



Chinese University of Hong Kong, Shenzhen

???

adapted from KTH ACM Contest Template Library

Contest (1)

base.hpp

<bits/stdc++.h> 25 lines

```
using std::abs, std::sin, std::cos, std::tan, std::asin,
    ↪std::acos, std::atan2;
using std::min, std::max, std::swap;
using std::pair, std::tuple;
using std::set, std::map, std::multiset;
using std::tie;
using std::vector, std::array, std::string;
```

```
template <class T> using Vec = vector<T>;
template <class T> using Opt = std::optional<T>;
```

```
using i8 = int8_t;
using u8 = uint8_t;
using i32 = int32_t;
using i64 = int64_t;
using u32 = uint32_t;
using u64 = uint64_t;
using i128 = __int128_t;
using u128 = __uint128_t;
```

```
inline std::mt19937_64 mt(
    std::chrono::steady_clock::now().time_since_epoch().count
    ↪());
```

```
template <class T> T rand_int(T l, T r) {
    return std::uniform_int_distribution<T>(l, r)(mt);
} // hash-cpp-all = ad2a9a13becc0025e4b88cd15efc960b
```

bashrc

5 lines

```
setxkbmap -option caps:escape
alias e='vim'
alias cls='clear -x'
alias mv='mv -i'
alias cp='cp -i'
```

Makefile

3 lines

```
CXXFLAGS = -O2 -std=gnu++20 -Wall -Wextra -Wno-unused-
    ↪result -pedantic -Wshadow -Wformat=2 -Wfloat-equal -
    ↪Wconversion -Wlogical-op -Wshift-overflow=2 -
    ↪Wduplicated-cond -Wcast-qual -Wcast-align
DEBUGFLAGS = -D_GLIBCXX_DEBUG -D_GLIBCXX_DEBUG_PEDANTIC -
    ↪fsanitize=address -fsanitize=undefined -fno-sanitize=
    ↪recover=all -fstack-protector -D_FORTIFY_SOURCE=2
CXXFLAGS += $(DEBUGFLAGS) # flags with speed penalty
```

vimrc

9 lines

```
set nocp ai bs=2 hls ic is lbr ls=2 mouse=a nu ru sc scs
    ↪smd so=3 sw=4 ts=4
filetype plugin indent on
syn on
map gA m'ggVG"+y''
```

```
set cindent cino=j1,(0,ws,Ws
```

```
com -range=% -nargs=1 P exe "<line1>,<line2>!"<q-args> |y|
    ↪sil u|echom @"
au FileType cpp com! -buffer -range=% Hash <line1>,<line2>P
    ↪cpp -dD -P -fpreprocessed | tr -d '[:space:]' |
    ↪md5sum
```

hash-cpp.sh

1 lines

```
cpp -dD -P -fpreprocessed | tr -d '[:space:]' | md5sum
```

fast-input.hpp

Description: Fast scanner implementation based on fread

59 lines

```
namespace fast_input {

struct Scanner {
    FILE* f;
    Scanner(FILE* f_ = stdin) : f(f_) {}

    char get() { // hash-cpp-1
        static array<char, 1 << 16> buf;
        static size_t s = 0, e = 0;
        if (s >= e) {
            buf[0] = 0;
            s = 0;
            e = fread(data(buf), 1, sizeof(buf), f);
        }
        return buf[s++];
    } // hash-cpp-1 = dbac8c21422ef521045397b89e192021
};

using Self = Scanner;
```

```
char skip_whitespaces() {
    char c;
    while ((c = get()) <= ' ') {
    }
    return c;
}
```

```
template <class T> Self& operator>>(T& x) {
    char c = skip_whitespaces();
    bool neg = false;
    if (c == '-') {
        neg = true;
        c = get();
    }
    x = 0;
    do {
        x = 10 * x + (c & 15);
    } while ((c = get()) >= '0');
    if (neg) x = -x;
    return *this;
}
```

```
Self& operator>>(string& x) {
    char c = skip_whitespaces();
    x = {};
    do {
        x += c;
    } while ((c = get()) > ' ');
    return *this;
}
```

```
Self& operator>>(double& x) {
    string z;
    *this >> z;
    x = stod(z);
    return *this;
};

} // namespace fast_input
```

Data Structure (2)

hash-map.hpp

Description: Faster and safer hash map.

<ext/pb_ds/assoc.container.hpp> 13 lines

```
struct CustomHash { // hash-cpp-1
    size_t operator()(uint64_t x) const {
        static const uint64_t z = std::chrono::steady_clock::
            ↪now().time_since_epoch().count(),
            c = uint64_t(4e18*acos(0))+71;
        return __builtin_bswap64((x^z)*c);
    }
}; // hash-cpp-1 = 3757d267e7e0ab0ba63368f565e830cd
```

```
template <class K, class V, class Hash = CustomHash> //
    ↪hash-cpp-2
using HashMap = __gnu_pbds::gp_hash_table<K, V, Hash>; //
    ↪hash-cpp-2 = 4fe2baba5ae354ac6dd53d37ad221011
```

```
template <class K, class Hash = CustomHash> // hash-cpp-3
using HashSet = HashMap<K, __gnu_pbds::null_type, Hash>; //
    ↪hash-cpp-3 = 1d899df3bf29329f777189feb8d1944c
```

binary-indexed-tree.hpp

Description: Supports computing partial sum $a_0 + \dots + a_{i-1}$ and incrementing some a_i by v

Time: Both operations are $\mathcal{O}(\log N)$

45 lines

```
template <class T> struct BIT {
    Vec<T> x;
    int s, w;
    BIT(int n) { build(n); }
    BIT(const Vec<T>& a) { build(a); }
```

```
void build(int n) { // hash-cpp-1
    x.clear();
    x.resize(s = n);
    w = std::bit_width<u32>(s)-1;
} // hash-cpp-1 = d609ae73bb14759f097e750981a47c31
```

```
void build(const Vec<T>& a) { // hash-cpp-2
    build(int(a.size()));
    copy(a.begin(), a.end(), x.begin());
    for (int i = 0; i < s; i++) {
        int j = i | (i+1);
        if (j < s) x[j] += x[i];
    }
} // hash-cpp-2 = 40280f94a7097b2d70d078828d1ba56d
```

```
void add(int i, T v) { // hash-cpp-3
    for (; i < s; i |= i+1) x[i] += v;
}

T sum(int i) {
    T res = 0;
    for (; i &= i-1) res += x[i-1];
    return res;
} // hash-cpp-3 = e7fbe70df2a7ecfa13485bb1c017438a
```

```
// Slightly tested; requires s >= 1
int kth(T k) { // hash-cpp-4
    int cur = 0;
    for (int i = w; i >= 0; i--) {
        int nxt = cur + (1 << i);
        if (nxt <= s && x[nxt-1] <= k) {
            k -= x[nxt-1];
            cur = nxt;
        }
    }
}
```

```

    }
    }
    return cur;
} // hash-cpp-4 = 788c41fbea7c5755e3df0caae1249411

int kth_helper(T k, int i = 0) { return kth(k + sum(i));
    ⇨ }
};

```

lazy-segtree.hpp

Description: Lazy segtree abstraction

167 lines

```

template <class M> struct LazySegtree {
    using S = M::S;
    using F = M::F;
    M m;
    Vec<S> d;
    Vec<F> lz;
    int n, h, sz;
    LazySegtree(M m_) : m(m_), n(0), h(0), sz(0) {}
    template <class A> LazySegtree(int n_, A a, M m_) : m(m_)
        ⇨ { build(n_, a); }
    template <class A> void build(int n_, A a) { // hash-cpp
        ⇨ -1
        n = n_;
        sz = std::bit_ceil<uint32_t>(n);
        h = std::countr_zero<uint32_t>(sz);
        d.resize(2 * sz);
        lz.assign(sz, m.id());
        for (int i = 0; i < n; i++) d[sz + i] = a(i);
        for (int i = n; i < sz; i++) d[sz + i] = m.e();
        for (int i = sz - 1; i >= 1; i--) update(i);
    } // hash-cpp-1 = 3daff936b4ff25e69bacb710b05a4914

    void update(int i) { // hash-cpp-2
        d[i] = m.op(d[2 * i], d[2 * i + 1]);
    } // hash-cpp-2 = 353f7580bfd321bdccddd446692b7f8b

    void apply(int i, F f) { // hash-cpp-3
        d[i] = m.mapping(f, d[i]);
        if (i < sz) lz[i] = m.composition(lz[i], f);
    } // hash-cpp-3 = 066198e6507bd0fbd8f62457b912fee

    void downdate(int i) { // hash-cpp-4
        apply(2 * i, lz[i]);
        apply(2 * i + 1, lz[i]);
        lz[i] = m.id();
    } // hash-cpp-4 = 46a017e02b26c704289940242c450305

    void downdate_range(int l, int r) { // hash-cpp-5
        l += sz, r += sz;
        for (int i = h; i >= 1; i--) {
            if (((l >> i) << i) != 1) downdate(l >> i);
            if (((r >> i) << i) != r) downdate((r - 1) >> i);
        }
    } // hash-cpp-5 = 740eb7bc3b5128e2958ac01b4a1b1814

    S prod(int l, int r) { // hash-cpp-6
        assert(0 <= l && l <= r && r <= n);
        if (l == r) return m.e();
        downdate_range(l, r);
        S sl = m.e(), sr = m.e();
        for (int a = l + sz, b = r + sz; a < b; a /= 2, b /= 2)
            ⇨ {
                if (a & 1) sl = m.op(sl, d[a++]);
                if (b & 1) sr = m.op(d[--b], sr);
            }
    }
}

```

```

    return m.op(sl, sr);
} // hash-cpp-6 = a59327a4ea4e2789d70fbf683619e523

void apply(int l, int r, F f) { // hash-cpp-7
    assert(0 <= l && l <= r && r <= n);
    if (l == r) return;
    downdate_range(l, r);
    l += sz, r += sz;
    for (int a = l, b = r; a < b; a /= 2, b /= 2) {
        if (a & 1) apply(a++, f);
        if (b & 1) apply(--b, f);
    }
    for (int i = l; i <= h; i++) {
        if (((l >> i) << i) != 1) update(l >> i);
        if (((r >> i) << i) != r) update((r - 1) >> i);
    }
} // hash-cpp-7 = 655465247dd934e37768c858108371fc

// You can use this to query stuff,
// which is sometimes more efficient than using prod
template <class G> void enumerate(int l, int r, G g) { //
    ⇨ hash-cpp-8
    assert(0 <= l && l <= r && r <= n);
    if (l == r) return;
    downdate_range(l, r);
    for (int a = l + sz, b = r + sz; a < b; a /= 2, b /= 2)
        ⇨ {
            if (a & 1) g(d[a++]);
            if (b & 1) g(d[--b]);
        }
} // hash-cpp-8 = 516415088e3e5ad3a49dbc0c0935faab

// Enumerating in some sequential order
template <bool l_to_r = true, class G>
void enumerate_in_order(int l, int r, G g) {
    assert(0 <= l && l <= r && r <= n);
    if (l == r) return; // hash-cpp-9
    downdate_range(l, r);
    static Vec<int> ls, rs;
    ls.clear(), rs.clear();
    for (int a = l + sz, b = r + sz; a < b; a /= 2, b /= 2)
        ⇨ {
            if (a & 1) ls.push_back(a++);
            if (b & 1) rs.push_back(--b);
        } // hash-cpp-9 = 2481fb42166bf39d0da2499c3e727a6d
    if constexpr (l_to_r) {
        for (int i : ls) g(d[i]);
        for (int z = int(rs.size()) - 1; z >= 0; z--) g(d[rs[
            ⇨ z]]);
    } else {
        for (int i : rs) g(d[i]);
        for (int z = int(ls.size()) - 1; z >= 0; z--) g(d[ls[
            ⇨ z]]);
    }
}

```

const S& all_prod() const { return d[1]; }

```

template <class P> pair<int, S> max_right(int l, P p) {
    ⇨ // hash-cpp-10
    assert(0 <= l && l <= n);
    if (l == n) return {n, m.e()};
    l += sz;
    for (int i = h; i >= 1; i--) downdate(l >> i);
    S s = m.e();
    assert(p(s));
    do {
        while (l % 2 == 0) l /= 2;
    }
}

```

```

    if (!p(m.op(s, d[l]))) {
        while (l < sz) {
            downdate(l);
            l = 2 * l;
            S t = m.op(s, d[l]);
            if (p(t)) {
                s = t;
                l++;
            }
        }
        return {l - sz, s};
    }
    s = m.op(s, d[l]);
    l++;
} while ((l & -l) != 1);
return {n, s};
} // hash-cpp-10 = 659b16e053dcfd226edd2f7354d3c75c

template <class P> pair<int, S> min_left(int r, P p) { //
    ⇨ hash-cpp-11
    assert(0 <= r && r <= n);
    if (r == 0) return {0, m.e()};
    r += sz;
    for (int i = h; i >= 1; i--) downdate((r - 1) >> i);
    S s = m.e();
    assert(p(s));
    do {
        r--;
        while (r > 1 && r % 2) r /= 2;
        if (!p(m.op(d[r], s))) {
            while (r < sz) {
                downdate(r);
                r = 2 * r + 1;
                S t = m.op(d[r], s);
                if (p(t)) {
                    s = t;
                    r--;
                }
            }
            return {r + 1 - sz, s};
        }
        s = m.op(d[r], s);
    } while ((r & -r) != r);
    return {0, s};
} // hash-cpp-11 = 679cc146eea81abf054b473f1e991349

void set(int p, S s) { // hash-cpp-12
    assert(0 <= p && p < n);
    p += sz;
    for (int i = h; i >= 1; i--) downdate(p >> i);
    d[p] = s;
    for (int i = l; i <= h; i++) update(p >> i);
} // hash-cpp-12 = eee80c946397620fdc779230722e1655
};

```

static-range.hpp

Description: Static range composition. You need to specify a composition function f and an identity element e
Time: $\mathcal{O}(N \log N)$ building and $\mathcal{O}(1)$ querying

34 lines

```

template <class T, class F> struct StaticRange {
    Vec<Vec<T>> d; // hash-cpp-1
    const F f;
    const T e;
    StaticRange(const Vec<T>& a, F f_, T e_) : f(f_), e(e_) {
        int n = int(size(a));
        int h = 0;
    }
}

