Reduction of a building's electricity costs after a PV installation

Student: Pol Boudou, MA3 Energy Management & Sustainability

Supervisor: Jagdish Achara

Professor: Jean-Yves Le Boudec

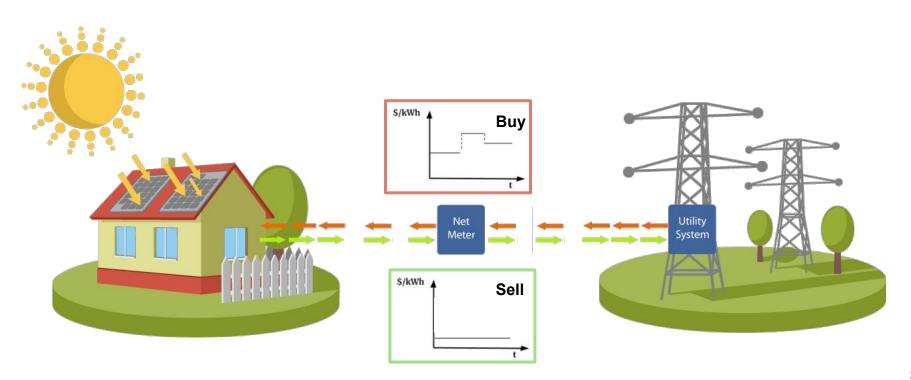


Laboratory for Communications and Applications LCA

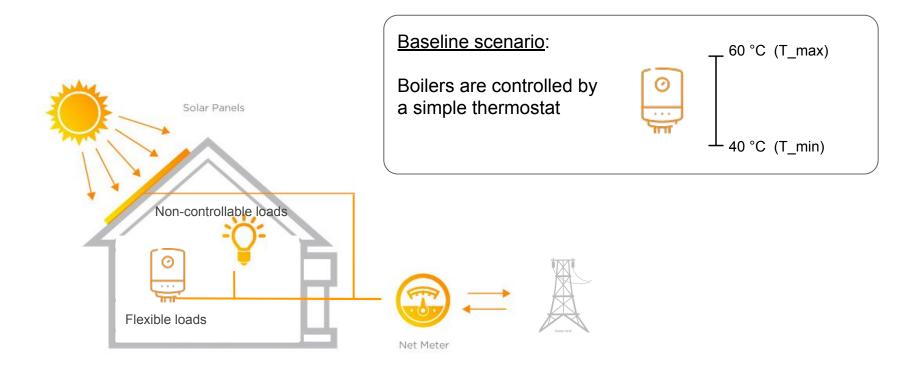
Outline

- 1. Context & building scenario
- 2. Control mechanisms
- 3. Simulation
- 4. First results & Coming work
- 5. Conclusion

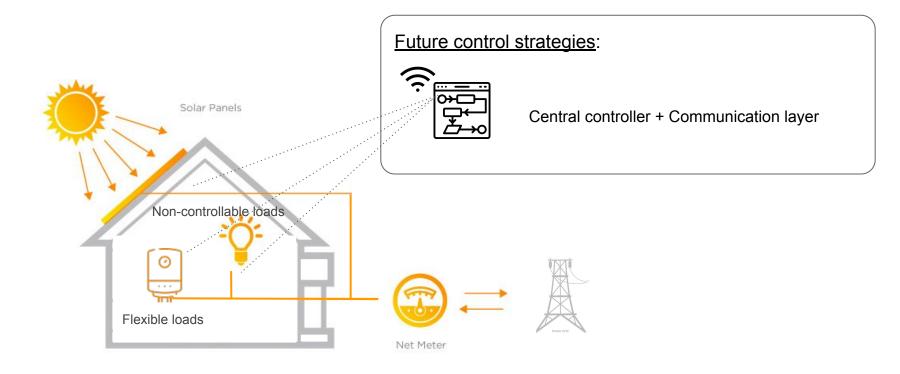
Context: building connected to the grid



Building description and EMS



Building description and EMS

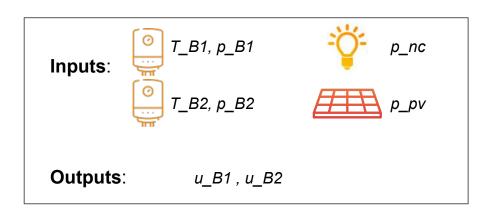


Control strategies

tested to reduce building's electricity bill.

