# Control Theory.

# Assignmentn2.

Polina Turishcheva. Group 3. Variant B

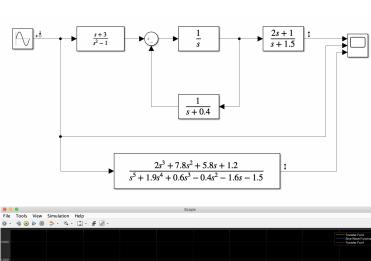
Task 2 2.1

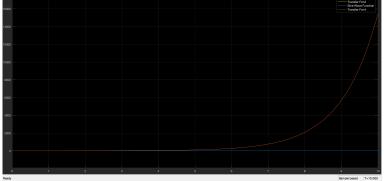
$$W = W_1 \frac{W_2}{1 + W_2 W_4} W_3$$

$$W = \frac{s+3}{s^2 - 1} * \frac{1/s}{1 + (1/s)(1/(s+0.4))} * \frac{2s+1}{s+1.5}$$

$$W = \frac{2s^3 + 7.8s^2 + 5.8s + 1.2}{s^5 + 1.9s^4 + 0.6s^3 - 0.4s^2 - 1.6s - 1.5}$$

2.2





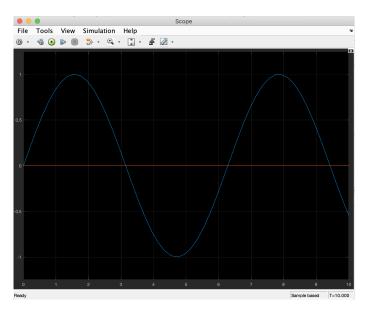


Figure 1: Frequency response describes the steady-state response of a system to sinusoidal inputs. Here input is sin(x). Yellow and red lines are the same one. The blue one is from input. Because of scale its shape is not clear, hence, it is also drawn separately.

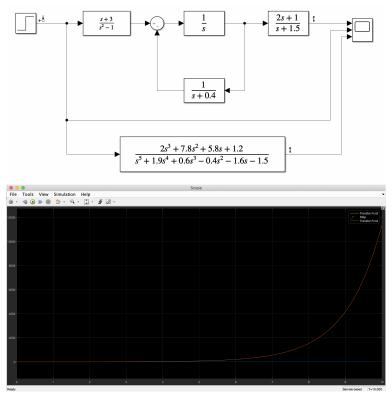


Figure 2: Step at time 1, amplitude 1.Again responses from initial and simplified systems are the same.

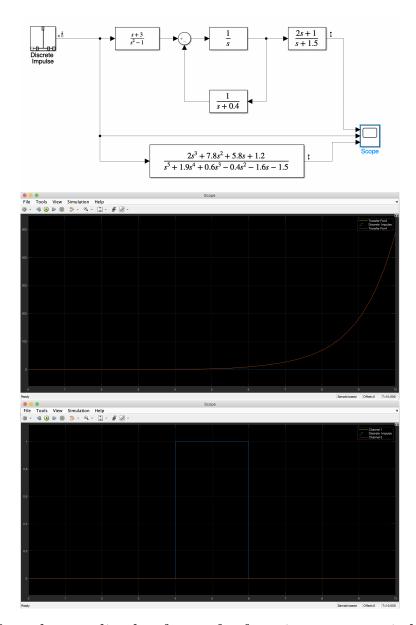


Figure 3: Here the amplitude of transfer function response is less and it is possible to notice the change in input. The amplitude of discrete impulse input is 1, duration= 2.

# **2.3** I have chosen a sin(x) input:

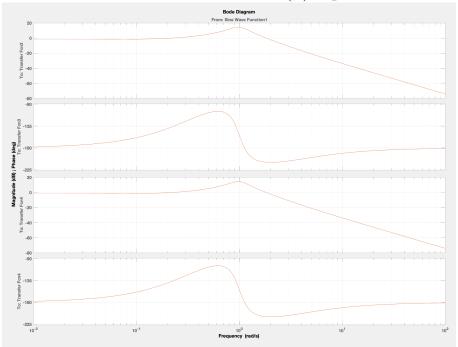


Figure 4: Bode Plot. Amplitude-Phase for non-simplified system and Amplitude-Phase for the simplified system are identical.

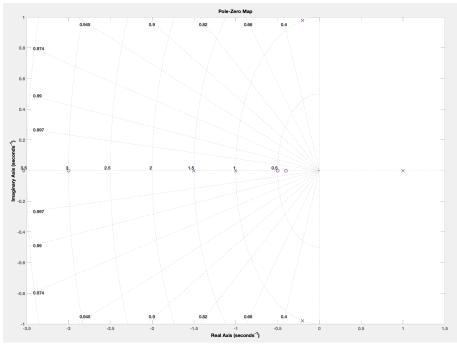


Figure 5: Pole-Zero: Poles at  $(-0.2, \pm 0.98i), (-1,0), (-1.5,0), (1,0)$ . Zeroes at (-3,0), (-0.5,0), (-0.4,0). If any pole has a positive real part there is a component in the output that increases without bound, causing the system to be unstable. We have a pole (1, 0), hence, system is unstable.

