# SfePy Documentation

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# 1 Notation

Ω	volume (sub)domain
Γ	surface (sub)domain
t	time
y any function	
$\underline{y}$	any vector function
<u>n</u>	unit outward normal
q, s	scalar test function
p, r	scalar unknown or parameter function
$\bar{p}$	scalar parameter function
$\underline{v}$	vector test function
$\underline{w}, \underline{u}$	vector unknown or parameter function
$\underline{b}$	vector parameter function
$\underline{\underline{e}}(\underline{u})$ Cauchy strain tensor $(\frac{1}{2}((\nabla u) + (\nabla u)^T))$	
$\underline{\underline{F}}$ deformation gradient $F_{ij} = \frac{\partial x_i}{\partial \partial X_j}$	
J	$\det(F)$
<u>C</u>	right Cauchy-Green deformation tensor $C = F^T F$
$\underline{\underline{E}}(\underline{u})$	Green strain tensor $E_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} + \frac{\partial u_m}{\partial x_i} \frac{\partial u_m}{\partial x_j} \right)$
$ \underline{\underline{\underline{E}}}(\underline{u}) \\ \underline{\underline{\underline{S}}} \\ \underline{\underline{f}} \\ \underline{f} $	second Piola-Kirchhoff stress tensor
$\underline{f}$	vector volume forces
f	scalar volume force (source)
ρ	density
$\nu$	kinematic viscosity
c	any constant
$\delta_{ij}, \underline{\underline{I}}$	Kronecker delta, identity matrix

The suffix  $"_0"$  denotes a quatity related to a previous time step. Term names are prefixed according to the following conventions:

dw	discrete weak	terms having a virtual (test) argument and zero or more unknown arguments, used for FE assembling
d	discrete	terms having all arguments known, the result is the scalar value of the integral
di	discrete integrated	like 'd' but the result is not a scalar (e.g. a vector)
dq	discrete quadrature	terms having all arguments known, the result are the values in quadrature points of elements
de	discrete element	terms having all arguments known, the result is a vector of integral averages over elements (element average of 'dq')

# 2 List of all terms

section	name	definition	
(13.1)	$d_biot_div$	$\int_{\Omega} r \; lpha_{ij} e_{ij}(\underline{w})$	
(6.1)	$d_{-}$ diffusion	$\int_{\Omega} K_{ij}  abla_i ar{p}  abla_j r$	
(7.1)	$d_{-}div$	$\int_{\Omega} ar{p} \;  abla \cdot \underline{w}$	
(12.1)	$d_{lin_elastic}$	$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{b}) e_{kl}(\underline{w})$	
(5.1)	$d\_surface\_dot$	$\int_{\Gamma} pr, \int_{\Gamma} \underline{u}\cdot \underline{w}$	
(5.2)	$d\_surface\_integrate$	$\int_{\Gamma} y$ , for vectors: $\int_{\Gamma} \underline{y} \cdot \underline{n}$	
(5.3)	$d_{-}$ volume	$\int_{\Omega} 1$	
(5.4)	$d\_volume\_dot$	$\int_{\Omega} pr,  \int_{\Omega} \underline{u} \cdot \underline{w}$	
(5.5)	$d\_volume\_integrate$	$\int_{\Omega} y$	
(5.6)	$d\_volume\_wdot$	$\int_{\Omega} y p r, \int_{\Omega} y \underline{u} \cdot \underline{w}$	
(5.7)	$de\_average\_variable$	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} y / \int_{T_K} 1$	
(12.2)	de_cauchy_strain	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} \underline{\underline{e}}(\underline{w}) / \int_{T_K} 1$	
(12.3)	$de\_cauchy\_stress$	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} D_{ijkl} e_k l(\underline{w}) / \int_{T_K} 1$	
(6.2)	$de\_diffusion\_velocity$	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} K_{ij} \nabla_j r / \int_{T_K} 1$	
(5.8)	$de\_volume\_average\_mat$	$\forall K \in \mathcal{T}_h: \int_{T_K} m / \int_{T_K} 1$	
(5.9)	$di\_volume\_integrate\_mat$	$\int_{\Omega} m$	
(7.2)	dq-grad	$(\nabla p) _{qp}$	
(7.3)	dq_lin_convect	$((\underline{b}\cdot abla)\underline{u}) _{qp}$	
(13.2)	$dw\_biot\_div$	$\int_{\Omega} q \; lpha_{ij} e_{ij}(\underline{u})$	
(13.3)	$dw\_biot\_div\_dt$	$\int_{\Omega} q  \alpha_{ij} \frac{e_{ij}(\underline{u}) - e_{ij}(\underline{u}_0)}{\Delta t}$	
(13.4)	$dw\_biot\_div\_th$	$\int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij}(t-\tau) \frac{\mathrm{d}e_{kl}(\underline{u}(\tau))}{\mathrm{d}\tau}  \mathrm{d}\tau \right] q$	
(13.5)	dw_biot_grad	$\int_{\Omega} p \; lpha_{ij} e_{ij}(\underline{v})$	
	$continued\dots$		