```

```

while ((2 << h) < n) h++;
d.resize(h+1);
d[0] = a;
for (int k = 0; k < h; k++) {
    d[k+1].resize(n, e);
    int s = 1 << (k+1);
    for (int i = s; i < n; i += 2*s) {
        T x = e;
        for (int j = i-1; j >= i-s; j--) {
            d[k+1][j] = x = f(a[j], x);
        }
        x = e;
        for (int j = i; j < i+s && j < n; j++) {
            d[k+1][j] = x = f(x, a[j]);
        }
    }
}
} // hash-cpp-1 = 6a493be3848c7679ff694dbec308c49d

T operator()(int l, int r) const { // hash-cpp-2
    if (l >= r) return e;
    r--;
    if (l == r) return d[0][l];
    int k = std::bit_width<u32>(l ^ r) - 1;
    return f(d[k][l], d[k][r]);
} // hash-cpp-2 = 53644a8954cd96497e83e9d294062852
};

```

treap.hpp

Description: Randomized Treap with split/merge support. `nodes.size() < nodes.capacity()` must be maintained. One strategy to save space is to refactor everything when the size of nodes is approximating its capacity
Time: $\mathcal{O}(\log N)$ per operation

202 lines

```

template <class M, bool persistent = false> struct
    ↪TreapManager {
    using S = M::S;
    using F = M::F;

    TreapManager(M m_, int alloc = 0) : m(m_) {
        if (alloc > 0) {
            nodes.reserve(alloc);
        } else {
            // make sure to understand what you're doing
            assert(!persistent);
        }

        for (int z = 0; z < 2; z++) {
            states[z] = u32(mt());
        }
    }

    using Tree = int;

    Tree make_empty() { return Tree(null); }

    Tree make_single(S s) { // hash-cpp-1
        int i = int(nodes.size());
        nodes.push_back(Node{null, null, 1, false, false, s, s,
            ↪ m.id()});
        return i;
    } // hash-cpp-1 = 6c4d20b86ebfc6f60d88165b76573a67

    Tree make_copy(Tree o) { return _make_copy(o); }

    int size(const Tree t) { return _size(t); }

```

```

int reverse(Tree t) { return _reverse(t); }
int apply(Tree t, F f) { return _apply(t, f); }
S prod(const Tree& t) { return _prod(t); }

Tree split_k(Tree& t, int k) { // hash-cpp-2
    Tree o;
    tie(t, o) = _split_k(t, k);
    return o;
} // hash-cpp-2 = c70f87700806d15a4c4ec662572f17ff

Tree merge(Tree a, Tree b) { return _merge(a, b); }

Tree build(const Vec<S>& a) { // hash-cpp-3
    if (a.empty()) return make_empty();
    return _build(a, 0, int(a.size()));
} // hash-cpp-3 = d5774c15e3b5b571de7d737f390da619

Vec<S> to_array(const Tree& t) { // hash-cpp-4
    Vec<S> buf;
    buf.reserve(size(t));
    _to_array(t, buf);
    return buf;
} // hash-cpp-4 = 7367030dad11dcd4f5db83533a4b3d26

private:
    static constexpr int null = -42;
    M m;

    struct Node { // hash-cpp-5
        int li, ri, sz;
        bool rev, app;
        S a, s;
        F f;
    };
    Vec<Node> nodes;
    Node& node(int i) { return nodes[i]; }
    int _size(int i) { return i == null ? 0 : node(i).sz; }
    ↪// hash-cpp-5 = 7ff1fec7f9265acee7e49866a73a5d75

    int _make_copy(int o) { // hash-cpp-6
        if constexpr (!persistent) return o;

        if (o == null) return null;
        assert(nodes.size() < nodes.capacity());
        int i = int(nodes.size());
        nodes.push_back(node(o));
        return i;
    } // hash-cpp-6 = 26a70edec35d6f656b6f85d49ceb2fc6

    int _build(const Vec<S>& a, int l, int r) { // hash-cpp-7
        if (r - l == 1) {
            return make_single(a[l]);
        }
        int md = (l + r) / 2;
        return _merge(_build(a, l, md), _build(a, md, r));
    } // hash-cpp-7 = 5b1df26f9cad8f5588e7f963e3252ea4

    void _update(int i) { // hash-cpp-8
        auto& n = node(i);
        n.s = m.op(_prod(n.li), m.op(n.a, _prod(n.ri)));
        n.sz = size(n.li) + size(n.ri) + 1;
    } // hash-cpp-8 = c5fb7048740c35c2a720845684e4ff19

    int _reverse(int i) { // hash-cpp-9
        if (i == null) return i;
        i = _make_copy(i);
        auto& n = node(i);
        n.rev = !n.rev;

```

```

        swap(n.li, n.ri);
        return i;
    } // hash-cpp-9 = 266d7203b1c04371492ea0bd85cb281d

    S _prod(int i) { return i == null ? m.e() : node(i).s; }

    int _apply(int i, F f) { // hash-cpp-10
        if (i == null) return i;
        i = _make_copy(i);
        auto& n = node(i);
        n.s = m.mapping_sz(f, n.s, n.sz);
        n.a = m.mapping_sz(f, n.a, 1);
        n.f = m.composition(f, n.f);
        n.app = true;
        return i;
    } // hash-cpp-10 = c1044aa4c9dbe3605f7e255c9ef1131b

    int downdate(int i) { // hash-cpp-11
        assert(i != null);
        i = _make_copy(i);
        auto& n = node(i);
        if (n.rev) {
            n.li = _reverse(n.li);
            n.ri = _reverse(n.ri);
            n.rev = false;
        }
        if (n.app) {
            n.li = _apply(n.li, n.f);
            n.ri = _apply(n.ri, n.f);
            n.f = m.id();
            n.app = false;
        }
        return i;
    } // hash-cpp-11 = de62225a6441397fe26f3bdae0f19423

    template <class F> pair<int, int> _split(int i, F go_left
        ↪) { // hash-cpp-12
        if (i == null) return {null, null};
        i = downdate(i);
        auto& n = node(i);
        int li = n.li, ri = n.ri;
        int x, y;
        if (go_left(li, ri)) {
            y = i;
            tie(x, n.li) = _split(n.li, go_left);
        } else {
            x = i;
            tie(n.ri, y) = _split(n.ri, go_left);
        }
        _update(i);
        return {x, y};
    } // hash-cpp-12 = 3162351f3f2db4155104ab28b68b8e49

    pair<int, int> _split_k(int i, int k) { // hash-cpp-13
        return _split(i, [&](int li, int) -> bool {
            int lsz = size(li);
            if (k <= lsz) {
                return true;
            } else {
                k -= lsz + 1;
                return false;
            }
        });
    } // hash-cpp-13 = 21661461b27eeb90e1e770dacc49c006

    // Use std::mt19937_64 if performance is not an issue
    // https://prng.di.unimi.it/xoroshiro64star.c
    inline u32 rotl(const u32 x, int k) { // hash-cpp-14

```

```

    return (x << k) | (x >> (32 - k));
}
u32 states[2];
u32 rng() {
    const u32 s0 = states[0];
    u32 s1 = states[1];
    const u32 res = s0 * 0x9E3779BB;
    s1 ^= s0;
    states[0] = rotl(s0, 26) ^ s1 ^ (s1 << 9);
    states[1] = rotl(s1, 13);
    return res;
} // hash-cpp-14 = e7808fealf575341ec66945f5eb60d5a

int _merge(int a, int b) { // hash-cpp-15
    if (a == null) return b;
    if (b == null) return a;
    int r;
    u32 sa = size(a), sb = size(b);
    if (rng() % (sa + sb) < sa) {
        r = downdate(a);
        node(r).ri = _merge(node(r).ri, b);
    } else {
        r = downdate(b);
        node(r).li = _merge(a, node(r).li);
    }
    _update(r);
    return r;
} // hash-cpp-15 = 5e3944c92c44935fc0a83a6a0cdeb76f

void _to_array(int i, Vec<S>& buf) { // hash-cpp-16
    if (i == null) return;
    downdate(i);
    auto& n = node(i);
    _to_array(n.li, buf);
    buf.push_back(n.a);
    _to_array(n.ri, buf);
} // hash-cpp-16 = f2ee73067be10b96ad2b205b24626251
};

```

queue-aggregation.hpp

Description: A queue that supports querying the composition of all elements

39 lines

```

template <class T, class F> struct QueueAggregation {
    const F f; // hash-cpp-1
    const T e;
    Vec<T> as, bs, ae, be;
    T vs, ve;
    QueueAggregation(F f_, T e_) : f(f_), e(e_), vs(e), ve(e)
        ↪ {} // hash-cpp-1 = aal2ea64acbd5f59b8b481d300dcebc03

    void push_s(const T& x) { // hash-cpp-2
        as.push_back(x), bs.push_back(vs = f(x, vs));
    }
    void push_e(const T& x) { ae.push_back(x), be.push_back(
        ↪ ve = f(ve, x)); }
    void reduce() {
        while (!ae.empty()) {
            push_s(ae.back()), ae.pop_back();
        }
        be.clear();
        ve = e;
    } // hash-cpp-2 = 8fa4388f714c1fcf480662f94acb94d7

    bool empty() const { // hash-cpp-3
        return as.empty() && ae.empty();
    }
}

```

```

int size() const { return int(as.size() + ae.size()); }
    ↪ // hash-cpp-3 = b5166973f8a1e060551da48002d67335

void push(const T& x) { // hash-cpp-4
    if (as.empty()) {
        push_s(x), reduce();
    } else {
        push_e(x);
    }
}
void pop() {
    assert(!empty());
    if (as.empty()) reduce();
    as.pop_back(), bs.pop_back();
    vs = (bs.empty() ? e : bs.back());
}
T prod() const { return f(vs, ve); } // hash-cpp-4 = 0
    ↪ b46cd5fba53f4c166094224da58ee1c
};

```

line-container.hpp

Description: Container where you can add lines of the form $y = kx + m$, and query maximum values at given points. Useful for dynamic programming (“convex hull trick”)

Time: $O(\log N)$ with a large constant factor

42 lines

```

namespace line_container {

struct Line { // hash-cpp-1
    mutable i64 k, m, p;
    bool operator<(const Line& o) const { return k < o.k; }
    bool operator<(i64 x) const { return p < x; }
}; // hash-cpp-1 = fe34d12ba12e83886abda0a6086b3ea0

struct LineContainer : multiset<Line, std::less<>> {
    using I = iterator; // hash-cpp-2
    // (for doubles, use inf = 1/.0, div(a,b) = a/b)
    static const i64 inf = std::numeric_limits<i64>::max();
    static i64 div(i64 a, i64 b) {
        return a / b - ((a ^ b) < 0 && a % b);
    } // hash-cpp-2 = 916c6b8fae9c3a6ff292036f8a529685
    bool isect(I x, I y) { // hash-cpp-3
        if (y == end()) return x->p = inf, 0;
        if (x->k == y->k) {
            x->p = x->m > y->m ? inf : -inf;
        } else {
            x->p = div(y->m - x->m, x->k - y->k);
        }
        return x->p >= y->p;
    } // hash-cpp-3 = dec9ff4585adbee96b3f9592b3614988
    void add(i64 k, i64 m) { // hash-cpp-4
        auto z = insert({k, m, 0}), y = z++, x = y;
        while (isect(y, z)) z = erase(z);
        if (x != begin() && isect(--x, y)) {
            isect(x, y = erase(y));
        }
        while ((y = x) != begin() && (--x)->p >= y->p) {
            isect(x, erase(y));
        }
    } // hash-cpp-4 = 78c5a4da92215ce013230b8b18572988
    i64 query(i64 x) { // hash-cpp-5
        assert(!empty());
        auto l = *lower_bound(x);
        return l.k * x + l.m;
    } // hash-cpp-5 = 368705d894929cc338d6d2732483f777
};

```

} // namespace line_container

persistent-array.hpp

Description: Persistent array based on persistent segtrees

69 lines

```

template <class D> struct PersistentArray {
    union N { // hash-cpp-1
        D v;
        array<int, 2> c;
        N(const D& a) : v(a) {}
        N(int a, int b) : c{a, b} {}
    };
    Vec<N> x;
    int s, h;
    // Modify this so that it can reserve memory for x
    PersistentArray() {} // hash-cpp-1 = 1
        ↪ ff3a53ab6ec6894dd8830d2abad7b10

    // All arrays share the same layout (length)
    int build(int n) { // hash-cpp-2
        x.clear();
        s = 1, h = 0;
        while (s < n) {
            s *= 2;
            h++;
        }
        int rt = make_leaf(D());
        for (int l = 0; l < h; l++) {
            rt = make_node(rt, rt);
        }
        return rt;
    } // hash-cpp-2 = 07caee6062571a915772221c203141f3

    int make_leaf(const D& a) { // hash-cpp-3
        x.emplace_back(a);
        return int(x.size())-1;
    }
    int make_node(int a, int b) {
        x.emplace_back(a, b);
        return int(x.size())-1;
    } // hash-cpp-3 = 1fee63ccaf8114c5295fe73f218cc786

    int set(int rt, int i, const D& a) { // hash-cpp-4
        static int buf[40];
        for (int l = 0; l < h; l++) {
            buf[l] = rt;
            if ((i >> (h-1-l)) & 1) {
                rt = x[rt].c[l];
            } else {
                rt = x[rt].c[0];
            }
        }
        int res = make_leaf(a);
        for (int l = h-1; l >= 0; l--) {
            int j = buf[l];
            if ((i >> (h-1-l)) & 1) {
                res = make_node(x[j].c[0], res);
            } else {
                res = make_node(res, x[j].c[l]);
            }
        }
        return res;
    } // hash-cpp-4 = ce571ab8758dbbaf6d393f0545a71302

    D get(int rt, int i) { // hash-cpp-5
        for (int l = h-1; l >= 0; l--) {
            if (i & (1 << l)) {

```

CUHK-SZ

```

    rt = x[rt].c[1];
} else {
    rt = x[rt].c[0];
}
}
return x[rt].v;
} // hash-cpp-5 = 3a880dd33ae85a7becf12470a5ee22d6
};

```

fast-set.hpp

Description: A set for insertion, removal and querying the predecessor/successor of some element

