

POK Operating System

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Forewords



- The POK project
 - Design and implement safe and secure system
 - Complete development process with model-based engineering
- Now, focus on the underlying operating system
 - Main guidelines
 - Architecture, services
 - Go into code organization

Outline



Introduction

Overall architecture

Kernel layer

Partition Layer

Conclusion

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Introduction



- Partitioning functionalities
 - Time isolation across partitions
 - Space isolation segments and communication control
- Interoperability
 - Ada and C programming interfaces
 - ARINC653 compliance
 - POSIX compliance
- Embedded architectures support
 - X86/QEMU
 - PPC/QEMU
 - SPARC/Leon

One OS, two layers



Kernel layer

- Critical functions
- Few services, prone to verification/certification
- Actually < 6000 SLOC

libpok

- Non-critical functions
- All remaining services
- Actually ~ 20000 SLOC

Project guidelines



- Real-Time compliance
 - O(1) algorithms
- High-integrity compliance
 - Static allocation of kernel/partitions resources
 - Avoid dead code, useless functionalities

- Embedded systems compliance
 - Low complexity
 - Avoid memory overhead

Development guidelines



- Reduce critical code
 - Few services in kernel
 - Remaining services in libpok
- Each snapshot must work
 - Compilation of all examples on all architectures
 - Prevent functionalities breakage
- Enforce coding style
 - Use rules inspired by best-pratices
 - See MISRA-C for example
 - Look at doc/CODING_GUIDELINES

Naming guidelines



- Resources dimensioning
 - POK_CONFIG_NB_* macros
 - Ex: POK_CONFIG_NB_THREADS
- Service configuration, services inclusion
 - POK_NEEDS_FUNCTIONS
 - Ex: POK_NEEDS_TIME, POK_NEEDS_SCHED, ...
- Headers
 - #ifndef __POK_SERVICE_NAME_H__
 - Ex: #ifndef __POK_SCHED_H__

Naming guidelines – cont'd



Types

- pok_typename_t
- See include/types.h for types definitions
- Ex: pok_partition_t, type that contains partition attributes

Functions

- pok_servicename_functionname ()
- Ex: pok partition load, function that loads a partition

Outline



Introduction

Overall architecture

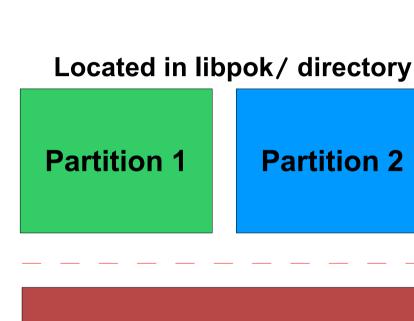
Kernel layer

Partition Layer

Conclusion

Main architecture





Kernel layer | Partition layer

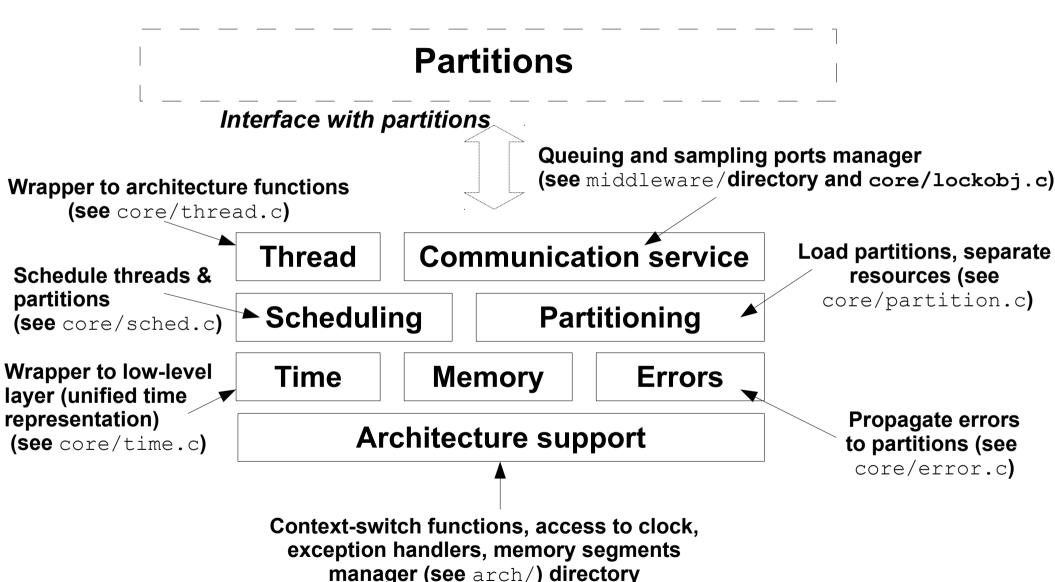
- Intra-partition comm.
- ARINC653 & POSIX layers
- Libc & libm support
- Ada layer
- Device drivers
- Ciphers algorithms
- Time & space partitioning
- I/O interface
- Scheduling

Located in kernel/ directory

Partitioning Kernel

Kernel architecture





We love globvars ...



