# SfePy Documentation

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# 1 Notation

Ω	$\Omega$ volume (sub)domain	
Γ	Γ surface (sub)domain	
continued		

$\dots continued$		
t	time	
y	any function	
$\underline{y}$	any vector function	
$\underline{n}$	unit outward normal	
q, s	scalar test function	
p, r	scalar unknown or parameter function	
$\bar{p}$	scalar parameter function	
$\underline{v}$	vector test function	
$\underline{w}, \underline{u}$	vector unknown or parameter function	
<u>b</u>	vector parameter function	
$\underline{\underline{e}}(\underline{u})$	Cauchy strain tensor $(\frac{1}{2}((\nabla u) + (\nabla u)^T))$	
<u>F</u>	deformation gradient $F_{ij} = \frac{\partial x_i}{\partial \partial X_j}$	
J	$\det(F)$	
<u>C</u>	right Cauchy-Green deformation tensor $C = F^T F$	
$\underline{\underline{E}}(\underline{u})$	Green strain tensor $E_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} + \frac{\partial u_m}{\partial x_i} \frac{\partial u_m}{\partial x_j} \right)$	
$ \underline{\underline{\underline{E}}}(\underline{\underline{u}}) \\ \underline{\underline{\underline{S}}} \\ \underline{\underline{f}} $	second Piola-Kirchhoff stress tensor	
<u>f</u>	vector volume forces	
f	scalar volume force (source)	
$\rho$	density	
$\nu$	kinematic viscosity	
c	any constant	
$\delta_{ij}, \underline{\underline{I}}$	Kronecker delta, identity matrix	

The suffix  $"_0"$  denotes a quatity related to a previous time step. Term names are prefixed according to the following conventions:

dw	discrete weak	terms having a virtual (test) argument and zero or more unknown arguments, used for FE assembling
d	discrete	terms having all arguments known, the result is the scalar value of the integral
di	discrete integrated	like 'd' but the result is not a scalar (e.g. a vector)
dq	discrete quadrature	terms having all arguments known, the result are the values in quadrature points of elements
de	discrete element	terms having all arguments known, the result is a vector of integral averages over elements (element average of 'dq')

