

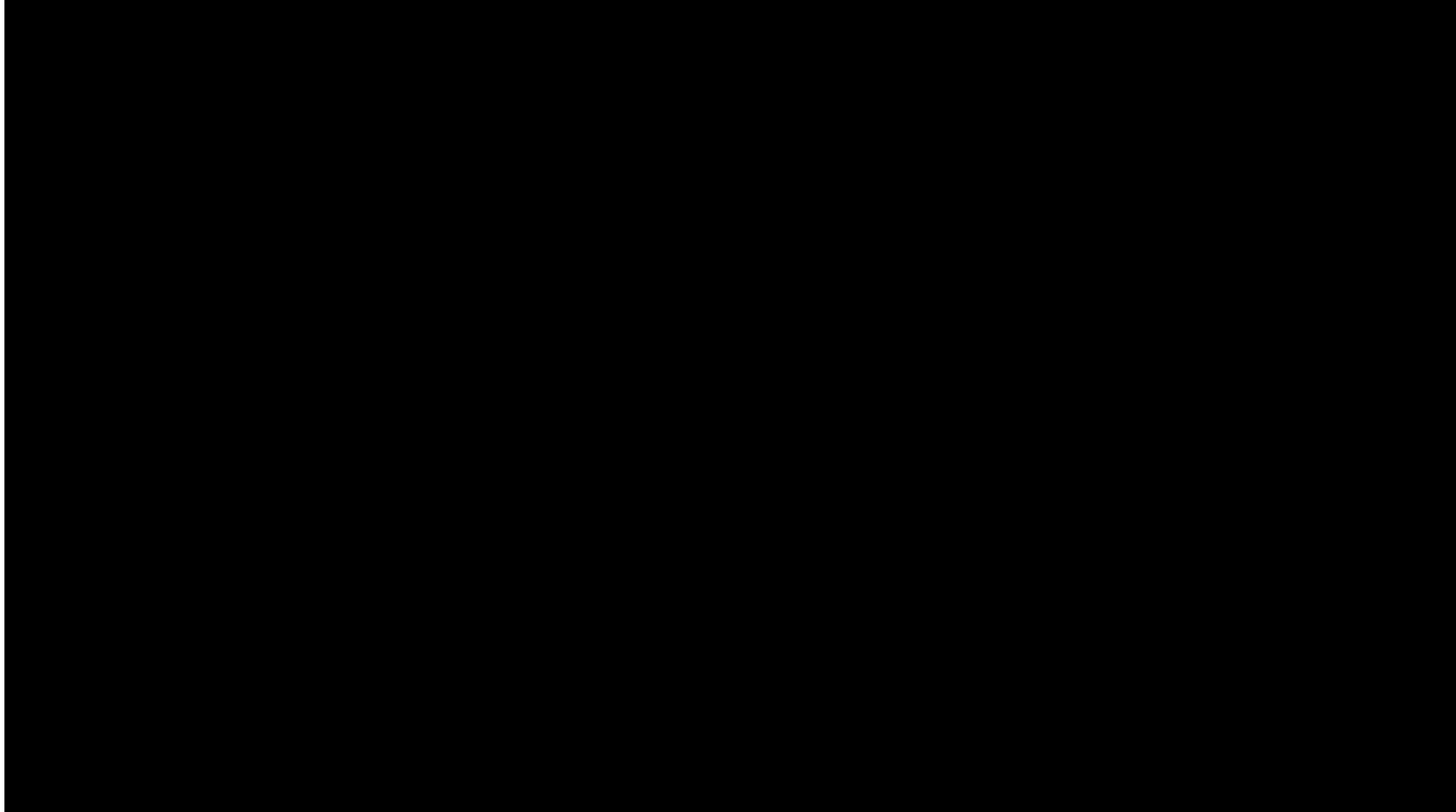


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Face recognition

What is face
recognition?

Face recognition



Face verification vs. face recognition

→ Verification

- Input image, name/ID
- Output whether the input image is that of the claimed person

1:1

99%

99.9

→ Recognition

- Has a database of K persons
- Get an input image
- Output ID if the image is any of the K persons (or “not recognized”)

1:K

K=100 ←

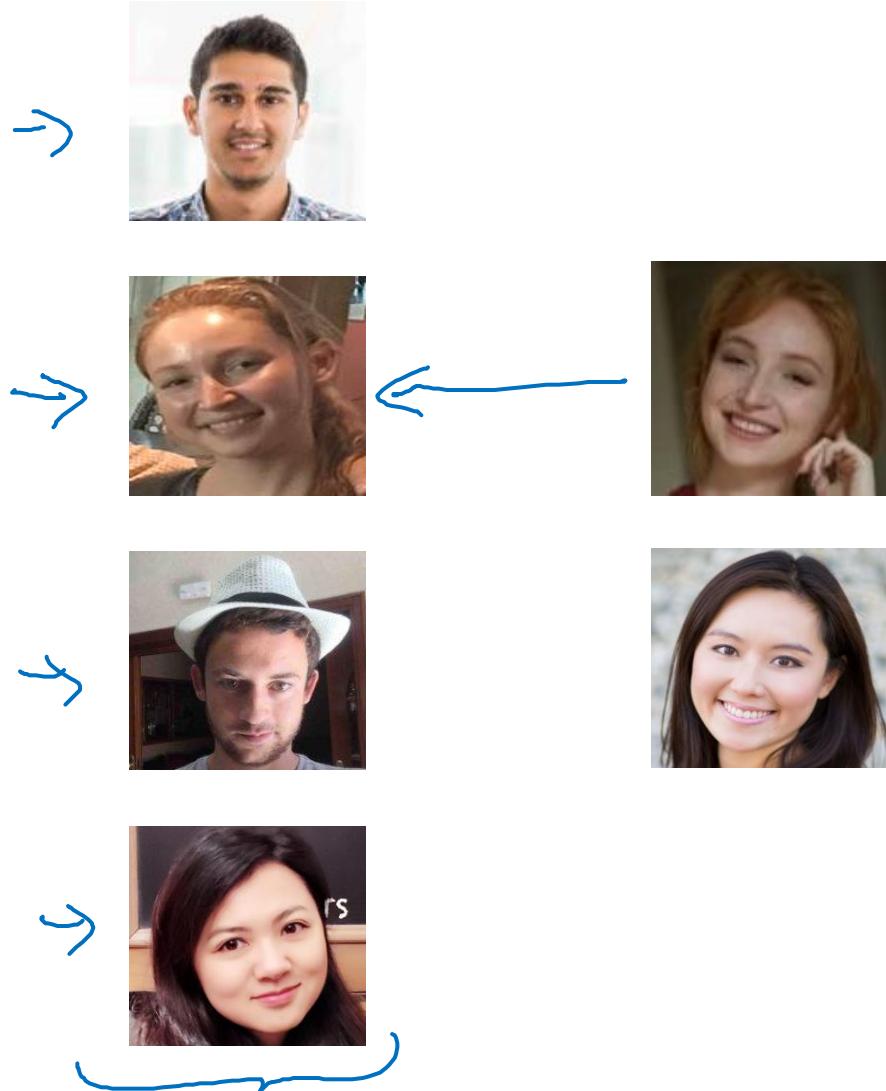


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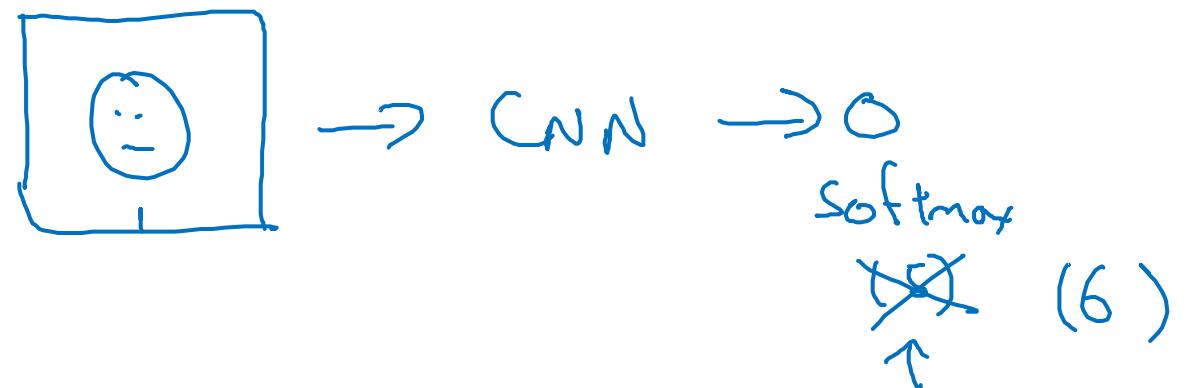
Face recognition

One-shot learning

One-shot learning



Learning from one example to recognize the person again



Learning a “similarity” function

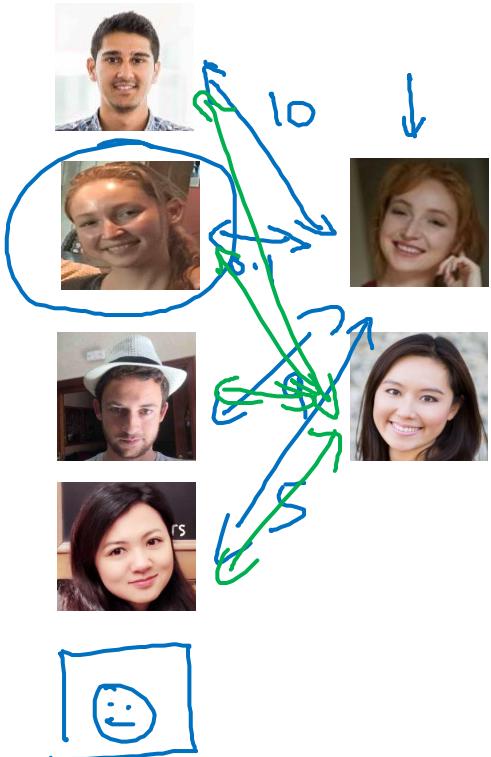
→ $d(\underline{\text{img1}}, \underline{\text{img2}})$ = degree of difference between images

If $d(\text{img1}, \text{img2}) \leq \tau$

$> \tau$

“some”
“different”

} Verification.