	$\dots continued$		
(13.6)	dw_biot_grad_dt	$\int_{\Omega} \frac{p-p_0}{\Delta t}  \alpha_{ij} e_{ij}(\underline{v})$	
(13.7)	dw_biot_grad_th	$\int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij}(t-\tau) p(\tau) \right] d\tau d\tau$	
(7.4)	dw_convect	$\int_{\Omega} ((\underline{u} \cdot \nabla)\underline{u}) \cdot \underline{v}$	
(6.3)	dw_diffusion	$\int_{\Omega} K_{ij} \nabla_i q \nabla_j p$	
(7.5)	dw_div	$\int_{\Omega} q \  abla \cdot \underline{u}$	
(7.6)	dw_div_grad	$\int_{\Omega}  u   abla \underline{v} :  abla \underline{u}$	
(7.7)	dw_grad	$\int_{\Omega} p \  abla \cdot \underline{v}$	
(7.8)	$dw_{grad_{dt}}$	$\int_{\Omega} rac{p-p_0}{\Delta t}  abla \cdot \underline{v}$	
(6.4)	dw_laplace	$c \int_{\Omega} \nabla s \cdot \nabla r$ or $\sum_{K \in \mathcal{T}_h} \int_{T_K} c_K \nabla s \cdot \nabla r$	
(7.9)	dw_lin_convect	$\int_{\Omega}((\underline{b}\cdot abla)\underline{u})\cdot\underline{v}$	
(12.4)	dw_lin_elastic	$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) e_{kl}(\underline{u})$	
(12.5)	dw_lin_elastic_iso	$\int_{\Omega} D_{ijkl}  e_{ij}(\underline{v}) e_{kl}(\underline{u}) \text{ with } D_{ijkl} = \mu(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk}) + \lambda  \delta_{ij}\delta_{kl}$	
(12.6)	dw_lin_viscous	$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) \frac{e_{kl}(\underline{u}) - e_{kl}(\underline{u}_0)}{\Delta t}$	
(12.7)	dw_lin_viscous_th	$\int_{\Omega} \left[ \int_{0}^{t} \mathcal{H}_{ijkl}(t-\tau)  \frac{\mathrm{d}e_{kl}(\underline{u}(\tau))}{\mathrm{d}\tau}  \mathrm{d}\tau \right]  e_{ij}(\underline{v})$	
(4.1)	dw_mass	$\int_{\Omega}  ho \underline{v} \cdot rac{\underline{u} - \underline{u}_0}{\Delta t}$	
(4.2)	dw_mass_scalar	$\int_{\Omega} q p$	
(4.3)	dw_mass_scalar_fine_coarse	$\int_{\Omega}q_{h}p_{H}$	
(4.4)	dw_mass_scalar_variable	$\int_{\Omega} cqp$	
(4.5)	dw_mass_vector	$\int_{\Omega} ho\; \underline{v}\cdot \underline{u}$	
(6.5)	dw_permeability_r	$\int_{\Omega} K_{ij} \nabla_j q$	
(9.1)	dw_point_lspring	$\underline{f}^i = -k\underline{u}^i  \forall \text{ FE node } i \text{ in region}$	
(7.10)	dw_st_grad_div	$\gamma \int_{\Omega} ( abla \cdot \underline{u}) \cdot ( abla \cdot \underline{v})$	
(7.11)	$dw_st_pspg_c$	$\sum_{K \in \mathcal{T}_h} \int_{T_K} \tau_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot \nabla q$	
(7.12)	$dw_st_pspg_p$	$\sum_{K \in \mathcal{T}_h} \int_{T_K} \tau_K \ \nabla p \cdot \nabla q$	
(7.13)	dw_st_supg_c	$\sum_{K \in \mathcal{T}_h} \int_{T_K} \delta_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot ((\underline{b} \cdot \nabla)\underline{v})$	
(7.14)	dw_st_supg_p	$\sum_{K \in \mathcal{T}_h} \int_{T_K} \delta_K  \nabla p \cdot ((\underline{b} \cdot \nabla) \underline{v})$	
(5.10)	$dw\_surface\_integrate$	$\int_{\Gamma} q$	
(11.1)	dw_surface_ltr	$\int_{\Gamma} \underline{v} \cdot \underline{\underline{\sigma}} \cdot \underline{n}$	
(8.1)	dw_tl_bulk_penalty	$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$	
(8.2)	dw_tl_he_mooney_rivlin	$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$	
(8.3)	dw_tl_he_neohook	$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$	
(5.11)	$dw\_volume\_integrate$	$\int_\Omega q$	
(10.1)	dw_volume_lvf	$\int_{\Omega} \underline{f} \cdot \underline{v} \text{ or } \int_{\Omega} fq$	
(5.12)	dw_volume_wdot	$\int_{\Omega} y q p, \int_{\Omega} y \underline{v} \cdot \underline{u}$	
(5.13)	dw_volume_wdot_dt	$\int_{\Omega} yq \frac{p-p_0}{\Delta t}, \int_{\Omega} y\underline{v} \cdot \frac{u-u_0}{\Delta t}$	
(5.14)	dw_volume_wdot_th	$\int_{\Omega} \left[ \int_{0}^{t} \mathcal{G}(t-\tau) p(\tau)  d\tau \right] q$	