Strategy 1:

<u>Rule-based control logic</u> → at each timestep, maintain boilers between temp bounds and supply PV power surplus to boilers to the extent possible

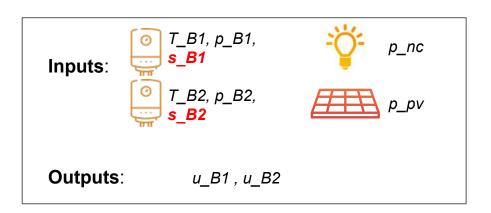


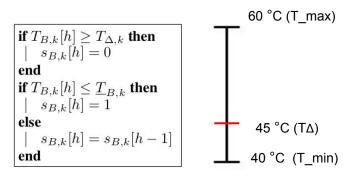
```
Start
p_x = p_{PV}[h] + p_{nc}[h] + p_{B1}[h] + p_{B2}[h]
sort \hat{T}_{B}[h] in ascending order
for each boiler k do
    if T_{B,k} \leq \underline{T}_{B,k} then
         u_{B,k} \leftarrow \overrightarrow{P}_k
         p_x = p_x - p_{B,k} + u_{B,k}
         if p_x > 0 then
              e_k^T[h] = max(0, \overline{T}_{B,k} - T_{B,k}[h])
              u_{B,k} \leftarrow max[-C_w \frac{e_k^T[h]}{\Delta t}, \overline{P}_k, -(p_x - p_{B,k})]
             p_x = p_x - p_{B,k} + u_{B,k}
         end
      end
 end
 return Control variables
  End
```

<u>Limitations</u>: 1) myopic approach, 2) oversimplificated boiler model, 3) inefficient action around T_min

Strategy 2: hysteresis control

Same rule-based control logic + hysteresis to avoid constant switching around lower bound temperature



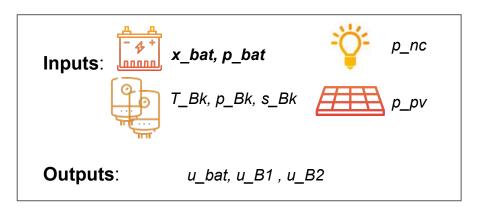


<u>Limitations</u>: 1) myopic approach, 2) oversimplificated boiler model

Strategy 3: adding battery storage

Similar rule-based control logic + battery backup:

→ only charged when boilers are at their T_max, only discharged when needed to keep boilers above T_min.



$$\begin{aligned} p_x &= p_{PV}[h] + p_{nc}[h] + p_{B1}[h] + p_{B2}[h] + p_{bat}[h] \\ \textit{take care of boilers as usual} \\ & \textbf{if } p_x \geq 0 \textbf{ then} \\ & | u_{bat} \leftarrow max[\frac{x_{bat}[h] - \overline{C}_{bat}}{\Delta t}, \overline{P}_{bat}^{ch}, -(p_x - p_{bat}[h])] \\ & \textbf{else} \\ & | u_{bat} \leftarrow min[\frac{x_{bat}[h] - \underline{C}_b}{\Delta t}, \overline{P}_{bat}^{disch}, -(p_x - p_{bat}[h])] \\ & \textbf{end} \end{aligned}$$

<u>Limitations</u>: 1) myopic approach, 2) oversimplificated boiler model

Strategy 4: adequate modelling

Same rule-based algorithm, with control action computed according to more accurate models:



$$T_B[h+1] = T_B[h] - \frac{p_B \Delta t}{C_B}$$

V: boiler volume

d: hot water consumption [litres]



$$x_b[h+1] = x_b[h] - p_b[h] \Delta t$$

$$x_b[h+1] = \alpha_b x_b[h] + \eta_b^+ u_b^+[h] + \eta_b^- u_b^-[h] \Delta t$$
$$u_b^+[h] = \max(0, u_b)$$
$$u_b^-[h] = \max(0, -u_b)$$