85 lines

```

struct FastSet {
    static constexpr int B = 64;

    int n, h;
    Vec<Vec<u64>> x;
    FastSet(int n_ = 0) : n(n_) {
        int m = (n ? n : 1);
        do {
            x.push_back(Vec<u64>((m + B - 1) / B));
            m = (m + B - 1) / B;
        } while (m > 1);
        h = int(size(x));
    } // hash-cpp-0 = d41d8cd98f00b204e9800998ecf8427e

    bool empty() const { // hash-cpp-1
        return !x[h - 1][0];
    }

    bool operator[](int i) const {
        return (x[0][i / B] >> (i % B) & 1) != 0;
    } // hash-cpp-1 = 757daa5e083e34270c6abb210a3bcdae

    void set(int i) { // hash-cpp-2
        for (int d = 0; d < h; d++) {
            int q = i / B, r = i % B;
            x[d][q] |= u64(1) << r;
            i = q;
        }
    } // hash-cpp-2 = f800fd0cfa9df69d8679dc495e0432fd

    void reset(int i) { // hash-cpp-3
        for (int d = 0; d < h; d++) {
            int q = i / B, r = i % B;
            x[d][q] &= ~(u64(1) << r);
            if (x[d][q]) break;
            i = q;
        }
    } // hash-cpp-3 = 964743f280b87681157a390bd7fd5449

    // min active j s.t. j >= i
    int next(int i) const { // hash-cpp-4
        if (i >= n) return n;
        i = max(i, 0);
        for (int d = 0; d < h; d++) {
            int q = i / B, r = i % B;
            if (q >= int(size(x[d]))) break;
            u64 up = x[d][q] >> r;
            if (up) {
                i += std::countl_zero(up);
                for (int e = d - 1; e >= 0; e--) {
                    i = i * B + std::countl_zero(x[e][i]);
                }
                return i;
            }
            i = q + 1;
        }
    }
}

```

```

    }
    return n;
} // hash-cpp-4 = 744dbbecee0c3e9dd0bac58360a1875c

// max active j s.t. j <= i
int prev(int i) const { // hash-cpp-5
    if (i < 0) return -1;
    i = min(i, n - 1);
    for (int d = 0; d < h; d++) {
        if (i < 0) break;
        int q = i / B, r = i % B;
        u64 lo = x[d][q] << (B - 1 - r);
        if (lo) {
            i -= std::countl_zero(lo);
            for (int e = d - 1; e >= 0; e--) {
                i = i * B + B - 1 - std::countl_zero(x[e][i]);
            }
            return i;
        }
        i = q - 1;
    }
    return -1;
} // hash-cpp-5 = 37e66d1d428168f7250d08686528b97b

// not tested
template <class F> void enumerate(int l, int r, F f) {
    for (int p = next(l); p < r; p = next(p + 1)) {
        f(p);
    }
}
};

```

Ad Hoc (3)

tree-dp.hpp

Description: All-direction tree DP blackbox

75 lines

```

using std::views::reverse;

template <class S> struct TreeDP {
    template <class RF, class CF> struct Inner {
        Vec<S> low, high;
        Vec<int> edges, par;
        const RF rake;
        const CF compress;
        Inner(const Vec<Vec<int>>& g, auto make, RF rake_, CF
            ↪ compress_)
            : rake(rake_), compress(compress_) {
            int n = int(size(g));
            auto single = Vec<S>(n);
            edges.resize(n - 1);
            for (int v = 0; v < n; v++) {
                single[v] = make(v);
                for (int e : g[v]) edges[e] ^= v;
            }

            auto bfs = Vec<int>{0};
            bfs.reserve(n);
            par.assign(n, -1);
            for (size_t z = 0; z < size(bfs); z++) {
                int v = bfs[z];
                for (int e : g[v]) {
                    if (par[v] == e) continue;
                    int w = v ^ edges[e];
                    par[w] = e;
                    bfs.push_back(w);
                }
            }
        }
    };
}

```

```

    }
}

low = single;
auto up = Vec<S>(n);
auto pref = Vec<S>(n);
for (int v : bfs | reverse) {
    for (int e : g[v]) {
        if (par[v] == e) continue;
        int w = v ^ edges[e];
        pref[w] = low[v];
        up[w] = compress(low[w], e, v);
        low[v] = rake(low[v], up[w], v);
    }
}

high.resize(n);
auto f = Opt<S>();
for (int v : bfs) {
    if (v != 0) [[likely]] {
        f = compress(high[v], par[v], v);
    }
    for (int e : g[v] | reverse) {
        if (par[v] == e) continue;
        int w = v ^ edges[e];
        if (f.has_value()) [[likely]] {
            high[w] = rake(pref[w], *f, v);
            f = rake(up[w], *f, v);
        } else {
            high[w] = pref[w];
            f = up[w];
        }
    }
}

S get_vertex(int v) const {
    if (v == 0) return low[v];
    return rake(low[v], compress(high[v], par[v], v), v);
}
};

template <class RF, class CF>
static auto solve(const Vec<Vec<int>>& g, auto make, RF
    ↪ rake, CF compress) {
    return Inner(g, make, rake, compress);
}
}; // hash-cpp-all = e6eb5c7b0a756da0ff868f7529ab74f2

```

monotone-minima.hpp

Description: Given an $N \times M$ matrix A , returns $m_i = \operatorname{argmin}_j A_{i,j}$ given that m_0, \dots, m_{N-1} is non-decreasing

17 lines

```

// f(i, j, k) := [A_{i,j} <= A_{i,k}], given j < k
template <class F> Vec<int> monotone_minima(int n, int m, F
    ↪ f) {
    auto res = Vec<int>(n);
    auto inner = [&](auto self, int s, int e, int l, int r) {
        if (s == e) return;
        int i = (s + e) / 2;
        int b = l;
        for (int k = l + 1; k < r; k++) {
            if (!f(i, b, k)) b = k;
        }
        res[i] = b;
        self(self, s, i, l, b + 1);
        self(self, i + 1, e, b, r);
    };
}

```

CUHK-SZ

```
};
inner(inner, 0, n, 0, m);
return res;
} // hash-cpp-all = 74852d91f028814bde26cc235dcac6bb
```

min-plus-convex.hpp

Description: Given a_0, \dots, a_{N-1} and b_0, \dots, b_{M-1} such that $a_{i+1} - a_i \leq a_{i+2} - a_{i+1}$, returns $c_0, \dots, c_{(N-1)+(M-1)}$ such that $c_k = \min_{i+j=k} a_i + b_j$

```
"ad-hoc/monotone-minima.hpp" 15 lines
// a convex and b arbitrary
template <class T> Vec<T> min_plus_convex(const Vec<T>& a,
    ↪const Vec<T>& b) {
    int n = int(size(a)), m = int(size(b));
    if (!n || !m) return {};
    auto x = monotone_minima(n + m - 1, m, [&](int i, int j,
        ↪int k) -> bool {
        if (i < k) return true;
        if (i - j >= n) return false;
        return a[i - j] + b[j] <= a[i - k] + b[k];
    });
    auto res = Vec<T>(n + m - 1);
    for (int i = 0; i < n + m - 1; i++) {
        res[i] = a[i - x[i]] + b[x[i]];
    }
    return res;
} // hash-cpp-all = 61c18c03ecb8ff250898af56d7c09e07
```

floor-ceil-range.hpp

```
28 lines
inline void floor_range(i64 n, auto f) {
    int rt = int(sqrt(double(n))); // hash-cpp-1
    int num = (i64(rt) * rt + rt <= n ? rt : rt - 1);
    i64 prv = n + 1;
    for (int q = 1; q <= num; q++) {
        i64 x = i64(double(n) / (q + 1)) + 1;
        f(q, x, prv);
        prv = x;
    }
    for (int l = rt; l >= 1; l--) {
        f(i64(double(n) / l), l, l + 1);
    } // hash-cpp-1 = 93b579b8e33ad19ecbdae71c9d87828d
}

inline void ceil_range(i64 n, auto f) {
    int rt = int(sqrt(double(n))); // hash-cpp-2
    i64 prv = std::numeric_limits<i64>::max();
    for (int q = 1; q <= rt; ++q) {
        i64 x = i64(double(n + q - 1) / q);
        f(q, x, prv);
        prv = x;
    }
    int num = (n <= i64(rt) * rt + rt ? rt : rt + 1);
    if (n == rt * rt) --num;
    for (int l = num; l >= 1; --l) {
        f(i64(double(n + l - 1) / l), l, l + 1);
    } // hash-cpp-2 = fclcdafel7e28a72208134fdc874de4c
}
```

palindromic-decomp-dp.hpp

Description: CF932G DP

```
"string/eertree.hpp" 56 lines
// dp[j] := sum_{i s.t. [i, j] is palindromic} {dp[i] * x}
template <class S, int sigma, bool even = false>
Vec<S> palindromic_decomp_dp(const Vec<int>& a,
```

```
auto add, S add_e,
auto mul_x, S mul_e) {
    int n = int(a.size()); // hash-cpp-1
    Vec<int> locs(n);
    Eertree<sigma> et(n);
    for (int i = 0; i < n; i++) {
        assert(0 <= a[i] && a[i] < sigma);
        locs[i] = et.append(a[i]);
    } // hash-cpp-1 = a13e04432b9972a781423e207b1ae08d

    int nnodes = et.size();
    Vec<int> nxt(nnodes);
    nxt[0] = -1;
    if constexpr (even) {
        assert(n % 2 == 0);
        for (int v = 1; v < nnodes; v++) {
            nxt[v] = (et[v].len() % 2 == 0 ? v : nxt[et[v].fail])
                ↪;
        }
    } else {
        iota(nxt.begin() + 1, nxt.end(), 1);
    }

    Vec<int> diff(nnodes, 1e9); // hash-cpp-2
    Vec<pair<int, int>> top(nnodes);
    for (int v = 2; v < nnodes; v++) {
        int w = nxt[et[v].fail];
        int d = et[v].len() - et[w].len();
        diff[v] = d;
        top[v] = (diff[v] == diff[w] ? top[w] : pair<int, int>(<
            ↪w, 0));
        top[v].second++;
    } // hash-cpp-2 = 904fb97daaf4a91bd6da446a3dcee9c

    Vec<S> dp(n+1, add_e), gdp = dp; // hash-cpp-3
    dp[0] = mul_e;
    for (int j = 0; j < n; j++) {
        int v = nxt[locs[j]];
        int i = (j+1) - et[v].len();
        while (v >= 2) {
            int d = diff[v];
            auto [p, s] = top[v];
            if (s == 1) {
                gdp[i] = dp[i];
            } else {
                gdp[i] = add(gdp[i], dp[i + d * (s-1)]);
            }
            dp[j+1] = add(dp[j+1], mul_x(gdp[i]));
            i += d * s;
            v = p;
        }
    } // hash-cpp-3 = 770718f9348189ea652a30650d5b66bf

    return dp;
}
```

Algebra (4)

modint.hpp

Description: Frees you from writing %mod stuff. This only works with prime modulo numbers that are determined during compile-time

```
47 lines
template <class T> T pow(T a, i64 b) {
    assert(b >= 0);
    T r = 1;
    while (b) {
```

```
    if (b & 1) r *= a;
    a *= a;
    b >>= 1;
}
return r;
}

template <u32 mod> struct ModInt {
    using mint = ModInt;

    static constexpr u32 m = mod; // hash-cpp-1
    u32 v;
    constexpr ModInt() : v(0) {}
    template <class T> constexpr ModInt(T a) { s(u32(a % m +
        ↪m)); }
    constexpr mint& s(u32 a) { v = a < m ? a : a-m; return *
        ↪this; }
    friend mint inv(const mint& n) { return pow(n, m-2); } //
        ↪hash-cpp-1 = 4dece1675e6b05bf2630f4e3f6e64fb3

    mint operator- () const { // hash-cpp-2
        mint res;
        res.v = v ? m-v : 0;
        return res;
    } // hash-cpp-2 = 682e0bd616a7a1b4efedf0025fd9946a

    friend bool operator == (const mint& a, const mint& b) {
        ↪return a.v == b.v; } // hash-cpp-3
    friend bool operator != (const mint& a, const mint& b) {
        ↪return !(a == b); } // hash-cpp-3 = 747
        ↪b64cd3779b0e594a5a9027b3c39d1

    mint& operator += (const mint& o) { return s(v + o.v); }
        ↪// hash-cpp-4
    mint& operator -= (const mint& o) { return s(v + m - o.v)
        ↪; }
    mint& operator *= (const mint& o) { v = u32(u64(v) * o.v
        ↪% m); return *this; }
    mint& operator /= (const mint& o) { return *this *= inv(o
        ↪); } // hash-cpp-4 = 5
        ↪f038b9c2be1f65c54a372c65ee72c5b

    friend mint operator + (const mint& a, const mint& b) {
        ↪return mint(a) + b; } // hash-cpp-5
    friend mint operator - (const mint& a, const mint& b) {
        ↪return mint(a) - b; }
    friend mint operator * (const mint& a, const mint& b) {
        ↪return mint(a) * b; }
    friend mint operator / (const mint& a, const mint& b) {
        ↪return mint(a) / b; } // hash-cpp-5 = 0
        ↪d3449609c465ca434b9110ef55a1bbb

    static constexpr u32 get_mod() { return m; }
    static constexpr mint get_root() {
        if (m == 998244353) return 3;
        if (m == 1053818881) return 2789;
        assert(false);
    }
};
```

nft.hpp

Description: NTT; mostly the same with fft.hpp?

```
59 lines
template <class T> void nft(Vec<T>& a, int n) {
    static Vec<int> rev = {0, 1}; // hash-cpp-1
    static Vec<T> rt(2, 1);
    if (ssize(rt) < n) {
```



```

    rev.resize(n);
    for (int i = 0; i < n; i++) {
        rev[i] = (rev[i >> 1] | ((i & 1) * n)) >> 1;
    }
    rt.reserve(n);
    for (int k = int(size(rt)); k < n; k *= 2) {
        rt.resize(2 * k);
        T z = pow(T::get_root(), (T::get_mod() - 1) / (2 * k)
            ↪);
        for (int i = k / 2; i < k; i++) {
            rt[2 * i] = rt[i];
            rt[2 * i + 1] = rt[i] * z;
        }
    }
} // hash-cpp-1 = cba95331cf1ba99f75ee2fafa229bb40
int s = std::countr_zero(u32(size(rev)) / n); // hash-cpp
    ↪-2
for (int i = 0; i < n; i++) {
    int j = rev[i] >> s;
    if (i < j) swap(a[i], a[j]);
}
for (int k = 1; k < n; k *= 2) {
    for (int i = 0; i < n; i += 2 * k) {
        auto it1 = begin(a) + i;
        auto it2 = it1 + k;
        for (int j = 0; j < k; j++, ++it1, ++it2) {
            T t = rt[j + k] * *it2;
            *it2 = *it1 - t;
            *it1 += t;
        }
    }
} // hash-cpp-2 = 1b6c673b5ee9b617060d250f010a7ec4
}

```

```

template <class T> void inft(Vec<T>& a, int n) { // hash-
    ↪cpp-3
    T d = inv(T(n));
    for (int i = 0; i < n; i++) a[i] *= d;
    reverse(begin(a) + 1, end(a));
    nft(a, n);
} // hash-cpp-3 = e89b7ab3e8c68c4b0bc3cc4883fe743d

template <class T> Vec<T> multiply(Vec<T> a, Vec<T> b) { //
    ↪hash-cpp-4
    int n = int(size(a));
    int m = int(size(b));
    if (!n || !m) return {};
    int s = std::bit_ceil<u32>(n + m - 1);
    a.resize(s), nft(a, s);
    b.resize(s), nft(b, s);
    T is = inv(T(s));
    for (int i = 0; i < s; i++) {
        a[i] *= b[i] * is;
    }
    reverse(begin(a) + 1, end(a));
    nft(a, s);
    a.resize(n + m - 1);
    return a;
} // hash-cpp-4 = 4dba4cf3b97f05245a59534493d49529

```

matrix.hpp

Description: Gaussian elimination and stuff. solve_lineareq returns the pair (some particular solution, a basis of the null space).