# 3 Introduction

Equations in SfePy are built using terms, which correspond directly to the integral forms of weak formulation of a problem to be solved. As an example, let us consider the Laplace equation:

$$c\Delta t = 0 \text{ in } \Omega, \quad t = \bar{t} \text{ on } \Gamma.$$
 (1)

The weak formulation of (1) is: Find  $t \in V$ , such that

$$\int_{\Omega} c \, \nabla t : \nabla s = 0, \quad \forall s \in V_0 \,. \tag{2}$$

In the syntax used in SfePy input files, this can be written as

$$dw_laplace.i1.0mega(coef, s, t) = 0,$$
 (3)

which directly corresponds to the discrete version of (2): Find  $t \in V_h$ , such that

$$m{s}^T(\int_{\Omega_h} c \ m{G}^T m{G}) m{t} = 0, \quad orall m{s} \in V_{h0} \ ,$$

where  $\nabla u \approx \mathbf{G}\mathbf{u}$ . The integral over the discrete domain  $\Omega_h$  is approximated by a numerical quadrature, that is named i1 in our case.

### 3.1 Term call syntax

In general, the syntax of a term call in SfePy is:

where <i> denotes an integral name (i.e. a name of numerical quadrature to use) and <r> marks a region (domain of the integral). In the following, <virtual> corresponds to a test function, <state> to a unknown function and parameter> to a known function arguments. We will now describe all the terms available in SfePy to date.

# 4 Terms in termsMass

### 4.1 dw\_mass

Class: MassTerm

**Description**: Inertial forces term (constant density).

Definition:

$$\int_{\Omega} \rho \underline{v} \cdot \frac{\underline{u} - \underline{u}_0}{\Delta t}$$

Arguments:

material.rho	ρ
ts.dt	$\Delta t$
parameter	$\underline{u}_0$

 $Syntax: dw_mass. <i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )$ 

### 4.2 dw\_mass\_scalar

Class: MassScalarTerm

**Description**: Scalar field mass matrix/rezidual.

Definition:

 $\int_{\Omega} qp$ 

 $Syntax: dw_mass_scalar.<i>.<r>( <virtual>, <state> )$ 

### 4.3 dw\_mass\_scalar\_fine\_coarse

Class: MassScalarFineCoarseTerm

**Description**: Scalar field mass matrix/rezidual for coarse to fine grid interpolation. Field  $p_H$ 

belong to the coarse grid, test field  $q_h$  to the fine grid.

**Definition**:

 $\int_{\Omega} q_h p_H$ 

Syntax: dw\_mass\_scalar\_fine\_coarse.<i>.<r>( <virtual>, <state>, <iemaps>, <pbase> )

# 4.4 dw\_mass\_scalar\_variable

Class: MassScalarVariableTerm

**Description**: Scalar field mass matrix/rezidual with coefficient c defined in nodes.

Definition:

 $\int_{\Omega} cqp$ 

Syntax: dw\_mass\_scalar\_variable.<i>.<r>( <material>, <virtual>, <state> )

### 4.5 dw\_mass\_vector

Class: MassVectorTerm

**Description**: Vector field mass matrix/rezidual.

Definition:

 $\int_{\Omega} \rho \ \underline{v} \cdot \underline{u}$ 

Syntax: dw\_mass\_vector.<i>.<r>( <material>, <virtual>, <state> )

# 5 Terms in termsBasic

# 5.1 d\_surface\_dot

 ${\bf Class:}\ Dot Product Surface Term$ 

**Description**: Surface  $L^2(\Gamma)$  dot product for both scalar and vector fields.

Definition:

 $\int_{\Gamma} pr, \int_{\Gamma} \underline{u} \cdot \underline{w}$ 

Syntax: d\_surface\_dot.<i>.<r>( <parameter\_1>, <parameter\_2> )