# 2 List of all terms

section	name	definition	
(5.5)	de_average_variable	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} y / \int_{T_K} 1$	
(14.1)	dw_biot	$\int_{\Omega} p \; \alpha_{ij} e_{ij}(\underline{v}), \; \int_{\Omega} q \; \alpha_{ij} e_{ij}(\underline{u})$	
(14.2)	dw_biot_th	$\int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij}(t-\tau) p(\tau) \right) d\tau \right] e_{ij}(\underline{v}),$	
		$\int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij}(t-\tau) e_{kl}(\underline{u}(\tau))  d\tau \right] q$	
(13.1)	de_cauchy_strain	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} \underline{\underline{e}}(\underline{w}) / \int_{T_K} 1$	
(13.2)	de_cauchy_stress	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} D_{ijkl} e_k l(\underline{w}) / \int_{T_K} 1$	
(7.3)	dw_convect	$\int_{\Omega}((\underline{u}\cdot abla)\underline{u})\cdot\underline{v}$	
(6.2)	dw_diffusion	$\int_{\Omega} K_{ij} \nabla_i q \nabla_j p,  \int_{\Omega} K_{ij} \nabla_i \bar{p} \nabla_j r$	
(6.1)	de_diffusion_velocity	vector of $\forall K \in \mathcal{T}_h : \int_{T_K} K_{ij} \nabla_j r / \int_{T_K} 1$	
(7.4)	dw_div_grad	$\int_{\Omega}  u    abla \underline{v} :  abla \underline{u}$	
(7.1)	$dq_{-grad}$	$(\nabla p) _{qp}$	
(6.3)	dw_laplace	$c \int_{\Omega} \nabla s \cdot \nabla r \text{ or } \sum_{K \in \mathcal{T}_h} \int_{T_K} c_K \nabla s \cdot \nabla r$	
(7.2)	dq_lin_convect	$((\underline{b}\cdot abla)\underline{u}) _{qp}$	
(7.5)	dw_lin_convect	$\int_{\Omega}((\underline{b}\cdot abla)\underline{u})\cdot\underline{v}$	
(13.3)	dw_lin_elastic	$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) e_{kl}(\underline{u})$	
(13.4)	dw_lin_elastic_iso	$\int_{\Omega} D_{ijkl} e_{ij}(\underline{v}) e_{kl}(\underline{u}) \text{ with } D_{ijkl} = \mu(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk}) + \lambda \delta_{ij}\delta_{kl}$	
(13.5)	dw_lin_elastic_th	$\int_{\Omega} \left[ \int_{0}^{t} \mathcal{H}_{ijkl}(t-\tau)  \frac{\mathrm{d}e_{kl}(\underline{u}(\tau))}{\mathrm{d}\tau}  \mathrm{d}\tau \right]  e_{ij}(\underline{v})$	
(4.1)	dw_mass	$\int_{\Omega} \rho \underline{v} \cdot \frac{\underline{u} - \underline{u}_0}{\Delta t}$	
(4.2)	dw_mass_scalar	$\int_{\Omega}qp$	
(4.3)	dw_mass_scalar_fine_coarse	$\int_{\Omega}q_{h}p_{H}$	
(4.4)	dw_mass_scalar_variable	$\int_{\Omega} cqp$	
(4.5)	dw_mass_vector	$\int_{\Omega}  ho \ \underline{v} \cdot \underline{u}$	
(6.4)	dw_permeability_r	$\int_{\Omega} K_{ij} \nabla_j q$	
(11.1)	dw_piezo_coupling	$\int_{\Omega} g_{kij} \ e_{ij}(\underline{u}) \nabla_k q, \ \int_{\Omega} g_{kij} \ e_{ij}(\underline{v}) \nabla_k p$	
(9.1)	dw_point_lspring	$\underline{f}^i = -k\underline{u}^i  \forall \text{ FE node } i \text{ in region}$	
(7.6)	dw_st_grad_div	$\gamma \int_{\Omega} (\nabla \cdot \underline{u}) \cdot (\nabla \cdot \underline{v})$	
(7.7)	$dw_st_pspg_c$	$\sum_{K \in \mathcal{T}_h} \int_{T_K} \tau_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot \nabla q$	
(7.8)	dw_st_pspg_p	$\sum_{K \in \mathcal{I}_h} \int_{T_K} \tau_K \ \nabla p \cdot \nabla q$	
(7.9)	dw_st_supg_c	$\sum_{K \in \mathcal{T}_h} \int_{T_K} \delta_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot ((\underline{b} \cdot \nabla)\underline{v})$	
(7.10)	dw_st_supg_p	$\sum_{K \in \mathcal{I}_h} \int_{T_K} \delta_K \ \nabla p \cdot ((\underline{b} \cdot \nabla) \underline{v})$	
(7.11)	dw_stokes	$\int_{\Omega} p \ \nabla \cdot \underline{v}, \ \int_{\Omega} q \ \nabla \cdot \underline{u}$	
(5.1)	d_surface_dot	$\int_{\Gamma} pr, \int_{\Gamma} \underline{u} \cdot \underline{w}$	
(5.9)	$dw\_surface\_integrate$	$\int_{\Gamma} q$	
	$continued\dots$		

	$\dots continued$		
(5.2)	d_surface_integrate	$\int_{\Gamma} y$ , for vectors: $\int_{\Gamma} \underline{y} \cdot \underline{n}$	
(12.1)	dw_surface_ltr	$\int_{\Gamma} \underline{v} \cdot \underline{\underline{\sigma}} \cdot \underline{n}$	
(8.1)	$dw_tl_bulk_penalty$	$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$	
(8.2)	dw_tl_he_mooney_rivlin	$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$	
(8.3)	$dw_tl_he_neohook$	$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$	
(5.3)	$d_{-}$ volume	$\int_{\Omega} 1$	
(5.6)	de_volume_average_mat	$\forall K \in \mathcal{T}_h: \int_{T_K} m/\int_{T_K} 1$	
(5.4)	$d_{volume_dot}$	$\int_{\Omega} pr,  \int_{\Omega} \underline{u} \cdot \underline{w}$	
(5.10)	$dw_volume_integrate$	$\int_{\Omega}q$	
(5.7)	di_volume_integrate	$\int_{\Omega}y,\int_{\Omega}\underline{y}$	
(5.8)	di_volume_integrate_mat	$\int_{\Omega} m$	
(10.1)	$dw_volume_volu$	$\int_{\Omega} \underline{f} \cdot \underline{v} \text{ or } \int_{\Omega} fq$	
(5.11)	$dw_volume_wdot$	$\int_{\Omega} yqp,  \int_{\Omega} y\underline{v} \cdot \underline{u},  \int_{\Omega} ypr,  \int_{\Omega} y\underline{u} \cdot \underline{w}$	
(5.12)	$dw\_volume\_wdot\_scalar\_th$	$\int_{\Omega} \left[ \int_{0}^{t} \mathcal{G}(t-\tau) p(\tau)  d\tau \right] q$	