"algebra/modint.hpp"

116 lines

namespace matrix {

template <class T>

using F_better = std::function<bool(T, T)>;

template <class T>
using F_zero = std::function<bool(T)>;

template <bool rref = false, class T>
pair<int, T> sweep(Vec<Vec<T>>& a,
 F_better<T> fb, F_zero<T> fz,
 int c = -1) {
 int h = int(a.size());
 if (!h) return {0, 0};
 int w = int(a[0].size());

if (c == -1) c = w; // hash-cpp-1
int r = 0;
T det = 1;
for (int j = 0; j < c; j++) {
 int p = -1;
 for (int i = r; i < h; i++) {
 if (p == -1 || fb(a[i][j], a[p][j])) p = i;
 }
 if (p == -1 || fz(a[p][j])) {
 det = 0;
 continue;
 }
 if (r != p) {
 det = -det;
 swap(a[r], a[p]);
 }
 auto& ar = a[r];
 det *= ar[j]; // hash-cpp-1 = 68409
 ↪b9e970dd293b0fbdda0e682d0c9

int is; // hash-cpp-2
T d = T(1) / ar[j];
if constexpr(rref) {
 for (int k = j; k < w; k++) {
 ar[k] *= d;
 }
 d = 1;
 is = 0;
} else {
 is = r+1;
} // hash-cpp-2 = 2e7107ced9297d66963c63feb0f864a8

for (int i = is; i < h; i++) { // hash-cpp-3
 if (i == r) continue;
 auto& ai = a[i];
 if (!fz(ai[j])) {
 T e = ai[j] * d;
 for (int k = j; k < w; k++) {
 ai[k] -= ar[k] * e;
 }
 }
 r++;
} // hash-cpp-3 = bf314b34183f0c8f2f977a8def861fab
return {r, det};
}

template <class T>
pair<Vec<T>, Vec<Vec<T>>> solve_lineareq(Vec<Vec<T>> a, Vec
 ↪<T> b,
 F_better<T> fb, F_zero<T> fz) {
 int h = int(a.size());
 assert(h);
 int w = int(a[0].size());

for (int i = 0; i < h; i++) a[i].push_back(b[i]); // hash
 ↪-cpp-4
int r = sweep<true>(a, fb, fz, w).first;
for (int i = r; i < h; i++) {
 if (!fz(a[i][w])) return {};
}
Vec<T> x(w);
Vec<int> pivot(w, -1);
int z = 0;
for (int i = 0; i < r; i++) {
 while (fz(a[i][z])) z++;
 x[z] = a[i][w], pivot[z] = i;
} // hash-cpp-4 = fb8df177c0b27e778f81b878f3f7ccbd
Vec<Vec<T>> ker; // hash-cpp-5
for (int j = 0; j < w; j++) {
 if (pivot[j] == -1) {
 Vec<T> v(w);
 v[j] = 1;
 for (int k = 0; k < j; k++) {
 if (pivot[k] != -1) v[k] = -a[pivot[k]][j];
 }
 ker.push_back(v);
 }
} // hash-cpp-5 = 39e8c67d53dbc75c4490fa63713b3358
return {x, ker};
}

template <class T> Vec<Vec<T>> mat_inv(Vec<Vec<T>> a,
 F_better<T> fb, F_zero<T> fz) { // hash-cpp-6
 int n = int(a.size());
 Vec<Vec<T>> m(n, Vec<T>(2*n));
 for (int i = 0; i < n; i++) {
 copy(begin(a[i]), end(a[i]), begin(m[i]));
 m[i][n+i] = 1;
 }
 if (sweep<true>(m, fb, fz, n).first != n) return {};
 Vec<Vec<T>> b(n);
 for (int i = 0; i < n; i++) {
 copy(begin(m[i]) + n, end(m[i]), back_inserter(b[i]));
 }
 return b;
} // hash-cpp-6 = 70c19d713df6357711f258894902980

template <class T> T mat_det(Vec<Vec<T>> a,
 F_better<T> fb, F_zero<T> fz) { // hash-cpp-7
 return sweep<false>(a, fb, fz).second;
} // hash-cpp-7 = fa5f2046eelbe299cee6c7f1f558ba9f

} // namespace matrix

Tree (5)

cartesian-tree.hpp

27 lines

template <class T> struct CartesianTree {
 int n, root;
 Vec<int> p;
 Vec<array<int, 2>> c;
 CartesianTree(const Vec<T>& a)
 : n(int(size(a))), root(0), p(n, -1), c(n, {-1, -1}) {
 auto stk = Vec<int>{0};
 stk.reserve(n);
 for (int i = 1; i < n; i++) {
 if (a[stk.back()] > a[i]) {
 while (size(stk) >= 2 && a[stk.end()[-2]] > a[i]) {
 stk.pop_back();
 }
 }
 }
 }
};


```

    }
    if (size(stk) == 1) {
        root = p[c[i][0] = stk.back()] = i;
    } else {
        p[c[i][0] = stk.back()] = i;
        c[p[i] = stk.end()[-2]][1] = i;
    }
    stk.back() = i;
} else {
    c[p[i] = stk.back()][1] = i;
    stk.push_back(i);
}
}
}; // hash-cpp-all = e127c42059822fa5cfd16e249d98fad5

```

hld.hpp

"data-structure/flatten-vector.hpp"

182 lines

```

struct HLD {
    int n;
    Vec<int> ord, iord, sz;
    Vec<int> depth;
    Vec<pair<int, int>> path;
    Vec<pair<int, int>> edges;
    HLD(int n_) : n(n_), iord(n), sz(n, 1), depth(n), path(n)
        ↪ {}

    void add_edge(int a, int b) {
        edges.emplace_back(a, b);
        edges.emplace_back(b, a);
    }

    void build(int r = 0) {
        auto tr = FlattenVector<int>(n, edges);

        auto par = Vec<int>(n, -1); // hash-cpp-1
        auto topo = Vec<int>(r);
        topo.reserve(n);
        for (int z = 0; z < n; z++) {
            int v = topo[z];
            for (int w : tr.at(v)) {
                if (w == par[v]) continue;
                par[w] = v;
                depth[w] = depth[v] + 1;
                topo.push_back(w);
            }
        } // hash-cpp-1 = 08a8b9df9103531feceb3b4e7cddc88f

        auto max_ch = Vec<int>(n, -1); // hash-cpp-2
        for (int v : topo | std::views::drop(1) | std::views::
            ↪ reverse) {
            int p = par[v];
            sz[p] += sz[v];
            if (max_ch[p] == -1 || sz[max_ch[p]] < sz[v]) {
                max_ch[p] = v;
            }
        } // hash-cpp-2 = 017206f47c6fb0fce7cecf88537ec4c1

        auto stk = Vec<pair<int, bool>>({r, true}); // hash-cpp
            ↪ -3
        stk.reserve(n);
        while (!stk.empty()) {
            auto [v, ir] = stk.back();
            stk.pop_back();
            int i = int(size(ord));
            ord.push_back(v);
            iord[v] = i;

```

```

        if (ir) {
            path[i] = {par[v] == -1 ? -1 : iord[par[v]], 1};
        } else {
            path[i] = {path[i - 1].first, path[i - 1].second +
                ↪ 1};
        }
        if (max_ch[v] == -1) continue;
        for (int w : tr.at(v)) {
            if (w == par[v] || w == max_ch[v]) continue;
            stk.emplace_back(w, true);
        }
        stk.emplace_back(max_ch[v], false);
    } // hash-cpp-3 = b328d8e8b4b6c4a6f4ec9029b660aa94

    bool in_subtree(int a, int v) const {
        return iord[a] <= iord[v] && iord[v] < iord[a] + sz[a];
    }

    Opt<int> get_ancestor(int a, int k) const { // hash-cpp-4
        assert(k >= 0);
        a = iord[a];
        while (a != -1 && k) {
            if (k >= path[a].second) {
                k -= path[a].second;
                a = path[a].first;
            } else {
                a -= k;
                k = 0;
            }
        }
        if (a != -1) {
            return ord[a];
        } else {
            return std::nullopt;
        }
    } // hash-cpp-4 = e2a19fffa4a8f39d85ba61c16889a45c

    int lca(int a, int b) const { // hash-cpp-5
        a = iord[a], b = iord[b];
        while (true) {
            if (a > b) swap(a, b);
            if (a > b - path[b].second) {
                return ord[a];
            }
            b = path[b].first;
        }
    } // hash-cpp-5 = 55dbd4c94db1271544da38e0e05015c1

    Opt<int> jump(int s, int t, int d) const { // hash-cpp-6
        int w = lca(s, t);
        if (d <= depth[s] - depth[w]) {
            return get_ancestor(s, d);
        } else {
            d = (depth[s] + depth[t] - 2 * depth[w]) - d;
            if (d >= 0) {
                return get_ancestor(t, d);
            } else {
                return std::nullopt;
            }
        }
    } // hash-cpp-6 = 656007c3e4cc94b03fc9827135d52ee6

    Vec<pair<int, int>> extract(int s, int t) { // hash-cpp-7
        static Vec<pair<int, int>> res;
        res.clear();
        s = iord[s], t = iord[t];
        while (true) {

```

```

            if (t > s - path[s].second) {
                res.emplace_back(s, t + 1);
                break;
            }
            res.emplace_back(s, s - path[s].second + 1);
            s = path[s].first;
        }
        return res;
    } // hash-cpp-7 = cfe7a03a44193fc1c00e3f6a5f40b1c8

    template <bool vertex = true, class F>
    void apply(int s, int t, F f) { // hash-cpp-8
        int a = lca(s, t);
        for (auto&& [x, y] : extract(s, a)) {
            f(x + 1, y);
        }
        if constexpr (vertex) {
            f(iord[a], iord[a] + 1);
        }
        auto des = extract(t, a);
        for (auto&& [x, y] : des | std::views::reverse) {
            f(y, x + 1);
        }
    } // hash-cpp-8 = 9f6536b32da8351e82174844f1be0f09

    template <class F> int get_lowest(int a, F f) const { //
        ↪ hash-cpp-9
        a = iord[a];
        while (a != -1) {
            int t = a - path[a].second + 1;
            if (!f(ord[t])) {
                a = path[a].first;
                continue;
            }
            int mi = t, ma = a + 1;
            while (ma - mi > 1) {
                int md = (mi + ma) / 2;
                if (f(ord[md]))
                    mi = md;
                else
                    ma = md;
            }
            return ord[mi];
        }
        return -1;
    } // hash-cpp-9 = 0d2776498d957db35fa731b99c42c002

    Vec<int> inds;
    pair<Vec<int>, Vec<int>> compress(Vec<int> vs) { // hash-
        ↪ cpp-10
        inds.resize(n, -1);
        auto cmp = [&](int a, int b) { return iord[a] < iord[b]
            ↪ };
        std::ranges::sort(vs, cmp);
        vs.erase(unique(begin(vs), end(vs)), end(vs));
        int num = int(size(vs));
        assert(num >= 1);
        for (int z = 1; z < num; z++) {
            vs.push_back(lca(vs[z - 1], vs[z]));
        }

        std::ranges::sort(vs, cmp);
        vs.erase(unique(begin(vs), end(vs)), end(vs));
        num = int(size(vs));
        for (int z = 0; z < num; z++) inds[vs[z]] = z;
        Vec<int> par(num, -1);
        for (int z = 1; z < num; z++) {
            par[z] = inds[lca(vs[z - 1], vs[z])];
        }
    }

```

```

    }
    return {vs, par};
} // hash-cpp-10 = 9529325c9d44175758bcc26856fb927d
};

```

Graph (6)

eulerian-trail.hpp

Description: Eulerian undirected/directed trail algorithm. Returns a list of (vertex, edge)'s in the trail with `src` at the start, or `std::nullopt` if there is no trail. Note that choosing the starting vertex can be somewhat ad-hoc.)

