MT08 - Markose Jacob, Pooja Kabra Acme Ackermann Steering Controller Iteration Backlog 1				
Unique ID	**Task**	**Target time (minutes)**	**Actual Time**	**Status**
1	**Plan and Design**	**405**	**416**	
1.01	Link github repo with travis CI	10	20	completed
1.02	Link github repo with Coveralls	20	22	completed
1.03	Create skeleton code for Sensor class	10	11	completed
1.04	Write constructors and destructors for Sensor class	10	16	completed
1.05	Create unit tests for Sensor class	20	20	completed
1.06	Write getters for Sensor class	10	10	completed
1.07	Write setters for Sensor class	10	10	completed
1.08	Create skeleton code for RobotKinematics class	10	20	completed
1.09	Write constructors and destructors for RobotKinematics class	10	10	completed
1.1	Create unit tests for RobotKinematics Class	20	17	completed
1.11	Write getters for RobotKinematics class	10	14	completed
1.12	Write setters for RobotKinematics class	10	8	completed
1.13	Inspect source code	20	15	completed
1.14	Create skeleton code for Controller class	20	8	completed
1.15	Write constructors and destructors for Controller class	10	8	completed
1.16	Create unit tests for Controller class	20	12	completed
1.17	Write getters for Controller class	10	11	completed
1.18	Write setters for Controller class	10	8	completed
1.19	Create skeleton code for ForwardKinematics class	10	4	completed
1.2	Write constructors and destructors for ForwardKinematics class	10	6	completed
1.21	Declare methods in ForwardKinematics class	5	5	completed
1.22	Create unit test for ForwardKinematics class	10	12	completed
1.23	Write getters for ForwardKinematics class	5	4	completed
1.24	Write setters for ForwardKinematics class	5	3	completed
1.25	Create skeleton code for InverseKinematics class	10	18	completed
1.26	Inspect source code	20	26	completed
1.27	Inspect unit test	25	23	completed
1.28	Added doxygen comments	45	60	completed
1.29	Update readme	20	15	completed