# 3 Introduction

Equations in SfePy are built using terms, which correspond directly to the integral forms of weak formulation of a problem to be solved. As an example, let us consider the Laplace equation in time interval  $t \in [0, t_{\text{final}}]$ :

$$\frac{\partial T}{\partial t} + c\Delta T = 0 \text{ in } \Omega, \quad T(t) = \bar{T}(t) \text{ on } \Gamma.$$
 (1)

The weak formulation of (1) is: Find  $T \in V$ , such that

$$\int_{\Omega} s \frac{\partial T}{\partial t} + \int_{\Omega} c \, \nabla T : \nabla s = 0, \quad \forall s \in V_0 \,, \tag{2}$$

where we assume no fluxes over  $\partial\Omega\setminus\Gamma$ . In the syntax used in SfePy input files, this can be written as

 $dw_mass_scalar.i1.0mega(s, dT/dt) + dw_laplace.i1.0mega(coef, s, T) = 0, (3)$ 

which directly corresponds to the discrete version of (2): Find  $T \in V_h$ , such that

$$m{s}^T(\int_{\Omega_h} m{\phi}^T m{\phi}) rac{\partial m{T}}{\partial t} + m{s}^T(\int_{\Omega_h} c \; m{G}^T m{G}) m{T} = 0, \quad orall m{s} \in V_{h0} \; ,$$

where  $u \approx \phi u$ ,  $\nabla u \approx G u$  for  $u \in \{s, T\}$ . The integrals over the discrete domain  $\Omega_h$  are approximated by a numerical quadrature, that is named i1 in our case.

## 3.1 Term call syntax

In general, the syntax of a term call in SfePy is:

where <i> denotes an integral name (i.e. a name of numerical quadrature to use) and <r> marks a region (domain of the integral). In the following, <virtual> corresponds to a test function, <state> to a unknown function and parameter> to a known function arguments. We will now describe all the terms available in SfePy to date.

## 4 Terms in termsMass

#### $4.1 \, dw_{mass}$

Class: MassTerm

**Description**: Inertial forces term (constant density).

**Definition:** 

$$\int_{\Omega} \rho \underline{v} \cdot \frac{\underline{u} - \underline{u}_0}{\Delta t}$$

**Arguments**:

material.rho	ρ
ts.dt	$\Delta t$
parameter	$\underline{u}_0$

Syntax: dw\_mass.<i>.<r>( <ts>, <material>, <virtual>, <state>, <parameter> )

## 4.2 dw\_mass\_scalar

Class: MassScalarTerm

**Description**: Scalar field mass matrix/rezidual.

**Definition**:

 $\int_{\Omega} qp$ 

Syntax: dw\_mass\_scalar.<i>.<r>( <virtual>, <state> )

### 4.3 dw\_mass\_scalar\_fine\_coarse

Class: MassScalarFineCoarseTerm

**Description**: Scalar field mass matrix/rezidual for coarse to fine grid interpolation. Field  $p_H$  belong to the coarse grid, test field  $q_h$  to the fine grid.

