

# EE23B022RprtLab3

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## 1 Introduction

I am Deepak Charan S (Roll No: EE23B022) and this is my report for the second assignment of Microprocessor Lab, which I had done on 27/8/24.

## 2 Objective:

- To wire the AVR atmega8 microcontroller along with the given peripherals in a breadboard.
- To program the microcontroller to read the DIP switch values and display it in an LED using assembly programming.
- To program the microcontroller to perform the addition and multiplication of two four-bit numbers which are read from the DIP switches connected to a port and display the result using LED's connected to another port.
- to program an LED pulse

## 3 Equipments/Software Required:

1. Atmel AVR (Atmel8L) Chip
2. A breadboard with microprocessor socket
3. 8-bit DIP switches
4. 5 LEDs
5. Capacitors, resistors and wires

6. AVR Programmer (USB-ASP)
7. A windows PC loaded with Microchip Studio 7 and AVR Burn-O-MAT (for burning asm)

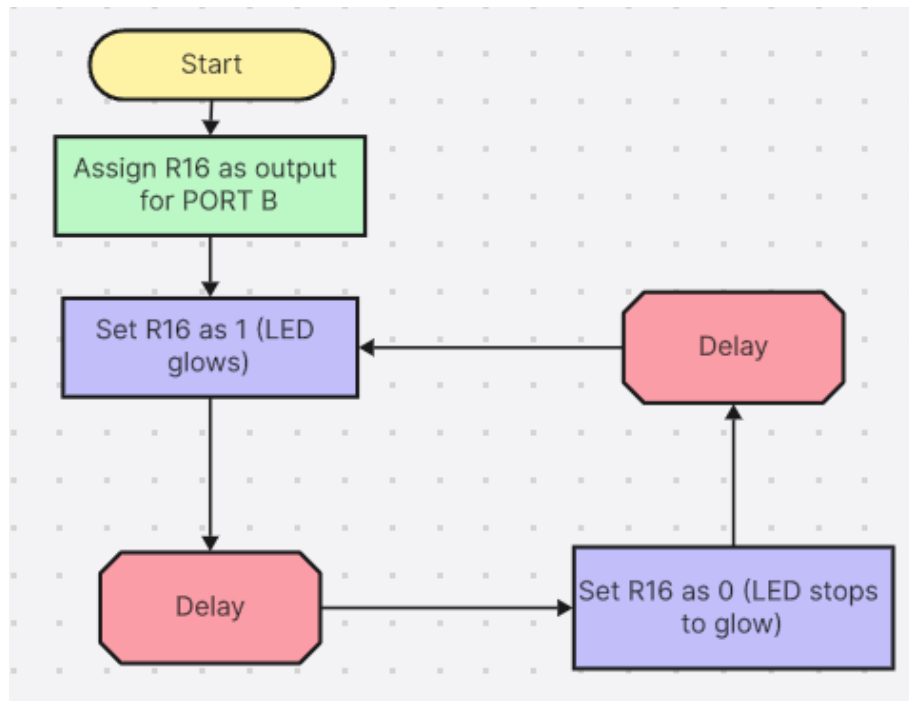
## **4 General Procedure:**

1. Write the AVR assembly code on microchip studio IDE to accomplish all the four objectives
2. Clean existing solutions and build new solution at the start of debugging
3. Debug and test them out line by line on microchip studio and analyse the values in registers, SRAM and carry flags
4. Wire the required components properly on the breadboard
5. Use the AVR Programmer to connect the breadboard and the PC
6. generate the .hex file from Microchip Studio
7. Use the .hex to burn the file into the AVR chip using AVR Burn-O-MAT
8. Test out the hardware to verify the result

## **5 Problem 1: Blinking an LED**

### **5.1 Implementation:**

1. We first initialise the R16 register as an output for PORT D
2. We assign value to 1 so that LED lights up
3. Then we create a nested for loop which does nothing but iterate over 5,00,000 times. This is done to create a delay for the LED to toggle to 0
4. set R16 to 0 so that LED stops glowing
5. repeat the delay process
6. loop back to step 2 so that we observe a continuous pulse



## 5.2 Code:

```

1  ;pulse.asm
2
3  .include "m8def.inc"
4
5  LDI R16 , 0xFF ; All bits set as 0 to make port as
   output
6  OUT DDRD, R16 ; DDRB = Data Direction Register for PORT
   D
7  again:
8  LDI R16, 0x01
9  OUT PORTD, R16 ;LED output is HIGH
10
11 LDI R17, 0x21 ; Creating a Delay Cycle to give a pulse
   width of 0.5 sec
12 LOOP4:LDI R18, 0x32
13 LOOP5:LDI R19, 0x64
14 LOOP6:DEC R19
15 BRNE LOOP6
16 DEC R18
17 BRNE LOOP5