$d(\text{img1}, \text{img2})$

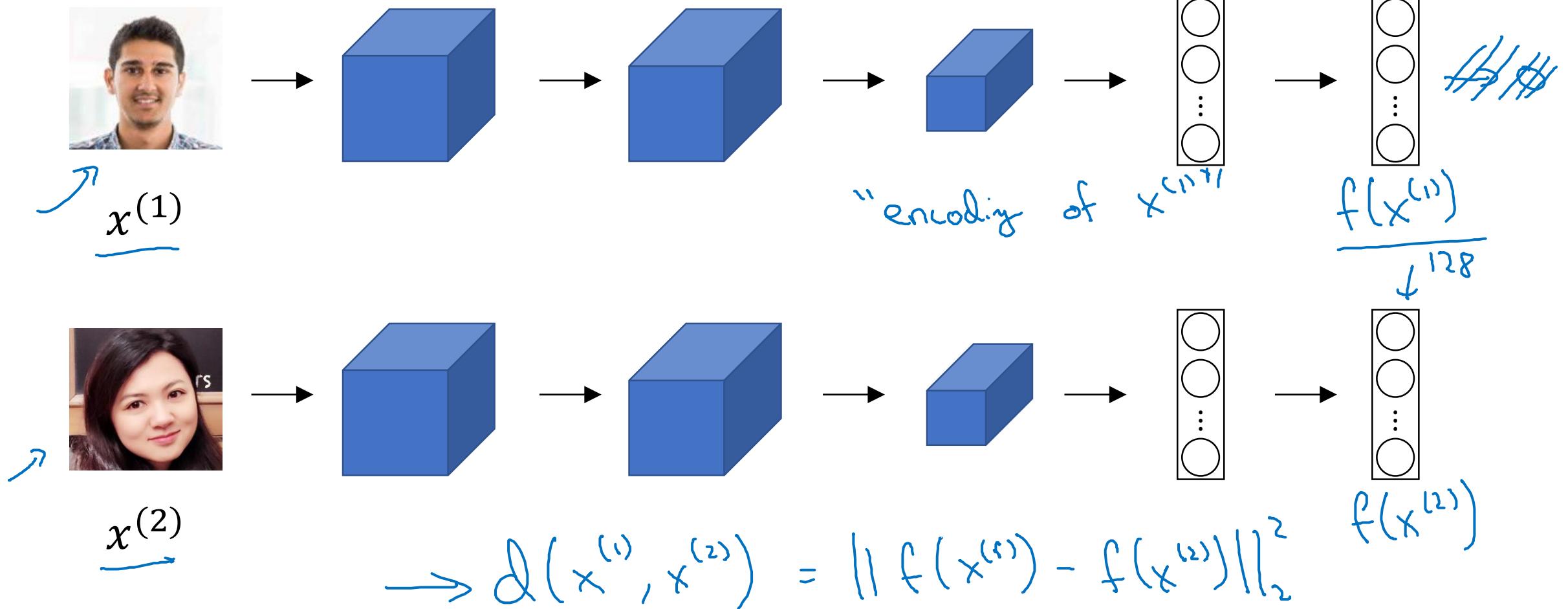


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Face recognition

Siamese network

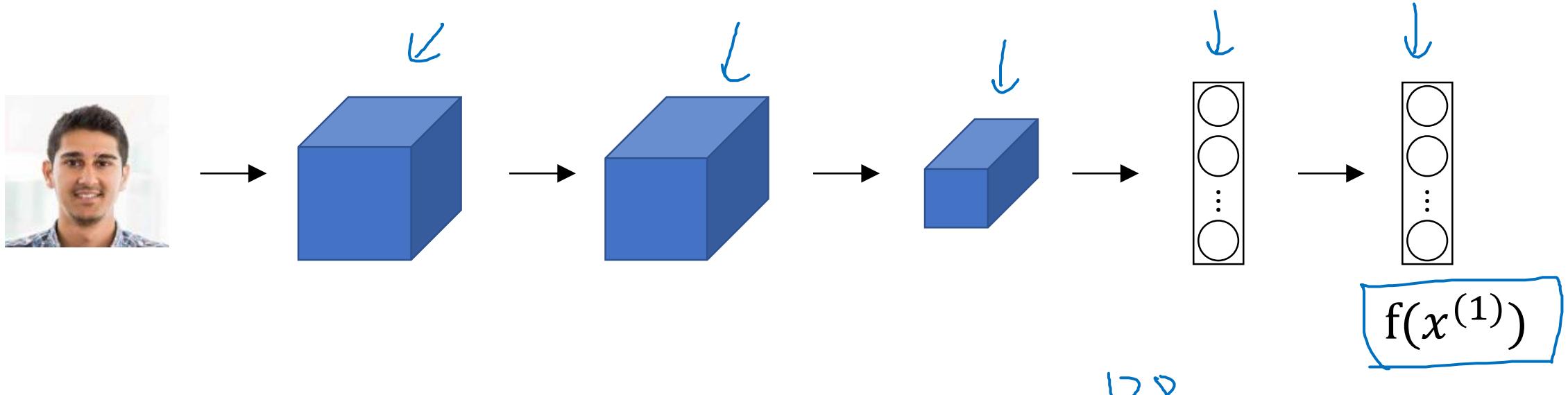
Siamese network



[Taigman et. al., 2014. DeepFace closing the gap to human level performance]

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Goal of learning



Parameters of NN define an encoding $f(x^{(i)})$

Learn parameters so that:

If $x^{(i)}, x^{(j)}$ are the same person, $\|f(x^{(i)}) - f(x^{(j)})\|^2$ is small.

If $x^{(i)}, x^{(j)}$ are different persons, $\|f(x^{(i)}) - f(x^{(j)})\|^2$ is large.

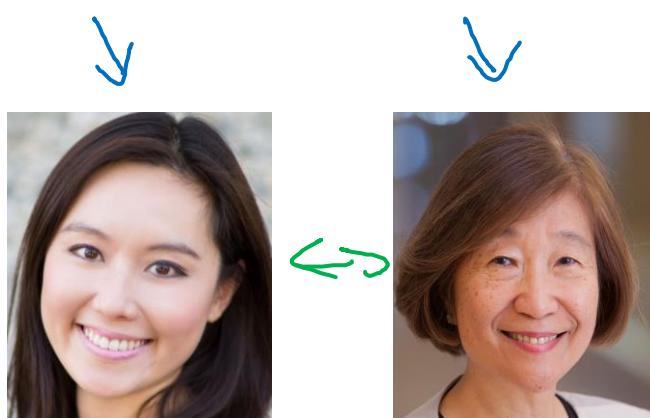
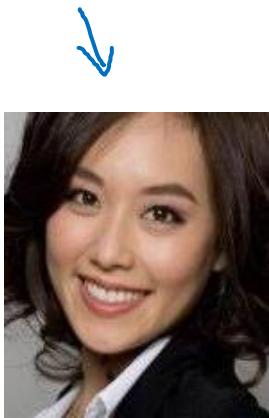
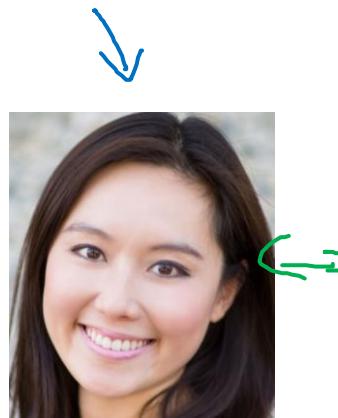


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Face recognition

Triplet loss

Learning Objective



Anchor Positive

$$A \quad d(A, P) = 0.5$$

Want:

$$\frac{\|f(A) - f(P)\|^2}{d(A, P)} + \alpha \leq 0.2$$

Anchor Negative

$$A \quad d(A, N) = \frac{N}{0.5} = 0.7$$

$$\frac{\|f(A) - f(N)\|^2}{d(A, N)}$$

$$\frac{\|f(A) - f(P)\|^2}{\circ} - \frac{\|f(A) - f(N)\|^2}{\circ} + \alpha \leq 0 \quad 4/4 \quad \text{Margin}$$

$f(\text{img}) = \vec{0}$

Loss function

Given 3 images

A, P, N :

$$\underline{L(A, P, N)} = \max \left(\left[\|f(A) - f(P)\|^2 - \|f(A) - f(N)\|^2 + \lambda \right], 0 \right)$$

$$J = \sum_{i=1}^m L(A^{(i)}, P^{(i)}, N^{(i)})$$

A, P
 T

Training set: $\underbrace{10k}_{\infty}$ pictures of $\frac{1k}{\infty}$ persons

Choosing the triplets A,P,N



During training, if A,P,N are chosen randomly,
 $d(A, P) + \alpha \leq d(A, N)$ is easily satisfied.

$$\underbrace{\|f(A) - f(P)\|^2}_{\text{Distance between } A \text{ and } P} + \alpha \leq \underbrace{\|f(A) - f(N)\|^2}_{\text{Distance between } A \text{ and } N}$$

Choose triplets that're “hard” to train on.

$$\underbrace{d(A, P)}_{\downarrow} + \alpha \approx \underbrace{d(A, N)}_{\uparrow}$$

Face Net
Deep Face



Training set using triplet loss

Anchor



Positive



Negative



:

:

:



