## BNPlib: A Nonparametric C++ Library

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https://github.com/poliprojects/BNPlib

## Introduction

## Bayesian approach

- parameter  $\vartheta$ : is a random variable
- ullet dataset y
- Bayes Theorem:

$$\begin{array}{c} \pi(\vartheta) \text{ prior distribution} \\ p(\boldsymbol{y}|\vartheta) \text{ likelihood} \end{array} \right\} \Rightarrow \pi(\vartheta|\boldsymbol{y}) \text{ posterior distribution} \\ \pi(\vartheta|\boldsymbol{y}) = \frac{p(\boldsymbol{y}|\vartheta) \ \pi(\vartheta)}{\int_{\Theta} p(\boldsymbol{y}|\vartheta) \ \pi(\vartheta) \ \mathrm{d}\vartheta} \\ \end{array}$$

## Markov Chain Monte Carlo (MCMC) methods

Approximate the integral

$$\mathcal{I} = \int h(x)f(x)\mathrm{d}x$$

 $y_1,\dots,y_n\sim f$  without directly simulating from  $f\Rightarrow$  Markov chain with stationary distribution f

• One algorithm for constructing chains: Gibbs Sampling.

## Non-parametric Bayesian model

Having observed the iid sample  $\{y_i\}_i$ , i = 1, ..., n:

#### Parametric model:

#### Non-parametric model:

$$y_1, \dots, y_n \mid \vartheta \stackrel{\mathsf{iid}}{\sim} f(y \mid \vartheta)$$
  $y_1, \dots, y_n \mid G \stackrel{\mathsf{iid}}{\sim} G$   $G \sim \pi$ 

### DP and DPM models

Dirichlet process model (discrete):

$$y_i|G \stackrel{\text{iid}}{\sim} G$$

$$G \sim DP(MG_0)$$

Dirichlet process mixture (DPM) model (continuous):

$$y_{i}|G \stackrel{\mathsf{iid}}{\sim} f_{G}(\cdot) = \int_{\Theta} f(\cdot|\boldsymbol{\vartheta}) G(\mathrm{d}\boldsymbol{\vartheta}) \qquad \iff \begin{aligned} y_{i}|\boldsymbol{\vartheta}_{i} \stackrel{\mathsf{ind}}{\sim} f(\cdot|\boldsymbol{\vartheta}_{i}) \\ \boldsymbol{\vartheta}_{i}|G \stackrel{\mathsf{iid}}{\sim} G \\ \boldsymbol{\vartheta}_{i}|G \stackrel{\mathsf{iid}}{\sim} G \\ \boldsymbol{G} \sim DP(MG_{0}) \end{aligned}$$

- ullet  $oldsymbol{artheta}_i$  latent variables
- G is discrete  $\implies$  ties: allocations  $c_i$ , unique values  $\phi_{c_i}$
- These form the *state* of the algorithm

### Case studies: hierarchies

Normal Normal-InverseGamma (NNIG) hierarchy:

$$\begin{split} f(y|\boldsymbol{\vartheta}) &= N(y|\mu,\sigma^2) \\ G_0(\boldsymbol{\vartheta}|\mu_0,\lambda_0,\alpha_0,\beta_0) &= N\left(\mu|\mu_0,\frac{\sigma^2}{\lambda_0}\right) \times \mathsf{Inv-Gamma}(\sigma^2|\alpha_0,\beta_0) \end{split}$$

with latent variables  $\boldsymbol{\vartheta} = (\mu, \sigma)$ 

Normal Normal-Wishart (NNW) hierarchy:

$$\begin{split} f(\mathbf{y}|\boldsymbol{\vartheta}) &= N(\mathbf{y}|\boldsymbol{\mu}, T^{-1}), \\ G_0(\boldsymbol{\vartheta}|\boldsymbol{\mu}_0, \lambda, T_0, \nu) &= N\left(\mu|\boldsymbol{\mu}_0, (\lambda T)^{-1}\right) \times \mathrm{Wish}(T|T_0, \nu). \end{split}$$

with latent variables  $\boldsymbol{\vartheta} = (\boldsymbol{\mu}, T)$ 

# **Algorithms**

## Neal's Algorithm 2

- Gibbs sampler for conjugate models
- ullet  $(oldsymbol{\phi}, \mathbf{c})$  is the **state** of a Markov chain
- Allocation sampling:

For  $i = 1, \ldots, n$ : update  $c_i$ 

- ▶ If  $c_i$  allocates  $\phi_{c_i}$  to a singleton, remove  $\phi_{c_i}$  from the state
- ightharpoonup Sample  $c_i$  as follows:

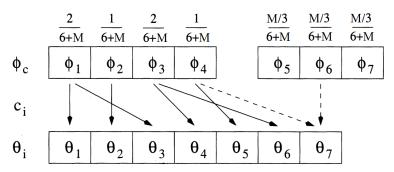
If 
$$c=c_j$$
 for some  $j\neq i$ :  $\mathbb{P}(c_i=c|\mathbf{c}_{-i},y_i,\pmb{\phi})\propto \frac{n_{-i,c}}{n-1+M}F(y_i,\phi_c)$  total  $\mathbb{P}(c_i\neq c_j \text{ for all } j|\mathbf{c}_{-i},y_i,\pmb{\phi})\propto \frac{M}{n-1+M}\int F(y_i,\phi)\,G_0(\mathrm{d}\phi)$ 

- ▶ If the new  $c_i$  allocates  $\phi_{c_i}$  to a singleton, draw  $\phi_{c_i} \sim G_0(\cdot|y_i)$  and add it to the state
- Unique values sampling:

For  $c \in \{c_1, \ldots, c_n\}$ : update  $\phi_c$ , given all the  $y_i$  with  $c_i = c$ 

## Neal's Algorithm 8

Gibbs sampling on the state, which is extended by the addition of m auxiliary blocks (here m=3, on the right)



## Neal's Algorithm 8

### Allocation sampling:

For  $i = 1, \ldots, n$ : update  $c_i$ 

- Sample auxiliary parameters:
  - $\circ \ c_i = c_j \text{ for some } j \Rightarrow \text{no connection}$
  - $\circ \ c_i \neq c_j \ \Rightarrow$  association to one of m

The other  $\phi$  values drawn from  $G_0$ 

▶ Draw  $c_i$  as follows:

$$P(c_i = c | \mathbf{c}_{-i}, y_i, \phi_1, \dots, \phi_h) \propto \begin{cases} \frac{n_{-i,c}}{n-1+M} F(y_i, \phi_c), & \text{for } 1 \le c \le k^-\\ \frac{M/m}{n-1+M} F(y_i, \phi_c), & \text{for } k^- + 1 < c \le h \end{cases}$$

with  $k^-$  unique values excluding  $c_i$  and  $h = k^- + m$ 

- lacktriangle Discard values in  $oldsymbol{\phi}$  not associated to any  $artheta_j$
- Unique values sampling:

For  $c \in \{c_1, \ldots, c_n\}$ : update  $\phi_c$  given  $y_i$  such that  $c_i = c$ 

# **Implementation**

### Libraries

#### bnplib depends on:

- Eigen
- Stan Math
  - Eigen
  - ▶ Boost
  - ▶ Intel's *Threading Building Blocks* (TBB)
  - Sundials
- Google's Protocol Buffer (Protobuf)

#### Python interface uses:

- Protobuf
- pybind11
- NumPy
- SciPy
- Scikit-learn
- Matplotlib

#### Model classes

• Mixture:

```
BaseMixture
mass_existing_cluster()
mass_new_cluster()
```

Derived: DirichletMixture, PitYorMixture

- Hypers: HypersFixedNNIG, HypersFixedNNW
- Hierarchy:

```
HierarchyBase<Hypers>
state
*hypers
eval_marg()
like()
sample_given_data()
draw()
```

Derived: HierarchyNNIG, HierarchyNNW

## Algorithm classes

template<template <class> class Hierarchy,
 class Hypers, class Mixture> class Algorithm

Constructor:

```
Algorithm(const Hypers &hypers_, const Mixture &mixture_, const Eigen::MatrixXd &data_, const unsigned int init = 0);
```

Method parameters:

```
unsigned int maxiter = 1000;
unsigned int burnin = 100;
```