**Definition**:

 $\int_{\Omega} q_h p_H$ 

Syntax: dw\_mass\_scalar\_fine\_coarse.<i>.<r>( <virtual>, <state>, <iemaps>, <pbase> )

### 4.4 dw\_mass\_scalar\_variable

Class: MassScalarVariableTerm

**Description**: Scalar field mass matrix/rezidual with coefficient c defined in nodes.

**Definition:** 

 $\int_{\Omega} cqp$ 

Syntax: dw\_mass\_scalar\_variable.<i>.<r>< ( <material>, <virtual>, <state> )

## 4.5 dw\_mass\_vector

Class: MassVectorTerm

**Description**: Vector field mass matrix/rezidual.

Definition:

$$\int_{\Omega} \rho \ \underline{v} \cdot \underline{u}$$

 $Syntax: dw_mass_vector.<i>.<r>( <material>, <virtual>, <state> )$ 

# 5 Terms in termsBasic

#### 5.1 d\_surface\_dot

 ${\bf Class:}\ {\bf DotProductSurfaceTerm}$ 

**Description**: Surface  $L^2(\Gamma)$  dot product for both scalar and vector fields.

**Definition**:

$$\int_{\Gamma} pr, \int_{\Gamma} \underline{u} \cdot \underline{w}$$

Syntax: d\_surface\_dot.<i>.<r>( <parameter\_1>, <parameter\_2> )

# 5.2 d\_surface\_integrate

Class: IntegrateSurfaceTerm

Definition:

$$\int_{\Gamma} y$$
, for vectors:  $\int_{\Gamma} \underline{y} \cdot \underline{n}$ 

Syntax: d\_surface\_integrate.<i>.<r>(

### 5.3 d volume

Class: VolumeTerm

**Description**: Volume of a domain. Uses approximation of the parameter variable.

Definition:

$$\int_{\Omega} 1$$

Syntax: d\_volume.<i>.<r>(

# 5.4 d\_volume\_dot

 ${\bf Class:}\ {\bf DotProductVolumeTerm}$ 

**Description**: Volume  $L^2(\Omega)$  dot product for both scalar and vector fields.

Definition:

$$\int_{\Omega} pr, \int_{\Omega} \underline{u} \cdot \underline{w}$$

Syntax: d\_volume\_dot.<i>.<r>( cparameter\_1>, , cparameter\_2> )

## 5.5 de\_average\_variable

Class: AverageVariableTerm

**Description**: Variable y averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h: \int_{T_K} y/\int_{T_K} 1$$

Syntax: de\_average\_variable.<i>.<r>( <parameter> )

# 5.6 de\_volume\_average\_mat

Class: AverageVolumeMatTerm

**Description**: Material parameter m averaged in elements. Uses approximation of y variable.

**Definition**:

$$\forall K \in \mathcal{T}_h : \int_{T_K} m / \int_{T_K} 1$$

## Arguments:

material	m (can have up to two dimensions)
parameter	y
shape	shape of material parameter parameter
mode	'const' or 'vertex' or 'ele- ment_avg'

 $Syntax: \ \, \texttt{de\_volume\_average\_mat.<i>.<r>}( \ \, \texttt{<material>}, \ \, \texttt{<parameter>}, \ \, \texttt{<mode>})$ 

# 5.7 di\_volume\_integrate

Class: IntegrateVolumeTerm

**Definition**:

$$\int_{\Omega} y$$
,  $\int_{\Omega} y$ 

Syntax: di\_volume\_integrate.<i>.<r>( cparameter> )

# 5.8 di\_volume\_integrate\_mat

 ${\bf Class:}\ {\bf IntegrateVolumeMatTerm}$ 

**Description**: Integrate material parameter m over a domain. Uses approximation of y variable.

**Definition:** 

$$\int_{\Omega} m$$

## **Arguments**:

material	m (can have up to two dimensions)
parameter	y
shape	shape of material parameter parameter
mode	'const' or 'vertex' or 'ele- ment_avg'

Syntax: di\_volume\_integrate\_mat.<i>.<r>( <material>, <parameter>, <shape>, <mode> )

# 5.9 dw\_surface\_integrate

Class: IntegrateSurfaceOperatorTerm

**Definition**:

 $\int_{\Gamma} q$ 

Syntax: dw\_surface\_integrate.<i>.<r>( <material>, <virtual> )

# 5.10 dw\_volume\_integrate

Class: IntegrateVolumeOperatorTerm

Definition:

 $\int_{\Omega} q$ 

Syntax: dw\_volume\_integrate.<i>.<r>( <virtual> )

### 5.11 dw\_volume\_wdot

Class: WDotProductVolumeTerm

**Description**: Volume  $L^2(\Omega)$  weighted dot product for both scalar and vector (not implemented

in weak form!) fields. Can be evaluated. Can use derivatives.