- Globvars = hell!
 - Don't use them, it introduces too many bugs!
- ... but useful when programming a kernel
 - pok_thread_t threads[POK_CONFIG_NB_THREADS]
 - pok_partition_t pok_partitions[POK_CONFIG_NB_PARTITIONS]
 - pok_port_t pok_ports[POK_CONFIG_NB_PORTS]
 - Used very carefully inside the kernel!

Libpok architecture



DES/Blowfish/ceasar cipher algorithms, OpenSSL backport (see protocols/ directory)

Partial support for ARINC653 APEX (see ada/and arinc653/directories)

Ethernet network in partition space, polling mode (see drivers/ directory)

Math functions, backport from NetBSD (see libm/ directory)

Cipher algorithms

Lib math

Ada ARÎNC653 layer

Restricted libc (see

POSIX layer

ARINC653 layer

Libc

Device drivers

Deterministic memory allocator see

(core/allocator.c)

Memory allocator

Errors handling

Kernel interface

Intra-partition comm.

Architecture support

Access to kernel functionalities:

- → thread creation
- → lockobj management
- → inter-partitions comm.
- → see include/syscall.h

Blackboards, buffers, events and semaphores handling (see middleware/) directory

Architecture-specific types (see arch/) directory

Services separation



- No globvars
 - Too many potential interactions
- Easily add/remove services
 - Rely on POK_NEEDS_* macros
- Services configuration
 - POK_CONFIG_* macros

Error Handling



Kernel level

- Kernel layer function
- Discriminant: raised error

Partition level

- Kernel layer function
- Discriminants: raised error, faulty partition

Process level

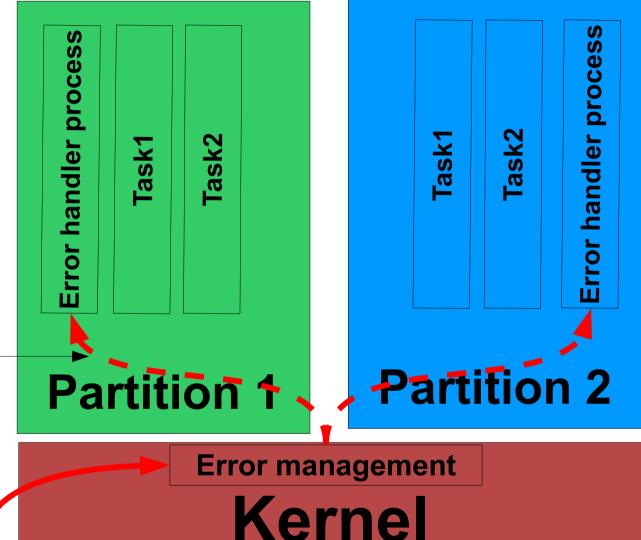
- Dedicated thread in each partition
- Discriminants: raised error, faulty partition
- Kernel receives exception and activates the thread

Process level error handling



Identify faulty partition and its associated faulty process

Detects error (ex: divide by 0)



Hardware

Outline



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Sources organization



- arch/
 - Architecture/BSP-dependent files
 - Ex: arch/x86/x86-qemu
- core/
 - Mainly wrappers to architecture-dependent services
 - Maintain isolation across partitions
 - Partitions loading
- middleware/
 - Inter-partitions communication

Resources organization



- Statically defined
 - All resources are statically defined
 - Massive use of arrays
- No memory allocation in kernel layer
 - Analysis purpose
 - Ease further certification/verification

pok_partition_t



```
typedef struct
   uint32 t
                          base addr;
   uint32 t
                          base vaddr;
   uint32 t
                          size;
   const char
                          *name;
   uint32 t
                          nthreads:
   uint8 t
                          priority;
   uint32 t
                          period;
   pok sched t
                          sched;
   uint32 t (*sched func) (uint32 t low, uint32/t hi/gh);
   uint64 t
                          activation;
   uint32 t
                          current thread;
                          thread index low;
   uint32 t
   uint32 t
                          thread index high;
                          thread index;
   uint32 t
#if defined(POK NEEDS LOCKOBJECTS)
defined (POK NEEDS ERROR HANDLING)
   uint8 t
                          lockobj index low;
   uint8 t
                          lockobj index high;
   uint8 t
                          nlockobjs;
#endif
/* ... */
} pok partition t;
```

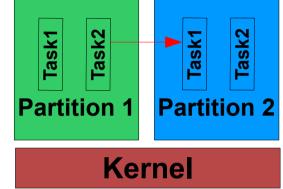
Indicates where the threads of a partition reside.