J

$$d(x^{(i)}, x^{(j)})$$

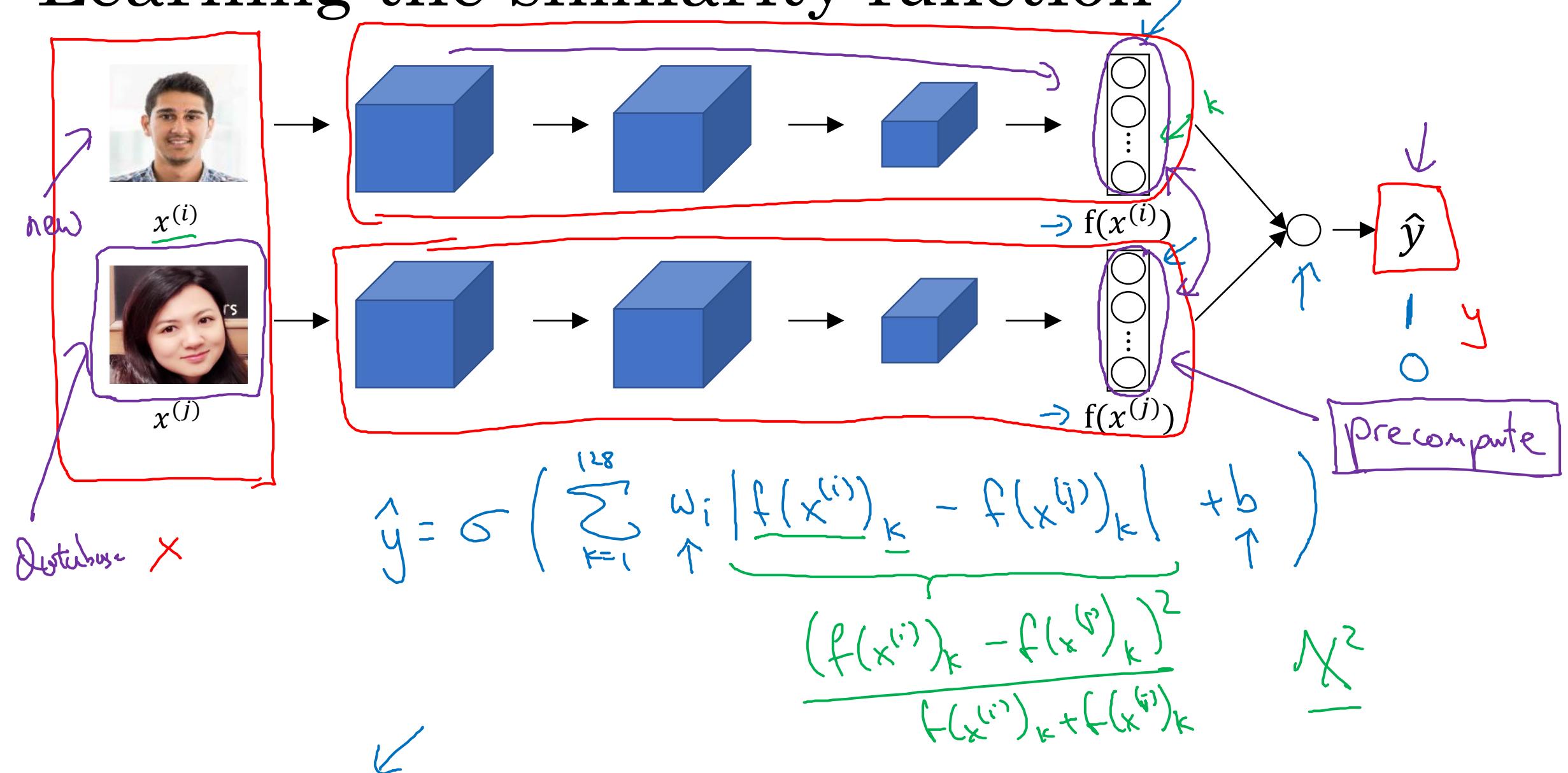


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Face recognition

Face verification and binary classification

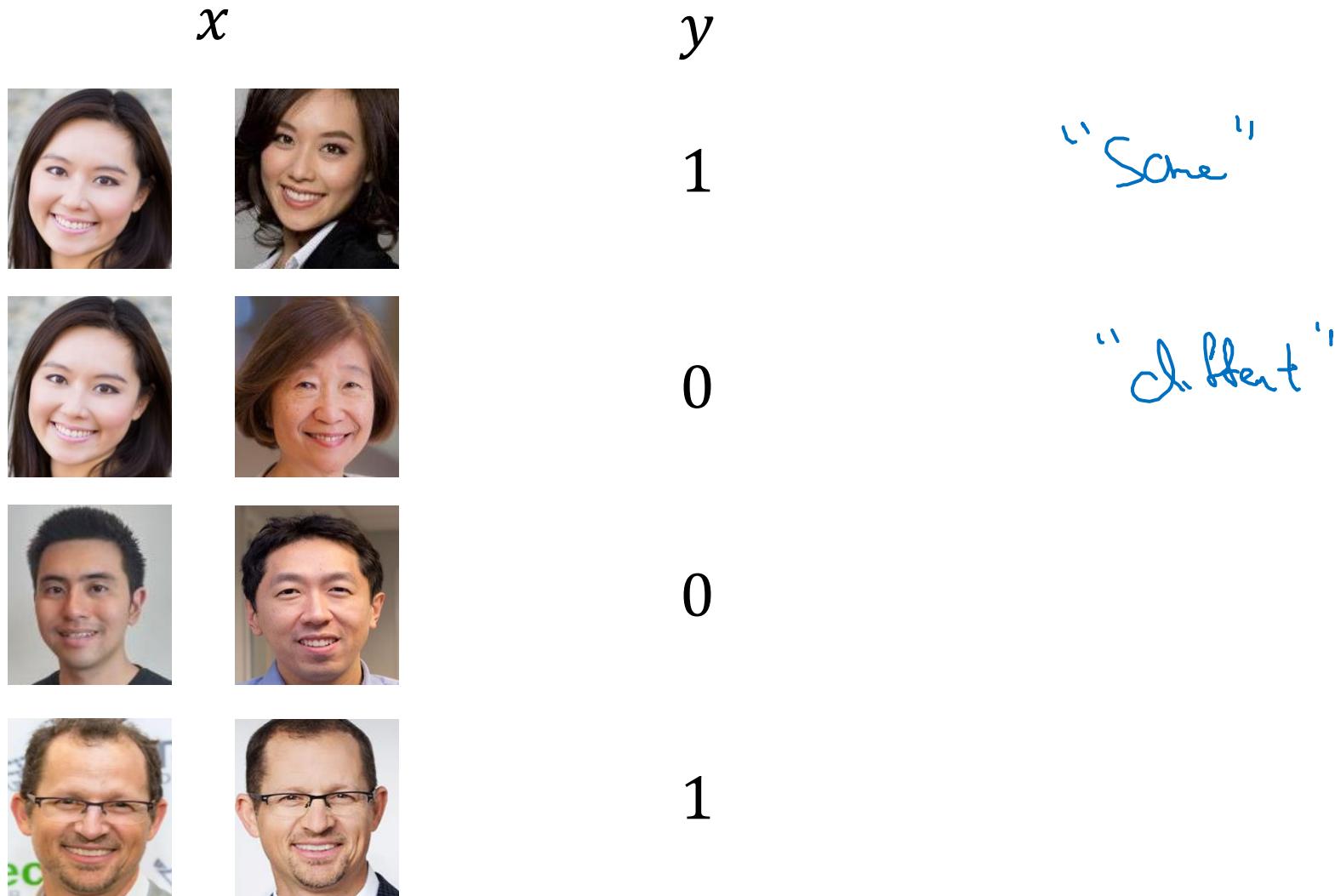
Learning the similarity function



[Taigman et. al., 2014. DeepFace closing the gap to human level performance]

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Face verification supervised learning





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Neural Style Transfer

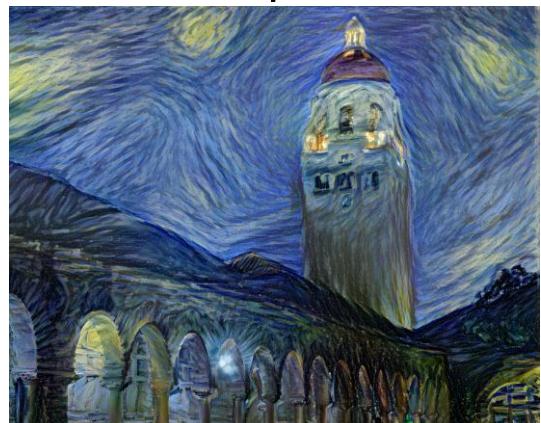
What is neural style
transfer?

Neural style transfer



Content (c)

Style (s)



Generated image (G)



Content (c)

Style (s)



Generated image (G)

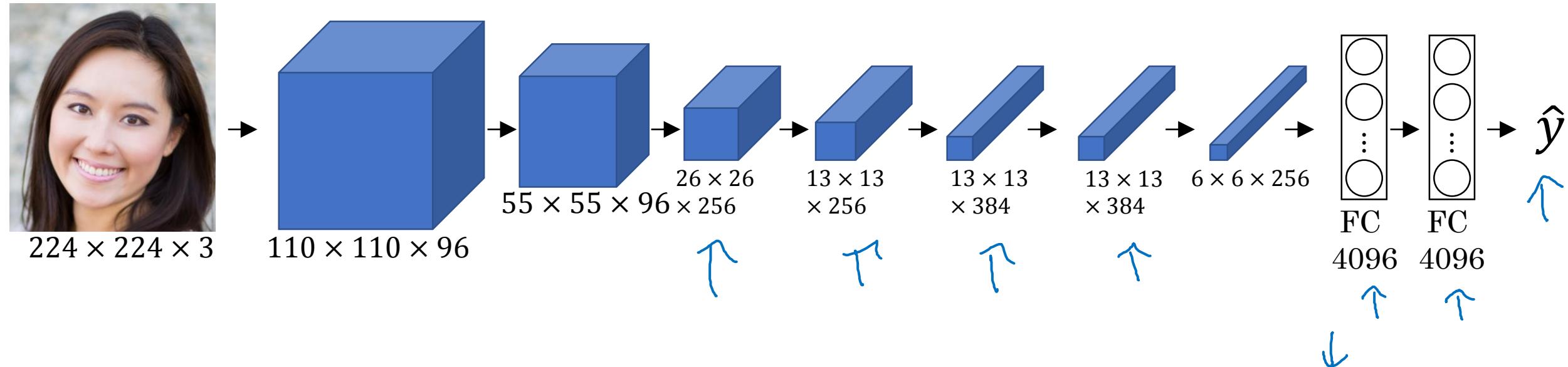


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Neural Style Transfer

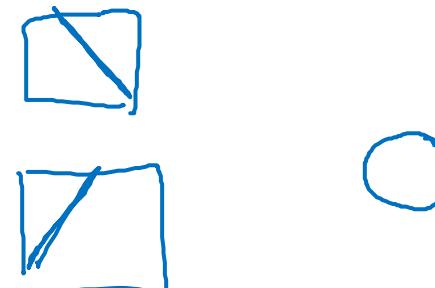
What are deep
ConvNets learning?

Visualizing what a deep network is learning



Pick a unit in layer 1. Find the nine image patches that maximize the unit's activation.

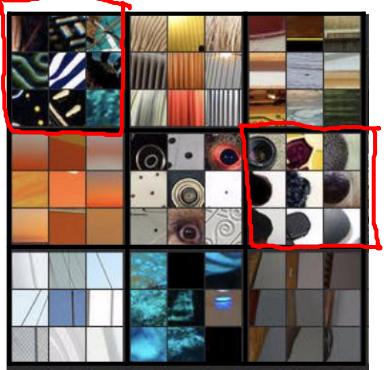
Repeat for other units.



Visualizing deep layers



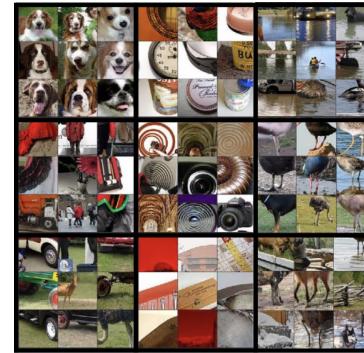
Layer 1



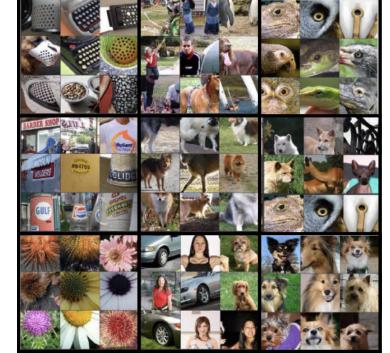
Layer 2



Layer 3



Layer 4



Layer 5

Visualizing deep layers: Layer 1



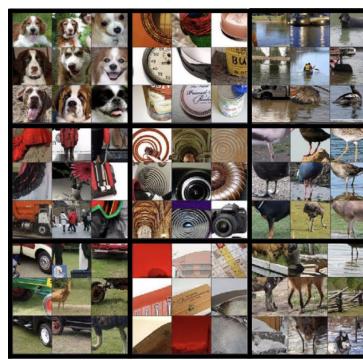
Layer 1



Layer 2



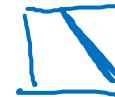
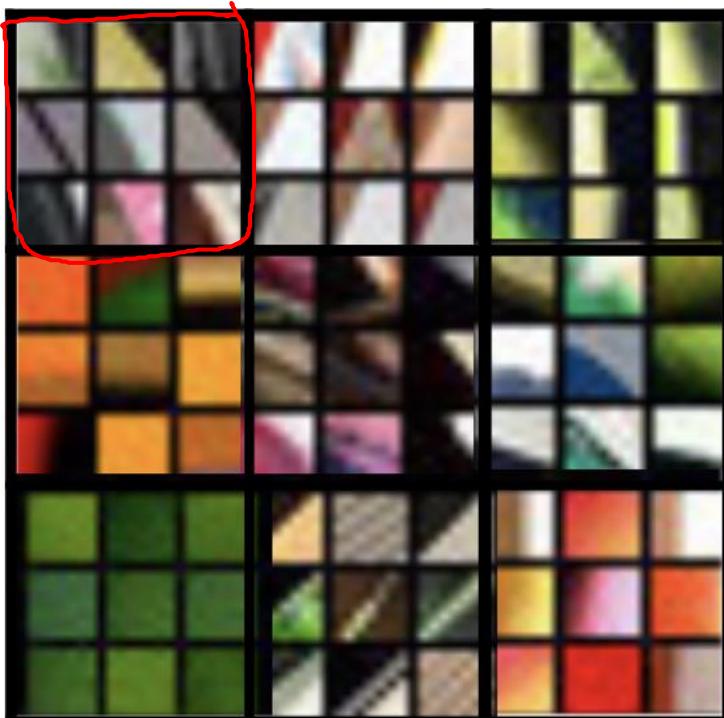
Layer 3