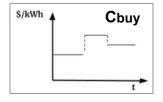
α: leakage coef

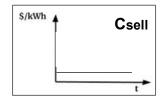
η: charging(+)/discharging(-) efficiencies

<u>Limitations</u>: 1) myopic approach

Strategy 5: MPC for boilers

$$min_{\hat{\boldsymbol{u}}_{B}} \sum_{h=0}^{H-1} C_{buy}[h] p_{g}^{+}[h] - C_{sell}[h] p_{g}^{-}[h]$$





$$p_g[h] + \hat{p}_{PV}[h] + \hat{p}_{nc}[h] + \sum_{k=1,2} u_{B,k}[h] = 0$$

$$p_g^-[h] = max(0, -p_g[h])$$

$$p_q^+[h] = max(0, +p_g[h])$$

$$\overline{P}_{B,k} \le u_{B,k}[h] \le 0$$
 for $k = 1, 2$

$$T_{B,k}[h+1] = A T_{B,k}[h] - B u_{B,k}[h] + C \hat{d}_{B,k}[h]$$
 for $k = 1, 2$

$$\underline{T}_{B,k} \le T_{B,k}[h] \le \overline{T}_{B,k} \text{ for } k = 1, 2$$

<u>Limitations</u>: need for forecasts (PV, loads, hot water consumption) and more computing time

Strategy 6: MPC for boilers and battery

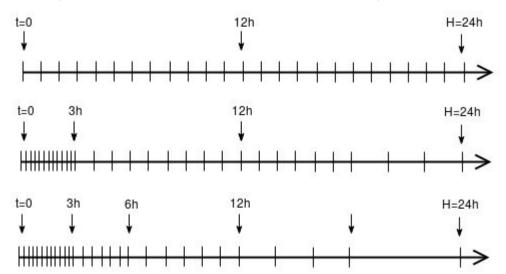
$$min_{\hat{\boldsymbol{u}}_{B},u_{bat}} \sum_{h=0}^{H-1} C_{buy}[h] p_{g}^{+}[h] - C_{sell}[h] p_{g}^{-}[h]$$

$$\begin{split} s.t. & \quad p_g[h] + \hat{p}_{PV}[h] + \hat{p}_{nc}[h] + \sum_{k=1,2} u_{B,k}[h] + u_{bat}[h] = 0 \\ & \quad p_g^-[h] = \max(0, -p_g[h]) \\ & \quad p_g^+[h] = \max(0, +p_g[h]) \\ & \quad u_{bat}^+[h] = \max(0, u_{bat}[h]) \\ & \quad u_{bat}^-[h] = \max(0, -u_{bat}[h]) \\ & \quad x_{bat}[h + 1] = \alpha_b \; x_{bat}[h] + \eta_b^+ \; u_{bat}^+[h] + \eta_b^- \; u_b^-[h] \; \Delta t \\ & \quad \underline{C}_{bat} \leq x_b[h] \leq \overline{C}_{bat} \\ & \quad \overline{P}_{bat}^{ch} \leq u_b[h] \leq \overline{P}_{bat}^{disch} \end{split}$$

<u>Limitations</u>: need for forecasts (PV, loads, hot water consumption) and more computing time

Future work: MPC with variable period

Idea: give more weight to short-term conditions than to long-term

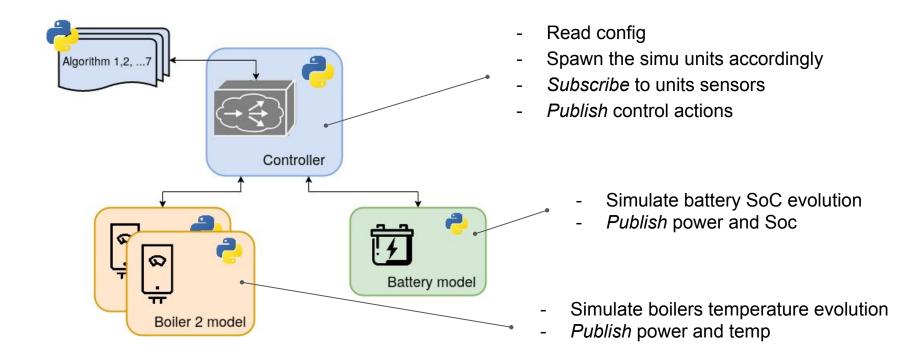


Faster control period with same computing cost as constant-period MPC.