# 5.2 d\_surface\_integrate

Class: IntegrateSurfaceTerm

Definition:

 $\int_{\Gamma} y$ , for vectors:  $\int_{\Gamma} y \cdot \underline{n}$ 

Syntax: d\_surface\_integrate.<i>.<r>( cparameter> )

### 5.3 d\_volume

Class: VolumeTerm

**Description**: Volume of a domain. Uses approximation of the parameter variable.

Definition:

 $\int_{\Omega} 1$ 

### 5.4 d\_volume\_dot

 ${\bf Class:}\ {\bf DotProductVolumeTerm}$ 

**Description**: Volume  $L^2(\Omega)$  dot product for both scalar and vector fields.

**Definition**:

 $\int_{\Omega} pr, \int_{\Omega} \underline{u} \cdot \underline{w}$ 

Syntax: d\_volume\_dot.<i>.<r>( cparameter\_1>, cparameter\_2> )

# 5.5 d\_volume\_integrate

Class: IntegrateVolumeTerm

Definition:

 $\int_{\Omega} y$ 

Syntax: d\_volume\_integrate.<i>.<r>(

### 5.6 d\_volume\_wdot

Class: WDotProductVolumeTerm

**Description**: Volume  $L^2(\Omega)$  weighted dot product for both scalar and vector fields.

Definition:

 $\int_{\Omega} ypr, \int_{\Omega} y\underline{u} \cdot \underline{w}$ 

**Arguments**:

material weight function y

Syntax: d\_volume\_wdot.<i>.<r>( <material>, <parameter\_1>, <parameter\_2> )

# 5.7 de\_average\_variable

Class: AverageVariableTerm

**Description**: Variable y averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h: \int_{T_K} y/\int_{T_K} 1$$

Syntax: de\_average\_variable.<i>.<r>( cparameter> )

# 5.8 de\_volume\_average\_mat

Class: AverageVolumeMatTerm

**Description**: Material parameter m averaged in elements. Uses approximation of y variable.

**Definition**:

$$\forall K \in \mathcal{T}_h : \int_{T_K} m / \int_{T_K} 1$$

### **Arguments**:

material	m (can have up to two dimensions)
parameter shape	y shape of material parameter pa-
snape	rameter
mode	'const' or 'vertex' or 'ele- ment_avg'

Syntax: de\_volume\_average\_mat.<i>.<r>( <material>, <parameter>, <shape>, <mode> )

# 5.9 di\_volume\_integrate\_mat

 ${\bf Class:}\ {\bf IntegrateVolumeMatTerm}$ 

**Description**: Integrate material parameter m over a domain. Uses approximation of y variable.

**Definition**:

$$\int_{\Omega} m$$

### **Arguments**:

material	m (can have up to two dimensions)
parameter shape	y shape of material parameter parameter
mode	'const' or 'vertex' or 'ele- ment_avg'

Syntax: di\_volume\_integrate\_mat.<i>.<r>( <material>, <parameter>, <shape>, <mode> )

# 5.10 dw\_surface\_integrate

Class: IntegrateSurfaceOperatorTerm

Definition:

 $\int_{\Gamma} q$ 

Syntax: dw\_surface\_integrate.<i>.<r>( <material>, <virtual> )

### 5.11 dw\_volume\_integrate

Class: IntegrateVolumeOperatorTerm

**Definition**:

 $\int_{\Omega} q$ 

 $Syntax: dw_volume_integrate.<i>.<r>( <virtual> )$ 

### 5.12 dw\_volume\_wdot

 ${\bf Class: \ WDotProductVolumeOperatorTerm}$ 

**Description**: Volume  $L^2(\Omega)$  weighted dot product operator for scalar and vector (not imple-

mented!) fields. **Definition**:

 $\int_{\Omega} yqp, \int_{\Omega} y\underline{v} \cdot \underline{u}$ 

**Arguments**:

material weight function $y$
------------------------------

 $Syntax: \ \, dw\_volume\_wdot. <i>.<r>( <material>, <virtual>, <state> )$ 

### 5.13 dw\_volume\_wdot\_dt

Class: WDotProductVolumeOperatorDtTerm

**Description**: Volume  $L^2(\Omega)$  weighted dot product operator for scalar and vector (not implemented!) fields.

Definition:

$$\int_{\Omega} yq \frac{p-p_0}{\Delta t}, \int_{\Omega} y\underline{v} \cdot \frac{\underline{u}-\underline{u}_0}{\Delta t}$$

**Arguments**:

	. 1 . 2
material	weight function $y$

Syntax: dw\_volume\_wdot\_dt.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