Time: $\mathcal{O}(V + E)$

87 lines

```

namespace eulerian_trail {

// (vertex, edge)
// For the returned list, edge is the preceding edge of
//   ↳that vertex
using E = pair<int, int>;
template <bool cyc_only = false>
Opt<Vec<E>> go(int nv, const Vec<Vec<E>>& g, int ne, int
    ↳src = 0) {
    assert(nv == int(size(g)));
    assert(0 <= src && src < nv);

    Vec<Vec<E>::const_iterator> its(nv); // hash-cpp-1
    for (int i = 0; i < nv; i++) its[i] = begin(g[i]);
    Vec<int> state(nv);
    if constexpr (!cyc_only) state[src]++;
    Vec<bool> seen(ne);
    Vec<E> res, stk = {E(src, -1)}; // hash-cpp-1 = 2
    ↳ce68639be60f45b59e1e28cbea708c0

    while (!stk.empty()) { // hash-cpp-2
        auto [i, p] = stk.back();
        auto& it = its[i];
        if (it == end(g[i])) {
            res.emplace_back(i, p);
            stk.pop_back();
            continue;
        }
        auto [j, e] = *(it++);
        if (!seen[e]) {
            state[i]--, state[j]++;
            stk.emplace_back(j, e);
            seen[e] = true;
        }
    }
    if (int(size(res)) != ne + 1) {
        return {};
    }
    for (int s : state) {
        if (s < 0) return {};
    }
    return Vec<E>(rbegin(res), rend(res)); // hash-cpp-2 =
    ↳334b4d0a9ab464b25cfaldd7a1b0714b
}

template <bool cyc_only = false>
Opt<Vec<E>> trail_undirected(int nv, const Vec<pair<int,
    ↳int>>& edges) {
    assert(nv > 0);

    Vec<Vec<E>> g(nv);
    int e = 0;

```

```

    for (auto [a, b] : edges) {
        g[a].emplace_back(b, e);
        g[b].emplace_back(a, e);
        e++;
    }

    int src = 0; // hash-cpp-3
    for (int i = 0; i < nv; i++) {
        if (!g[i].empty()) src = i;
    }
    for (int i = 0; i < nv; i++) {
        if (size(g[i]) % 2 == 1) src = i;
    } // hash-cpp-3 = 80724ceaae254adebb9b8f246229e6d6
    return go<cyc_only>(nv, g, int(size(edges)), src);
}

template <bool cyc_only = false>
Opt<Vec<E>> trail_directed(int nv, const Vec<pair<int, int
    ↳>>& edges) {
    assert(nv > 0);

    Vec<Vec<E>> g(nv);
    Vec<int> indeg(nv);
    int e = 0;
    for (auto [a, b] : edges) {
        g[a].emplace_back(b, e);
        indeg[b]++;
        e++;
    }

    int src = 0; // hash-cpp-4
    for (int i = 0; i < nv; i++) {
        if (!g[i].empty()) src = i;
    } // hash-cpp-4 = a6820e1aab49fceff350c7c4747a3e7c
    return go<cyc_only>(nv, g, int(size(edges)), src);
}

} // namespace eulerian_trail

```

bipartite.hpp

Description: Hopcroft-Karp algorithm that gives a maximum bipartite matching. edges should be a sequence of edges (a_i, b_i) such that $a_i \in [n_l]$ and $b_i \in [n_r]$

Time: $\mathcal{O}(E\sqrt{V})$

93 lines

```

struct Bipartite {
    int nl, nr;
    Vec<Vec<int>> g;
    Vec<int> mtl, mtr, lvl;
    Vec<bool> seen;
    Bipartite(int nl_, int nr_)
        : nl(nl_), nr(nr_),
          g(nl),
          mtl(nl, -1),
          mtr(nr, -1),
          lvl(nl),
          seen(nr) {}

    void add_edge(int a, int b) { g[a].push_back(b); }

    void run() {
        Vec<int> q;

```

```

        q.reserve(nl);
        while (true) {
            q.clear(); // hash-cpp-1
            for (int i = 0; i < nl; i++) {
                if (mtl[i] == -1) {
                    lvl[i] = 0;
                    q.push_back(i);
                } else {
                    lvl[i] = -1;
                }
            }
            // If there is an alternating path that
            // leads to some unmatched left-side vertex
            bool f = false;
            for (int z = 0; z < int(q.size()); z++) {
                int i = q[z];
                for (int j : g[i]) {
                    int o = mtr[j];
                    if (o == -1) {
                        f = true;
                    } else if (lvl[o] == -1) {
                        lvl[o] = lvl[i] + 1;
                        q.push_back(o);
                    }
                }
            }
            if (!f) {
                for (int i : q) {
                    for (int j : g[i]) seen[j] = true;
                }
                break;
            } // hash-cpp-1 = 7810f15a14alc2f2460b4a75dc158b26

            Vec<bool> done(nl); // hash-cpp-2
            for (int s = 0; s < nl; s++) {
                if (mtl[s] != -1) continue;

                auto dfs = [&](auto self, int i) -> bool {
                    if (done[i]) return false;
                    done[i] = true;
                    for (int j : g[i]) {
                        int o = mtr[j];
                        if (o == -1 ||
                            (lvl[i] + 1 == lvl[o] && self(self, o))) {
                            mtl[i] = j, mtr[j] = i;
                            return true;
                        }
                    }
                    return false;
                };
                dfs(dfs, s);
            } // hash-cpp-2 = 815ba2fd9b6cbd3873d6b1685e348d6d
        }

        Vec<pair<int, int>> matching() { // hash-cpp-3
            Vec<pair<int, int>> res;
            for (int i = 0; i < nl; i++) {
                int j = mtl[i];
                if (j != -1) res.emplace_back(i, j);
            }
            return res;
        } // hash-cpp-3 = 99b9b84954bc198aa01b8e0472d9bc57

        pair<Vec<int>, Vec<int>> vertex_cover() { // hash-cpp-4
            Vec<int> lvs, rvs;
            for (int i = 0; i < nl; i++) {
                if (lvl[i] == -1) lvs.push_back(i);

```

```
    }
    for (int j = 0; j < nr; j++) {
        if (seen[j]) rvs.push_back(j);
    }
    return {lvs, rvs};
} // hash-cpp-4 = eefb9beeb3ba02086a05cd06bd677af7
};
```

enumerate-triangles.hpp

Description: Enumerates all triangles (x, y, z) in an undirected graph
Time: TODO

```
25 lines
template <class F> void triangles(int n, const Vec<pair<int
    ↪, int>>& edges, F f) {
    Vec<int> deg(n); // hash-cpp-1
    for (auto [a, b] : edges) {
        deg[a]++, deg[b]++;
    }
    Vec<Vec<int>> adj(n);
    for (auto [a, b] : edges) {
        if (tie(deg[a], a) > tie(deg[b], b)) swap(a, b);
        adj[a].push_back(b);
    } // hash-cpp-1 = 9b0f43606d4027f45b8f261dc68a595e

    Vec<int> ind(n); // hash-cpp-2
    int i = 0;
    for (int x = 0; x < n; x++) {
        ++i;
        for (int y : adj[x]) ind[y] = i;
        for (int y : adj[x]) {
            for (int z : adj[y]) {
                if (ind[z] == i) {
                    f(x, y, z);
                }
            }
        }
    } // hash-cpp-2 = 9c84ca8b936d3ec0bc78ceeab0f70576
}
```

block-cut.hpp

```
47 lines
template <class E> Vec<Vec<int>> block_cut_tree(int n,
    ↪const Vec<Vec<E>>& g) {
    Vec<Vec<int>> tr(n); // hash-cpp-1
    auto add = [&](int b, int v) -> void {
        tr[b].push_back(v);
        tr[v].push_back(b);
    }; // hash-cpp-1 = 71a481760eb715a52de9c708094631dc

    Vec<int> stk; stk.reserve(n);
    Vec<int> idx(n, -1);
    int t = 0;
    for (int s = 0; s < n; s++) {
        if (idx[s] != -1) continue;
        yc([&](auto self, int v, int p) -> int {
            stk.push_back(v); // hash-cpp-2
            idx[v] = t++;
            int low = idx[v] = t++;
            int c = 0;
            for (int w : g[v]) {
                if (w == p) continue;
                if (idx[w] == -1) {
                    c++;
                    auto z = stk.size();
                    int nlow = self(w, v);
                    low = min(low, nlow);
                }
            }
        });
    }
}
```

```
if ((p == -1 && c > 1) || (p != -1 && idx[v] <=
    ↪nlow)) {
    int b = int(tr.size());
    tr.resize(b+1);
    add(b, v);
    while (z < stk.size()) {
        add(b, stk.back());
        stk.pop_back();
    }
} else {
    low = min(low, idx[w]);
}
}
return low; // hash-cpp-2 = 7
    ↪cc064051424c44ab789d52113b58040
))(s, -1);
int b = int(tr.size()); // hash-cpp-3
tr.resize(b+1);
for (int v : stk) add(b, v);
stk.clear(); // hash-cpp-3 = 98651
    ↪a8db6af759650d4c4be638030dd
}

return tr;
}
```

Number Theory (7)

factor.hpp

Description: Returns prime factors in ascending order (e.g. 2299 -> {11, 11, 19})

Time: $\mathcal{O}(n^{1/4})$

```
73 lines
namespace factor {

template <class T> T pow_mod(T a, u64 b, T m) { // hash-cpp
    ↪-1
    T r = 1;
    while (b) {
        if (b & 1) r = r * a % m;
        a = a * a % m;
        b >>= 1;
    }
    return r;
} // hash-cpp-1 = 8153dd104c95c28bf40b51ccfa359c28

template <class T> bool is_prime(T n) { // hash-cpp-2
    if (n <= 1 || n % 2 == 0) return (n == 2);
    int s = __builtin_ctzll(n - 1);
    T d = (n - 1) >> s;
    for (u128 a : {2, 325, 9375, 28178, 450775, 9780504,
        ↪1795265022}) {
        a %= n;
        if (a == 0) continue;
        a = pow_mod<u128>(a, d, n);
        if (T(a) == 1 || T(a) == n - 1) continue;
        for (int i = 0; i < s - 1; i++) {
            a = a * a % n;
            if (T(a) == n - 1) break;
        }
        if (T(a) != n - 1) return false;
    }
    return true;
} // hash-cpp-2 = 91830792ecc62049005cfc63ebf602cb
```

```
template <class T> T pollard(T n) { // hash-cpp-3
    T x = 0, y = 0, t = 30, p = 2, it = 1;
    auto f = [&](T a) { return T(u128(a) * a % n) + it; };
    while (t++ % 40 || std::gcd(p, n) == 1) {
        if (x == y) {
            x = ++it, y = f(x);
        }
        T d = max(x, y) - min(x, y);
        if (T q = T(u128(p) * d % n); q) {
            p = q;
        }
        x = f(x), y = f(f(y));
    }
    return std::gcd(p, n);
} // hash-cpp-3 = 750e917ce8d6b979f4af39351f6fedc1

// Returns prime factors in ascending order
template <class T> Vec<T> factorize(T n) { // hash-cpp-4
    if (n == 1) return {};
    if (is_prime(n)) return {n};
    T f = pollard(n);
    auto a = factorize(f), b = factorize(n / f);
    Vec<T> c(a.size() + b.size());
    merge(begin(a), end(a), begin(b), end(b), begin(c));
    return c;
} // hash-cpp-4 = 33d26dfcca56fce967c8610a56b9f578

template <class T> T primitive_root(T p) {
    assert(is_prime(p));
    auto f = factorize(p - 1);
    T c;
    while (true) {
        c = rand_int<T>(1, p - 1);
        if (!std::ranges::any_of(f, [&](T d) {
            return pow_mod<u128>(c, (p - 1) / d, p) == 1;
        })) {
            break;
        }
    }
    return c;
}

} // namespace factor

int-kth-root.hpp
Description: Computes  $[a^{1/k}]$ 
18 lines
template <class I = u64> I int_kth_root(I a, I k) {
    if (k == 1) return a;
    if (k >= 64) return (a == 0 ? 0 : 1);

    using T = __uint128_t;
    auto works = [&](T x) -> bool {
        T r = 1;
        for (int n = int(k); n; n >>= 1) {
            if (n & 1) r *= x;
            x *= x;
        }
        return r <= a;
    };
    if (a == I(-1)) a--;
    I rt = I(pow(double(a), nextafter(1 / double(k), 0)));
    while (works(rt + 1)) rt++;
    return rt;
} // hash-cpp-all = df0dda344149ce60f0cfff3a65363fcc
```

eratosthenes.hpp

Description: Prime sieve for generating all primes up to a certain limit n

```

18 lines
inline Vec<int> prime_enumerate(int n) {
    auto sieve = Vec<bool>(n / 3 + 1, true); // hash-cpp-1
    int qe = int(size(sieve));
    int n2 = int(sqrt(n));
    for (int p = 5, d = 4, i = 1; p <= n2; p += d = 6 - d, i
        ↪++) {
        if (!sieve[i]) continue;
        for (int q = p * p / 3, r = d * p / 3 + (d * p % 3 ==
            ↪2), s = 2 * p;
            q < qe; q += r = s - r) {
            sieve[q] = false;
        }
    } // hash-cpp-1 = dd325b3ad774bc7c50b9ae91467d6a84
    auto res = Vec<int>{2, 3}; // hash-cpp-2
    for (int p = 5, d = 4, i = 1; p <= n; p += d = 6 - d, i
        ↪++) {
        if (sieve[i]) res.push_back(p);
    }
    while (!res.empty() && res.back() > n) res.pop_back();
    return res; // hash-cpp-2 =
        ↪c90bbe8732ffd47485a6c953502a419d
}

```

multiplicative-sum.hpp

Description: Blackbox sieve. Modify $f(v, p, c)$ to fit your wish

```

191 lines
namespace multiplicative_sum {
    using std::sqrt, std::cbrt;

    inline i64 isqrt(i64 n) { return i64(sqrt(n)); }
    inline i64 icbrt(i64 n) { return i64(cbrt(n)); }
    inline i64 sq(i64 a) { return a * a; }

    inline i64 sump(int k, i64 n) {
        if (k == 0) {
            return n;
        }
        // Unreachable
        assert(false);
        return 0;
    }

    template <class T, int K> struct counting_primes {
        using A = array<T, K>; // hash-cpp-1
        void add(A& a, const A& b) {
            for (int k = 0; k < K; k++) a[k] += b[k];
        }
        void sub(A& a, const A& b) {
            for (int k = 0; k < K; k++) a[k] -= b[k];
        }
        const Vec<int>& ps;
        const i64 n;
        const int n2, n3, n6;
        int s;
        Vec<i64> vs;
        Vec<A> sum, fw;
        A pref; // hash-cpp-1 = 5ba8cd301505a2b3b37ae1caef795746

        A getpows(T p) { // hash-cpp-2
            A res;
            res[0] = 1;
            for (int k = 1; k < K; k++) {

