

MT08 - Markose Jacob, Pooja Kabra

Acme Ackermann Steering Controller

Iteration Backlog 2

Unique ID	Task	Target time (minutes)	Actual Time	Status
2	Implementation	500	441	
2.01	Implement calculateHeadingError method	20	25	completed
2.02	Create unit test for calculateHeadingError	20	15	completed
2.03	Implement calculateSpeedError method	25	23	completed
2.04	Create unit test for calculateSpeedError	15	18	completed
2.05	Inspect source code	20	15	completed
2.06	Implement solve method	40	50	completed
2.07	Create unit test for solve	30	20	completed
2.08	Inspect source code	15	12	completed
2.09	Implement calculateWheelSpeed method	15	13	completed
2.1	Create unit test for calculateWheelSpeed	15	10	completed
2.11	Implement calculateWheelAngles method	15	15	completed
2.12	Create unit test for calculateWheelAngles	15	10	completed
2.13	Inspect source code	15	10	completed
2.14	Implement Main function	20	10	completed
2.15	Create visualization	60	50	completed
2.16	Tune parameters	40	30	completed
2.17	Update readme	20	25	completed
2.18	Run and fix cpplint	20	25	completed
2.19	Run and fix Cppcheck	20	20	completed
2.2	Run and fix Valgrind	20	5	completed
2.21	Generate documentation	40	40	completed