### 5.14 dw\_volume\_wdot\_th

 ${\bf Class:}\ {\bf WDotProductVolumeOperatorTHTerm}$ 

**Definition**:

$$\int_{\Omega} \left[ \int_0^t \mathcal{G}(t-\tau) p(\tau) \, d\tau \right] q$$

Syntax: dw\_volume\_wdot\_th.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

# 6 Terms in termsLaplace

### 6.1 d\_diffusion

 ${\bf Class:}\ {\bf DiffusionIntegratedTerm}$ 

**Description**: Integrated general diffusion term with permeability  $K_{ij}$  constant or given in mesh

vertices. **Definition**:

$$\int_{\Omega} K_{ij} \nabla_i \bar{p} \nabla_j r$$

Syntax: d\_diffusion.<i>.<r>( <material>, <parameter\_1>, <parameter\_2> )

# 6.2 de\_diffusion\_velocity

Class: DiffusionVelocityTerm

**Description**: Diffusion velocity averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h: \int_{T_K} K_{ij} \nabla_j r / \int_{T_K} 1$$

Syntax: de\_diffusion\_velocity.<i>.<r>( <material>, <parameter> )

### 6.3 dw\_diffusion

Class: DiffusionTerm

**Description**: General diffusion term with permeability  $K_{ij}$  constant or given in mesh vertices.

**Definition**:

$$\int_{\Omega} K_{ij} \nabla_i q \nabla_j p$$

Syntax: dw\_diffusion.<i>.<r>( <material>, <virtual>, <state> )

### 6.4 dw\_laplace

Class: LaplaceTerm

**Description**: Laplace term with c constant or constant per element.

Definition:

$$c \int_{\Omega} \nabla s \cdot \nabla r$$
 or  $\sum_{K \in \mathcal{T}_h} \int_{T_K} c_K \nabla s \cdot \nabla r$ 

Syntax: dw\_laplace.<i>.<r>( <material>, <virtual>, <state> )

# $6.5 ext{ dw_permeability_r}$

Class: PermeabilityRTerm

**Description**: Special-purpose diffusion-like term with permeability  $K_{ij}$  constant or given in mesh vertices (to use on a right-hand side).

Definition:

$$\int_{\Omega} K_{ij} \nabla_j q$$

Syntax: dw\_permeability\_r.<i>.<r>( <material>, <virtual>, <index> )

# 7 Terms in termsNavierStokes

# $7.1 d_{-}div$

 ${\bf Class:}\ {\bf DivIntegratedTerm}$ 

**Description**: Integrated divergence term (weak form).

Definition:

$$\int_{\Omega} \bar{p} \, \nabla \cdot \underline{w}$$

Syntax: d\_div.<i>.<r>( <parameter\_1>, <parameter\_2> )

# 7.2 dq\_grad

Class: GradQTerm

**Description**: Gradient term (weak form) in quadrature points.

Definition:

$$(\nabla p)|_{qp}$$

Syntax: dq\_grad.<i>.<r>( <state> )

# 7.3 dq\_lin\_convect

Class: LinearConvectQTerm

**Description**: Linearized convective term evaluated in quadrature points.

**Definition**:

$$((\underline{b} \cdot \nabla)\underline{u})|_{qp}$$

Syntax: dq\_lin\_convect.<i>.<r>( <parameter>, <state> )

# 7.4 dw\_convect

Class: ConvectTerm

**Description**: Nonlinear convective term.

**Definition**:

$$\int_{\Omega} ((\underline{u} \cdot \nabla)\underline{u}) \cdot \underline{v}$$

Syntax: dw\_convect.<i>.<r>( <virtual>, <state> )

### $7.5 \, \mathrm{dw_div}$

Class: DivTerm

**Description**: Divergence term (weak form).

**Definition**:

$$\int_{\Omega} q \nabla \cdot \underline{u}$$

Syntax: dw\_div.<i>.<r>( <virtual>, <state> )

# 7.6 dw\_div\_grad

Class: DivGradTerm

**Description**: Diffusion term.

Definition:

$$\int_{\Omega} \nu \ \nabla \underline{v} : \nabla \underline{u}$$

Syntax: dw\_div\_grad.<i>.<r>( <material>, <virtual>, <state> )

# 7.7 dw\_grad

Class: GradTerm

**Description**: Gradient term (weak form).

Definition:

$$\int_{\Omega} p \, \nabla \cdot \underline{v}$$

Syntax: dw\_grad.<i>.<r>( <virtual>, <state> )

# $7.8 \, dw_{grad_dt}$

Class: GradDtTerm

**Description**: Gradient term (weak form) with time-discretized  $\dot{p}$ .

**Definition:** 

$$\int_{\Omega} \frac{p - p_0}{\Delta t} \nabla \cdot \underline{v}$$

**Arguments**:

ts.dt	$\Delta t$
parameter	$p_0$

Syntax: dw\_grad\_dt.<i>.<r>( <ts>, <virtual>, <state>, <parameter> )

