High Performance Computer Architectures Practical Course - Exercise 5 -

Tutorium 1

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May 22, 2023

1 Section XYZ

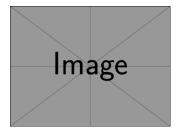


Figure 1: Output

```
1
    // SIMD calculations with Vc using dataSIMD3 as input
         (use cast here)
2
     TStopwatch timerSIMD3;
3
     for (int io = 0; io < NIterOut; io++)</pre>
4
       for (int i = 0; i < NVectors; i++)</pre>
5
         // Using reinterpret_cast we reinterpret the
6
             memory representation of the input data-
             structure as Vc vectors
7
         float_v &aV = *(reinterpret_cast < float_v *>(
             dataSIMD3.data[i].a));
8
         float_v &bV = *(reinterpret_cast<float_v *>(
             dataSIMD3.data[i].b));
9
         float_v &cV = *(reinterpret_cast < float_v *>(
             dataSIMD3.data[i].c));
10
         float_v &xV = *(reinterpret_cast < float_v *>(
             dataSIMD3.data[i].x));
11
12
         // We calculate the discriminant and roots here
             using SIMD operations
13
         const float_v det = bV * bV - 4 * aV * cV;
         xV = (-bV + sqrt(det)) / (2 * aV);
14
15
16
     timerSIMD3.Stop();
```

File 1: QuadraticEquation.cpp