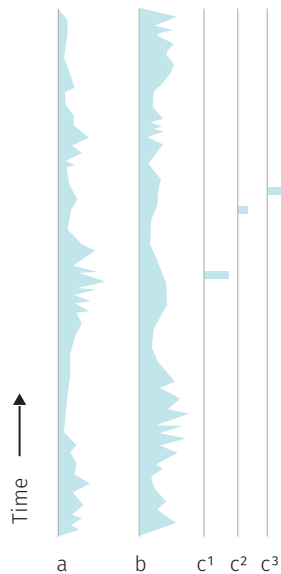


- Existence in time-space frame
- Projection on map plane



Hypothetical data collection
across time-space lifespan