```

```

                res[k] = res[k - 1] * p;
            }
            return res;
        } // hash-cpp-2 = 1282c5b86030aad73569a7ce5b1492b8

        void trans(int i, int p) { // hash-cpp-3
            A w = getpows(p);
            int j = get_idx(vs[i] / p);
            for (int k = 0; k < K; k++) {
                sum[i][k] -= (sum[j][k] - pref[k]) * w[k];
            }
        } // hash-cpp-3 = 1b75b45369ff775f2ea7ab66bf8c1726

        void trans2(int i, int p) { // hash-cpp-4
            A w = getpows(p);
            int j = get_idx(vs[i] / p);
            A z = sum[j];
            if (j >= n3) {
                j -= n3;
                for (; j < int(fw.size()); j += (j + 1) & (-j - 1)) {
                    add(z, fw[j]);
                }
            }
            for (int k = 0; k < K; k++) {
                sum[i][k] -= (z[k] - pref[k]) * w[k];
            }
        } // hash-cpp-4 = 4f7b414359537414dc08ba63b39ad6ec

        void upd(int i, i64 cur, bool f) { // hash-cpp-5
            if (!f) {
                A w = getpows(cur);
                for (int j = get_idx(cur) - n3; j >= 0; j -= (j + 1)
                    ↪& (-j - 1)) {
                    sub(fw[j], w);
                }
            }
            for (int j = i; cur * ps[j] <= vs[n3]; j++) {
                upd(j, cur * ps[j], false);
            }
        } // hash-cpp-5 = 439188de4fe2b38413e6f3a29720a190

        counting_primes(i64 n_, const Vec<int>& ps_)
            : ps(ps_),
              n(n_),
              n2(int(isqrt(n))),
              n3(int(icbrt(n))),
              n6(int(icbrt(n2))) { // hash-cpp-6

            {
                i64 v = n;
                while (v) {
                    vs.push_back(v);
                    v = n / (n / v + 1);
                }
            }
            s = int(vs.size());

            sum.resize(s);
            for (int i = 0; i < s; i++) {
                for (int k = 0; k < K; k++) {
                    sum[i][k] = sump(k, vs[i]) - 1;
                }
            }

            int idx = 0;
            pref = {};
            {
                while (ps[idx] <= n6) {
                    for (int i = 0; i < s; i++) {

```

```

                        if (sq(ps[idx]) > vs[i]) break;
                        trans(i, ps[idx]);
                    }
                }
                add(pref, getpows(ps[idx]));
                idx++;
            }
            {
                fw.resize(s - n3);
                while (ps[idx] <= n3) {
                    for (int i = 0; i < n3; i++) {
                        if (sq(ps[idx]) > vs[i]) break;
                        trans2(i, ps[idx]);
                    }
                    upd(idx, ps[idx], true);
                    add(pref, getpows(ps[idx]));
                    idx++;
                }
                for (int i = s - n3 - 1; i >= 0; i--) {
                    int j = i + ((i + 1) & (-i - 1));
                    if (j < int(fw.size())) {
                        add(fw[i], fw[j]);
                    }
                }
                for (int i = 0; i < s - n3; i++) {
                    add(sum[i + n3], fw[i]);
                }
            }
            {
                while (ps[idx] <= n2) {
                    for (int i = 0; i < s; i++) {
                        if (sq(ps[idx]) > vs[i]) break;
                        trans(i, ps[idx]);
                    }
                    add(pref, getpows(ps[idx]));
                    idx++;
                }
            }
        } // hash-cpp-6 = 3e7e01a3e2d245e5d87c8b8857b1a63a

        int get_idx(i64 a) { // hash-cpp-7
            return int(a <= n2 ? s - a : n / a - 1);
        } // hash-cpp-7 = 3b7faedb45f949fd7fa348ec51114b4

        // f(v)=f(p^c), where p is some prime
        // totient function as an example:
        T f(i64, int p, int c) {
            T res = p - 1;
            for (int z = 0; z < c - 1; z++) {
                res *= p;
            }
            return res;
        }

        Vec<T> buf;
        T multiplicative_sum() { // hash-cpp-8
            // sum of [p is prime] f(p)
            buf.resize(s);
            for (int i = 0; i < s; i++) {
                buf[i] = sum[i][1] - sum[i][0];
            }

            T ans = 1 + buf[0];
            auto dfs =
                yc([&](auto self, int i, int c, i64 v, i64 lim, T cur
                    ↪) -> void {
                    ans += cur * f(v * ps[i], ps[i], c + 1);
                    if (lim >= sq(ps[i])) {

```

```

        self(i, c + 1, v * ps[i], lim / ps[i], cur);
    }
    cur *= f(v, ps[i], c);
    ans += cur * (buf[get_idx(lim)] - buf[get_idx(ps[i]
        ↪)]));
    for (int j = i + 1; sq(ps[j]) <= lim; j++) {
        self(j, 1, ps[j], lim / ps[j], cur);
    }
});
for (int i = 0; true; i++) {
    if (sq(ps[i]) <= n) {
        dfs(i, 1, ps[i], n / ps[i], 1);
    } else {
        break;
    }
}
return ans;
} // hash-cpp-8 = 4f3d37cb3d7f7ca7c9d6e8ac6ea65fec
};

} // namespace multiplicative_sum

```

String (8)

z-algorithm.hpp

Description: Returns r_0, \dots, r_N such that $s[0..r_i) = s[i..i + r_i)$. In particular, $r_0 = N$ and $r_N = 0$

Time: $\mathcal{O}(N)$

```

template <class S> Vec<int> z_algo(const S& s) {
    int n = int(size(s));
    auto res = Vec<int>(n + 1);
    for (int i = 1, j = 0; i <= n; i++) {
        int& k = res[i];
        if (j + res[j] <= i) {
            k = 0;
        } else {
            k = min(res[j] + j - i, res[i - j]);
        }
        while (i + k < n && s[k] == s[i + k]) k++;
        if (j + res[j] < i + res[i]) j = i;
    }
    res[0] = n;
    return res;
} // hash-cpp-all = 4cea91273404f4082bf8a501cb55b583

```

manacher.hpp

Description: Returns maximum lengths of “palindromic” (whatever that means) substrings of S centered at each point

Time: $\mathcal{O}(N)$

```

/*
 * eq(i, j): whether [i, j] (inclusive) is palindromic,
 * given that [i+1, j-1] is palindromic.
 * Properties:
 *   * res[i] == i (mod 2)
 *   * k + res[i-k] < res[i] => res[i+k] = res[i-k]
 *   * k + res[i-k] >= res[i] => res[i-k] >= res[i] - k
 * [i, j] being palindromic <=> j-i <= res[i+j]
 * In particular, res[2*i+1] = -1 states that [i, i] is not
   ↪ palindromic.
 */
template <class E> Vec<int> manacher(int n, E e) {
    auto res = Vec<int>(2 * n + 1);
    int i = 0, a = 0, b = 0;

```

```

while (i <= 2 * n) {
    while (0 < a && b < n) {
        if (i - 2 * a >= -1 && !e(a - 1, b)) break;
        a--, b++;
    }
    int j = b - a;
    res[i] = j;
    int k = 1;
    while (k < j && k + res[i - k] < j) {
        res[i + k] = res[i - k];
        k++;
    }
    i += k, a += k;
}
return res;
} // hash-cpp-all = 000c505275977a4289a6af3e23a739d2

```

hashint.hpp

Description: Self-explanatory string hashing structure

```

struct HashInt {
    using H = HashInt; // hash-cpp-1
    using T = unsigned long long;
    using L = __uint128_t;
    static constexpr T m = (T(1) << 61) - 1;
    static constexpr T m8 = m * 8;

    T v;
    HashInt() : v(0) {}
    HashInt(T a) : v(a % m * 8) {}
    T get() const { return v == m8 ? 0 : v; } // hash-cpp-1 =
        ↪ 441ee64fd18fdc7b1df56890de357f06

    H& operator += (const H& o) { // hash-cpp-2
        if (__builtin_uaddll_overflow(v, o.v, &v)) v -= m8;
        return *this;
    }
    H& operator -= (const H& o) {
        if (__builtin_usubll_overflow(v, o.v, &v)) v += m8;
        return *this;
    } // hash-cpp-2 = 03a79be35c3f8731c3c4e64a1799cc94

    H& operator *= (const H& o) { // hash-cpp-3
        L t = L(v) * o.v;
        T x = T(t >> 67 << 3);
        T y = T(t << 61 >> 64);
        if (__builtin_uaddll_overflow(x, y, &v)) v -= m8;
        return *this;
    } // hash-cpp-3 = c535ff913f601dd75b6c039556dda31a

    friend H operator + (const H& a, const H& b) { return H(a
        ↪) += b; } // hash-cpp-4
    friend H operator - (const H& a, const H& b) { return H(a
        ↪) -= b; }
    friend H operator * (const H& a, const H& b) { return H(a
        ↪) *= b; }
    friend bool operator == (const H& a, const H& b) { return
        ↪ a.get() == b.get(); } // hash-cpp-4 =
        ↪ b15740d449ec094c54eaf820a3f31571
};

inline HashInt rand_base() {
    return 2 * std::uniform_int_distribution<uint64_t>(4e10,
        ↪ 5e10) (mt) + 1;
}

```

suffix-array.hpp

Description: Builds the suffix array given a string

Time: $\mathcal{O}(N)$ building

```

// Work in progress
117 lines

struct SuffixArray {
    int n;
    Vec<int> sa;
    Vec<int> isa;
    Vec<int> lcp;
    SuffixArray(int n_) : n(n_) {}

    template <class S> static SuffixArray construct(const S&
        ↪ s) {
        int n = int(s.size());
        SuffixArray sa(n);

        sa.build_sa_fast(s);

        sa.build_isa();
        sa.build_lcp(s);

        return sa;
    }

    template <class S> void build_sa_fast(S s) {
        sa.resize(n+1);
        // kinda weird
        int sigma = 0;
        for (auto v : s) {
            sigma = max(sigma, int(v));
            assert(int(v) > 0);
        }
        ++sigma;
        s.push_back(0);
        // what exactly should be these sizes?
        Vec<int> freq(2 * max(n+1, sigma)), lms(2 * (n+1));
        Vec<char> type(2 * (n+1));
        sais(n, s.data(), sa.data(), sigma, freq.data(), lms.
            ↪ data(), type.data());
    }

    template <class S> static void sais(int n, S* s, int* sa,
        ↪ int sigma,
        int* freq, int* lms, char* which) {
        int n2 = -1; // hash-cpp-1
        which[n] = 1;
        for (int i = n-1; i >= 0; i--) {
            which[i] = (s[i] == s[i+1] ? which[i+1] : s[i] < s[i
                ↪ +1]);
            if (which[i] == 0 && which[i+1] == 1) {
                which[i+1] = 2;
                lms[++n2] = i+1;
            }
        }
        std::reverse(lms, lms + (n2+1));
        std::fill(freq, freq + sigma, 0);
        for (int i = 0; i <= n; i++) ++freq[int(s[i])];
        std::partial_sum(freq, freq + sigma, freq); // hash-cpp
            ↪ -1 = d2b13dfc346726fd0e87317ea25a4085

        auto induce = [&](int* v) { // hash-cpp-2
            std::fill(sa, sa + n+1, 0);
            int* cur = freq + sigma;
            auto pushS = [&](int i) { sa[--cur[int(s[i])]] = i;
                ↪ };

```

```

    auto pushL = [&](int i) { sa[cur[int(s[i])]]++ = i;
    ↪};
    std::copy(freq, freq + sigma, cur);
    for (int i = n2; i >= 0; i--) pushS(v[i]);
    std::copy(freq, freq + sigma-1, cur + 1);
    for (int i = 0; i <= n; i++) {
        int j = sa[i]-1;
        if (j >= 0 && which[j] == 0) pushL(j);
    }
    std::copy(freq, freq + sigma, cur);
    for (int i = n; i >= 0; i--) {
        int j = sa[i]-1;
        if (j >= 0 && which[j]) pushS(j);
    }
}; // hash-cpp-2 = e81905738085f0bfa7c9e4e52b1ac974

auto eq = [&](int i, int j) { // hash-cpp-3
    if (s[i] == s[j]) {
        while (s[++i] == s[++j]) {
            if (which[i] == 2) return true;
        }
    }
    return false;
}; // hash-cpp-3 = 208a2ae3b819fd126c46e4e3a88d30c0

induce(lms); // hash-cpp-4
int sigma2 = -1;
int* s2 = std::remove_if(sa, sa + n, [&](int i) {
    ↪return which[i] != 2; });
for (int i = 0; i <= n2; i++) {
    if (sigma2 <= 0 || !eq(sa[i], sa[i-1])) sigma2++;
    s2[sa[i]>>1] = sigma2;
}
for (int i = 0; i <= n2; i++) s2[i] = s2[lms[i]>>1];
++sigma2;
if (sigma2 <= n2) {
    sais(n2, s2, sa, sigma2,
        freq + sigma, lms + (n2+1), which + (n+1));
} else {
    for (int i = 0; i <= n2; i++) sa[s2[i]] = i;
}
auto buf = lms + (n2+1);
for (int i = 0; i <= n2; i++) buf[i] = lms[sa[i]];
induce(buf); // hash-cpp-4 = 2343
    ↪d6679d81286e35f22880aacf2343
}

void build_isa() { // hash-cpp-5
    isa.resize(n+1);
    for (int i = 0; i <= n; i++) isa[sa[i]] = i;
} // hash-cpp-5 = bcb546b2fc94176fc80672b20a808f7f

template <class S> void build_lcp(const S& s) {
    assert(n == int(s.size()));
    lcp.resize(n+1); // hash-cpp-6
    for (int i = 0, k = 0; i < n-1; i++) {
        int r = isa[i]-1, j = sa[r];
        while (k < n - max(i, j) && s[i+k] == s[j+k]) k++;
        lcp[r] = k;
        if (k) k--;
    } // hash-cpp-6 = 85193c3617ced5f805117ffdf20255aa
}
};

```

eertree.hpp

Description: Palindrome tree. Call reset() to move back to the root

55 lines

```

// 0, ..., K-1
template <int sigma> struct Eertree {
    struct Node { // hash-cpp-1
        array<int, sigma> ch;
        int par, fail;
        int l, r; // location of the first ocurrence
        Node(int p_, int f_, int l_, int r_) : ch(), par(p_),
            ↪fail(f_), l(l_), r(r_) {}
        int len() const { return r-l; }
    };
    Vec<Node> x;
    Vec<int> buf;
    int cur; // hash-cpp-1 = d7cdae0bbec5fe81ccfad852c935e23c
    Eertree(int alloc = 0) {
        if (alloc) {
            x.reserve(alloc+2);
            buf.reserve(alloc);
        }
        x.emplace_back(-1, -1, 1, 0);
        x.emplace_back(0, 0, 0, 0);
        reset();
    }

    void reset() {
        cur = 1;
        buf.clear();
    }

    int append(int a) { // hash-cpp-2
        int i = int(buf.size());
        buf.push_back(a);
        auto works = [&](int v) -> bool {
            int l = i - x[v].len();
            return l > 0 && buf[l-1] == a;
        };
        for (; !works(cur); cur = x[cur].fail) {}
        if (!x[cur].ch[a]) {
            int f = x[cur].fail;
            if (f != -1) {
                for (; !works(f); f = x[f].fail) {}
            }
            int nf = (f == -1 ? 1 : x[f].ch[a]);
            x[cur].ch[a] = int(x.size());
            x.emplace_back(cur, nf, i - x[cur].len() - 1, i + 1);
        }
        cur = x[cur].ch[a];
        return cur;
    } // hash-cpp-2 = 304d80d300ae59c03bad13256f8fc973

    int size() const {
        return int(x.size());
    }
    const Node& operator [](int i) const {
        return x[i];
    }
};

