1 \phi$$
, where $\phi = C^{-1}DC$.

- ▶ Eigenvalues of ϕ : ϕ is similar to $D \Rightarrow$ The eigenvalues of ϕ are the same as the eigenvalues of D, i.e., $\{e^{-i\omega_k}\}_{k=1}^n$.
- $ightharpoonup S_1$ and S_2 have full rank, so ϕ is uniquely given by

$$\phi = (S_1^* S_1)^{-1} S_1^* S_2.$$

ESPIRIT:

▶ Compute estimated \hat{R} for some m > n.



We have

$$S_2 = S_1 \phi$$
, where $\phi = C^{-1}DC$.

- **Eigenvalues** of ϕ : ϕ is similar to $D \Rightarrow \text{The eigenvalues}$ of ϕ are the same as the eigenvalues of D, i.e., $\{e^{-i\omega_k}\}_{k=1}^n$.
- $ightharpoonup S_1$ and S_2 have full rank, so ϕ is uniquely given by

$$\phi = (S_1^* S_1)^{-1} S_1^* S_2.$$

ESPIRIT:

- ▶ Compute estimated \hat{R} for some m > n.
- ▶ Use SVD to get \hat{S} and construct \hat{S}_1 and \hat{S}_2 .



We have

$$S_2 = S_1 \phi$$
, where $\phi = C^{-1}DC$.

- ▶ Eigenvalues of ϕ : ϕ is similar to $D \Rightarrow$ The eigenvalues of ϕ are the same as the eigenvalues of D, i.e., $\{e^{-i\omega_k}\}_{k=1}^n$.
- ▶ S_1 and S_2 have full rank, so ϕ is uniquely given by

$$\phi = (S_1^* S_1)^{-1} S_1^* S_2.$$

ESPIRIT:

- ▶ Compute estimated \hat{R} for some m > n.
- ▶ Use SVD to get \hat{S} and construct \hat{S}_1 and \hat{S}_2 .
- ► Let $\hat{\phi} = (\hat{S}_1^* \hat{S}_1)^{-1} \hat{S}_1^* \hat{S}_2$ (LS-solution).



We have

$$S_2 = S_1 \phi$$
, where $\phi = C^{-1}DC$.

- ▶ Eigenvalues of ϕ : ϕ is similar to $D \Rightarrow$ The eigenvalues of ϕ are the same as the eigenvalues of D, i.e., $\{e^{-i\omega_k}\}_{k=1}^n$.
- $ightharpoonup S_1$ and S_2 have full rank, so ϕ is uniquely given by

$$\phi = (S_1^* S_1)^{-1} S_1^* S_2.$$

ESPIRIT:

- ▶ Compute estimated \hat{R} for some m > n.
- ▶ Use SVD to get \hat{S} and construct \hat{S}_1 and \hat{S}_2 .
- ► Let $\hat{\phi} = (\hat{S}_1^* \hat{S}_1)^{-1} \hat{S}_1^* \hat{S}_2$ (LS-solution).
- Let \hat{v}_k be the eigenvalues of $\hat{\phi}$. Then the estimated frequencies are

$$\hat{\omega}_k = -\arg(\hat{v}_k).$$



► We have

$$S_2 = S_1 \phi$$
, where $\phi = C^{-1}DC$.

- ▶ Eigenvalues of ϕ : ϕ is similar to $D \Rightarrow$ The eigenvalues of ϕ are the same as the eigenvalues of D, i.e., $\{e^{-i\omega_k}\}_{k=1}^n$.
- $ightharpoonup S_1$ and S_2 have full rank, so ϕ is uniquely given by

$$\phi = (S_1^* S_1)^{-1} S_1^* S_2.$$

ESPIRIT:

- ▶ Compute estimated \hat{R} for some m > n.
- ▶ Use SVD to get \hat{S} and construct \hat{S}_1 and \hat{S}_2 .
- ► Let $\hat{\phi} = (\hat{S}_{1}^{*}\hat{S}_{1})^{-1}\hat{S}_{1}^{*}\hat{S}_{2}$ (LS-solution).
- Let \hat{v}_k be the eigenvalues of $\hat{\phi}$. Then the estimated frequencies are

$$\hat{\omega}_k = -\arg(\hat{v}_k).$$

If estimates of α_k are needed, use LS with the estimated frequencies.



Performance

- ▶ All methods can achieve super resolution (beyond the Periodogram)
- Finding the frequencies through subspace methods is tractable as opposed to NLS (typically)
- ► ESPRIT is typically slightly better than the others
- We still have to choose the order n

Method	Computational Burden	Accuracy / Resolution	Risk for False Freq Estimates
Periodogram	small	medium-high	medium
Nonlinear LS	very high	very high	very high
Yule-Walker	medium	high	medium
Pisarenko	small	low	none
MUSIC	high	high	medium
Min-Norm	medium	high	small
ESPRIT	medium	very high	none

per.mattssonk@it.uu.se SysCon, IT, UU



MATLAB

Useful MATLAB functions:

- ▶ hoyw()
- music()
- minnorm()
- esprit()
- ▶ freqaphi()
- ▶ lsa()



Summary

- ▶ Alternatives to NLS, based on ARMA and covariance model
- ► HOYW, MUSIC, Min-Norm, ESPRIT
- Complicated derivation but easy to use (and implement)



Summary

- ► Alternatives to NLS, based on ARMA and covariance model
- ► HOYW, MUSIC, Min-Norm, ESPRIT
- Complicated derivation but easy to use (and implement)

Next lecture:

- ► How to choose the model order?
- Information criteria
- Heuristic approaches
- Cross validation