### 7.9 dw\_lin\_convect

Class: LinearConvectTerm

**Description**: Linearized convective term.

Definition:

$$\int_{\Omega} ((\underline{b} \cdot \nabla)\underline{u}) \cdot \underline{v}$$

Syntax: dw\_lin\_convect.<i>.<r>( <virtual>, <parameter>, <state> )

# 7.10 dw\_st\_grad\_div

Class: GradDivStabilizationTerm

**Description**: Grad-div stabilization term ( $\gamma$  is a global stabilization parameter).

Definition:

$$\gamma \int_{\Omega} (\nabla \cdot \underline{u}) \cdot (\nabla \cdot \underline{v})$$

Syntax: dw\_st\_grad\_div.<i>.<r>( <material>, <virtual>, <state> )

### $7.11 \quad dw_st_pspg_c$

Class: PSPGCStabilizationTerm

**Description:** PSPG stabilization term, convective part ( $\tau$  is a local stabilization parameter).

Definition:

$$\sum_{K \in \mathcal{T}_h} \int_{T_K} \tau_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot \nabla q$$

Syntax: dw\_st\_pspg\_c.<i>.<r>( <material>, <virtual>, <parameter>, <state> )

#### 7.12 $dw_st_pspg_p$

Class: PSPGPStabilizationTerm

**Description:** PSPG stabilization term, pressure part ( $\tau$  is a local stabilization parameter), alias

to Laplace term dw\_laplace.

Definition:

$$\sum_{K \in \mathcal{T}_h} \int_{T_K} \tau_K \ \nabla p \cdot \nabla q$$

Syntax: dw\_st\_pspg\_p.<i>.<r>( <material>, <virtual>, <state> )

#### 7.13 dw\_st\_supg\_c

Class: SUPGCStabilizationTerm

**Description**: SUPG stabilization term, convective part ( $\delta$  is a local stabilization parameter).

Definition:

$$\sum_{K \in \mathcal{T}_h} \int_{T_K} \delta_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot ((\underline{b} \cdot \nabla)\underline{v})$$

Syntax: dw\_st\_supg\_c.<i>.<r>( <material>, <virtual>, <parameter>, <state> )

#### 7.14dw\_st\_supg\_p

Class: SUPGPStabilizationTerm

**Description**: SUPG stabilization term, pressure part ( $\delta$  is a local stabilization parameter).

Definition:

$$\sum_{K \in \mathcal{T}_h} \int_{T_K} \delta_K \ \nabla p \cdot ((\underline{b} \cdot \nabla) \underline{v})$$

Syntax: dw\_st\_supg\_p.<i>.<r>( <material>, <virtual>, <parameter>, <state> )

#### Terms in termsHyperElasticity 8

#### 8.1 dw\_tl\_bulk\_penalty

Class: BulkPenaltyTerm

**Description**: Hyperelastic bulk penalty term. Stress  $S_{ij} = K(J-1) J C_{ij}^{-1}$ .

**Definition:** 

$$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$$

Syntax: dw\_tl\_bulk\_penalty.<i>.<r>( <material>, <virtual>, <state> )

#### 8.2 dw\_tl\_he\_mooney\_rivlin

Class: MooneyRivlinTerm

**Description**: Hyperelastic Mooney-Rivlin term. Effective stress  $S_{ij} = \kappa J^{-\frac{4}{3}} (C_{kk} \delta_{ij} - C_{ij} \frac{2}{3}I_2C_{ij}^{-1}$ ). **Definition**:

$$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$$

Syntax: dw\_tl\_he\_mooney\_rivlin.<i>.<r>( <material>, <virtual>, <state> )

### 8.3 dw\_tl\_he\_neohook

Class: NeoHookeanTerm

**Description**: Hyperelastic neo-Hookean term. Effective stress  $S_{ij} = \mu J^{-\frac{2}{3}} (\delta_{ij} - \frac{1}{3} C_{kk} C_{ij}^{-1})$ .

Definition:

$$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$$

Syntax: dw\_tl\_he\_neohook.<i>.<r>( <material>, <virtual>, <state> )

### 9 Terms in termsPoint

# 9.1 dw\_point\_lspring

Class: LinearPointSpringTerm

Description: Linear springs constraining movement of FE nodes in a reagion; use as a relaxed

Dirichlet boundary conditions.