```

```

18  DEC R17
19  BRNE LOOP4
20
21  LDI R16, 0x00
22  OUT PORTD, R16    ;LED output is LOW
23
24  LDI R17, 0x21      ;Creating another Delay Cycle
25  LOOP1:LDI R18, 0x32
26  LOOP2:LDI R19, 0x64
27  LOOP3:DEC R19
28  BRNE LOOP3
29  DEC R18
30  BRNE LOOP2
31  DEC R17
32  BRNE LOOP1
33
34  RJMP again        ; Creating an infinite loop to generate
                    continuous pulses

```

### 5.3 Photos:

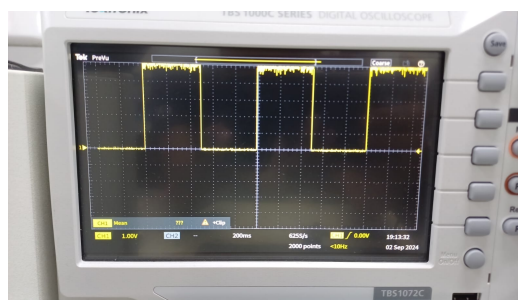
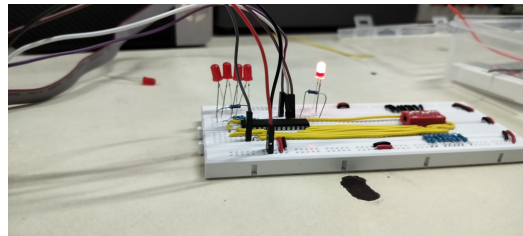
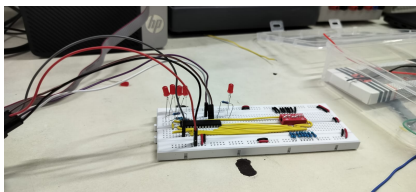


Figure 1: pulse waveform measured using an oscilloscope

## 6 Problem 2: Controlling an LED using push button

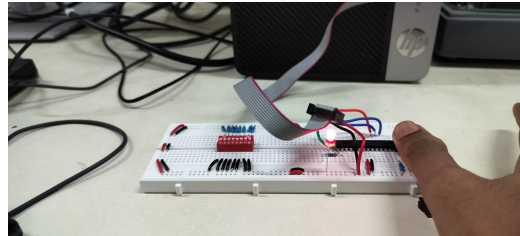
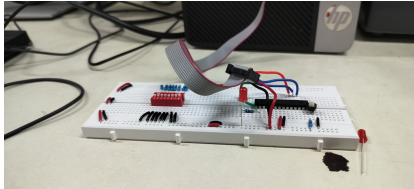
### 6.1 Implementation:

1. We first initialise the R16 register as 0xFF, i.e., make all its bits equal to 1.
2. We write the contents of R16 onto DDRD to make port D an output port.
3. Then we made R16 0x00, i.e, we made all bits of R16 equal to 0.
4. We write the contents of R16 onto DDRB to make port B an input pin.
5. Then we store the input of port B in R16 and write it onto port D.  
*Note: Since input is low when push button is pressed, we need to invert the R16 value while sending it as output for port D*
6. LED is connected to port D.

### 6.2 Code:

```
1 ;  
2 ; push.asm  
3  
4 .include "m8def.inc"  
5 again: LDI R16 , 0xFF ; All bits set as 1 to make port  
        as output  
6         OUT DDRD , R16 ; DDRD = Data Direction Register  
           for PORT D  
7         LDI R16 , 0x00 ; All bits set as 0 to make port  
           as input  
8         OUT DDRB , R16 ; DDRB = Data Direction Register  
           for PORT B  
9         IN R16 , PINB ; Store the input of PORT B to  
           register R16  
10        COM R16 ; reason mentioned in implementation  
           section  
11        OUT PORTD , R16 ; Set LED connected to PDx as  
           input of PBx  
12        RJMP again
```