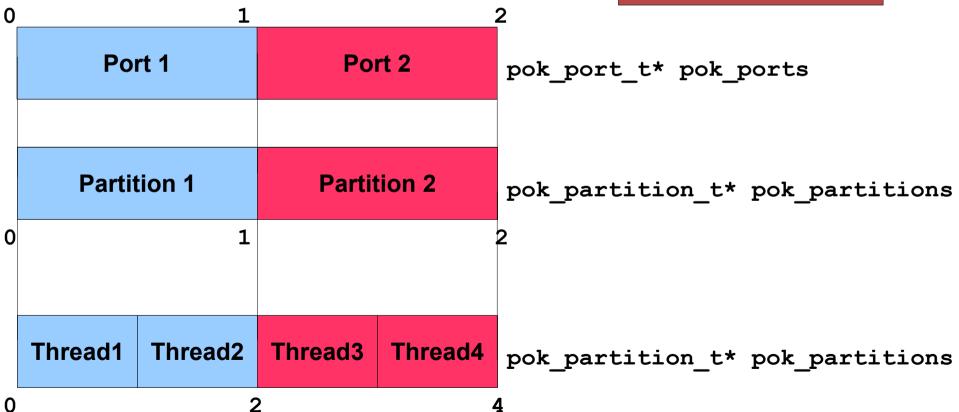
Bound partition accesses in the lockobjects array.

Critical functions must absolutly CHECK these bound to enforce resources isolation.

Resources organization







Kernel startup (core/boot.c)



```
void pok boot ()
  pok arch init();
  pok bsp init();
#if defined (POK NEEDS TIME) || defined (POK NEEDS SCHED) || defined (POK NEEDS THREADS)
  pok time init();
#endif
                                         Activate services according
#ifdef POK NEEDS PARTITIONS
  pok partition init ();
                                  to system requirements (POK NEEDS*)
#endif
#ifdef POK NEEDS THREADS
  pok thread init ();
#endif
                                                                   Initialize kernel services
#if defined (POK NEEDS SCHED) || defined (POK NEEDS THREADS)
  pok sched init ();
#endif
#if (defined POK NEEDS LOCKOBJ) || defined (POK NEEDS PORTS QUEUEING) || defined (POK NEEDS PORTS SAMPLING
  pok lockobj init ();
#endif
#if defined (POK NEEDS PORTS QUEUEING) || defined (POK NEEDS PORTS SAMPLING)
  pok port init ();
  pok queue init ();
#endif
#if defined (POK NEEDS DEBUG) || defined (POK NEEDS CONSOLE)
  pok cons write ("POK kernel initialized\n", 23);
#endif
  pok arch preempt enable();
```

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Sources organization



- arch/
 - Architecture/BSP-dependent files
 - Ex: arch/x86/x86-qemu
- core/
 - Mainly wrappers to architecture-dependent services
 - Maintain isolation across partitions
 - Partitions loading
- middleware/
 - Inter-partitions communication

Important functions



- pok_sched()
 - Called every tick
 - Reschedule the system, enforce time isolation
 - Flush partitions ports when major time frame is reached

- pok_core_syscall ()
 - Interface with partitions
 - Highly critical
 - Check space isolation of arguments

Important functions – cont'd



- pok_port_flushall ()
 - Called at each major time frame
 - Flush partitions ports

- pok_error_declare ()
 - Wakeup the error process in the partition
 - Complete necessary information to handle the error (error type, faulty thread)

Important functions – cont'd



- pok_partition_error ()
 - Raised an error at the partition level
 - Error handler differentiates each partition

- pok_kernel_error ()
 - Raise an error at kernel level

Important variables



- pok_threadt_t* threads
 - Contain informations about all threads of all partitions
 - Include IDLE and KERNEL threads
 - Access to current thread: POK_CURRENT_THREAD
- pok_partition_t* pok_partitions
 - Array of all partitions
 - Statically defined
 - Used everywhere in the sources
 - Access to the current partition: POK CURRENT PARTITION

Important variables – cont'd



- pok_port_t *pok_ports
 - Information about ALL ports of ALL partitions
 - Used in the middleware layer (sampling & queuing ports)
- pok_queue_t pok_queue
 - Big array
 - Contain data of ALL ports of the current node
 - Statically bound

Important variables – cont'd



- uint64_t current_time
 - Amount of elapsed ticks
 - Clock granularity in POK: 1ms

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Architecture-dependent layer



- Syscall handling ...
 - Marshall syscall args
- ... but mainly types interfacing
 - Do not handle many low-level functions
 - Use unprivileged rights (ring 3 on x86)
- Other functions on x86
 - PCI management
 - Input/Output ports

Kernel interfacing



Access to kernel functionalities

- Threads
- Mutexes
- Partition management
- Inter-partitions ports
- Time
- •
- Use software interrupts (aka syscalls)
 - Syscalls functions for many potential arguments
 - See.include/core/syscall.h

Intra-partition comm.



