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# CAS Applied Data Science University of Bern Module 6 Deep Learning – Music vs Speech Classification

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- 3. Goal
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  - With Pooling
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Jupyter notebook on Github: Link

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## Objective & Data

#### **Objective**

> This project tries to implement a deep learning model that classifies audio samples in music or speech.

#### Data

- > 128 audio files of 30 seconds each
  - 64 speech files
  - 64 music files

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# Data preparation, preprocessing and split

#### Split in train and test set

- > Get directory of each audio file
- > All audios from a category (i.e. speech or music) are split into a training (80%) and validation (20%) set

#### **Data preprocessing**

- Load audio files for music and speech datasets separately for training and validation
- > Applying discrete Fourier Transformation
- > Transform and cut into smaller slices (79 per audio)
- > Put together samples of speech and music
- > Add labels
- > Results in:
  - Training set: 8'058

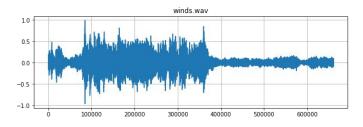
0

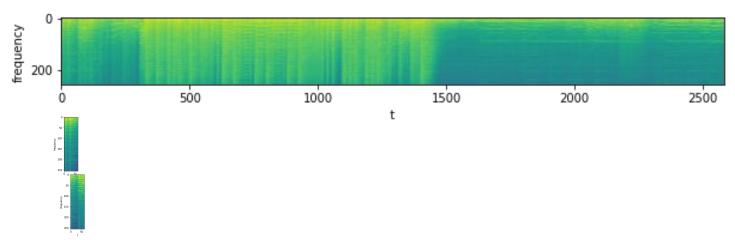




## Data preparation, preprocessing and split

Example of the **frequence** of a music file (winds.wav) including a **fourier transformation** and the first **slice**.





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## Model building

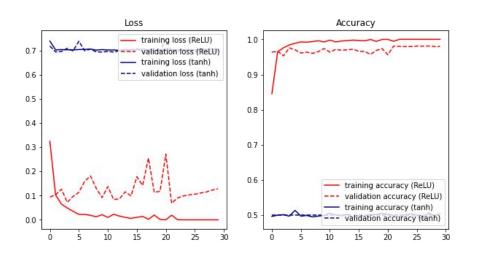
#### **Model architecture**

- > With and without Pooling Layers
  - $\circ$  Epochs = 30
  - o Batch Size = 10
- > Testing different activations functions for hidden layers
  - ReLU and tanh
- > Chose model based on accuracy
- > Try different hyperparameters
  - Stride
  - Kernels
- > Test Learnings rates
  - 0.0005
  - 0.001



## Model building - only Convolutional Layers



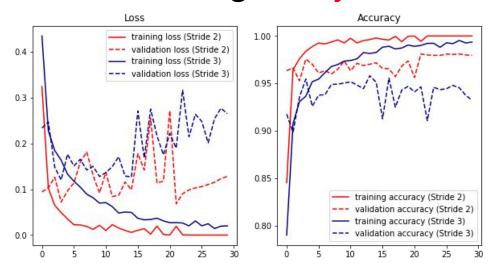


- tanh activation function does not seem to work
- tanh activation function has some drawbacks
- One of the main limitations is the "vanishing gradient" problem.
- This makes it difficult for the model to learn and converge.



## Model building - only Convolutional Layers

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- Using a smaller stride value will result in a larger output volume which can increase the computational cost of the network.
- Using a larger stride can also result in a loss of information as some areas of the input may not be considered in the output.
- According to the plot implementing stride 2 leads to lower validation loss and better validation accuracy

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### Model building - only Convolutional Layers

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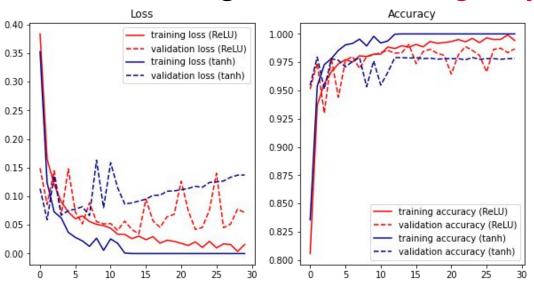
#### **Findings**

- tanh activation function does not seem to work
- Better implement ReLU activation function
- Stride of 2 leads to lower validation loss and better validation accuracy than stride of 3



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## Model building - with Pooling Layers

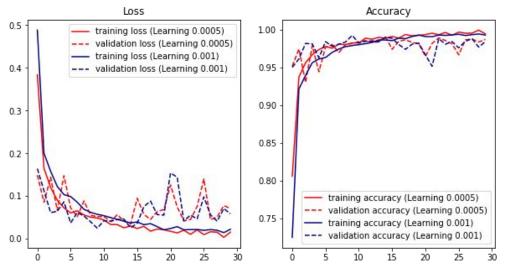


 ReLU activation function shows lower validation loss and better validation accuracy than tanh activation function



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## Model building - with Pooling Layers



- Testing model 1 with different learnings rates (0.0005 and 0.001)
- No visible difference with different learning rates





## Model building - with Pooling Layers

- Testing different value for kernel size, stride and learning rate does not show strong differences in validation set.
- For the final model the following parameters will be implemented:
  - Activation function ReLU (Rectified Linear Unit)
  - Padding "same"
  - Kernel size = 2x2
  - Strides = 2
    - Higher strides does not work well with many layers
  - Learning rate = 0.0005