Simulation framework

to allow us to compare all of the controller algorithms in the same building conditions.

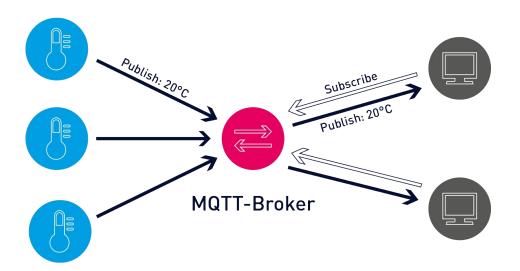
Simulation environment



Simulation environment

MQTT messaging protocol (Message Queuing Telemetry Transport)

→ publish-subscribe network protocol that transports messages between devices.



First simulations

Cost attractiveness of implementing a simple rule-based control algorithm

Simulation conditions

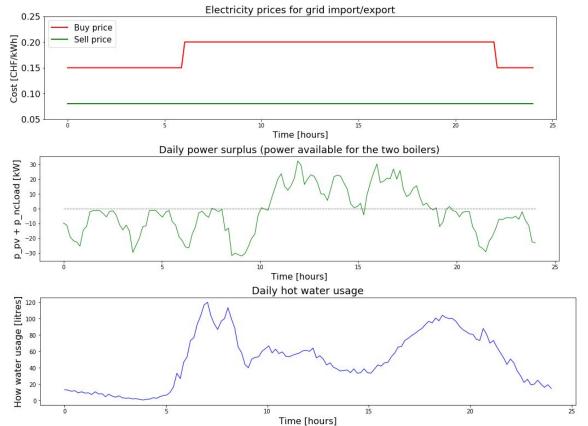
Day in march, power profile of a big building with multiple households

Boilers models:

Volume: 800 litres

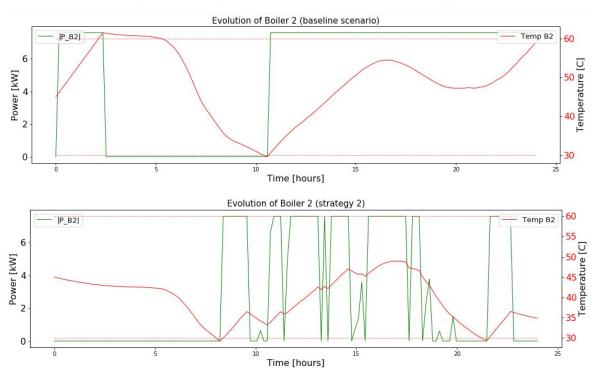
Temp bounds: [40°C; 60°C]

Cold water temp: 20°C



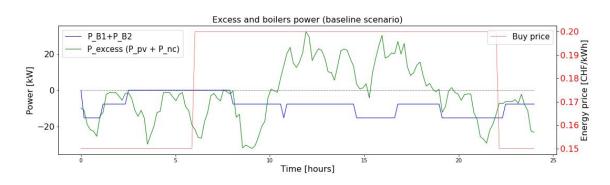
First results

Comparing a basic rule based logic (strategy 2) with a no-EMS strategy (baseline scenario):

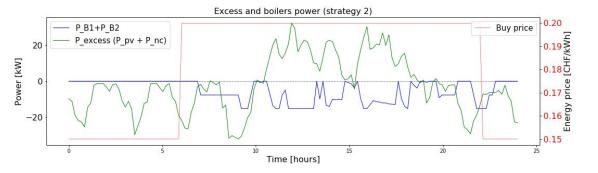


First results & Coming work

Comparing a basic rule based logic (Strategy 2) with a no-EMS strategy (baseline scenario):



Daily electricity bill: 37.62 CHF



Daily electricity bill: 27.50 CHF

Conclusion

- Defined a **specific building scenario**, with its assumptions and models.
- Defined multiple energy management strategies.
- Simulated such building and the controller implementing the different control strategies.
- TO DO: Experiment with 7 control strategies, **analyze their cost-effectiveness**, and point their limitations.

MPC implementation