**Definition**:

 $\int_{\Omega} yqp, \int_{\Omega} y\underline{v} \cdot \underline{u}, \int_{\Omega} ypr, \int_{\Omega} y\underline{u} \cdot \underline{w}$ 

**Arguments:** 

material weight function y

Syntax: dw\_volume\_wdot.<i>.<r>( <arguments> ) where <arguments> is one of:

<material>, <virtual>, <state>
<material>, <parameter\_1>, <parameter\_2>

#### 5.12 dw\_volume\_wdot\_scalar\_th

 ${\bf Class: \ WDot SProduct Volume Operator TH Term}$ 

**Description**: Fading memory volume  $L^2(\Omega)$  weighted dot product for scalar fields. Can use

derivatives. **Definition**:

 $\int_{\Omega} \left[ \int_0^t \mathcal{G}(t-\tau) p(\tau) \, d\tau \right] q$ 

Syntax: dw\_volume\_wdot\_scalar\_th.<i>.<r>( <ts>, <material>, <virtual>, <state> )

# 6 Terms in termsLaplace

## 6.1 de\_diffusion\_velocity

Class: DiffusionVelocityTerm

**Description**: Diffusion velocity averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h : \int_{T_K} K_{ij} \nabla_j r / \int_{T_K} 1$$

Syntax: de\_diffusion\_velocity.<i>.<r>( <material>, <parameter> )

## 6.2 dw\_diffusion

Class: DiffusionTerm

**Description**: General diffusion term with permeability  $K_{ij}$  constant or given in mesh vertices.

Can be evaluated. Can use derivatives.

Definition:

$$\int_{\Omega} K_{ij} \nabla_i q \nabla_j p$$
,  $\int_{\Omega} K_{ij} \nabla_i \bar{p} \nabla_j r$ 

Syntax: dw\_diffusion.<i>.<r>( <arguments> ) where <arguments> is one of:

<material>, <virtual>, <state>
<material>, <parameter\_1>, <parameter\_2>

## 6.3 dw\_laplace

Class: LaplaceTerm

**Description**: Laplace term with c constant or constant per element.

Definition:

$$c \int_{\Omega} \nabla s \cdot \nabla r$$
 or  $\sum_{K \in \mathcal{T}_h} \int_{T_K} c_K \ \nabla s \cdot \nabla r$ 

Syntax: dw\_laplace.<i>.<r>( <material>, <virtual>, <state> )

# $6.4 \, dw_permeability_r$

Class: PermeabilityRTerm

**Description**: Special-purpose diffusion-like term with permeability  $K_{ij}$  constant or given in mesh

vertices (to use on a right-hand side).

**Definition**:

$$\int_{\Omega} K_{ij} \nabla_j q$$

Syntax: dw\_permeability\_r.<i>.<r>( <material>, <virtual>, <index> )

# 7 Terms in termsNavierStokes

## $7.1 dq_grad$

Class: GradQTerm

**Description**: Gradient term (weak form) in quadrature points.

**Definition**:

$$(\nabla p)|_{ap}$$

Syntax: dq\_grad.<i>.<r>( <state> )

## 7.2 dq\_lin\_convect

Class: LinearConvectQTerm

**Description**: Linearized convective term evaluated in quadrature points.

**Definition**:

$$((\underline{b} \cdot \nabla)\underline{u})|_{ap}$$

Syntax: dq\_lin\_convect.<i>.<r>(

## 7.3 dw\_convect

Class: ConvectTerm

**Description**: Nonlinear convective term.

Definition:

$$\int_{\Omega} ((\underline{u} \cdot \nabla)\underline{u}) \cdot \underline{v}$$

Syntax: dw\_convect.<i>.<r>( <virtual>, <state> )

## 7.4 dw\_div\_grad

Class: DivGradTerm

**Description**: Diffusion term.

**Definition:** 

$$\int_{\Omega} \nu \, \nabla \underline{v} : \nabla \underline{u}$$

Syntax: dw\_div\_grad.<i>.<r>( <material>, <virtual>, <state> )

