chapter-07-02

March 14, 2025

Run in Google Colab

1 Understanding Simple LSTM Neural Networks in Keras

1.1 Import Libraries

```
[2]: from pandas import read_csv
import numpy as np
from keras.models import Sequential
from keras.layers import Dense, Dropout, LSTM
from sklearn.preprocessing import MinMaxScaler
from sklearn.metrics import mean_squared_error
import math
import matplotlib.pyplot as plt
```

1.2 Running the LSTM on Sunspots Dataset

Let's run a complete RNN on a simple time series dataset. We'll need to follow these steps:

- Read the dataset from a given URL
- Split the data into training and test sets
- Prepare the input to the required Keras format
- Create an RNN model and train it
- Make the predictions on training and test sets and print the root mean square error on both sets
- View the result

Step 1, 2: Reading Data and Splitting Into Train and Test

The following function reads the train and test data from a given URL and splits it into a given percentage of train and test data. It returns single-dimensional arrays for train and test data after scaling the data between 0 and 1 using MinMaxScaler from scikit-learn.

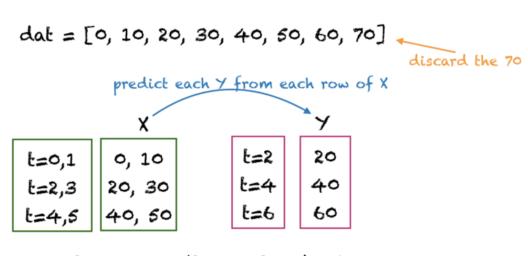
```
[3]: # Parameter split_percent defines the ratio of training examples
def get_train_test(url, split_percent=0.8):
    df = read_csv(url, usecols=[1], engine='python')
    data = np.array(df.values.astype('float32'))
    scaler = MinMaxScaler(feature_range=(0, 1))
    data = scaler.fit_transform(data).flatten()
```

```
n = len(data)
# Point for splitting data into train and test
split = int(n*split_percent)
train_data = data[range(split)]
test_data = data[split:]
return train_data, test_data, data
```

Step 3: Reshaping Data for Keras

The next step is to prepare the data for Keras model training. The input array should be shaped as: total_samples x time_steps x features.

There are many ways of preparing time series data for training. We'll create input rows with non-overlapping time steps. An example for time steps = 2 is shown in the figure below. Here, time steps denotes the number of previous time steps to use for predicting the next value of the time series data.



input previous 'time_steps' values output value at the next time: time_steps+1

(source: "Understanding Simple Recurrent Neural Networks in Keras" by Mehreen Saeed, Machine Learning Mastery)

The following function get_XY() takes a one-dimensional array as input and converts it to the required input X and target Y arrays. We'll use 12 time_steps for the sunspots dataset as the sunspots generally have a cycle of 12 months. You can experiment with other values of time_steps.

```
[4]: # Prepare the input X and target Y

def get_XY(dat, time_steps):
    Y_ind = np.arange(time_steps, len(dat), time_steps)
    Y = dat[Y_ind]
    rows_x = len(Y)
    X = dat[range(time_steps*rows_x)]
    X = np.reshape(X, (rows_x, time_steps, 1))
```

Step 4: Create RNN Model and Train

The function below returns a model that includes a SimpleRNN layer and a Dense layer for learning sequential data. The input_shape specifies the parameter (time_steps x features). We'll simplify everything and use univariate data, i.e., one feature only; the time steps are discussed below.

```
[5]: def create_LSTM(time_steps):
         model = Sequential()
         # The first LSTM layer with 50 units and the input shape (time_steps, 1) is_u
      \hookrightarrow added.
         # This layer is configured to return sequences using the
      ⇔return_sequences=True parameter.
         # It means this layer will produce output sequences for each time step in \Box
      ⇔the input sequence.
         model.add(LSTM(50, input_shape=(time_steps, 1), return_sequences=True))
         # After each LSTM layer, a dropout layer is added with a dropout rate of O.
      \hookrightarrow 2. Dropout is
         # a regularization technique that helps prevent overfitting by randomly u
      ⇔"dropping out"
         # a fraction of neurons during training.
         model.add(Dropout(0.2))
         # The second LSTM layer with 50 units is added. It also returns sequences.
         model.add(LSTM(50, return_sequences=True))
         model.add(Dropout(0.2))
         # The third LSTM layer with 50 units is added, but this time it's
      ⇔configured to return only the final output,
         # not sequences.
         model.add(LSTM(50, return_sequences=False))
         model.add(Dropout(0.2))
         # A single dense layer with one output unit is added. This layer is ...
      →typically used for regression tasks,
         # where the model predicts a continuous numeric value.
         model.add(Dense(1))
         model.summary()
         # The model is configured for training. It uses mean squared error (MSE) as __
      ⇔the loss function,
         # which is a common choice for regression problems. The 'adam' optimizer is \Box
      →used for gradient
         # descent optimization.
         model.compile(loss='mean_squared_error', optimizer='adam')
         return model
```