2.4 We know poles and zeroes from the previous step. Actually, they are As for constant,  $c_1 = 1.2$  in numerator,  $c_2 = -1.5$  in denominator, in final simplified version of the transfer function.. Hence, we have a line at  $20log_{10}|\frac{1.2}{-1.5}| = -1.93.$ 

For real poles (real zeros in denominator, clear from part 2.1), we have -20dB for a decade (e.g. -20 for 10, -40 for 100), we start subtraction after  $w_0$  frequency, which is exactly the value of the current pole. For real zeroes (zeroes in the numerator), we have +20dB for a decade, starting exactly from current zero. For both real poles and zeros before the  $w_0$ they are assumed to have 0 amplitude. Note that we take absolute values of real poles and zeroes. For complex poles we have  $s^2 - 2\epsilon w_0 s + w_0^2 =$  $s^2 + 0.4s + 1$ , hence,  $w_0 = 1$ ,  $\epsilon = 0.2$ , therefore, we have resonance peak at  $w_r = w_0 * \sqrt{1 - 2\epsilon^2} = 0.96$  with height  $h = -20log_{10}(2\epsilon\sqrt{1 - \epsilon^2}) = 8.14$ , than it starts decreasing from this point with -40dB for a decade. There are no complex zeroes in this case. Summing all of those we get the following:

ing: 
$$A(f) = \begin{cases} -1.93, & \text{if } f < 0.4. \\ -1.93 + 20\log_{10}(\frac{w}{0.4}), & \text{if } 0.4 \leq f < 0.5. \\ -1.93 + 20\log_{10}(\frac{w}{0.4}) + 20log_{10}(\frac{w}{0.5}), & \text{if } 0.5 \leq f < 0.96. \\ -1.93 + 20\log_{10}(\frac{w}{0.4}) + 20log_{10}(\frac{w}{0.5}) + 8.14 = 19.48, & \text{if } f = 0.96. \\ -1.93 + 20\log_{10}(\frac{w}{0.4}) + 20log_{10}(\frac{w}{0.5}) - 40log_{10}(\frac{w}{0.96}), & \text{if } 0.96 \leq f < 1. \\ -1.93 + 20\log_{10}(\frac{w}{0.4}) + 20log_{10}(\frac{w}{0.5}) - 40log_{10}(\frac{w}{0.96}) - & \text{if } 1 \leq f < 1.5. \\ -2*20\log_{10}(\frac{w}{1}) = -19.3 + 20log_{10}(\frac{1}{0.2} - 40log_{10}(\frac{w}{0.96}) - 2*20log_{10}(\frac{w}{0.96}) = 12.05 - 40log_{10}(\frac{w}{0.96}) \\ & \text{we have } 2 \text{ here as there are } 1 \text{ and } -1 \text{ frequencies.} \\ 12.05 - 40\log_{10}(\frac{w}{0.96}) - 20log_{10}(\frac{w}{1.5}), & \text{if } 1.5 \leq f < 3. \\ 12.05 - 40\log_{10}(\frac{w}{0.96}) - 20log_{10}(\frac{w}{1.5}) + 20log_{10}(\frac{w}{3}), & \text{otherwise.} \end{cases}$$

$$(1)$$
From the function definition we can find approximate axis intersection and max value. They are:  $A = 0 \Rightarrow f = 0.40 \text{ or } f = 1.39, f = 0 \Rightarrow A = -1.93$ , peak value (at  $x = 0.96$ ) is  $19.48 - f = 0.96$  is also the break

-1.93, peak value (at x = 0.96) is 19.48 - f = 0.96 is also the break frequency value.

Real values from the matlab bode plot are  $A = 0 \Rightarrow f \approx 0.2 \text{ or } f \approx 1.8$ ,  $f = 0 \Rightarrow A \approx -1.93$ , peak value (at  $x \approx 0.96$ ) is  $\approx 14.5$ .