• Data and value containers:

```
Eigen::MatrixXd data;
std::vector<unsigned int> cardinalities;
std::vector<unsigned int> allocations;
std::vector< Hierarchy<Hypers> > unique_values;
std::pair< Eigen::MatrixXd, Eigen::VectorXd > density;
Mixture mixture;
State best_clust;
```

## Algorithm classes

```
void step(){
    sample_allocations();
    sample_unique_values();
    sample_weights();
    update_hypers();
void run(BaseCollector* collector){
    initialize();
    unsigned int iter = 0;
    collector->start();
    while(iter < maxiter){</pre>
        step();
        if(iter >= burnin){
            save_state(collector, iter);
    iter++;
     collector->finish();
```

#### Neal2

- Derived from Algorithm class
- Overriden methods:
  - initialize()
  - ▶ sample\_allocations()
  - sample\_unique\_values()

#### Neal8

- Derived from Neal2 class
- Additional members:

```
unsigned int n_aux = 3;
std::vector<Hierarchy<Hypers>> aux_unique_values;
```

- Overriden method:
  - ▶ sample\_allocations()

#### Cluster Estimate

• Best clustering, i.e. best dissimilarity matrix  $D^{(k)}$ :

$$\hat{k} = \arg\min_{k} \|D^{(k)} - \bar{D}\|_{F}^{2} = \arg\min_{k} \sum_{i,j} (D_{ij}^{(k)} - \bar{D}_{ij})^{2}$$

• Algorithm method:

unsigned int cluster\_estimate(BaseCollector\* coll);

- ► Eigen::SparseMatrix class
- Save a State object into best\_clust member
- Writing utility:

write\_clustering\_to\_file(const std::string &filename);

## **Density Estimate**

• Density:

$$\hat{f}(x) = \frac{1}{K} \sum_k \hat{f}^{(k)}(x) \quad \text{with} \quad$$

$$\hat{f}^{(k)}(x) = \sum_{j} \frac{n_j^{(k)}}{M+n} f\left(x|\phi_j^{(k)}\right) + \frac{M}{M+n} \hat{m}(x)$$

• Algorithm method:

- density\_marginal\_component() subroutine, specific for each derived class
- ▶ Save result into density member
- Writing utility:

write\_density\_to\_file(const std::string &filename);

#### Collectors

Use Protobuf messages to store data:

```
message Par Col {
    repeated double elems = 1;
}
message Param {
    repeated Par Col par cols = 1;
}
message UniqueValues {
    repeated Param params = 1;
message State {
    repeated int32 allocations = 1;
    repeated UniqueValues uniquevalues = 2;
```

#### Collectors

#### Collector types:

- FileCollector: saves State objects into binary file
- MemoryCollector: deque of State objects

#### Writing mode:

- start()
- collect()
- close()

#### Reading mode:

- get\_chain()
- get\_next\_state()
- get\_state(unsigned int i)

## Algorithm factory

```
template<class AbstractProduct, typename... Args>
    class Factory
```

- For runtime choice of the algorithm
- Builder:

```
Builder = std::function<std::unique_ptr<
    AbstractProduct>(Args...)>
```

• Storage for algorithm builders:

```
std::map<Identifier, Builder> storage;
```

- Builders in the storage: neal2, neal8
- Variadic template for possibly different number of parameters as input in constructors

## Python interface

```
PYBIND11_MODULE(bnplibpy, m){
       m.doc() = "Nonparametric library for cluster and
           density estimation";
       m.def("run NNIG Dir", &run NNIG Dir);
  • Using Numpy for array structures
  get_multidim_grid()
  deserialize() (via Protobuf)
 clust_rand_score() (via Scikit-learn)
Plotting tools via Matplotlib:
  o chain barplot()
  • plot density points()
  • plot density contour()
  plot_clust_cards().
```

# Performance and optimization

## Sparse vs dense matrices

- For memory usage reasons in cluster\_estimate()
- ullet If k equal clusters, the nonzero entries for a dissimilarity matrix are

$$k\left(\binom{n/k}{2} - n\right) = \frac{n^2}{2k} - \frac{n}{2} - nk \ll n^2$$

Similar efficiency:

	sparse	dense
test 1	4.51696840e+07	4.15315598e+07
test 2	1.18633301e+09	9.17060859e+08
test 3	2.91540577e+07	3.00693867e+07
test 4	1.27339513e+08	1.22764857e+08
test 5	1.50049441e+08	1.37240555e+08
test 6	1.28818714e+08	1.16328396e+08