Layer 4



Layer 5



Visualizing deep layers: Layer 2



Layer 1



Layer 2



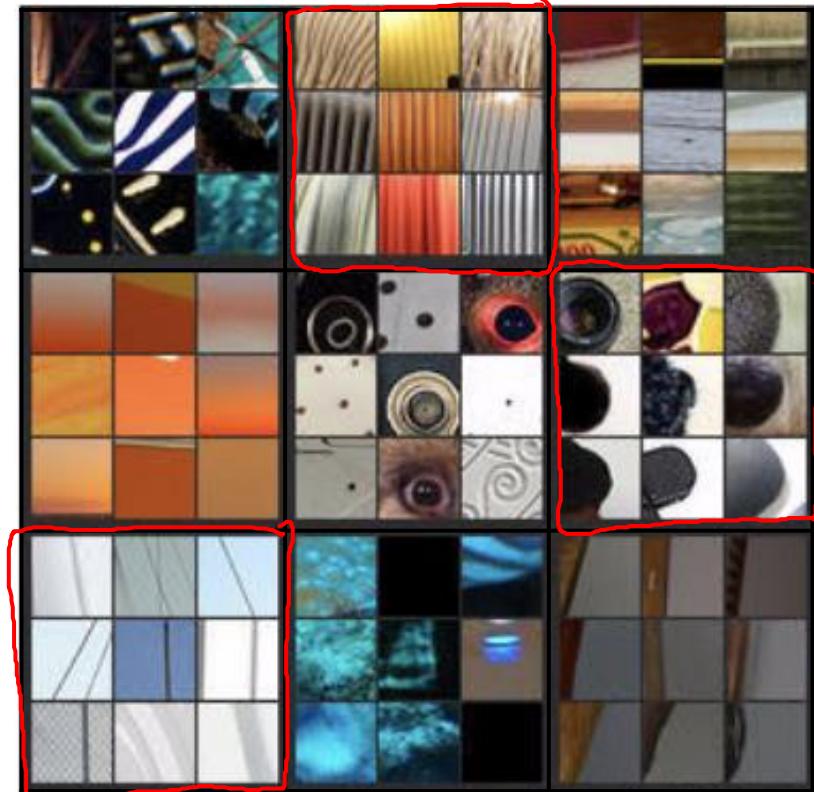
Layer 3



Layer 4



Layer 5



Visualizing deep layers: Layer 3



Layer 1



Layer 2



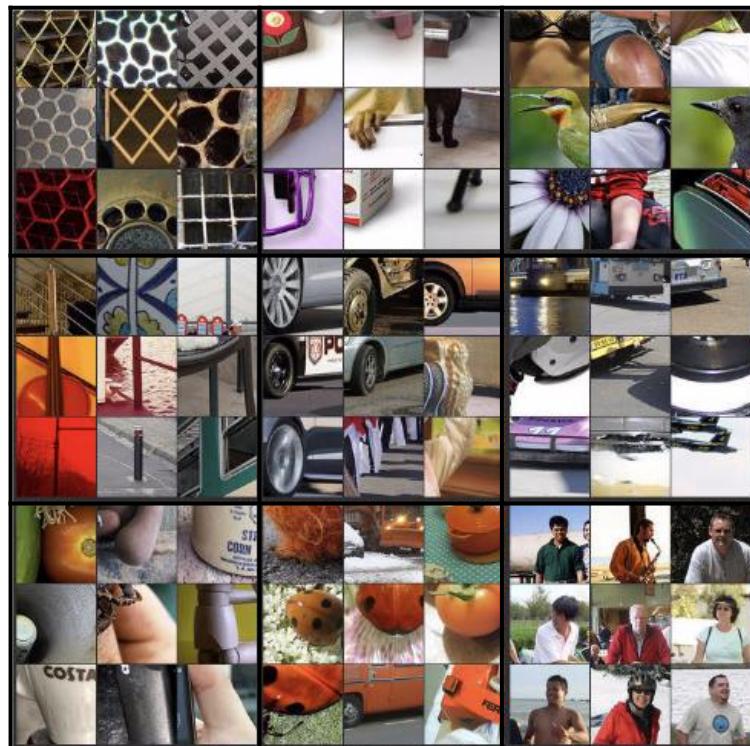
Layer 3



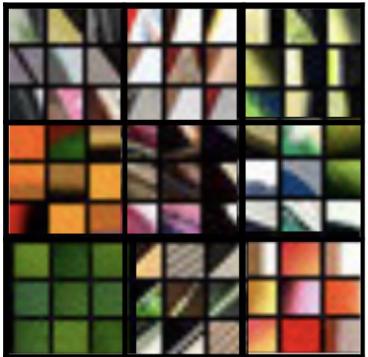
Layer 4



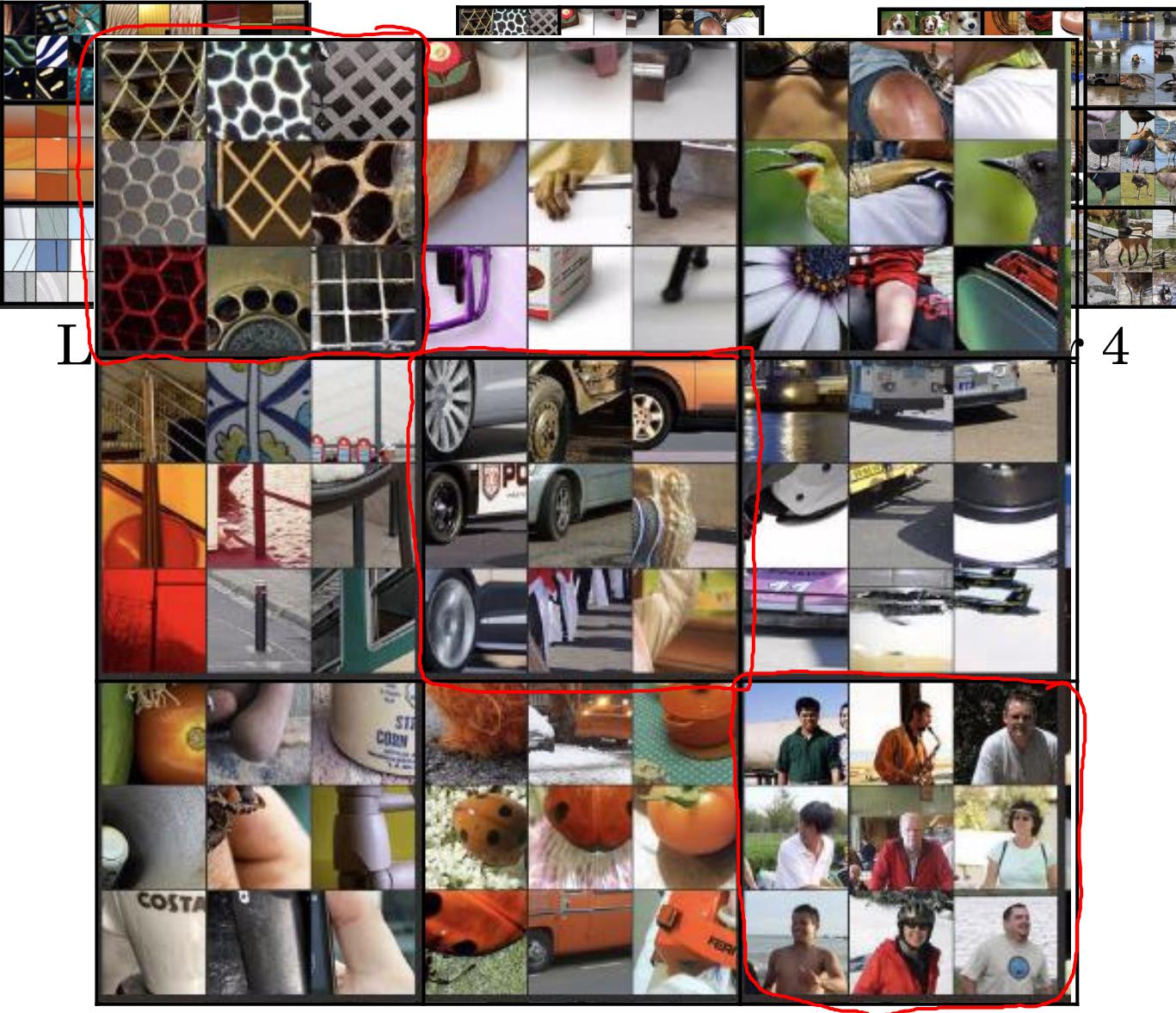
Layer 5



Visualizing deep layers: Layer 3

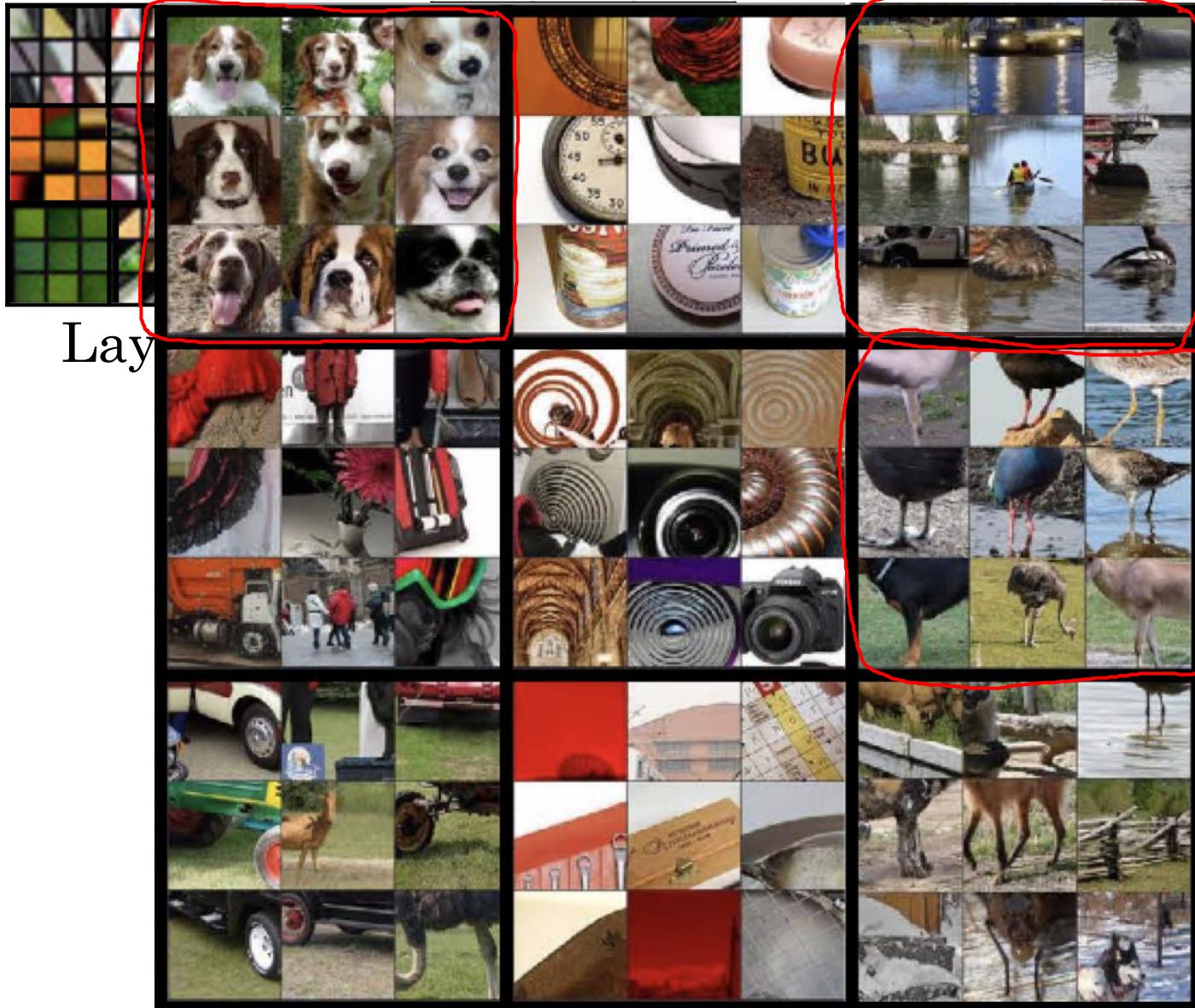


Layer 1



Layer 5

Visualizing deep layers: Layer 4



Layer 4

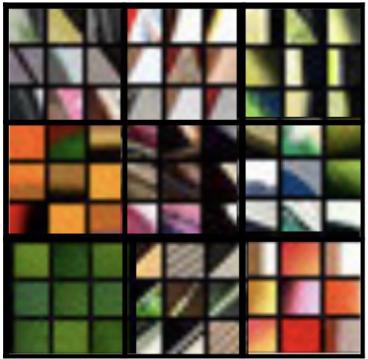


Layer 4



Layer 5

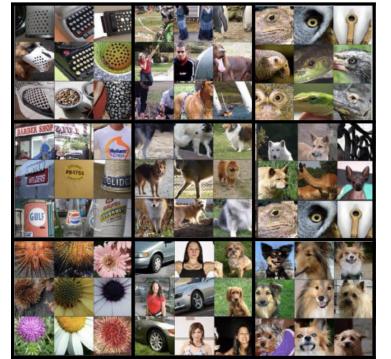
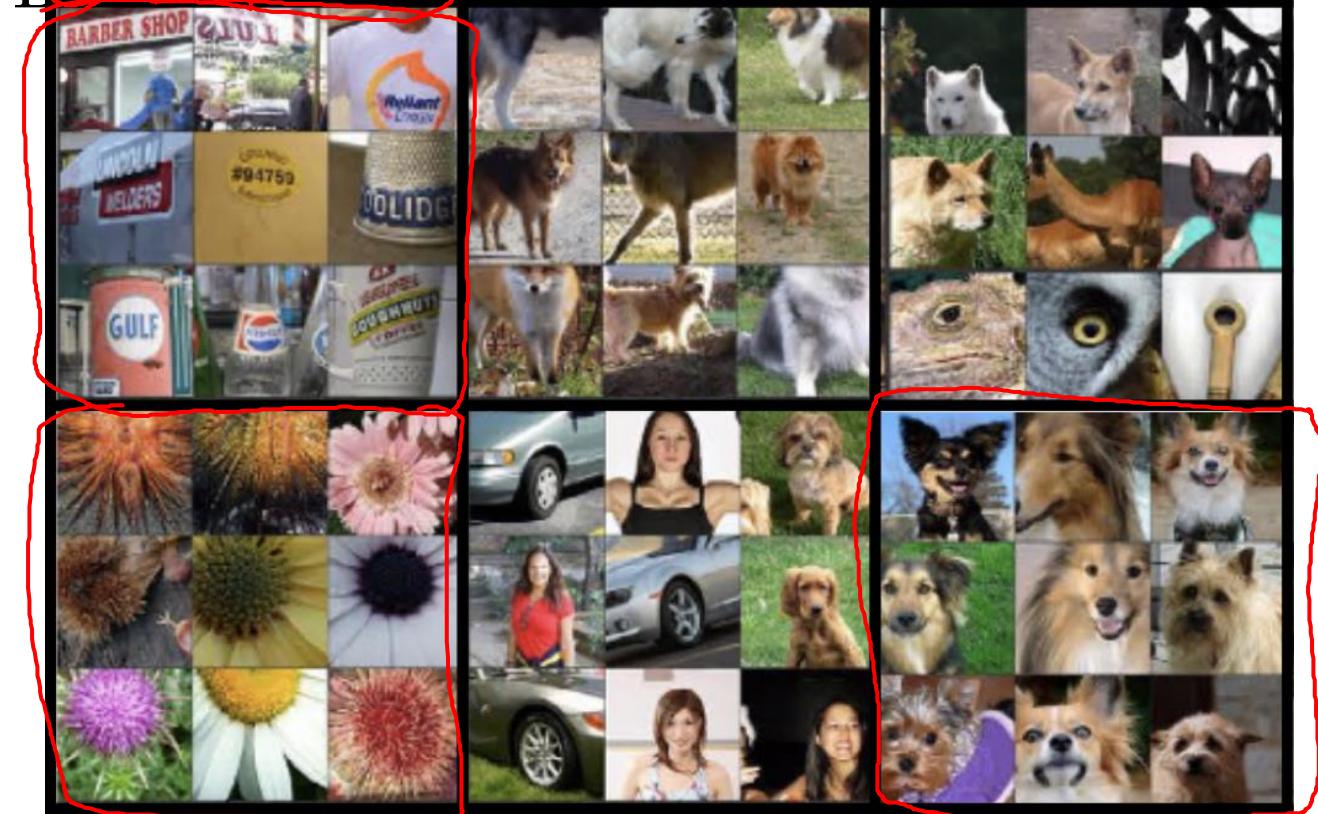
Visualizing deep layers: Layer 5



Layer 1



I



Layer 5



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Neural Style Transfer

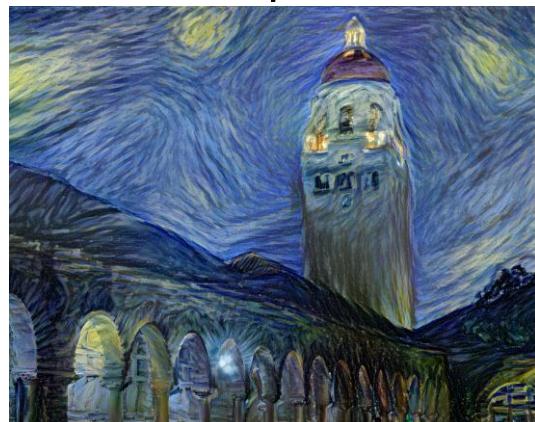
Cost function

Neural style transfer cost function



Content C

Style S



Generated image G

$$J(G) = \alpha J_{\text{Content}}(C, G) + \beta J_{\text{Style}}(S, G)$$