### Task 3

From lab we have the formula for Total Transfer Function of the same system:

$$T(s) = \frac{W(s)}{1 + W(s)}G + \frac{M(s)}{1 + W(s)}F$$
In this case  $W(s) = \frac{s^2 + 4s + 1}{2s^2 + 5s}$ ,  $M(s) = \frac{3}{s - 3}$ 
Hence,  $\frac{W(s)}{1 + W(s)} = \frac{(s^2 + 4s + 1)/(2s^2 + 5s)}{(3s^2 + 9s + 1)/(2s^2 + 5s)} = \frac{s^2 + 4s + 1}{3s^2 + 9s + 1}$ 

$$\frac{M(s)}{1+W(s)} = \frac{(3)(s-3)}{(3s^2+9s+1)/(2s^2+5s)} = \frac{3(2s^2+5s)}{3(s^3-2s^2-2s-1)} = \frac{2s^2+5s}{s^3-2s^2-2s-1}$$

Therefore, our total transfer function looks like:

$$T(s) = \frac{s^2 + 4s + 1}{3s^2 + 9s + 1}G + \frac{2s^2 + 5s}{s^3 - 2s^2 - 2s - 1}F$$

#### Task 4

System:

$$A = \begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix} B = \begin{pmatrix} 2 \\ 1 \end{pmatrix} C = \begin{pmatrix} 3 & 0 \end{pmatrix} D = \begin{pmatrix} 0 \end{pmatrix}$$

Solution:

Transfer function =  $C(sI - A)^{-1}B + D$ 

$$(sI - A) = \begin{pmatrix} s - 1 & 1 \\ -2 & s - 1 \end{pmatrix} \Rightarrow (sI - A)^{-1} = \frac{1}{(s - 1)^2 + 2} \begin{pmatrix} s - 1 & 2 \\ -1 & s - 1 \end{pmatrix}$$
$$C(sI - A)^{-1}B = \frac{1}{(s - 1)^2 + 2} \begin{pmatrix} 3 & 0 \end{pmatrix} \begin{pmatrix} s - 1 & 2 \\ -1 & s - 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} =$$
$$= \frac{1}{(s - 1)^2 + 2} \begin{pmatrix} 3s - 3 & 6 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \frac{6s}{(s - 1)^2 + 2}$$

Transfer function = 
$$C(sI - A)^{-1}B + D = \frac{6s}{(s-1)^2 + 2}$$

### Task 5

System:

$$A = \begin{pmatrix} 1 & -2 \\ 2 & -1 \end{pmatrix} B = \begin{pmatrix} 2 & 3 \\ 2 & 0 \end{pmatrix} C = \begin{pmatrix} -1 & 4 \end{pmatrix} D = \begin{pmatrix} 2 & 1 \end{pmatrix}$$

### Solution:

Transfer function =  $C(sI - A)^{-1}B + D$ 

$$(sI - A) = \begin{pmatrix} s - 1 & 2 \\ -2 & s - 1 \end{pmatrix} \Rightarrow (sI - A)^{-1} = \frac{1}{s^2 + 3} \begin{pmatrix} s - 1 & -2 \\ 2 & s - 1 \end{pmatrix}$$
$$C(sI - A)^{-1}B = \frac{1}{s^2 + 3} \begin{pmatrix} -1 & 4 \end{pmatrix} \begin{pmatrix} s - 1 & -2 \\ 2 & s - 1 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 2 & 0 \end{pmatrix} =$$
$$= \frac{1}{s^2 + 3} \begin{pmatrix} 7 - s & 4s - 2 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 2 & 0 \end{pmatrix} = \frac{1}{s^2 + 3} \begin{pmatrix} 10 + 6s & 21 - 3s \end{pmatrix}$$

Transfer function =  $C(sI - A)^{-1}B + D = \frac{1}{s^2 + 3} (12 + 6s, 22 - 3s)$ 

## Task 6

$$X = 0 \Rightarrow \Phi_f(x) = \frac{W_5 W_6 W_7}{1 - W_4 W_6} * \frac{W_3}{1 - \frac{W_3 W_5 W_6 W_8}{(1 - W_4 W_6)}}$$

$$F = 0 \Rightarrow \Phi(x) = \frac{W_5 W_6 W_7}{1 - W_4 W_6} * \frac{W_3}{1 - \frac{W_3 W_5 W_6 W_8}{(1 - W_4 W_6)}} * \frac{W_2}{1 - \frac{W_1 W_2}{W_4}}$$