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# **Model Comparison**

#### Model with pooling layer

Model: "sequential_14"		
Layer (type)	Output Shape	Param #
conv2d_56 (Conv2D)	(None, 128, 32, 32)	160
max_pooling2d_28 (MaxPoolin g2D)	(None, 64, 16, 32)	
conv2d_57 (Conv2D)	(None, 64, 16, 64)	8256
max_pooling2d_29 (MaxPoolin g2D)	(None, 32, 8, 64)	
conv2d_58 (Conv2D)	(None, 32, 8, 128)	32896
max_pooling2d_30 (MaxPoolin g2D)	(None, 16, 4, 128)	
conv2d_59 (Conv2D)	(None, 16, 4, 256)	131328
max_pooling2d_31 (MaxPoolin g2D)	(None, 8, 2, 256)	
flatten_14 (Flatten)	(None, 4096)	
dense_28 (Dense)	(None, 512)	2097664
dense_29 (Dense)	(None, 2)	1026
Total params: 2,271,330 Trainable params: 2,271,330 Non-trainable params: 0		

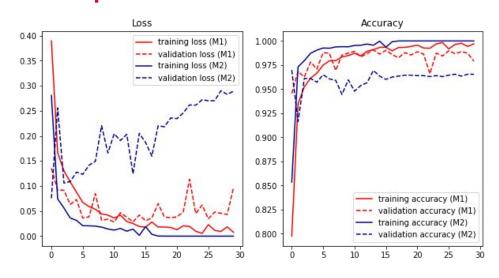
#### Model only convolutional layer

Layer (type)	Output Shape	Param #
======================================	(None, 128, 32, 32)	320
conv2d_61 (Conv2D)	(None, 64, 16, 64)	18496
conv2d_62 (Conv2D)	(None, 32, 8, 128)	73856
conv2d_63 (Conv2D)	(None, 16, 4, 256)	295168
flatten_15 (Flatten)	(None, 16384)	0
dense_30 (Dense)	(None, 512)	8389120
dense_31 (Dense)	(None, 2)	1026
======================================		



#### Comparison Model 1 & Model 2





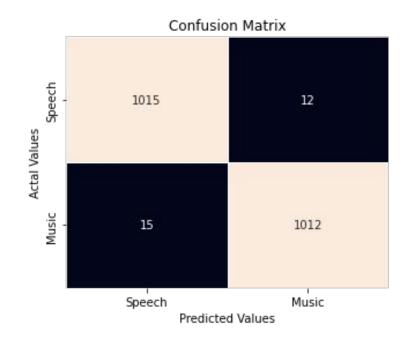
- The comparison of the model with pooling layers and the model only with convolutional layers shows lower validation loss and better training accuracy with pooling layer.
- Apparently this is mainly due to the pooling layer which improves the performance with less trainable parameters



#### **Evaluation - Confusion Matrix**

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- > Validation accuracy: 98%
- Even distribution of wrong predicted classes

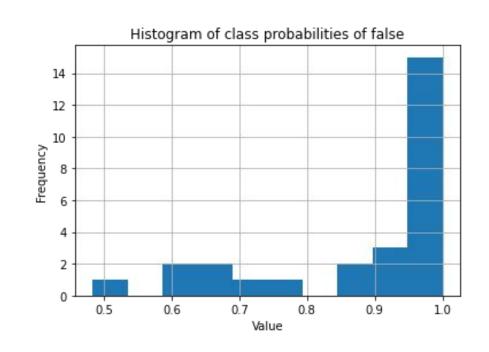




#### Evaluation - Probabilities and Audio Files

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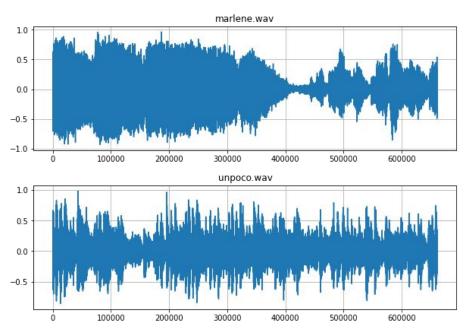
- > Fairly high probabilities by wrong ones
- > Remember: 79 slices per audio
  - Not whole song, only segment is wrongly predicted
- > Names of wrong predicted audio files
  - o ncherry.wav': 4,
  - o gravity.wav': 8,
  - voices.wav': 1,
  - o nj105.wav': 2,
  - o dialogue1.wav': 2,
  - o nj105a.wav': 2,
  - o dialogue.wav': 6,
  - o my\_voice.wav': 2

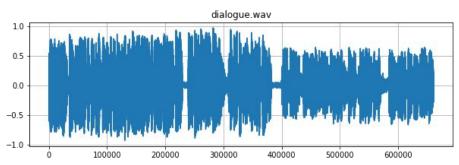




## Evaluation - Speech recognized as Music

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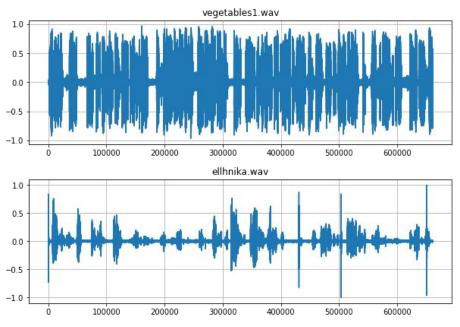


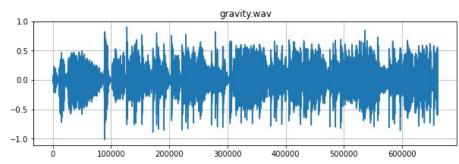




## Evaluation - Music recognized as Speech

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#### Conclusion

- > Model works very good with moderate computational effort
- > Pooling layers improved the performance with less trainable parameters
- > Variation of model parameters would be better done by grid search