Find the generated image G

1. Initiate G randomly

$\underline{G: 100 \times 100 \times 3}$

\uparrow
 RGB



2. Use gradient descent to minimize $\underline{J(G)}$

$$G_t := G - \frac{\partial}{\partial G} J(G)$$





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Neural Style Transfer

Content cost function

Content cost function

$$\underline{J}(G) = \alpha \underline{J}_{content}(C, G) + \beta J_{style}(S, G)$$

- Say you use hidden layer \underline{l} to compute content cost.
- Use pre-trained ConvNet. (E.g., VGG network)
- Let $\underline{a}^{[l](C)}$ and $\underline{a}^{[l](G)}$ be the activation of layer \underline{l} on the images
- If $\underline{a}^{[l](C)}$ and $\underline{a}^{[l](G)}$ are similar, both images have similar content

$$J_{content}(C, G) = \frac{1}{2} \left\| \underline{a}^{[l](C)} - \underline{a}^{[l](G)} \right\|^2$$

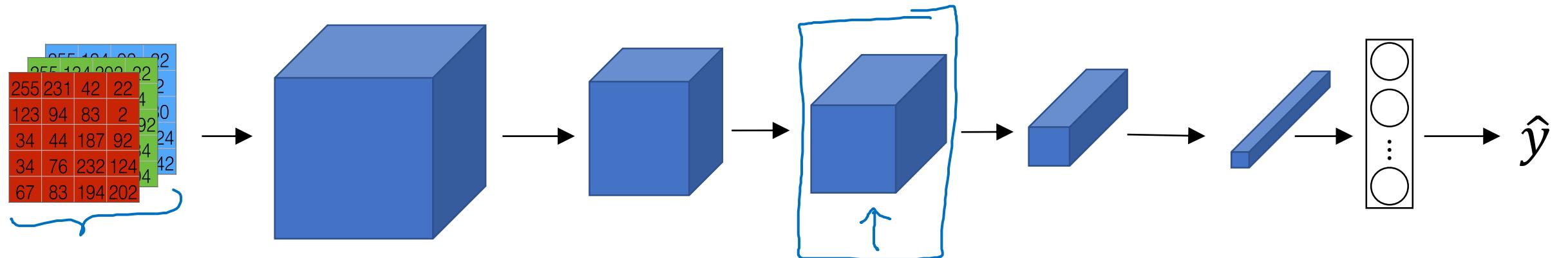


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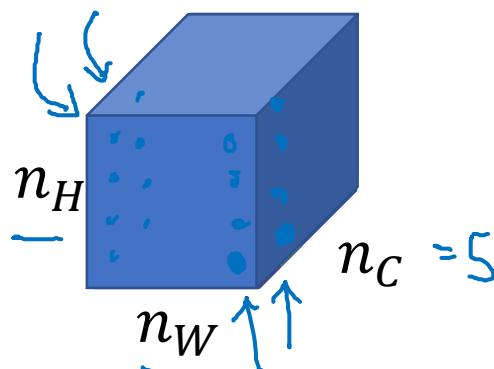
Neural Style Transfer

