上周实验结果汇总:

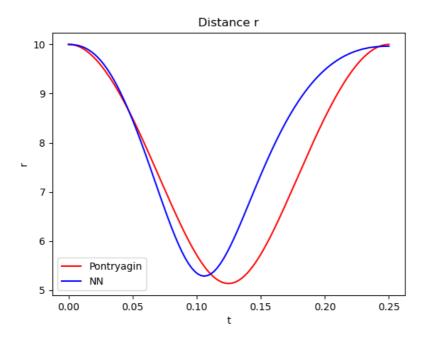
测试了两个情景:无约束和有约束,曲线的绘制:距离变化,位置XYZ变化,3D轨迹,控制律XYZ变化

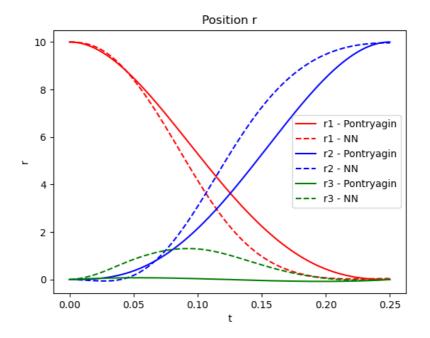
$$J = rac{1}{2} \int_{t_0}^{t_f} \mathbf{u}^\intercal \mathbf{u} dt$$

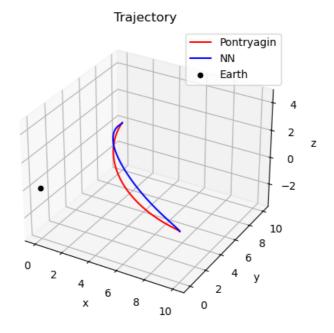
无约束情景

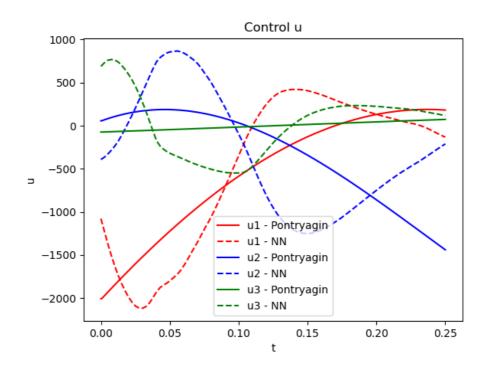
1. Loss: $\mathcal{L} = ||\mathbf{y}(t_f) - \mathbf{y_f}|| + J$,Pontryagin对应能量最低的曲线,NN对应MLP的曲线

最低能量: J = 135808.8331247889 NN学习轨迹的能量: J = 199833.375





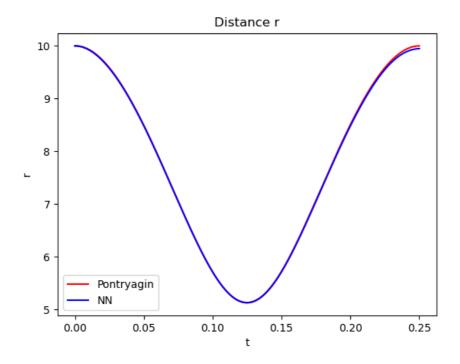


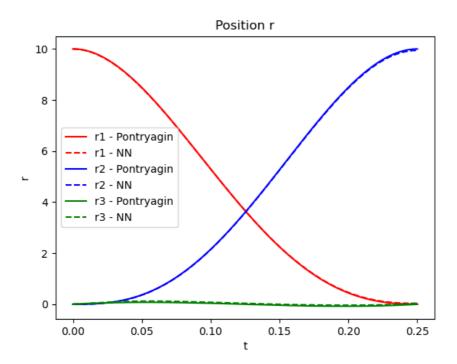


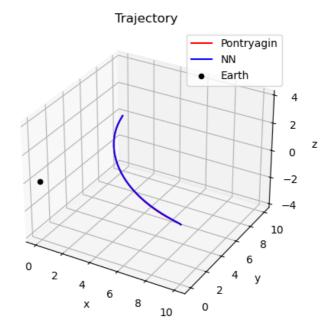
2. 有最优轨迹数据,Loss: $L = Mean(||\mathbf{y} - \mathbf{y_{bench}}||)$