```

Geometry (9)

base.hpp

Description: Primitive operations

109 lines

```

namespace geometry {

```

```

using std::fmod;

```

```

const double EPS = 1e-9;
template <class T> inline int sgn(T a) { return (a > EPS) -
    ↪ (a < -EPS); }
template <class T> inline int sgn(T a, T b) { return sgn(a
    ↪ - b); }

const double PI = acos(-1.);

template <class T> struct Point {
    using P = Point;
    T x, y;
    Point(T x_ = T(), T y_ = T()) : x(x_), y(y_) {}

    P& operator+=(const P& p) { // hash-cpp-1
        x += p.x, y += p.y;
        return *this;
    }
    P& operator-=(const P& p) {
        x -= p.x, y -= p.y;
        return *this;
    }
    friend P operator+(const P& a, const P& b) { return P(a
        ↪ += b); }
    friend P operator-(const P& a, const P& b) {
        return P(a) -= b;
    } // hash-cpp-1 = 32704ee5f47251cb7a5a8bcddb7996e3

    P& operator*=(const T& t) { // hash-cpp-2
        x *= t, y *= t;
        return *this;
    }
    P& operator/=(const T& t) {
        x /= t, y /= t;
        return *this;
    }
    friend P operator*(const P& a, const T& t) { return P(a
        ↪ *= t); }
    friend P operator/(const P& a, const T& t) {
        return P(a) /= t;
    } // hash-cpp-2 = 56a8dfabc9e0968b82d5006dda2d4d7e

    friend T dot(const P& a, const P& b) { return a.x * b.x +
        ↪ a.y * b.y; }
    friend T crs(const P& a, const P& b) { return a.x * b.y -
        ↪ a.y * b.x; }

    P operator-() const { return P(-x, -y); }

    friend int cmp(const P& a, const P& b) { // hash-cpp-3
        int z = sgn(a.x, b.x);
        return z ? z : sgn(a.y, b.y);
    } // hash-cpp-3 = 1553bdfc52835908d4fc0bd0a91b7134

    friend bool operator<(const P& a, const P& b) { return
        ↪ cmp(a, b) < 0; }
    friend bool operator<=(const P& a, const P& b) { return
        ↪ cmp(a, b) <= 0; }

    friend T dist2(const P& p) { return p.x * p.x + p.y * p.y
        ↪; }
    friend auto dist(const P& p) { return sqrt(D(dist2(p)));
        ↪; }

    friend P unit(const P& p) { return p / p.dist(); }

```



```

friend double arg(const P& p) { return atan2(p.y, p.x); }

friend T rabs(const P& p) { return max(abs(p.x), abs(p.y))
    ↪); }

friend bool operator==(const P& a, const P& b) {
    return sgn(rabs(a - b)) == 0;
}
friend bool operator!=(const P& a, const P& b) { return
    ↪!(a == b); }

explicit operator pair<T, T>() const { return pair<T, T>(
    ↪x, y); }

static P polar(double m, double a) { return P(m * cos(a),
    ↪m * sin(a)); }
};

template <class T> std::istream& operator>>(std::istream&
    ↪is, Point<T>& p) {
    return is >> p.x >> p.y;
}

template <class T>
int sgn crs(const Point<T>& a, const Point<T>& b) { // hash-
    ↪cpp-4
    T cr = crs(a, b);
    if (abs(cr) <= (rabs(a) + rabs(b)) * EPS) return 0;
    return (cr < 0 ? -1 : 1);
} // hash-cpp-4 = 16e5d8b9630b699a9c02dd9f87a381ac

// not tested
template <class D> D norm_angle(D a) { // hash-cpp-5
    D res = fmod(a + PI, 2 * PI);
    if (res < 0) {
        res += PI;
    } else {
        res -= PI;
    }
    return res;
} // hash-cpp-5 = 8d996afb8002237f3ae57e1308edf700

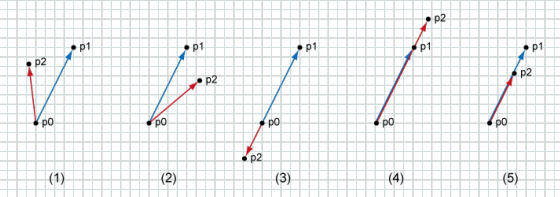
// not tested
template <class D> D norm_nonnegative(D a) { // hash-cpp-6
    D res = fmod(a, 2 * PI);
    if (res < 0) res += 2 * PI;
    return res;
} // hash-cpp-6 = 9b568a78d4e45eabe33de16e27a603e2

// arg given lengths a, b, c,
// assuming a, b, c are valid
template <class D> D arg(D a, D b, D c) { // hash-cpp-7
    return acos(std::clamp<D>((a * a + b * b - c * c) / (2 *
    ↪a * b), -1, 1));
} // hash-cpp-7 = 2a5ba3e05833252f908cf246319cb8a5

} // namespace geometry

```

ccw.hpp

Description:


"geometry/base.hpp" 23 lines

```

namespace geometry {

// CGL_1_C
// 1: COUNTER_CLOCKWISE (1)
// -1: CLOCKWISE (2)
// 2: ONLINE_BACK (3)
// -2: ONLINE_FRONT (4)
// 0: ON_SEGMENT (5)
template <class T> int ccw(const Point<T>& a, const Point<T>
    ↪& b) {
    int s = sgn crs(a, b); // hash-cpp-1
    if (s) return s;
    if (!sgn(rabs(b)) || !sgn(rabs(b - a))) return 0;
    if (dot(a, b) < 0) return 2;
    if (dot(-a, b - a) < 0) return -2;
    return 0; // hash-cpp-1 = 69
    ↪b3ea9eb828036b9188f3ad430e43c6
}

template <class T>
int ccw(const Point<T>& a, const Point<T>& b, const Point<T>
    ↪& c) {
    return ccw(b - a, c - a);
}

} // namespace geometry

```

linear.hpp**Description:** Line/segment operations

"geometry/ccw.hpp" 78 lines

```

namespace geometry {

// Work in progress
template <class T> struct L {
    using P = Point<T>; // hash-cpp-1
    P s, t;
    L(P s_ = P(), P t_ = P()) : s(s_), t(t_) {}
    friend P vec(const L& l) { return l.t - l.s; }
    friend auto dist(const L& l) { return dist(vec(l)); }
    friend double arg(const L& l) { return arg(vec(l)); } //
    ↪hash-cpp-1 = 3b47cb7801ce03c60d9e99647d747e3e
};

template <class T> Point<T> project(const L<T>& l, const
    ↪Point<T>& p) {
    Point<T> v = vec(l); // hash-cpp-2
    return l.s + v * dot(v, p - l.s) / dot2(v); // hash-cpp
    ↪-2 = 1648b2909b8a019a73d6dca8c2221821
}

template <class T> int ccw(const L<T>& l, const Point<T>& p
    ↪) {
    return ccw(l.s, l.t, p);
}

```

```

template <class T> bool insSL(const L<T>& s, const L<T>& l)
    ↪ {
    int a = ccw(l, s.s), b = ccw(l, s.t); // hash-cpp-3
    return (a % 2 == 0 || b % 2 == 0 || a != b); // hash-cpp
    ↪-3 = b9a91465128f28ef356c93ebaf83fe9a
}

template <class T> bool insSS(const L<T>& s, const L<T>& t)
    ↪ {
    int a = ccw(s, t.s), b = ccw(s, t.t), c = ccw(t, s.s),
    d = ccw(t, s.t); // hash-cpp-4
    return (a * b <= 0 && c * d <= 0); // hash-cpp-4 = 9
    ↪b7a89c2e911aa573091b5a1faa61c73
}

template <class T> double distLP(const L<T>& l, const Point
    ↪<T>& p) {
    return abs(crs(vec(l), p - l.s)) / dist(l);
} // hash-cpp-4 = d41d8cd98f00b204e9800998ecf8427e

template <class T> double distSP(const L<T>& s, const Point
    ↪<T>& p) {
    Point<T> q = project(s, p); // hash-cpp-5
    if (ccw(s, q) == 0) {
        return dist(p - q);
    } else {
        return min(dist(s.s - p), dist(s.t - p));
    } // hash-cpp-5 = 945f48b295abe750e175655b55622d68
}

template <class T> double distSS(const L<T>& s, const L<T>&
    ↪t) {
    if (insSS(s, t)) return 0; // hash-cpp-6
    return min({distSP(s, t.s), distSP(s, t.t), distSP(t, s.s
    ↪),
        distSP(t, s.t)}); // hash-cpp-6 = 137892
    ↪a1f3cc7267c5428d5afcd2f912
}

// TODO: usage
template <class T> int crossLL(const L<T>& l, const L<T>& m
    ↪, Point<T>& r) {
    Point<T> vl = vec(l), vm = vec(m); // hash-cpp-7
    T crl = crs(vl, vm), cr2 = crs(vl, l.t - m.s);
    if (sgn crs(vl, vm) == 0) {
        r = l.s;
        if (sgn crs(vec(l), l.t - m.s)) return 0;
        return -1;
    }
    r = m.s + vm * cr2 / crl;
    return 1; // hash-cpp-7 = 4
    ↪a241749cafeaf60a788de611ef3bfc7
}

// TODO usage
template <class T> int crossSS(const L<T>& l, const L<T>& m
    ↪, Point<T>& r) {
    int u = crossLL(l, m, r); // hash-cpp-8
    if (u == 0) return 0;
    if (u == -1) {
        r = max(min(l.s, l.t), min(m.s, m.t));
        Point<T> q = min(max(l.s, l.t), max(m.s, m.t));
        return (q < r) ? 0 : (q == r ? 1 : -1);
    }
    if (ccw(l, r) == 0 && ccw(m, r) == 0) return 1;
    return 0; // hash-cpp-8 =
    ↪fd35bfd104a3ff8b53a0830d8c5fb4de
}

```



```
} // namespace geometry
```

polygonal.hpp

Description: Polygon operations

"geometry/ccw.hpp", "geometry/linear.hpp"

127 lines

```
namespace geometry {
```

```
template <class T> T area2(const Vec<Point<T>>& pol) {
    if (pol.empty()) return 0; // hash-cpp-1
    T res = 0;
    auto a = pol.back();
    for (auto b : pol) {
        res += crs(a, b);
        a = b;
    }
    return res; // hash-cpp-1 = 775
    ↪ aelac4c8001aeb02f544d07a49976
}

// (1:left) | (2:right) is inside between v[i] -- v[i + 1]
template <class T>
Vec<pair<Point<T>, int>> insPolL(const Vec<Point<T>>& pol,
    ↪ const L<T>& l) {
    using Pi = pair<Point<T>, int>; // hash-cpp-2
    Vec<Pi> v;
    Point<T> a, b = pol.back();
    for (auto c : pol) {
        a = b;
        b = c;
        Point<T> p;
        if (crossLL({a, b}, l, p) != 1) continue;
        int sa = ccw(l, a) % 2, sb = ccw(l, b) % 2;
        if (sa > sb) swap(sa, sb);
        if (sa != 1 && sb == 1) v.push_back({p, 1});
        if (sa == -1 && sb != -1) v.push_back({p, 2});
    }
    sort(begin(v), end(v), [&](Pi x, Pi y) {
        auto vl = vec(l);
        return dot(vl, x.first - l.s) < dot(vl, y.first - l.s);
    });
    int m = int(size(v));
    Vec<Pi> res;
    for (int i = 0; i < m; i++) {
        if (i) v[i].second ^= v[i - 1].second;
        if (!res.empty() && res.back().first == v[i].first) res
            ↪ .pop_back();
        res.push_back(v[i]);
    }
    return res; // hash-cpp-2 =
    ↪ fa0aa36808c1117f5e0c435f1e650188
}
```

```
// 0: outside, 1: on line, 2: inside
template <class T> int contains(const Vec<Point<T>>& pol,
    ↪ const Point<T>& p) {
    if (pol.empty()) return 0; // hash-cpp-3
    int in = -1;
    Point<T> a_, b_ = pol.back();
    for (auto c : pol) {
        a_ = b_, b_ = c;
        Point<T> a = a_, b = b_;
        if (ccw(a, b, p) == 0) return 1;
        if (a.y > b.y) swap(a, b);
        if (!(a.y <= p.y && p.y < b.y)) continue;
        if (sgn(a.y, p.y) ? (crs(a - p, b - p) > 0) : (a.x > p.
            ↪ x)) in *= -1;
    }
```

```
}
return in + 1; // hash-cpp-3 = 9
    ↪ ba68a043a41b17dc2cfad19ed936b10
}

// pol: sorted and distinct
template <class T> Vec<Point<T>> convex_lower(const Vec<
    ↪ Point<T>>& pts) {
    assert(size(pts) >= 2); // hash-cpp-4
    Vec<Point<T>> res;
    for (auto d : pts) {
        while (size(res) > 1) {
            //if (ccw(res.end() [-2], res.end() [-1], d) != -1)
            ↪ break;
            if (ccw(res.end() [-2], res.end() [-1], d) == 1) break;
            res.pop_back();
        }
        res.push_back(d);
    }
    return res; // hash-cpp-4 = 62
    ↪ c051fd3c3066045c90f92f8c68e03f
}

template <class T> Vec<Point<T>> convex(Vec<Point<T>> pts)
    ↪ {
    sort(begin(pts), end(pts)); // hash-cpp-5
    pts.erase(unique(begin(pts), end(pts)), end(pts));
    if (size(pts) <= 1) return pts;
    Vec<Point<T>> lo = convex_lower(pts);
    reverse(begin(pts), end(pts));
    Vec<Point<T>> up = convex_lower(pts);
    lo.insert(begin(lo), begin(up) + 1, end(up) - 1);
    return lo; // hash-cpp-5 =
    ↪ af18b531b56e6e036e34231d4e170357
}

template <class T>
Vec<Point<T>> convex_cut(const Vec<Point<T>>& pol, const L<
    ↪ T>& l) {
    if (pol.empty()) return {}; // hash-cpp-6
    Vec<Point<T>> q;
    Point<T> a, b = pol.back();
    for (auto c : pol) {
        a = b, b = c;
        if ((ccw(l, a) % 2) * (ccw(l, b) % 2) < 0) {
            Point<T> buf;
            crossLL(l, L(a, b), buf);
            q.push_back(buf);
        }
        if (ccw(l, b) != -1) q.push_back(b);
    }
    return q; // hash-cpp-6 =
    ↪ b9b1502c04e92d079177d5fe2332a098
}

// pol: convex; this calls f(a, b) for each candidate (a, b
    ↪ )
template <class T, class F> void diameter(const Vec<Point<T>
    ↪ >> pol, F f) {
    int n = int(size(pol)); // hash-cpp-7
    if (n == 2) {
        f(pol[0], pol[1]);
        return;
    }
    int x = 0, y = 0;
    for (int i = 1; i < n; i++) {
        if (pol[i] < pol[x]) x = i;
        if (pol[y] < pol[i]) y = i;
    }
```

```
}
int sx = x, sy = y;
while (sx != y || sy != x) {
    f(pol[x], pol[y]);
    int nx = (x + 1 < n) ? x + 1 : 0, ny = (y + 1 < n) ? y
        ↪ + 1 : 0;
    if (crs(pol[nx] - pol[x], pol[ny] - pol[y]) < 0) {
        x = nx;
    } else {
        y = ny;
    }
} // hash-cpp-7 = af059874cebb4defb8479540d6cc0a64
}

// namespace geometry
```

circular.hpp

Description: Circle operations

"geometry/base.hpp", "geometry/linear.hpp"