## Alternative implementation

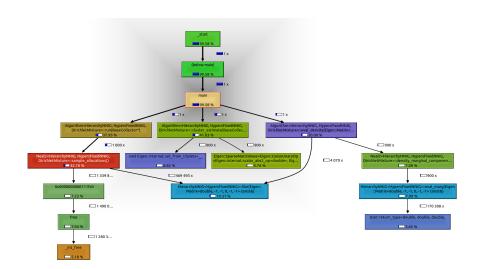
- Different approach of storing data, e.g. with an std::map of clusters
- A way to erase and add clusters more efficiently

#### Custom multivariate likelihood

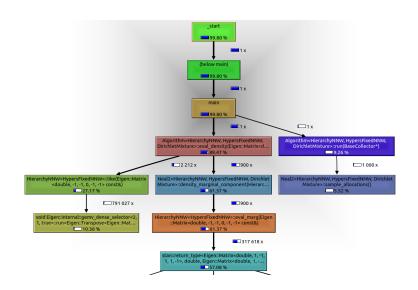
- In the HierarchyNNW class, as opposed to using the default Stan version
- Save matrix factorizations and determinants into the class to use them multiple times
- Improvement:

	run()	eval_density()	total
Stan	47700683	14317337	62018020
custom	39615848	10353269	49969117
speedup	1.20×	1.38x	1.25×

## callgrind profiling: univariate



## callgrind profiling: multivariate



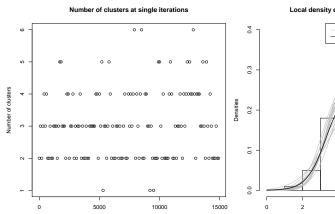
## Results

## Sensitivity analysis

### Set-up:

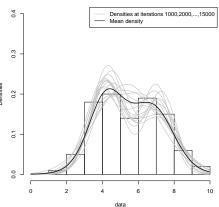
- n = 100 observations:
  - $y_1,\ldots,y_{50} \stackrel{\mathsf{iid}}{\sim} \mathcal{N}(4,1)$
  - $y_{51}, \ldots, y_{100} \stackrel{\text{iid}}{\sim} \mathcal{N}(7, 1)$
- Prior parameters for the Normal-NIG model:
  - $\mu_0 = 5$
  - $\lambda_0 = 1$
  - $\alpha_0 = 2$
  - $\beta_0 = 2$
- ullet Dirichlet Mixture with variable M
- Method parameters:
  - m=3 (for Neal8)
  - ightharpoonup maxiter = 20000
  - $\blacktriangleright$  burnin = 5000

### Oscillations

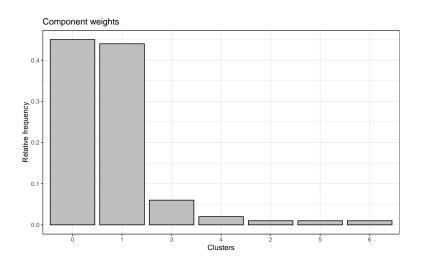


Iterations 100,200,...,15000

#### Local density estimates at single iterations



## Clustering



## Python tests

#### Data:

test	n	process
1		$y \sim 0.5 \mathcal{N}(-3, 1) + 0.5 \mathcal{N}(3, 1)$
2	1000	$y \sim 0.9 \mathcal{N}(-5, 1) + 0.1 \mathcal{N}(5, 1)$
3	200	$y \sim 0.3 \mathcal{N}(-2, 0.8^2) + 0.3 \mathcal{N}(0, 0.8^2) + 0.4 \mathcal{N}(2, 1)$
4	400	$y \sim 0.5 t_5(-5,1) + 0.5  SkewNormal(5,1,2)$
5,6	400	$y \sim 0.5 \mathcal{N}(-3 \cdot 1_d, I_d) + 0.5 \mathcal{N}(3 \cdot 1_d, I_d) \ d = 2, 5$

## Python tests: parameters

- Hyperparameters for all NNIG hierarchies:
  - $\mu_0 = 0.0$
  - $\lambda = 0.1$

