Computer Systems Week 4 Lab

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Theory Questions

What is ROM and what is its primary purpose?

ROM is short for "Read Only Memory" and as the name implies, it is memory that you can only read from. ROM is generally used for things like storing the BIOS of a system since you only want to be reading from it where writing over it could be potentially catastrophic to the system's operation.

What is RAM and how is it different from ROM?

RAM is short for "Random Access Memory", which as the name insists allows for quick random access of information from memory. The main difference between it and ROM is that RAM is volatile, meaning that it loses all information when it loses power, which ROM is non-volatile.

What is the difference between static RAM and dynamic RAM?

The main differences between the two types of RAM are that static RAM loses its state once it loses power while dynamic RAM keeps its state as long as it is periodically given more power and static RAM requires a larger area of silicon per byte compared to dynamic RAM.

What type of memory is typically used in USB thumb drives? Why shouldn't we rely on this for critical data storage?

USB drives typically use a type of memory called electrical erasable read only memory, or EEPROM for short. Over time, the memory itself will degrade and then eventually fail. This can be mitigated somewhat by use of wear levelling logic but eventually it will finally fail, losing access to any data you may have had on the drive which makes it not very suitable for critical data storage.

Consider a computer with 1GB of RAM (1024MB). Given memory addressing is for each byte, how many bits are needed to address all bytes in the system's RAM?

You would require 30 bits to address every word in the 1GB of RAM. This can be calculated with the formula log2(n), where is the amount of bytes being addressed.

Give a brief description of the Von Neumann and Harvard computing architectures. What are the fundamental differences between the two and for what is each designed to achieve?

The high level difference between the two architectures is that Von Nuemann stores the instruction memory and data memory in the same location while the Harvard architecture stores it in two separate physical areas of memory. Von Nuemann allows for cheaper and more extensible production but has both speed and security issues because of the shared memory space and bus. Harvard then solves this with the two separate physical areas of memory which also inherently means that there are two separate buses for the two areas of memory. This offers both security and speed but then sacrifices the extensibility of the architecture, which in turn makes it more expensive to produce.

What is cache memory and what is its primary role?

Cache memory is memory that is stored extremely close to the CPU, giving it easy and fast access to it. Cache memory is generally used for anything that the CPU needs quick access to such as recently used variables.

Explain the concept of an interrupt and list four common types

Interrupts are how we can better interact with hardware such as peripherals that might be connected to your system. It works by the device sending an interrupt signal to the CPU which will then stop what it's doing to handle the interrupt. Common types of interrupts include:

- Errors
- Input devices (mouse/keyboard)
- Networking
- Exceptions

Briefly explain polling and why it is not commonly used

Polling is an alternative to how interrupts work. Instead of handling interrupts as they come in, polling works by essentially "checking in" with each component to see how things are going at a fixed rate. If anything needs to have something handled, then the CPU will handle it. Because polling happens at a constant rate, this means that it is

always using CPU time as opposed to interrupts which will only use CPU time as it is required.

Explain the general concept of a stack – how do they work, and what is their primary purpose

Stacks are a data structure that allows you to store a collection of data. It works by pushing data on top of the stack and then popping it off the top. Stacks are very common when we want to store a set of instructions that we wish to execute in a specific order.

How are stacks useful for handling interrupts?

When an interrupt signal is received the CPU will actually push the current task it is working on to the stack so it can access it later. When it is done handling the interrupt it will then pop the next task off the stack so it can continue where it left off before.

How are stacks useful in programming?

Stacks in programming are useful if you have a particular way you wish to be able to access the data within a collection, like for example if you wanted to program in a deck of cards that you are able to draw only from the top of.

Practical Questions

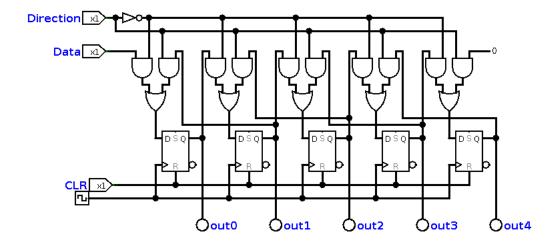


Figure 1: 5 bit deep 1 bit wide stack

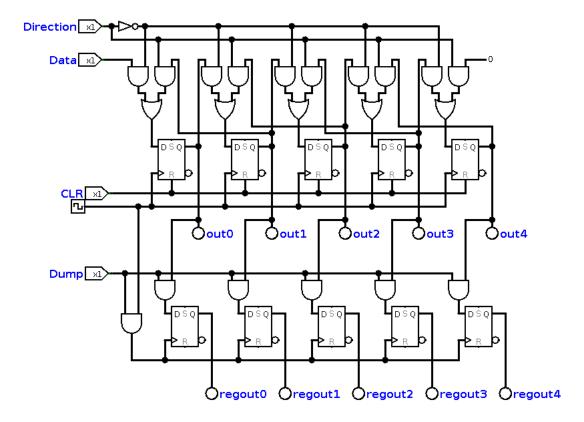


Figure 2: 5 bit deep 1 bit wide stack with parallel dump to register