Style cost function

Meaning of the “style” of an image

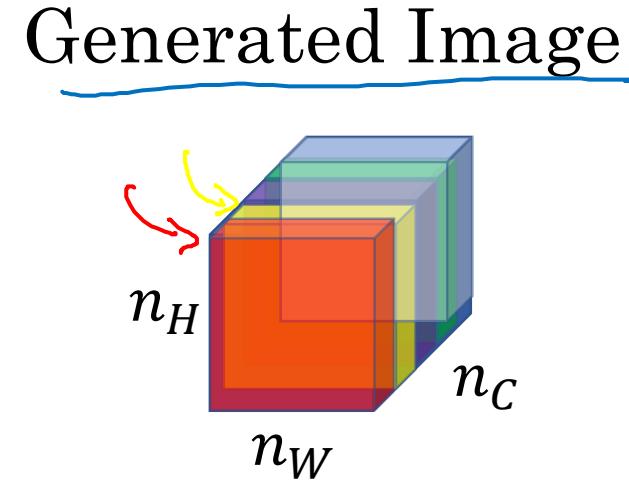
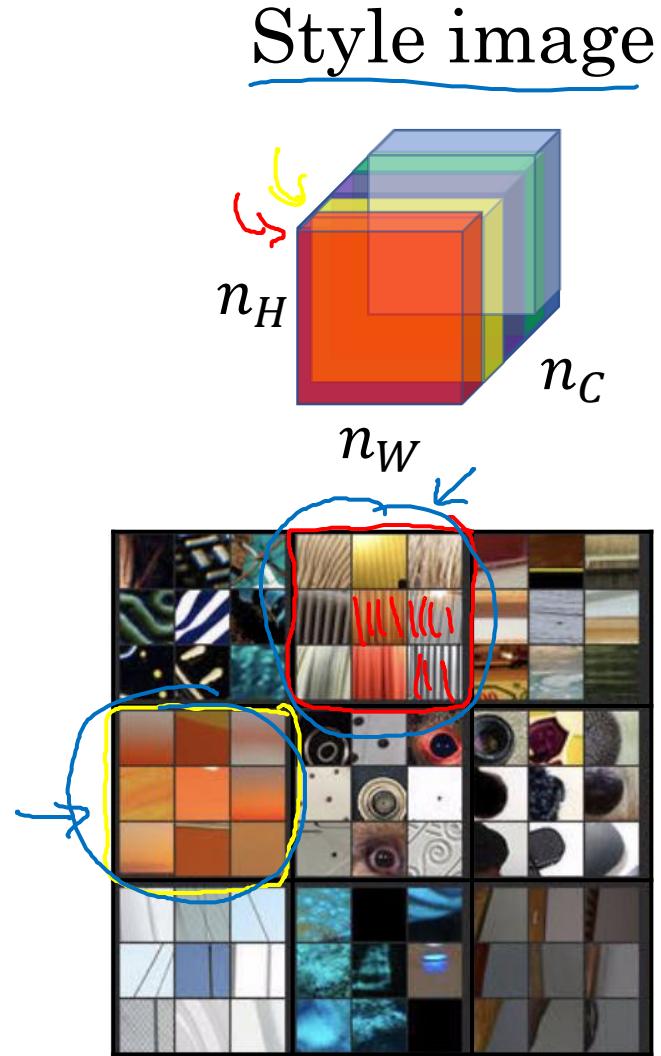


Say you are using layer l 's activation to measure “style.”
Define style as correlation between activations across channels.



How correlated are the activations
across different channels?

Intuition about style of an image



Style matrix

Let $a_{i,j,k}^{[l]}$ = activation at (i, j, k) . $G^{[l]}$ is $n_c^{[l]} \times n_c^{[l]}$

$$\rightarrow G_{kk'}^{[l](s)} = \sum_{i=1}^{n_h^{[l]}} \sum_{j=1}^{n_w^{[l]}} a_{ijk}^{[l](s)} a_{ijk'}^{[l](s)}$$

$$\rightarrow G_{kk'}^{[l](G)} = \sum_{i=1}^{n_h^{[l]}} \sum_{j=1}^{n_w^{[l]}} a_{ijk}^{[l](G)} a_{ijk'}^{[l](G)}$$

H W C
↓ ↓ ↓

n_c

$$G_{kk'}^{[l]} \quad \forall k, k' \in \{1, \dots, n_c\}$$

"Gram matrix"

$$\begin{aligned} J_{style}^{[l]}(S, G) &= \frac{1}{(\dots)} \| G_{kk'}^{[l](s)} - G_{kk'}^{[l](G)} \|_F^2 \\ &= \frac{1}{(2n_h^{[l]} n_w^{[l]} n_c^{[l]})^2} \sum_k \sum_{k'} (G_{kk'}^{[l](s)} - G_{kk'}^{[l](G)})^2 \end{aligned}$$

Style cost function

$$\left\| G^{[l](s)} - G^{[l](G)} \right\|_F^2$$

$$J_{style}^{[l]}(S, G) = \frac{1}{\left(2n_H^{[l]} n_W^{[l]} n_C^{[l]}\right)^2} \sum_k \sum_{k'} (G_{kk'}^{[l](s)} - G_{kk'}^{[l](G)})$$

$$J_{style}(S, G) = \sum_l \lambda^{[l]} J_{style}^{[l]}(S, G)$$

$$\underbrace{J(G)}_G = \alpha J_{content}(S, G) + \beta J_{style}(S, G)$$

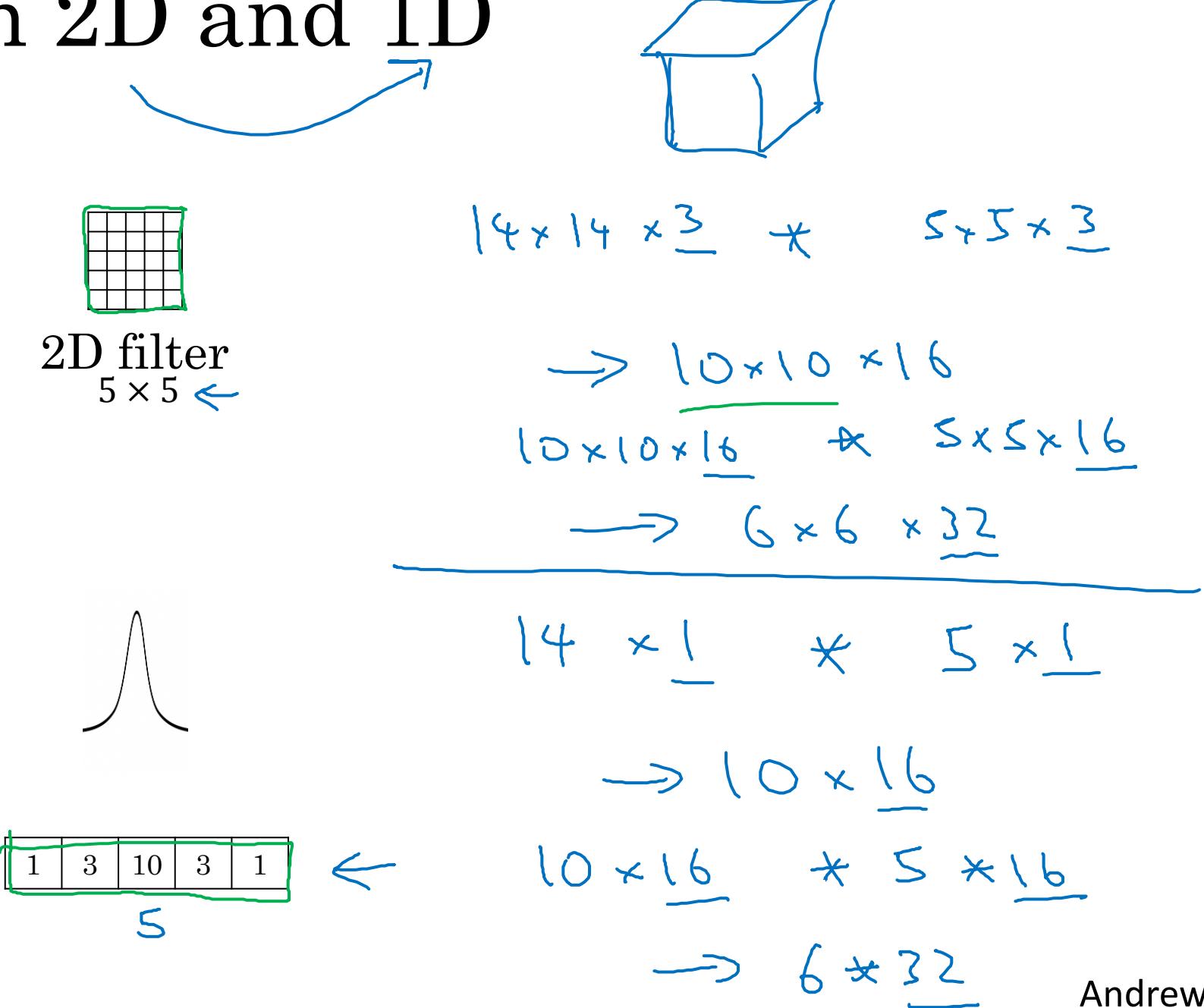
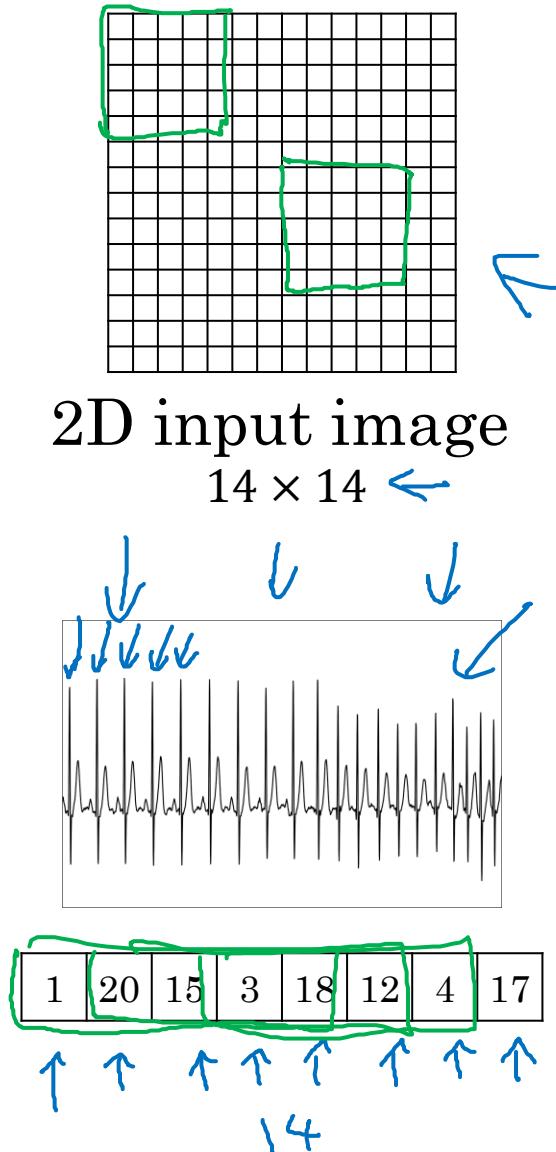