  - $\beta = 2$
- Hyperparameters for all *d*-dimensional NNW hierarchies:
  - $\mu_0 = \overline{y}$
  - $\lambda = 0.2$
  - $\nu = d + 3$
  - $au_0 = \frac{1}{\nu} I_d$
- ullet Dirichlet Mixture with M=1
- Method parameters for Neal2:
  - ightharpoonup maxiter = 500
  - ▶ burnin = 100

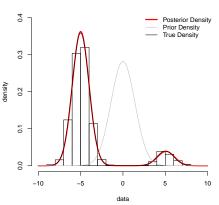
#### Posterior Estimate

# Posterior Density Prior Density True Density

# -4 -2 0 2 4



#### **Posterior Estimate**



Test 2. ARI = 1.0

0.4

0.3

0.2

0.1

density

#### Posterior Estimate

# Posterior Density Prior Density True Density

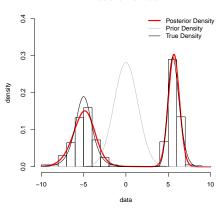
2

### Test 3. ARI = 0.45

data

-2

#### Posterior Estimate



Test 4. ARI = 0.99

0.4

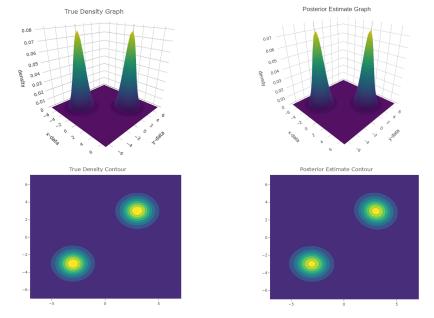
0.3

0.2

0.7

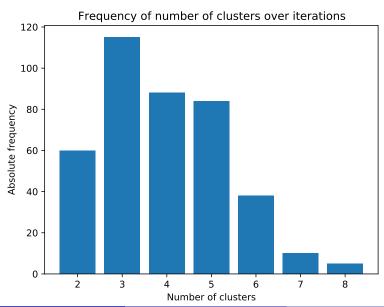
0.0

density



Test 5. True pdf on the left, posterior pdf on the right. ARI=1.0

## Example of chain\_barplot() for test 1



#### Extensions

- Complete runtime implementation
- ullet Adaptation for hyper-priors on total mass M or on Hypers
- Implementation of other Hierarchy / Mixture / Algorithm classes (split-and-merge, slice samplers, handling non-conjugacy)
- Interface with R
- FileCollector without get\_chain()
- Code parallelization (in cluster\_estimate(); consensus Monte Carlo)
- Integration of generic Normalized Random Measures
- Full generalization?

## Bibliography P. Muller, F. A. Quintana, Bayesian Nonparametric Data Analysis R. M. Neal (2000), Markov Chain Sampling Methods for Dirichlet Process Mixture Models H. Ishwaran, L. F. James (2001), Gibbs Sampling Methods for Stick-Breaking Priors J. Pitman, M. Yor (1997), The two-parameter Poisson-Dirichlet distribution derived from a stable subordinator K. P. Murphy (2007), Conjugate Bayesian analysis of the Gaussian distribution Rand W. (1971), Objective Criteria for the Evaluation of Clustering Methods Stan documentation: http://mc-stan.org/math. Code found at https://github.com/stan-dev/math Eigen documentation: https://eigen.tuxfamily.org/dox. Code is included in the Stan package Protocol Buffers Tutorial for C++: https://developers.google.com/protocol-buffers/docs/cpptutorial. Code found at https://github.com/protocolbuffers/protobuf pybind11 tutorial and documentation: http://pybind11.readthedocs.org/en/master scikit-learn user guide: https://scikit-learn.org/stable/user\_guide.html Codes of Mario Beraha and Riccardo Corradin for similar projects, found at

- https://github.com/mberaha/partial\_exchangeability and https://github.com/rcorradin/BNPmix respectively

  Course material for Bayesian Statistics by Prof. Guglielmi:
  - https://beep.metid.polimi.it/web/2019-20-bayesian-statistics-alessandra-guglielmi-/
  - Course material for Advanced Programming for Scientific Computing by Prof. Formaggia:

    https://beep.metid.polimi.it/web/102725282