

MT08 - Markose Jacob, Pooja Kabra

Acme Ackermann Steering Controller

Iteration Backlog 1

Unique ID	Task	Target time (minutes)	Actual Time	Status
1	Plan and Design	325	42	
1.01	Link github repo with travis CI	10	20	
1.02	Link github repo with Coveralls	10	22	
1.03	Create skeleton code for Sensor class	10		
1.04	Write constructors and destructors for Sensor class	10		
1.05	Create unit tests for Sensor class	20		
1.06	Write getters for Sensor class	10		
1.07	Write setters for Sensor class	10		
1.08	Create skeleton code for RobotKinematics class	10		
1.09	Write constructors and destructors for RobotKinematics class	10		
1.1	Create unit tests for RobotKinematics Class	20		
1.11	Write getters for RobotKinematics class	10		
1.12	Write setters for RobotKinematics class	10		
1.13	Inspect source code	20		
1.14	Create skeleton code for Controller class	20		
1.15	Write constructors and destructors for Controller class	10		
1.16	Create unit tests for Controller class	20		
1.17	Write getters for Controller class	10		
1.18	Write setters for Controller class	10		
1.19	Create skeleton code for ForwardKinematics class	10		
1.2	Write constructors and destructors for ForwardKinematics class	10		
1.21	Create skeleton code for InverseKinematics class	10		
1.22	Inspect source code	20		
1.23	Inspect unit test	25		
1.24	Update readme	20		