## 7.5 dw\_lin\_convect

Class: LinearConvectTerm

**Description**: Linearized convective term.

**Definition:** 

$$\int_{\Omega} ((\underline{b} \cdot \nabla) \underline{u}) \cdot \underline{v}$$

Syntax: dw\_lin\_convect.<i>.<r>( <virtual>, <parameter>, <state> )

# 7.6 dw\_st\_grad\_div

Class: GradDivStabilizationTerm

**Description**: Grad-div stabilization term ( $\gamma$  is a global stabilization parameter).

**Definition**:

$$\gamma \int_{\Omega} (\nabla \cdot \underline{u}) \cdot (\nabla \cdot \underline{v})$$

Syntax: dw\_st\_grad\_div.<i>.<r>( <material>, <virtual>, <state> )

# $7.7 ext{ dw\_st\_pspg\_c}$

Class: PSPGCStabilizationTerm

**Description:** PSPG stabilization term, convective part ( $\tau$  is a local stabilization parameter).

**Definition**:

$$\sum_{K \in \mathcal{T}_b} \int_{\mathcal{T}_K} \tau_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot \nabla q$$

Syntax: dw\_st\_pspg\_c.<i>.<r>( <material>, <virtual>, <parameter>, <state> )

## $7.8 ext{dw_st_pspg_p}$

Class: PSPGPStabilizationTerm

**Description:** PSPG stabilization term, pressure part ( $\tau$  is a local stabilization parameter), alias

to Laplace term dw\_laplace.

Definition:

$$\sum_{K \in \mathcal{T}_h} \int_{T_K} \tau_K \ \nabla p \cdot \nabla q$$

Syntax: dw\_st\_pspg\_p.<i>.<r>( <material>, <virtual>, <state> )

# $7.9 ext{ dw\_st\_supg\_c}$

Class: SUPGCStabilizationTerm

**Description**: SUPG stabilization term, convective part ( $\delta$  is a local stabilization parameter).

Definition:

$$\sum_{K \in \mathcal{T}_b} \int_{\mathcal{T}_K} \delta_K \ ((\underline{b} \cdot \nabla)\underline{u}) \cdot ((\underline{b} \cdot \nabla)\underline{v})$$

Syntax: dw\_st\_supg\_c.<i>.<r>( <material>, <virtual>, <parameter>, <state> )

# $7.10 \quad dw_st_supg_p$

Class: SUPGPStabilizationTerm

**Description**: SUPG stabilization term, pressure part ( $\delta$  is a local stabilization parameter).

**Definition**:

$$\sum_{K \in \mathcal{T}_h} \int_{\mathcal{T}_K} \delta_K \ \nabla p \cdot ((\underline{b} \cdot \nabla)\underline{v})$$

Syntax: dw\_st\_supg\_p.<i>.<r>( <material>, <virtual>, <parameter>, <state> )

#### 7.11 dw\_stokes

Class: StokesTerm

Description: Stokes problem coupling term. Corresponds to weak forms of gradient and diver-

gence terms. Can be evaluated.

Definition:

$$\int_{\Omega} p \ \nabla \cdot \underline{v}, \ \int_{\Omega} q \ \nabla \cdot \underline{u}$$

Syntax: dw\_stokes.<i>.<r>( <arguments> ) where <arguments> is one of:

# 8 Terms in termsHyperElasticity

## 8.1 dw\_tl\_bulk\_penalty

Class: BulkPenaltyTerm

**Description**: Hyperelastic bulk penalty term. Stress  $S_{ij} = K(J-1) J C_{ij}^{-1}$ .

Definition:

$$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$$

Syntax: dw\_tl\_bulk\_penalty.<i>.<r>( <material>, <virtual>, <state> )

### 8.2 dw\_tl\_he\_mooney\_rivlin

Class: MooneyRivlinTerm

**Description**: Hyperelastic Mooney-Rivlin term. Effective stress  $S_{ij} = \kappa J^{-\frac{4}{3}} (C_{kk} \delta_{ij} - C_{ij} - \frac{2}{3} I_2 C_{ij}^{-1})$ .