**Definition**:

$$\underline{f}^i = -k\underline{u}^i \quad \forall \text{ FE node } i \text{ in region}$$

 $Syntax: \ \, dw\_point\_lspring. <i>.<r>( <material>, <virtual>, <state> )$ 

# 10 Terms in termsVolume

### 10.1 dw volume lyf

Class: LinearVolumeForceTerm

**Description**: Vector or scalar linear volume forces (weak form) — a right-hand side source term.

**Definition**:

$$\int_{\Omega} \underline{f} \cdot \underline{v} \text{ or } \int_{\Omega} fq$$

Syntax: dw\_volume\_lvf.<i>.<r>( <material>, <virtual> )

# 11 Terms in termsSurface

# 11.1 dw\_surface\_ltr

Class: LinearTractionTerm

**Description**: Linear traction forces (weak form), where, depending on dimension of 'material' argument,  $\underline{\sigma} \cdot \underline{n}$  is  $\bar{p}\underline{\underline{I}} \cdot \underline{n}$  for a given scalar pressure,  $\underline{f}$  for a traction vector, and itself for a stress tensor.

Definition:

$$\int_{\Gamma} \underline{v} \cdot \underline{\underline{\sigma}} \cdot \underline{n}$$

Syntax: dw\_surface\_ltr.<i>.<r>( <material>, <virtual> )

# 12 Terms in termsLinElasticity

### 12.1 d lin elastic

Class: LinearElasticIntegratedTerm

**Description**: Integrated general linear elasticity term.

Definition:

$$\int_{\Omega} D_{ijkl} e_{ij}(\underline{b}) e_{kl}(\underline{w})$$

Syntax: d\_lin\_elastic.<i>.<r>( <material>, <parameter\_1>, <parameter\_2> )

# 12.2 de\_cauchy\_strain

Class: CauchyStrainTerm

**Description**: Cauchy strain tensor averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h : \int_{T_K} \underline{\underline{e}}(\underline{w}) / \int_{T_K} 1$$

Syntax: de\_cauchy\_strain.<i>.<r>>( <parameter> )

# 12.3 de\_cauchy\_stress

Class: CauchyStressTerm

**Description**: Cauchy stress tensor averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h: \int_{T_K} D_{ijkl} e_k l(\underline{w}) / \int_{T_K} 1$$

Syntax: de\_cauchy\_stress.<i>.<r>( <material>, <parameter> )

### 12.4 dw\_lin\_elastic

Class: LinearElasticTerm

**Description**: General linear elasticity term, with  $D_{ijkl}$  given in the usual matrix form exploiting symmetry: in 3D it is  $6 \times 6$  with the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it is  $3 \times 3$  with the indices ordered as [11, 22, 12].

Definition:

$$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) e_{kl}(\underline{u})$$

Syntax: dw\_lin\_elastic.<i>.<r>( <material>, <virtual>, <state> )

### 12.5 dw\_lin\_elastic\_iso

Class: LinearElasticIsotropicTerm

**Description**: Isotropic linear elasticity term.

Definition:

$$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) e_{kl}(\underline{u}) \text{ with } D_{ijkl} = \mu(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk}) + \lambda \ \delta_{ij}\delta_{kl}$$

Syntax: dw\_lin\_elastic\_iso.<i>.<r>( <material>, <virtual>, <state> )

### 12.6 dw\_lin\_viscous

Class: LinearViscousTerm

**Description**: General linear viscosity term, with  $D_{ijkl}$  given in the usual matrix form exploiting symmetry: in 3D it is  $6 \times 6$  with the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it is  $3 \times 3$  with the indices ordered as [11, 22, 12].

**Definition**:

$$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) \frac{e_{kl}(\underline{u}) - e_{kl}(\underline{u}_0)}{\Delta t}$$

Arguments:

ts.dt	$\Delta t$	
material	$D_{ijkl}$	
continued		

$\dots continued$		
virtual	$\underline{v}$	
state	$\underline{u}$ (displacements of current time step)	
parameter	$\underline{u}_0$ (known displacements of previous time step)	

Syntax: dw\_lin\_viscous.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

### 12.7 dw\_lin\_viscous\_th

Class: LinearViscousTHTerm

Definition:

$$\int_{\Omega} \left[ \int_{0}^{t} \mathcal{H}_{ijkl}(t-\tau) \, \frac{\mathrm{d}e_{kl}(\underline{u}(\tau))}{\mathrm{d}\tau} \, \mathrm{d}\tau \right] \, e_{ij}(\underline{v})$$

Syntax: dw\_lin\_viscous\_th.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

# 13 Terms in termsBiot

### 13.1 d\_biot\_div

Class: BiotDivRIntegratedTerm

**Description**: Integrated Biot divergence-like term (weak form) with  $\alpha_{ij}$  given in vector form exploiting symmetry: in 3D it has the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it has the indices ordered as [11, 22, 12].