- Four communications functionalities
 - Blackboard
 - Buffer
 - Semaphore
 - Event
- Resources statically allocated
 - cf. POK_CONFIG_NB_BLACKBOARDS, POK_CONFIG,NB_BUFFERS, ...
 - Same mechanisms as inter-partitions functionalities in kernel
- Rely on kernel interfacing functions
 - Require mutex handling

Errors handling



Error process handler creation

- cf. pok_error_handler_create ()
- Create a task, entrypoint=pok_error_handler_worker

Error handler internals

- Declare as ready (pok_error_handler_set_ready ())
- Catch an error (pok_error_get ())
- Handle error (written by the developer)

Execution of error process

Executed as soon as an error is raised

Errors handling – con't



- Raise application error
 - cf. pok_raise_application_error ()
 - Report errors to the error handler process

Error worker example



```
void pok error handler worker ()
                                        Get error informations
 pok_error_status_t error status;
                                       (fault type, faulty thread)
  while (1)
    pok thread stop self ();
   pok error get (&(error status));
    switch (error status.failed thread)
      case 1:
          case POK ERROR KIND APPLICATION ERROR:
                                                          Error code
            pok thread restart (1);
            break;
          case POK ERROR KIND NUMERIC ERROR:
            pok partition set mode (POK PARTITION MODE INIT WARM);
            break;
                                           Restart the partition
        break;
```

libc



- Memory allocation (stdlib.h)
 - Rely on the deterministic memory allocation
- String handling (string.h)
 - memcmp(), strcpy(), ...
- Basic input/output (stdio.h)
 - Basic printf()
- Partial implementation
 - Some functions are missing (see include/libc/)
 - Easily extendable with code reuse from NetBSD

Device drivers



- Requires access to low-level concerns
 - Reservation of low-level access at initialization time
 - No reservation allowed at runtime

lacktriangle

Polling mode

- Experiment with one device
 - Realtek 8029, network device of QEMU
 - See drivers/ directory

Device drivers - cont'd



- Constrained to partition restrictions
 - Time & space isolation
 - Communication with other partitions using interpartitions mechanisms
- Analyze end to end latency
 - Time isolation increases response time
 - See impact of the major frame
- Incoming work on this topic
 - Preliminary work with implementation of HFPPS scheduling algorithm (cf. Burns and Nolte work)

ARINC653 layer



- Implementation of ARINC653 APEX
 - Definition of APEX in include/arinc653
- Wrapper to POK legacy API
 - Use kernel interface
 - Use on intra-partition communication
- Complete implementation
 - Almost all functions are implemented
 - Need to synchronize with newer version of the APEX

Lib math



- Access to mathematical functions
 - Required by some application code (Simulink, Lustre)

- Complete implementation
 - Successful usage with Lustre and OpenSSL algorithms

- Port of NetBSD libm
 - No licence conflicts

Cipher algorithms



- Cipher data before sending
 - Prevent data sniffing over ethernet networks
- Implementation of symmetric algorithms
 - Data Encryption Standard (DES)
 - Blowfish
 - Ceasar
- Configuration with dedicated macros
 - POK_NEEDS_PROTOCOLS
 - POK_BLOWFISH_KEY, POK_DES_KEY, ...
- Port of OpenSSL algorithms

Ada ARINC653 layer



- Compliant with standardize ARINC653 APEX
- Wrapper to the C version
 - Keep consistency between types
 - Massive use of with Interfaces.C
- Disable Ada runtime
 - Lose benefits of Ada runtime (Task, Protected objects ...)
 - Lightweight implementation
 - pragma No_Run_Time

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Conclusion



- First libre partitioned operating system !
 - Really libre (not a GPL-like software !)
- Remaining technical challenges
 - Integrate device drivers with respect to T&S isolation
 - Improve system analysis
- Improve POK!
 - Better standard support
 - Feel free to join the POK community

Thanks to ...



- François Goudal
 - Initial project (Gunther)
- Julian Pidancet
 - First version of space isolation
- Laurent Lec
 - Device drivers & Ada/ARINC653 layer
- Fabien Chouteau
 - SPARC/LEON port & Ada/ARINC653 layer
- Tristan Gingol
 - PowerPC/QEMU port



Questions?