Definition:

$$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$$

Syntax: dw\_tl\_he\_mooney\_rivlin.<i>.<r>( <material>, <virtual>, <state> )

## 8.3 dw\_tl\_he\_neohook

Class: NeoHookeanTerm

**Description**: Hyperelastic neo-Hookean term. Effective stress  $S_{ij} = \mu J^{-\frac{2}{3}} (\delta_{ij} - \frac{1}{3} C_{kk} C_{ij}^{-1})$ .

Definition:

$$\int_{\Omega} S_{ij}(\underline{u}) \delta E_{ij}(\underline{u};\underline{v})$$

Syntax: dw\_tl\_he\_neohook.<i>.<r>( <material>, <virtual>, <state> )

# 9 Terms in termsPoint

## 9.1 dw\_point\_lspring

Class: LinearPointSpringTerm

Description: Linear springs constraining movement of FE nodes in a reagion; use as a relaxed

Dirichlet boundary conditions.

**Definition**:

$$\underline{f}^i = -k\underline{u}^i \quad \forall \text{ FE node } i \text{ in region}$$

 $Syntax: \ \, dw\_point\_lspring. <i>.<r>( <material>, <virtual>, <state> )$ 

# 10 Terms in termsVolume

## 10.1 dw\_volume\_lvf

 ${\bf Class:}\ {\bf Linear Volume Force Term}$ 

**Description**: Vector or scalar linear volume forces (weak form) — a right-hand side source term.

Definition:

$$\int_{\Omega} f \cdot \underline{v} \text{ or } \int_{\Omega} fq$$

Syntax: dw\_volume\_lvf.<i>.<r>( <material>, <virtual> )

# 11 Terms in termsPiezo

# 11.1 dw\_piezo\_coupling

Class: PiezoCouplingTerm

**Description**: Piezoelectric coupling term.

Definition:

$$\int_{\Omega} g_{kij} e_{ij}(\underline{u}) \nabla_k q$$
,  $\int_{\Omega} g_{kij} e_{ij}(\underline{v}) \nabla_k p$ 

Syntax: dw\_piezo\_coupling.<i>.<r>( <arguments> ) where <arguments> is one of:

<material>, <virtual>, <state> <material>, <state>, <virtual>

# 12 Terms in termsSurface

### 12.1 dw\_surface\_ltr

Class: LinearTractionTerm

**Description**: Linear traction forces (weak form), where, depending on dimension of 'material' argument,  $\underline{\underline{\sigma}} \cdot \underline{\underline{n}}$  is  $\underline{\bar{p}}\underline{\underline{I}} \cdot \underline{\underline{n}}$  for a given scalar pressure,  $\underline{\underline{f}}$  for a traction vector, and itself for a stress tensor.

Definition:

$$\int_{\Gamma} \underline{v} \cdot \underline{\underline{\sigma}} \cdot \underline{n}$$

Syntax: dw\_surface\_ltr.<i>.<r>( <material>, <virtual> )

# 13 Terms in termsLinElasticity

## 13.1 de\_cauchy\_strain

Class: CauchyStrainTerm

**Description**: Cauchy strain tensor averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h: \int_{\mathcal{T}_K} \underline{\underline{e}}(\underline{w}) / \int_{\mathcal{T}_K} 1$$

# 13.2 de\_cauchy\_stress

Class: CauchyStressTerm

**Description**: Cauchy stress tensor averaged in elements.

**Definition**: vector of

$$\forall K \in \mathcal{T}_h: \int_{T_K} D_{ijkl} e_k l(\underline{w}) / \int_{T_K} 1$$

Syntax: de\_cauchy\_stress.<i>.<r>( <material>, <parameter> )

#### 13.3 dw\_lin\_elastic

Class: LinearElasticTerm

**Description**: General linear elasticity term, with  $D_{ijkl}$  given in the usual matrix form exploiting symmetry: in 3D it is  $6 \times 6$  with the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it is  $3 \times 3$  with the indices ordered as [11, 22, 12]. Can be evaluated. Can use derivatives.