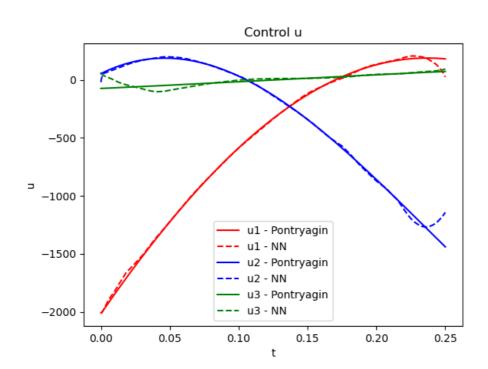
最低能量: J = 135808.8331247889

NN学习能量: J=132750.65625



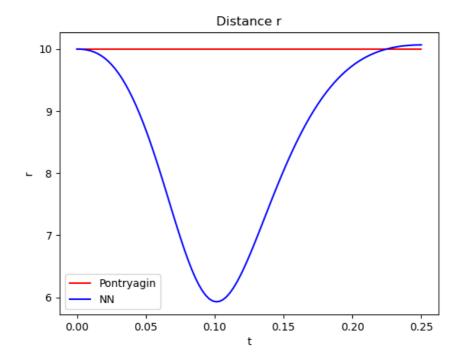


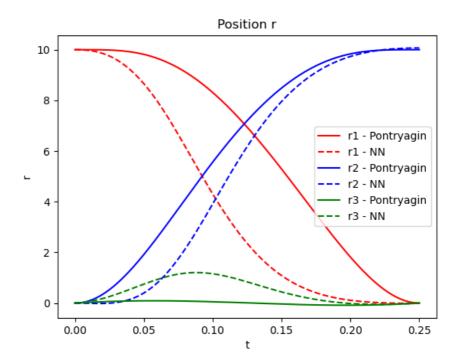


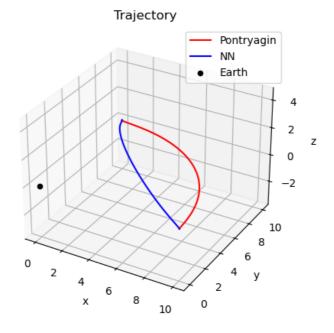


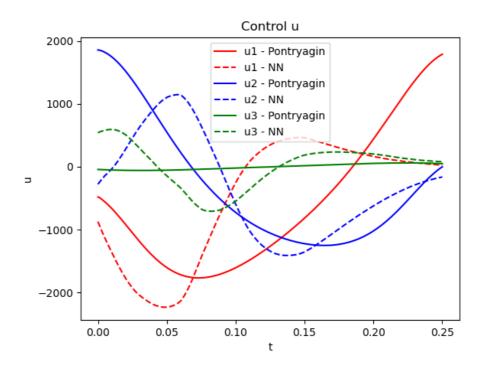
有约束场景:

1. Loss: $\mathcal{L}=10^5 imes||\mathbf{y}(t_f)-\mathbf{y_f}||+10^5 imes+J$,曲线最终不满足约束





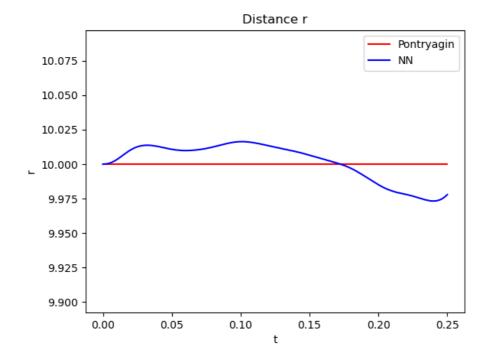


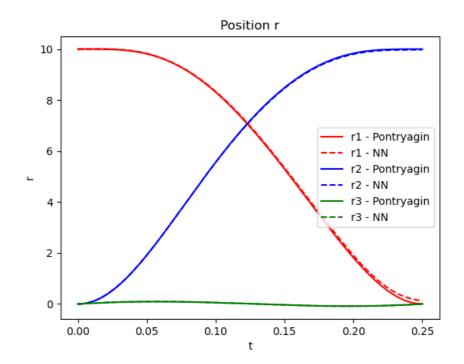


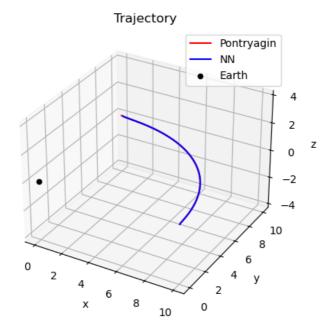
2. 有最优轨迹数据,Loss: $L = Mean(||\mathbf{y} - \mathbf{y_{bench}}||)$

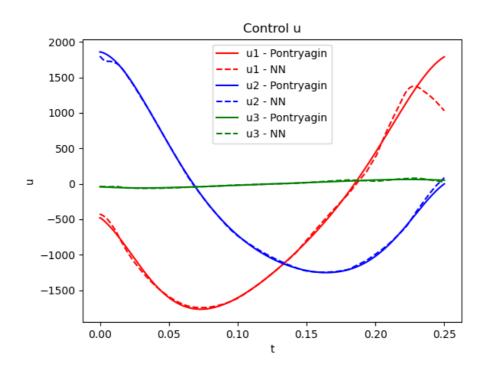
最低能量: J = 312561.90460526873

NN学习能量: J = 312434.34375, Loss = 0.6441755129676159









从实验结果来看,如果有轨迹数据可以逼近的话,MLP是可以近似表达出轨迹对应的控制律的,但是在没有数据只有Loss的情况下,MLP无法学出能量最优的轨迹对应的控制律,也很难满足轨迹的约束。