Step 5: Compute and Print the Root Mean Square Error

The function print_error() computes the mean square error between the actual and predicted values.

```
[6]: def print_error(trainY, testY, train_predict, test_predict):
    # Error of predictions
    train_rmse = math.sqrt(mean_squared_error(trainY, train_predict))
    test_rmse = math.sqrt(mean_squared_error(testY, test_predict))
    # Print RMSE
    print('Train RMSE: %.3f RMSE' % (train_rmse))
    print('Test RMSE: %.3f RMSE' % (test_rmse))
```

Step 6: View the Result

The following function plots the actual target values and the predicted values. The red line separates the training and test data points.

```
[9]: # Create model and train
model = create_LSTM(time_steps)
```

Model: "sequential"

Layer (type)	Output Shape	Param #
lstm (LSTM)	(None, 12, 50)	10400
dropout (Dropout)	(None, 12, 50)	0
lstm_1 (LSTM)	(None, 12, 50)	20200
dropout_1 (Dropout)	(None, 12, 50)	0

```
      lstm_2 (LSTM)
      (None, 50)
      20200

      dropout_2 (Dropout)
      (None, 50)
      0

      dense (Dense)
      (None, 1)
      51
```

Total params: 50851 (198.64 KB)
Trainable params: 50851 (198.64 KB)
Non-trainable params: 0 (0.00 Byte)

[10]: model.fit(trainX, trainY, epochs=20, batch_size=1, verbose=2)

```
Epoch 1/20
187/187 - 23s - loss: 0.0106 - 23s/epoch - 124ms/step
Epoch 2/20
187/187 - 2s - loss: 0.0096 - 2s/epoch - 11ms/step
Epoch 3/20
187/187 - 2s - loss: 0.0081 - 2s/epoch - 9ms/step
Epoch 4/20
187/187 - 2s - loss: 0.0078 - 2s/epoch - 11ms/step
Epoch 5/20
187/187 - 2s - loss: 0.0071 - 2s/epoch - 11ms/step
Epoch 6/20
187/187 - 2s - loss: 0.0065 - 2s/epoch - 9ms/step
Epoch 7/20
187/187 - 2s - loss: 0.0056 - 2s/epoch - 10ms/step
Epoch 8/20
187/187 - 2s - loss: 0.0061 - 2s/epoch - 9ms/step
Epoch 9/20
187/187 - 2s - loss: 0.0051 - 2s/epoch - 9ms/step
Epoch 10/20
187/187 - 2s - loss: 0.0054 - 2s/epoch - 10ms/step
Epoch 11/20
187/187 - 2s - loss: 0.0075 - 2s/epoch - 10ms/step
Epoch 12/20
187/187 - 2s - loss: 0.0049 - 2s/epoch - 9ms/step
Epoch 13/20
187/187 - 2s - loss: 0.0054 - 2s/epoch - 9ms/step
Epoch 14/20
187/187 - 2s - loss: 0.0058 - 2s/epoch - 9ms/step
Epoch 15/20
187/187 - 2s - loss: 0.0050 - 2s/epoch - 10ms/step
Epoch 16/20
187/187 - 2s - loss: 0.0052 - 2s/epoch - 10ms/step
Epoch 17/20
```

```
187/187 - 2s - loss: 0.0049 - 2s/epoch - 10ms/step

Epoch 18/20

187/187 - 2s - loss: 0.0048 - 2s/epoch - 11ms/step

Epoch 19/20

187/187 - 2s - loss: 0.0052 - 2s/epoch - 11ms/step

Epoch 20/20

187/187 - 2s - loss: 0.0056 - 2s/epoch - 12ms/step
```

[10]: <keras.src.callbacks.History at 0x12858f6f790>

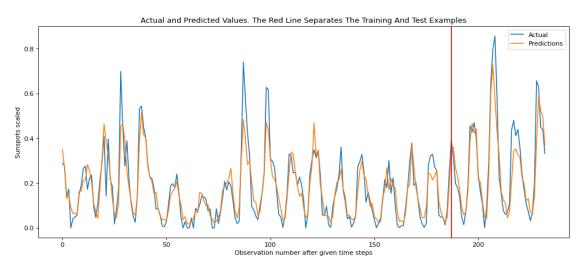
```
[11]: # make predictions
    train_predict = model.predict(trainX)
    test_predict = model.predict(testX)

# Print error
    print_error(trainY, testY, train_predict, test_predict)

#Plot result
    plot_result(trainY, testY, train_predict, test_predict)
```

```
6/6 [=======] - 2s 8ms/step 2/2 [=========] - 0s 7ms/step
```

Train RMSE: 0.061 RMSE Test RMSE: 0.087 RMSE



1.3 Reference and Credits

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- 1.4 Mehreen Saeed Understanding Simple Recurrent Neural Networks in Keras, Machine Learning Mastery
- Mehreen Saeed An Introduction to Recurrent Neural Networks and the Math That Powers Them, Machine Learning Mastery