102 lines

```
namespace geometry {
```

```
template <class T = double> struct C {
    using P = Point<T>;
    P c;
    T r;
    C(P c_ = P(), T r_ = T()) : c(c_), r(r_) {}

    friend P eval(const C& a, const double& angle) {
        return a.c + P::polar(a.r, angle);
    }
};

// NOT TESTED
// 0: outside; 1: on; 2: inside
template <class T> inline int contains(const C<T>& c, const
    ↪ Point<T>& p) {
    return sgn(c.r - dist(p - c.c)) + 1;
}

// 0-apart; 1-coincide;
// 2-a<b; 3-a<=b;
// 4-a>b; 5-a>=b;
// 6-a touches b; 7-a cross b
template <class T> inline int insCC(const C<T>& a, const C<
    ↪ T>& b) {
    T c = dist(a.c - b.c); // hash-cpp-1
    if (sgn(c) == 0 && sgn(a.r, b.r) == 0) return 1;
    int d = sgn(c + a.r - b.r);
    if (d <= 0) return d + 3;
    int e = sgn(c + b.r - a.r);
    if (e <= 0) return e + 5;
    int f = sgn(c - a.r - b.r);
    if (f <= 0) return -f + 6;
    return 0; // hash-cpp-1 = 61
    ↪ a31bab15e0280eeef65e91f68fbb64
}
```

```
template <class T>
inline C<T> incircle(const Point<T>& a, const Point<T>& b,
    ↪ const Point<T>& c) {
    T da = dist(b - c); // hash-cpp-2
    T db = dist(a - c);
    T dc = dist(a - b);
    T s = da + db + dc;
    return C((a * da + b * db + c * dc) / s,
        ↪ abs(crs(b - a, c - a)) / s); // hash-cpp-2 =
    ↪ d09688b6ea5a6265adc9f01e2eladd42
```

```

}

template <class T>
inline C<T> outcircle(const Point<T>& a, Point<T> b, Point<
    ↪T> c) {
    b -= a, c -= a; // hash-cpp-3
    T bb = dist2(b) / 2;
    T cc = dist2(c) / 2;
    T g = crs(b, c);
    T x = (bb * c.y - b.y * cc) / g;
    T y = (b.x * cc - bb * c.x) / g;
    T r = sqrt(x * x + y * y);
    x += a.x, y += a.y;
    return C(P(x, y), r); // hash-cpp-3 = 2
    ↪c91ea98a4cda854f4fa8655033c30f9
}

template <class T>
inline int crossCL(const C<T>& c, const L<T>& l, array<
    ↪Point<T>, 2>& res) {
    T u = distLP(l, c.c); // hash-cpp-4
    int t = sgn(u, c.r);
    if (t == 1) return 0;
    Point<T> v = project(l, c.c);
    Point<T> d = (t == 0 ? Point<T>(0, 0)
        : vec(l) * (sqrt(c.r * c.r - u * u) / dist(l))
        ↪);
    res = {v - d, v + d};
    return 1 - t; // hash-cpp-4 = 9845747
    ↪b9f30e2ef9396ccc9a677a456
}

// args of two intersections r, l seen by a.c,
// assuming two circles cross
template <class T>
inline pair<T, T> crossCC_args(const C<T>& a, const C<T>& b
    ↪) {
    Point<T> diff = b.c - a.c; // hash-cpp-5
    T c = arg(diff);
    T d = arg(a.r, dist(diff), b.r);
    return {c - d, c + d}; // hash-cpp-5 =
    ↪e8f0f4a9396b9a5ae56850fd644fa152
}

template <class T>
inline int crossCC(const C<T>& a, const C<T>& b, array<
    ↪Point<T>, 2>& res) {
    int t = insCC(a, b); // hash-cpp-6
    if (t == 0 || t == 1 || t == 2 || t == 4) return 0;
    auto [l, r] = crossCC_args(a, b);
    res = {eval(a, l), eval(a, r)};
    return 2 - (t == 3 || t == 5 || t == 6); // hash-cpp-6 =
    ↪56e3f5fa57011d34e17135616a072b98
}

template <class T>
inline int tangent(const C<T>& c, const Point<T>& p, array<
    ↪Point<T>, 2>& res) {
    Point<T> diff = p - c.c; // hash-cpp-7
    T dd = dist(diff);
    int t = sgn(c.r, dd);
    if (t == 1) return 0;
    T d = acos(min<T>(c.r / dd, 1));
    T a = arg(diff);
    res = {eval(c, a - d), eval(c, a + d)};
    return 1 - t; // hash-cpp-7 = 4220898
    ↪d66b628e02feef4e341179834
}

```

```

} // namespace geometry

```

closest-pair.hpp

Description: Given a set of points, returns an arbitrary closest pair of points.

"geometry/base.hpp" 54 lines

```

namespace geometry {

template <class T> using P = Point<T>;

// PRECONDITION: There are at least 2 points
template <class T, class F> inline void closest_pair(Vec<P<
    ↪T>> pts, F f) {
    int n = int(size(pts));
    using PT = P<T>;
    std::ranges::sort(pts, [](PT a, PT b) -> bool { return a.
        ↪x < b.x; });
    T d = std::numeric_limits<T>::max();

    auto st = multiset<PT, decltype([](PT a, PT b) { return a
        ↪.y < b.y; })>();
    auto its = Vec<typename decltype(st)::const_iterator>(
        ↪size(pts));

    auto update = [&](PT a, PT b) {
        T d2 = dist2(a - b);
        if (d2 < d) {
            d = d2;
            f(a, b);
        }
    };

    for (int i = 0, j = 0; i < n; i++) {
        PT p = pts[i];

        auto sq = [](T x) { return x * x; };
        while (j < i && sq(p.x - pts[j].x) >= d) {
            st.erase(its[j++]);
        }
        auto u = st.upper_bound(p);
        {
            auto t = u;
            while (true) {
                if (t == begin(st)) break;
                t = prev(t);
                update(*t, p);
                if (sq(p.y - t->y) >= d) break;
            }
        }
        auto t = u;
        while (true) {
            if (t == end(st)) break;
            if (sq(p.y - t->y) >= d) break;
            update(*t, p);
            t = next(t);
        }
        its[i] = st.emplace_hint(u, p);
    }
}

} // namespace geometry
// hash-cpp-all = f61a49795db13676d1c4b34fce0b00ad

```

Other (10)

two-sat.hpp

Description: Calculates a valid assignment to boolean variables a, b, c,... to a 2-SAT problem, so that an expression of the type $(a \vee b) \wedge (\neg a \vee c) \wedge (d \vee \neg b)$ becomes true, or reports that it is unsatisfiable. Negated variables are represented by bit inversions ($\sim x$)

Usage: TwoSat ts(number of boolean variables);
 ts.either(0, ~3); // Var 0 is true or var 3 is false
 ts.set_value(2); // Var 2 is true
 ts.at_most_one({0, ~1, 2}); // ≤ 1 of vars 0, ~1 and 2 are true
 ts.solve(); // Returns true iff it is solvable
 ts.values[0..N-1] holds the assigned values to the vars
Time: $O(N + E)$

"data-structure/flatten-vector.hpp" 62 lines

```

struct TwoSat {
    int n;
    Vec<pair<int, int>> edges;
    TwoSat(int n_ = 0) : n(n_) {}

    int add_var() { return n++; }
    void either(int a, int b) {
        a = max(2 * a, -1 - 2 * a);
        b = max(2 * b, -1 - 2 * b);
        edges.emplace_back(a ^ 1, b);
        edges.emplace_back(b ^ 1, a);
    }
    void set_value(int x) { either(x, x); }
    // NOT VERIFIED
    void at_most_one(const Vec<int>& vs) {
        if (size(vs) <= 1) return;
        int cur = ~vs[0];
        for (int v : vs | std::views::drop(2)) {
            int nxt = add_var();
            either(cur, ~v);
            either(cur, nxt);
            either(~v, nxt);
            cur = ~nxt;
        }
        either(cur, ~vs[1]);
    }

    Opt<Vec<i8>> solve() {
        auto r = Vec<i8>(n, -1);
        auto g = FlattenVector<int>(2 * n, std::move(edges));
        auto q = Vec<int>();
        auto bfs = [&](int s) -> bool {
            q.clear();
            q.push_back(s);
            r[s / 2] = !(s % 2);
            for (size_t z = 0; z < size(q); z++) {
                int v = q[z];
                for (int w : g.at(v)) {
                    if (r[w / 2] == -1) {
                        r[w / 2] = !(w % 2);
                        q.push_back(w);
                    } else if (r[w / 2] == w % 2) {
                        return false;
                    }
                }
            }
            return true;
        };
        for (int i = 0; i < n; i++) {
            if (r[i] != -1 || bfs(2 * i + 1)) {
                continue;
            }
        }
    }
}

```

```
    }
    for (int v : q) {
        r[v / 2] = -1;
    }
    if (!bfs(2 * i)) {
        return std::nullopt;
    }
}
return r;
}
}; // hash-cpp-all = c1189f33baf223e329d39785f061acc7
```

Appendix (11)

techniques.txt	159 lines	
Recursion		Combinatorics
Divide and conquer		Computation of binomial coefficients
Finding interesting points in N log N		Pigeon-hole principle
Algorithm analysis		Inclusion/exclusion
Master theorem		Catalan number
Amortized time complexity		Pick's theorem
Greedy algorithm		Number theory
Scheduling		Integer parts
Max contiguous subvector sum		Divisibility
Invariants		Euclidean algorithm
Huffman encoding		Modular arithmetic
Graph theory		* Modular multiplication
Dynamic graphs (extra book-keeping)		* Modular inverses
Breadth first search		* Modular exponentiation by squaring
Depth first search		Chinese remainder theorem
* Normal trees / DFS trees		Fermat's little theorem
Dijkstra's algorithm		Euler's theorem
MST: Prim's algorithm		Phi function
Bellman-Ford		Frobenius number
Konig's theorem and vertex cover		Quadratic reciprocity
Min-cost max flow		Pollard-Rho
Lovasz toggle		Miller-Rabin
Matrix tree theorem		Hensel lifting
Maximal matching, general graphs		Vieta root jumping
Hopcroft-Karp		Game theory
Hall's marriage theorem		Combinatorial games
Graphical sequences		Game trees
Floyd-Warshall		Mini-max
Euler cycles		Nim
Flow networks		Games on graphs
* Augmenting paths		Games on graphs with loops
* Edmonds-Karp		Grundy numbers
Bipartite matching		Bipartite games without repetition
Min. path cover		General games without repetition
Topological sorting		Alpha-beta pruning
Strongly connected components		Probability theory
2-SAT		Optimization
Cut vertices, cut-edges and biconnected components		Binary search
Edge coloring		Ternary search
* Trees		Unimodality and convex functions
Vertex coloring		Binary search on derivative
* Bipartite graphs (=> trees)		Numerical methods
* 3^n (special case of set cover)		Numeric integration
Diameter and centroid		Newton's method
K'th shortest path		Root-finding with binary/ternary search
Shortest cycle		Golden section search
Dynamic programming		Matrices
Knapsack		Gaussian elimination
Coin change		Exponentiation by squaring
Longest common subsequence		Sorting
Longest increasing subsequence		Radix sort
Number of paths in a dag		Geometry
Shortest path in a dag		Coordinates and vectors
Dynprog over intervals		* Cross product
Dynprog over subsets		* Scalar product
Dynprog over probabilities		Convex hull
Dynprog over trees		Polygon cut
3^n set cover		Closest pair
Divide and conquer		Coordinate-compression
Knuth optimization		Quadrees
Convex hull optimizations		KD-trees
RMQ (sparse table a.k.a 2^k-jumps)		All segment-segment intersection
Bitonic cycle		Sweeping
Log partitioning (loop over most restricted)		Discretization (convert to events and sweep)
		Angle sweeping
		Line sweeping
		Discrete second derivatives
		Strings
		Longest common substring
		Palindrome subsequences
		Knuth-Morris-Pratt
		Tries
		Rolling polynomial hashes
		Suffix array
		Suffix tree
		Aho-Corasick
		Manacher's algorithm
		Letter position lists
		Combinatorial search
		Meet in the middle
		Brute-force with pruning
		Best-first (A*)
		Bidirectional search
		Iterative deepening DFS / A*
		Data structures
		LCA (2^k-jumps in trees in general)
		Pull/push-technique on trees
		Heavy-light decomposition
		Centroid decomposition
		Lazy propagation
		Self-balancing trees
		Convex hull trick (wcipeg.com/wiki/Convex_hull_trick)
		Monotone queues / monotone stacks / sliding queues
		Sliding queue using 2 stacks
		Persistent segment tree