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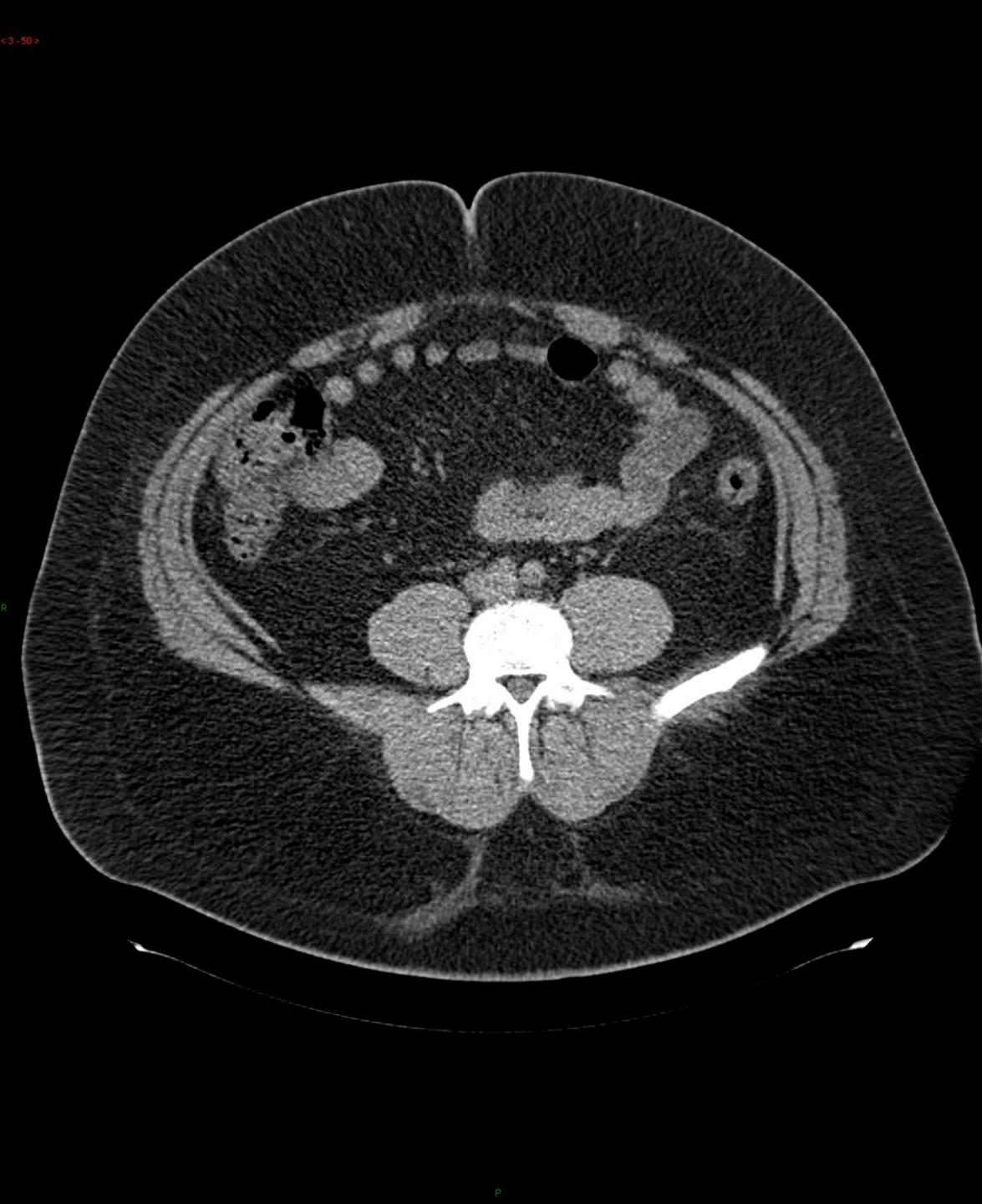
Convolutional Networks in 1D or 3D