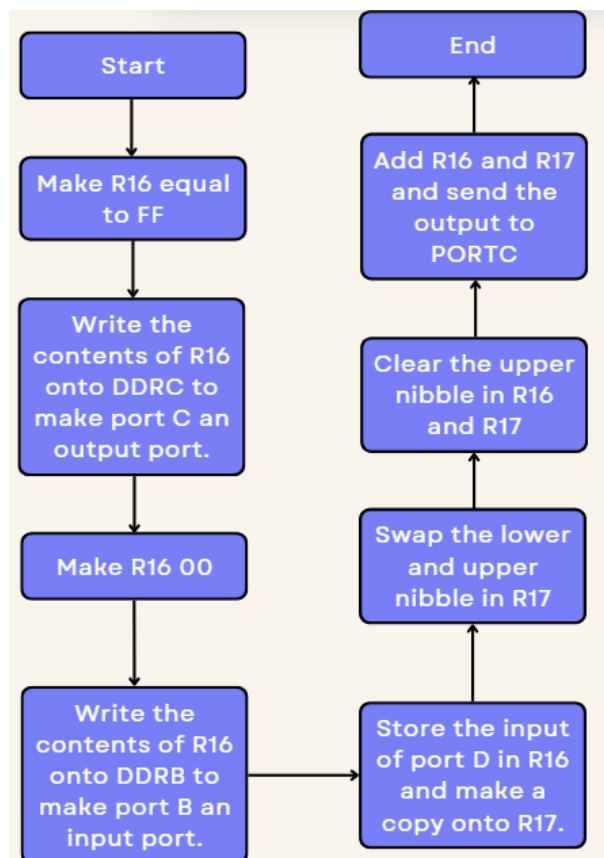
### 6.3 Photos:



## 7 Problem 3: Displaying 4 bit addition

### 7.1 Implementation:

1. We first initialise the R16 register as 0xFF, i.e., make all its bits equal to 1.
2. We write the contents of R16 onto DDRC to make port C an output port.
3. Then we made R16 0x00, i.e, we made all bits of R16 equal to 0.
4. We write the contents of R16 onto DDRD to make port D an input pin.
5. DIP switches are connected to port D.
6. Then we store the input of port D in R16 and make a copy onto R17.
7. Swap the lower and upper nibble in R17
8. Clear the upper nibble in R16 and R17 to get first 4 bits and last 4 bits from DIP switches in two separate registers
9. Add R16 and R17 and send the output to PORTC
10. 5 LEDs are connected to port C.



## 7.2 Code:

```

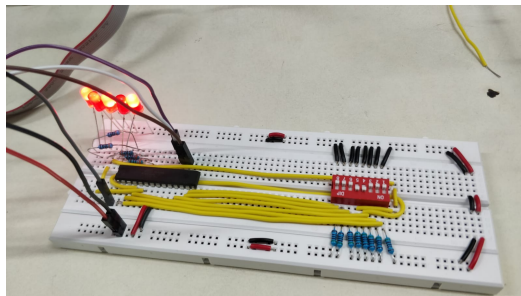
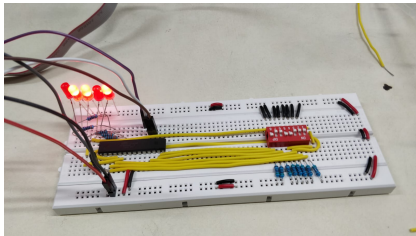
1 ; 4bit_add.asm
2
3 .include "m8def.inc"
4 again: LDI R16, 0xFF ; All bits set as 1 to make port as
        output
5         LDI R17, 0x00 ; Clearing register for later use
6         OUT DDRC, R16 ; DDRC = Data Direction Register
        for PORT C
7         LDI R16, 0x00 ; All bits set as 0 to make port
        as input
8         OUT DDRD, R16 ; DDRD = Data Direction Register
        for PORT D
9         IN R16, PIND ; Store the input of PORT D to
        register R0
10        MOV R17, R16 ; Copy input to R1
11        ANDI R16, 0x0F ; Make R0 only first 4 bits
  
```

```

12      SWAP R17 ;
13      ANDI R17, 0x0F; Make R1 only first 4 bits
14      ADD R16, R17 ; Add and store result in R0
15      OUT PORTC, R16 ; Set LED connected to PCx as
        input of PDx
16      RJMP again

```

### 7.3 Photos:



## 8 Interpretations of result

Controlling AVR Peripherals through Assembly Programming was demonstrated through a breadboard circuit.

*Note: The code for blinking LED was done by me.*

## 9 References:

Handouts and Instruction Manual of AVR provided in moodle. Slight reference from Mazidi's "The AVR Microcontroller and embedded systems" was also used.