**Definition**:

$$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) e_{kl}(\underline{u})$$

Syntax: dw\_lin\_elastic.<i>.<r>( <arguments> ) where <arguments> is one of:

## 13.4 dw\_lin\_elastic\_iso

Class: LinearElasticIsotropicTerm

**Description**: Isotropic linear elasticity term.

Definition:

$$\int_{\Omega} D_{ijkl} \ e_{ij}(\underline{v}) e_{kl}(\underline{u}) \text{ with } D_{ijkl} = \mu(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk}) + \lambda \ \delta_{ij}\delta_{kl}$$

Syntax: dw\_lin\_elastic\_iso.<i>.<r>( <material>, <virtual>, <state> )

## 13.5 dw\_lin\_elastic\_th

Class: LinearElasticTHTerm

**Definition**:

$$\int_{\Omega} \left[ \int_{0}^{t} \mathcal{H}_{ijkl}(t-\tau) \, \frac{\mathrm{d}e_{kl}(\underline{u}(\tau))}{\mathrm{d}\tau} \, \mathrm{d}\tau \right] \, e_{ij}(\underline{v})$$

Syntax: dw\_lin\_elastic\_th.<i>.<r>( <ts>, <material>, <virtual>, <state> )

# 14 Terms in termsBiot

#### 14.1 dw\_biot

Class: BiotTerm

**Description**: Biot coupling term with  $\alpha_{ij}$  given in vector form exploiting symmetry: in 3D it has the indices ordered as [11, 22, 33, 12, 13, 23], in 2D it has the indices ordered as [11, 22, 33, 12, 13, 23]. Corresponds to weak forms of Biot gradient and divergence terms. Can be evaluated.

**Definition**:

$$\int_{\Omega} p \ \alpha_{ij} e_{ij}(\underline{v}), \ \int_{\Omega} q \ \alpha_{ij} e_{ij}(\underline{u})$$

Syntax: dw\_biot.<i>.<r>( <arguments> ) where <arguments> is one of:

#### 14.2 dw\_biot\_th

Class: BiotTHTerm

**Description**: Can have time derivatives.

Definition:

$$\int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij}(t-\tau) p(\tau) \right) d\tau \right] e_{ij}(\underline{v}), \int_{\Omega} \left[ \int_{0}^{t} \alpha_{ij}(t-\tau) e_{kl}(\underline{u}(\tau)) d\tau \right] q$$

Syntax: dw\_biot\_th.<i>>.<r>( <arguments> ) where <arguments> is one of:

<ts>, <material>, <virtual>, <state> <ts>, <material>, <state>, <virtual>

## 15 Term caches in cachesFiniteStrain

#### 15.1 finite\_strain\_tl

Class: FiniteStrainTLDataCache

cache = term.get\_cache( 'finite\_strain\_tl', <index> )
data = cache( <data name>, <ig>, <ih>, state )

## 16 Term caches in cachesBasic

## 16.1 cauchy\_strain

Class: CauchyStrainDataCache

cache = term.get\_cache( 'cauchy\_strain', <index> )

data = cache( <data name>, <ig>, <ih>, state, get\_vector )

## 16.2 div\_vector

```
Class: DivVectorDataCache
cache = term.get_cache( 'div_vector', <index> )
data = cache( <data name>, <ig>, <ih>, state )
```

## 16.3 grad\_scalar

```
Class: GradScalarDataCache
cache = term.get_cache( 'grad_scalar', <index> )
data = cache( <data name>, <ig>>, <ih>>, state )
```

# $16.4 \quad grad\_vector$

```
Class: GradVectorDataCache
cache = term.get_cache( 'grad_vector', <index> )
data = cache( <data name>, <ig>, <ih>, state )
```

# 16.5 mat\_in\_qp

```
Class: MatInQPDataCache
cache = term.get_cache( 'mat_in_qp', <index> )
data = cache( <data name>, <ig>>, <ih>>, mat, ap, assumed_shapes, mode_in )
```

# 16.6 state\_in\_surface\_qp

```
Class: StateInSurfaceQPDataCache
cache = term.get_cache( 'state_in_surface_qp', <index> )
data = cache( <data name>, <ig>, <ih>>, state )
```

# 16.7 state\_in\_volume\_qp

```
Class: StateInVolumeQPDataCache
cache = term.get_cache( 'state_in_volume_qp', <index> )
data = cache( <data name>, <ig>>, <ih>>, state, get_vector )
```

#### 16.8 volume

```
Class: VolumeDataCache
cache = term.get_cache( 'volume', <index> )
data = cache( <data name>, <ig>>, <ih>>, region, field )
```