Total Transfer Function  $=\Phi(s)G + \Phi_f(s)F$ 

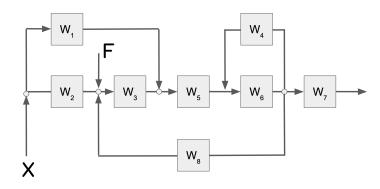


Figure 6: Initial scheme

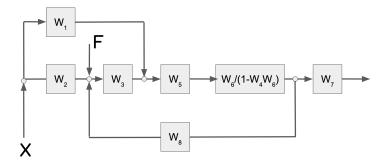


Figure 7: Simplified loop with  $W_4$  and  $W_6$ 

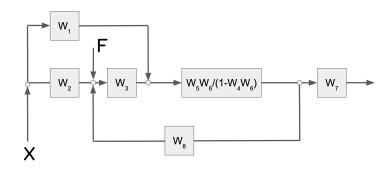


Figure 8: Combined  $W_5$  with former loop

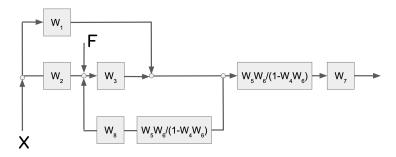


Figure 9: Moving take-off point before a block

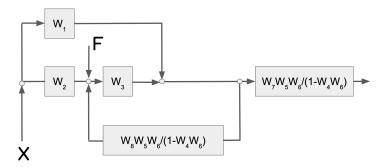


Figure 10: Combined  $W_8$  and  $W_7$  with their branches

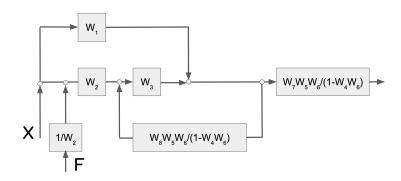


Figure 11: Moving summing point with F before  $W_2$  block

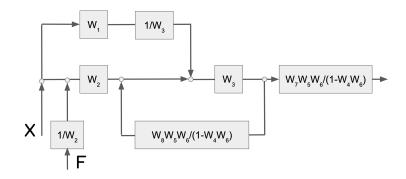


Figure 12: Moving summing point from bottom branch before  $W_3$  block

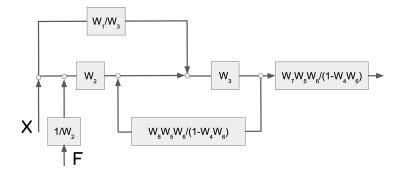


Figure 13: Combined  $W_1$  with its branch

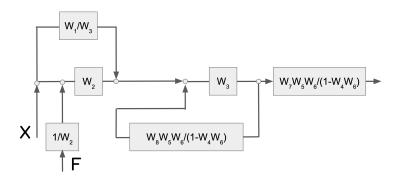


Figure 14: Associative Law - changed the order of summing points without a block between them

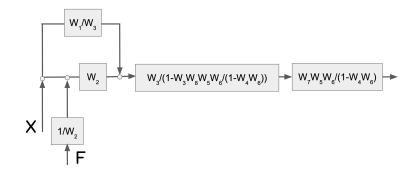


Figure 15: Simplified loop with  $W_3$ 

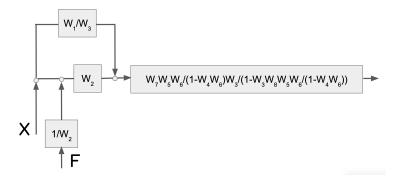


Figure 16: Combined two last blocks before output

$$\frac{W_5 W_6 W_7}{1 - W_4 W_6} * \frac{W_3}{1 - \frac{W_3 W_5 W_6 W_8}{(1 - W_4 W_6)}}$$

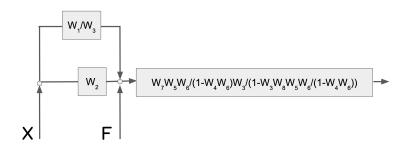


Figure 17: Move summing point after a block.

As 
$$W_2 * \frac{1}{W_2} = 1$$
 it becomes just F



Figure 18: Simplified loop with  $W_2$  and  $\frac{W_1}{W_3}$ 

#### 5.3. Rules for reduction of Block Diagram model: Sl. No. Rule Configuration Equivalent Name No. G<sub>1</sub>(s) **G**<sub>2</sub>(s) -C(s) R(s) $G_1(s)G_2(s)$ -C(s) 1 R(s) Rule 1 Cascade G<sub>1</sub>(s) R(s) • G<sub>1</sub>(s)+G<sub>2</sub>(s) Parallel 2 Rule 2 G<sub>2</sub>(s) G(s) -C(s) R(s) 3 Rule 3 Loop $\overline{1\pm G(s)H(s)}$ H(s) R(s) R(s) Associative 4 Rule 4 Law X<sub>1</sub>(s) X2(s) $X_1(s)$ $X_2(s)$ G(s) G(s) R(s)-R(s) Move take-5 Rule 5 off point after a block 1/G(s) X(s)≺ X(s) **∢** G(s) **→**C(s) G(s) Move take-→ C(s) off point 6 Rule 6 before a block X(s)∢ G(s) ► C(s) R(s) Move G(s) summing-7 Rule 7 G(s) point point after a block X(s) X(s) ₩ G(s) Move G(s) summing-1/G(s) 8 Rule 8 point point before a X(s) X(s) block

Figure 19: **P.S.** Here is the list of rules used during simplification process.