**Definition**:

$$\int_{\Omega} r \, \alpha_{ij} e_{ij}(\underline{w})$$

Syntax: d\_biot\_div.<i>.<r>( <material>, <parameter\_1>, <parameter\_2> )

### 13.2 dw\_biot\_div

Class: BiotDivTerm

**Description**: Biot divergence-like term (weak form) with  $\alpha_{ij}$  given in vector form exploiting symmetry: in 3D it has the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it has the indices ordered as [11, 22, 12].

**Definition**:

$$\int_{\Omega} q \, \alpha_{ij} e_{ij}(\underline{u})$$

Syntax: dw\_biot\_div.<i>.<r>( <material>, <virtual>, <state> )

### 13.3 dw\_biot\_div\_dt

Class: BiotDivDtTerm

**Description**: Biot divergence-like rate term (weak form) with  $\alpha_{ij}$  given in vector form exploiting symmetry: in 3D it has the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it has the indices ordered as [11, 22, 12].

**Definition**:

$$\int_{\Omega} q \, \alpha_{ij} \frac{e_{ij}(\underline{u}) - e_{ij}(\underline{u_0})}{\Delta t}$$

Syntax: dw\_biot\_div\_dt.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

# 13.4 dw\_biot\_div\_th

Class: BiotDivTHTerm

**Definition**:

$$\int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij} (t - \tau) \frac{\mathrm{d}e_{kl}(\underline{u}(\tau))}{\mathrm{d}\tau} \, \mathrm{d}\tau \right] q$$

Syntax: dw\_biot\_div\_th.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

### 13.5 dw\_biot\_grad

Class: BiotGradTerm

**Description**: Biot gradient-like term (weak form) with  $\alpha_{ij}$  given in vector form exploiting symmetry: in 3D it has the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it has the indices ordered

as [11, 22, 12]. **Definition**:

$$\int_{\Omega} p \ \alpha_{ij} e_{ij}(\underline{v})$$

Syntax: dw\_biot\_grad.<i>.<r>( <material>, <virtual>, <state> )

### 13.6 dw\_biot\_grad\_dt

Class: BiotGradDtTerm

**Description**: Biot gradient-like term (weak form) with time-discretized  $\dot{p}$  and  $\alpha_{ij}$  given in vector form exploiting symmetry: in 3D it has the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it has the indices ordered as [11, 22, 12].

**Definition:** 

$$\int_{\Omega} \frac{p - p_0}{\Delta t} \ \alpha_{ij} e_{ij}(\underline{v})$$

**Arguments**:

ts.dt	$\Delta t$
parameter	$p_0$

Syntax: dw\_biot\_grad\_dt.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

# 13.7 dw\_biot\_grad\_th

Class: BiotGradTHTerm

Definition:

$$\int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij}(t-\tau) p(\tau) \right) d\tau \right] e_{ij}(\underline{v})$$

Syntax: dw\_biot\_grad\_th.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

# 14 Term caches in cachesFiniteStrain

# 14.1 finite\_strain\_tl

Class: FiniteStrainTLDataCache

cache = term.get\_cache( 'finite\_strain\_tl', <index> )

data = cache( <data name>, <ig>, <ih>, state )

# 15 Term caches in cachesBasic

# 15.1 cauchy\_strain

```
Class: CauchyStrainDataCache
cache = term.get_cache( 'cauchy_strain', <index> )
data = cache( <data name>, <ig>>, <ih>>, state )
```

### 15.2 div\_vector

```
Class: DivVectorDataCache
cache = term.get_cache( 'div_vector', <index> )
data = cache( <data name>, <ig>>, <ih>>, state )
```

# 15.3 grad\_scalar

```
Class: GradScalarDataCache
cache = term.get_cache( 'grad_scalar', <index> )
data = cache( <data name>, <ig>>, <ih>>, state )
```

### 15.4 grad\_vector

```
Class: GradVectorDataCache
cache = term.get_cache( 'grad_vector', <index> )
data = cache( <data name>, <ig>>, <ih>>, state )
```

### $15.5 \quad \text{mat\_in\_qp}$

```
Class: MatInQPDataCache
cache = term.get_cache( 'mat_in_qp', <index> )
data = cache( <data name>, <ig>>, <ih>>, mat, ap, assumed_shapes, mode_in )
```

### 15.6 state\_in\_surface\_qp

```
Class: StateInSurfaceQPDataCache
cache = term.get_cache( 'state_in_surface_qp', <index> )
data = cache( <data name>, <ig>, <ih>>, state )
```

# 15.7 state\_in\_volume\_qp

```
Class: StateInVolumeQPDataCache
cache = term.get_cache( 'state_in_volume_qp', <index> )
data = cache( <data name>, <ig>, <ih>, state )
```

### 15.8 volume

```
Class: VolumeDataCache
cache = term.get_cache( 'volume', <index> )
data = cache( <data name>, <ig>>, <ih>>, region, field )
```