

MT08 - Markose Jacob, Pooja Kabra

Acme Ackermann Steering Controller

Iteration Backlog 2

Unique ID	Task	Target time (minutes)	Actual Time	Status
2	Implementation	410	0	
2.01	Implement calculateHeadingError method	20		
2.02	Create unit test for calculateHeadingError	20		
2.03	Implement calculateSpeedError method	20		
2.04	Create unit test for calculateSpeedError	20		
2.05	Inspect source code	20		
2.06	Implement solve method	40		
2.07	Create unit test for solve	30		
2.08	Inspect source code	20		
2.09	Implement calculateWheelSpeed method	15		
2.1	Create unit test for calculateWheelSpeed	15		
2.11	Implement calculateWheelAngles method	15		
2.12	Create unit test for calculateWheelAngles	15		
2.13	Inspect source code	20		
2.14	Implement Main function	20		
2.15	Create visualization	60		
2.16	Tune parameters	40		
2.17	Update readme	20		