1D and 3D
generalizations of
models

Convolutions in 2D and 1D



3D data

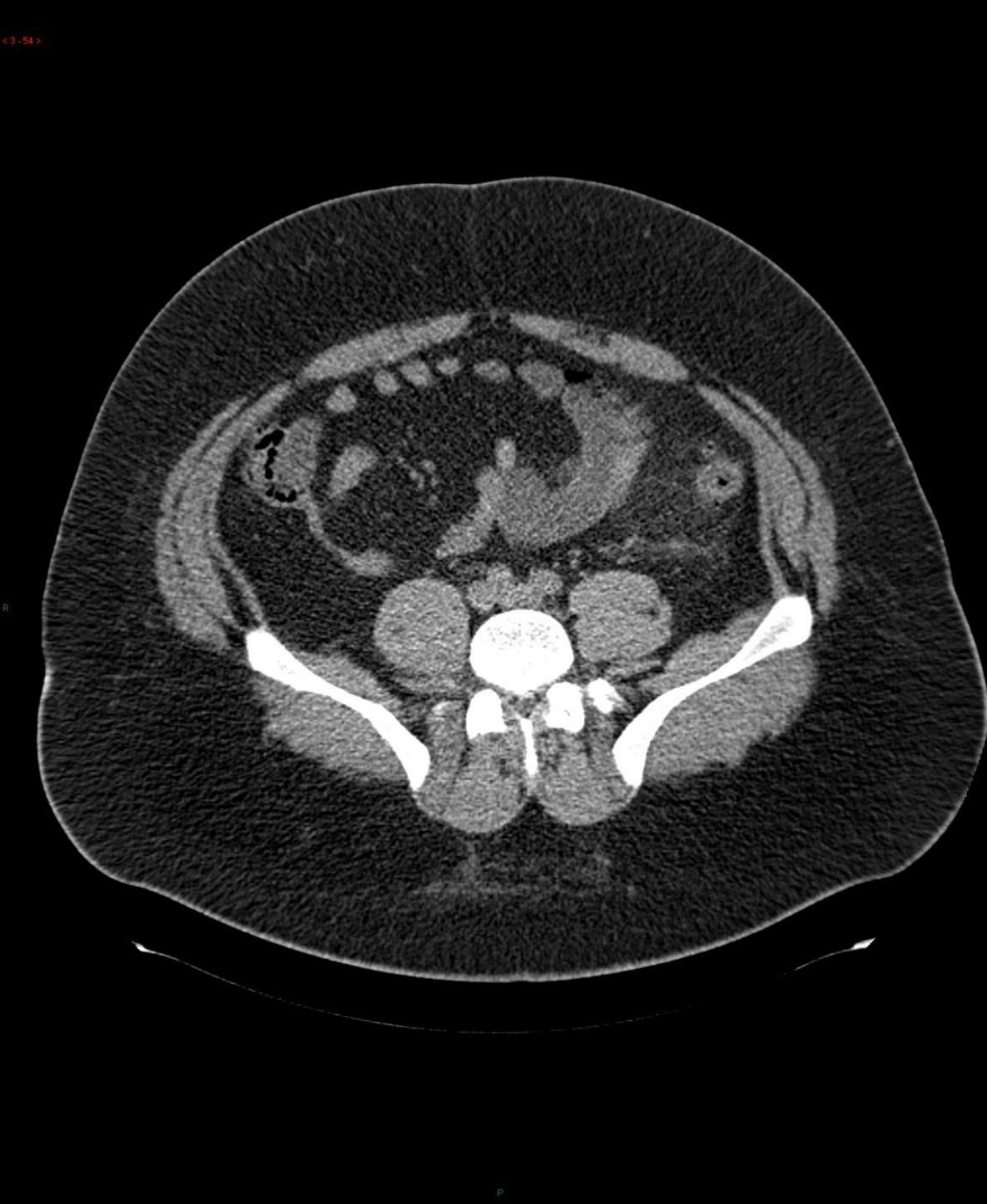


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3D data

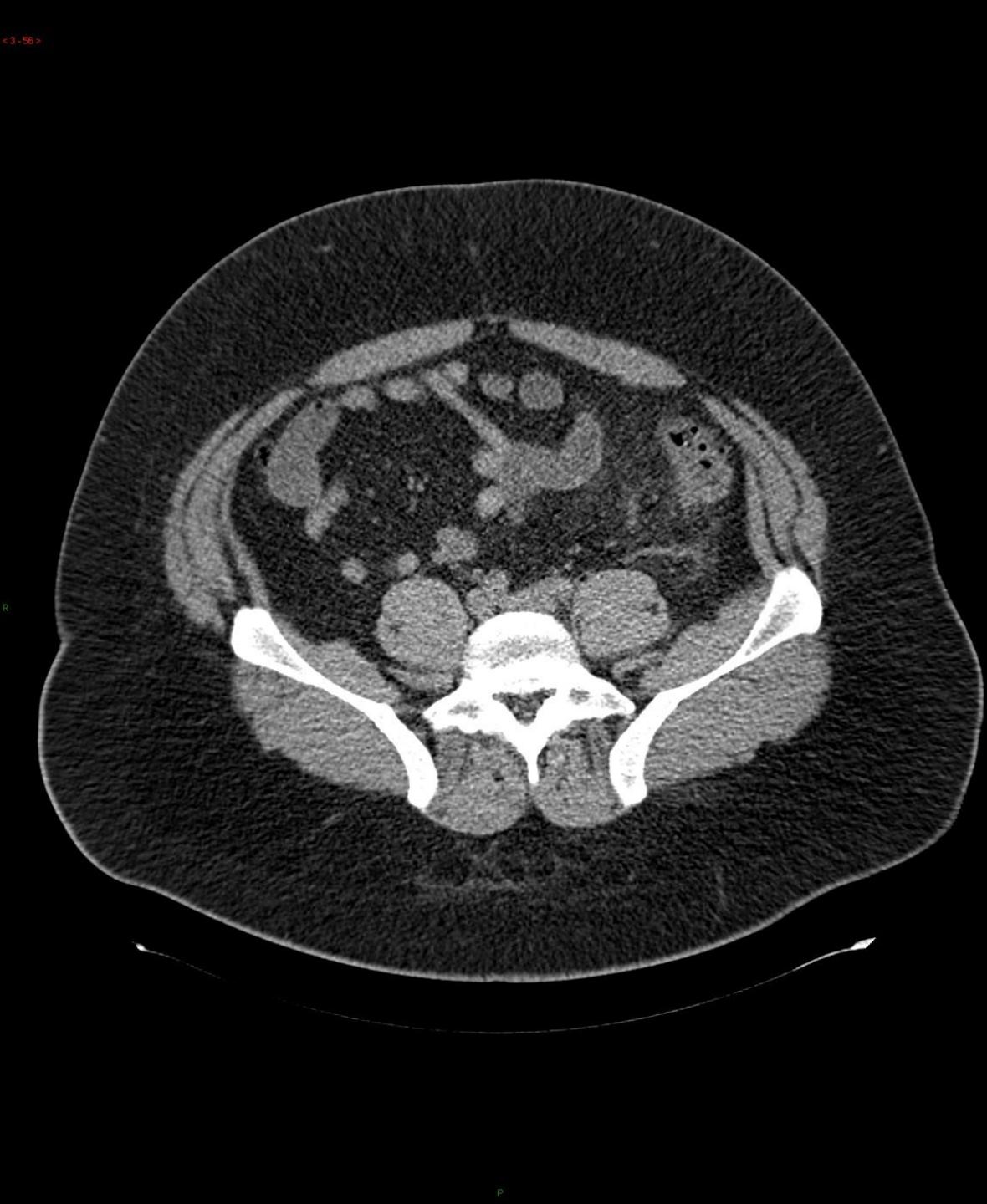


3D data

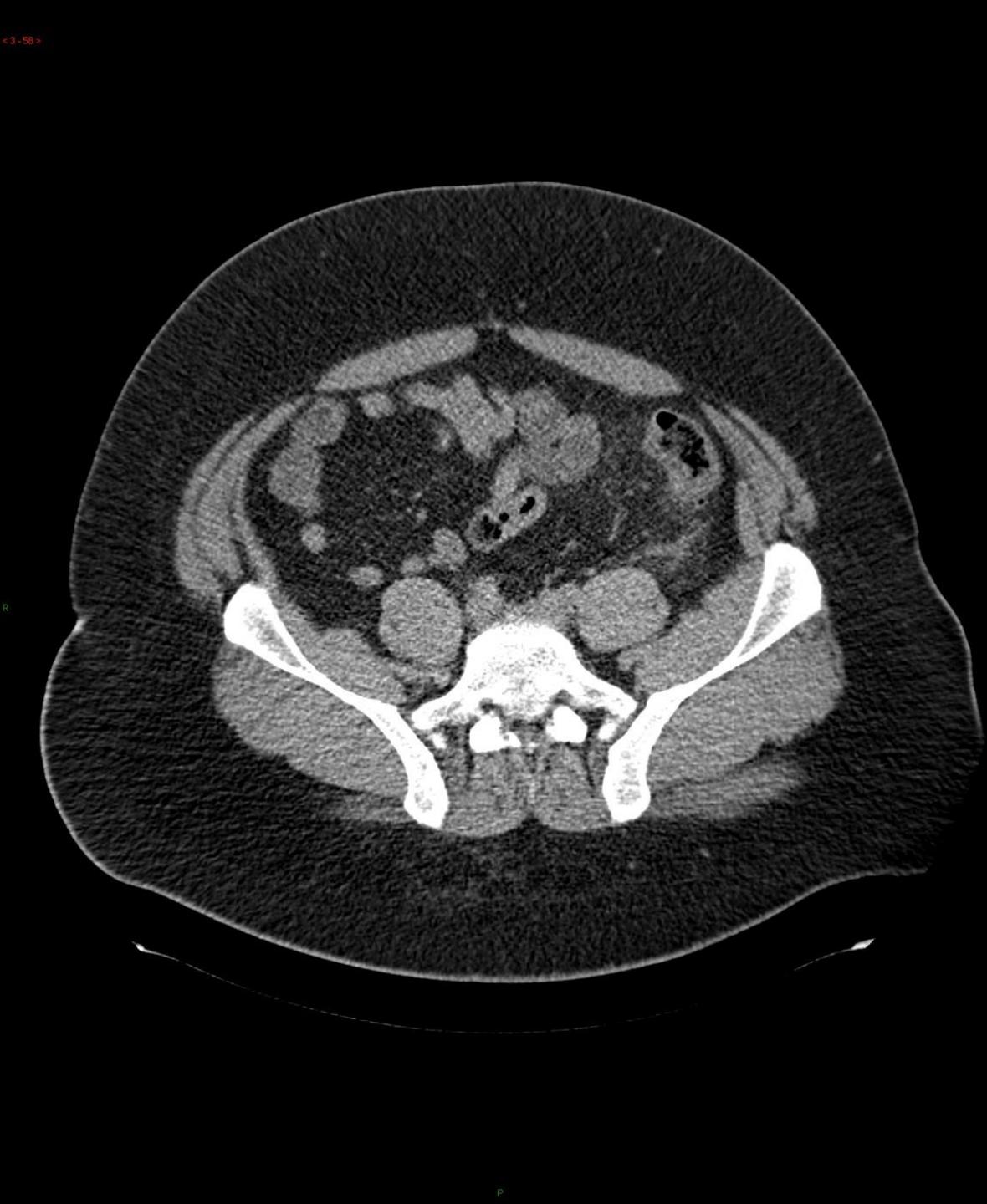


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3D data

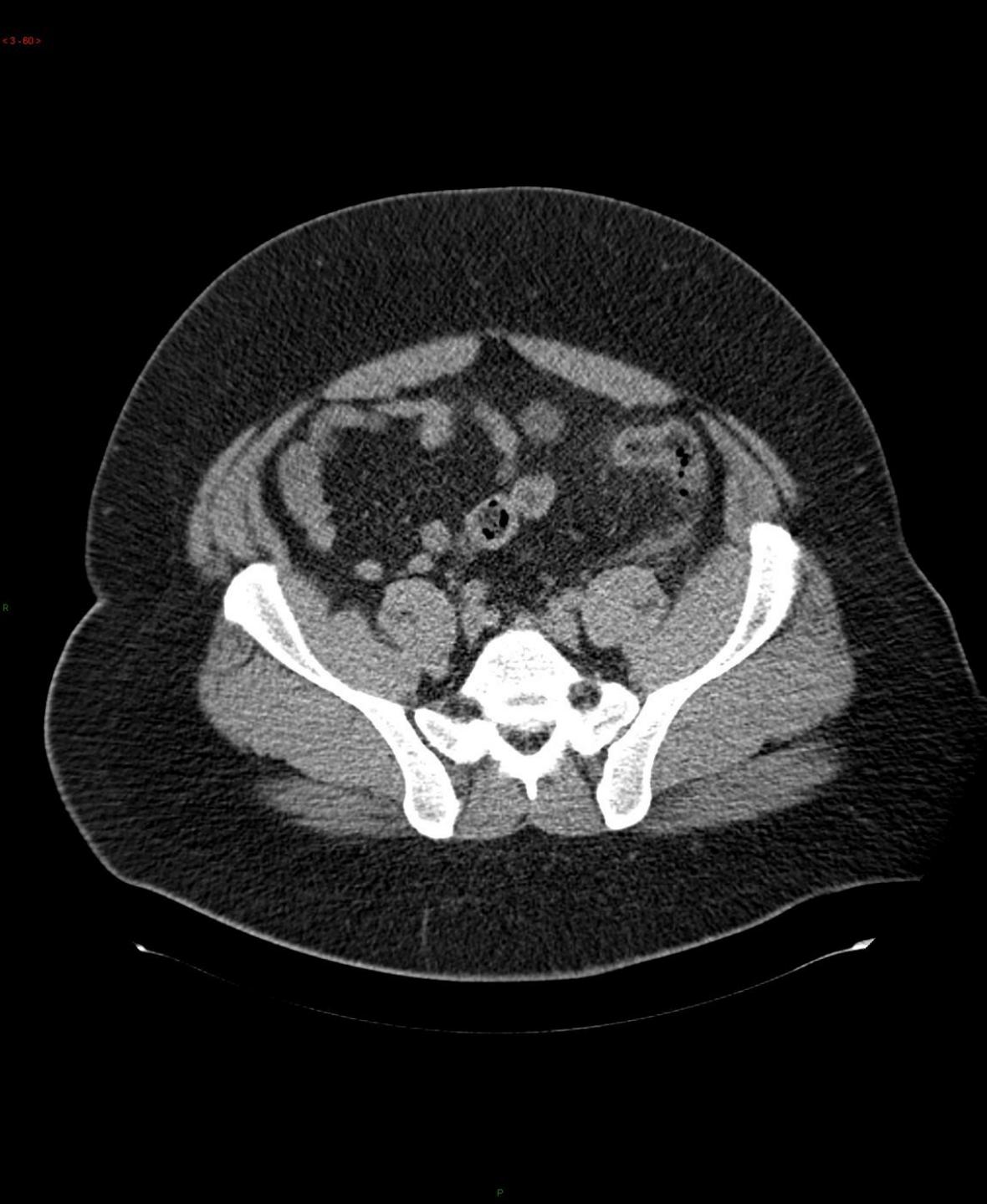


3D data



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3D data



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3D data



3D data



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3D data

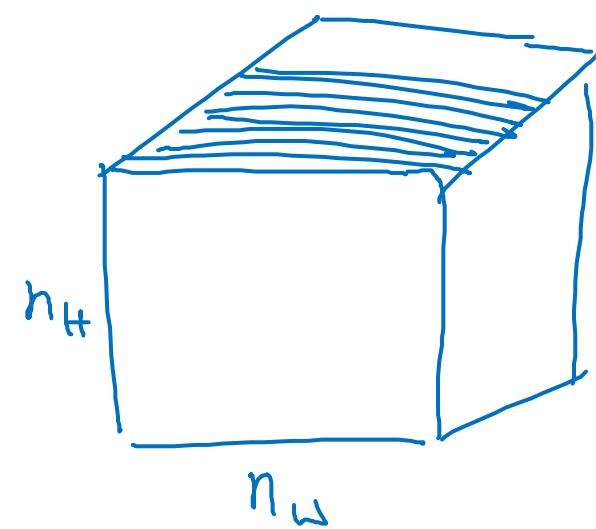


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3D data

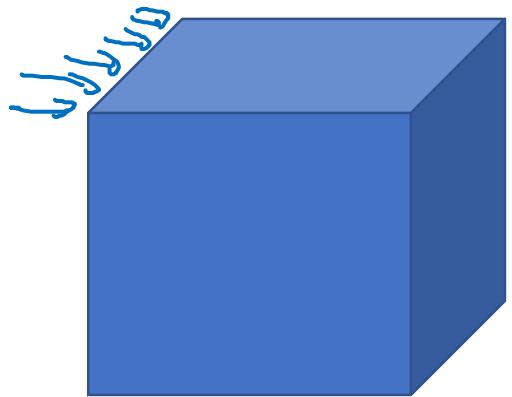


3D data

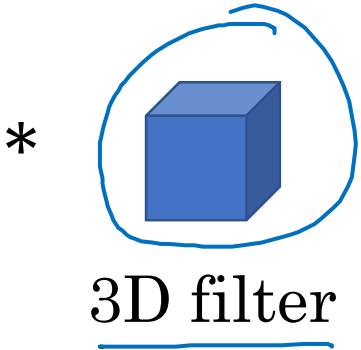


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3D convolution



3D volume



$$\begin{array}{c} \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\ \underbrace{4 \times 14 \times 14}_{\text{Input}} \times 1 \\ * \quad \underbrace{5 \times 5 \times 5}_{\text{Filter}} \times 1 \quad 16 \text{ filters.} \\ \rightarrow 10 \times 10 \times 10 \times 16 \\ * \quad \underbrace{5 \times 5 \times 5}_{\text{Stride}} \times 16 \\ \rightarrow 6 \times 6 \times 6 \times 32 \end{array}$$

Diagram illustrating the 3D convolution process:

- The input is a 3D volume of size $4 \times 14 \times 14$.
- The input is processed by a 3D filter of size $5 \times 5 \times 5$, resulting in 16 filters.
- The output is a tensor of size $10 \times 10 \times 10 \times 16$.
- The output is then processed by another 3D filter of size $5 \times 5 \times 5$, resulting in 32 filters.
- The final output is a tensor of size $6 \times 6 \times 6 \times 32$.