UML class

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PIDController

- Kp: double
- Kd: double
- Ki: double
- dt: double
- max: double
- min: double
- setPoint: double
- currentVal: double
- + setKp()
- + setKd() + setKi()
- + getKp(): double + getKd(): double

- + getKi(): double + compute(): double