

→ \* Algorithm :-

1. create an empty board where no queens are placed which start state.
2. Heuristic (h): h is the number of attacking queens pairs, where lower values are better.
3. priority f<sup>n</sup> :  $f(h) = g(h) + h(h)$   
 where g(h) is the number of queens placed so far  
 where as f prioritizes states with fewer attacking queens.
4. Add start state to the priority queue:
  - \* Add the initial empty board with f = 0
  - \* while queue not empty
    - select states with lowest attacking queens
    - Now check for the sol<sup>n</sup> :- if all the 8 queens are placed without any difficulties then return the board.
    - place a queen in the next row in valid columns & add each state to the queue.
5. Return solution ~~if no solution found~~  
~~is empty.~~

### \* Implementation of Hill climbing algorithm for 8 queens

#### → initialize :-

- start with a random configuration of 8 queens on a board.

where one queen per column is placed.

#### → Evaluate Heuristic :-

Now calculate the number of pairs of queens that are attacking each other. (lower values are better  $h$ ).

→ For each queen, move it within its column to each row & calculate new heuristic for each board -ing state.

→ select the neighboring state with the lowest heuristic value  $h'$ .

if  $h'$  is lower than the current  $h$ , update the current state to this neighbor.

→ Repeat :- continue evaluating neighbors until  $h=0$

→ If stuck in any state, restart with new state or random state, repeat same

Proceed



\* code:- Pseudocode:

function A\* (start)

open\_set = priority queue()

open\_set.enqueue (start, priority = heuristic (start))

while open\_set is not empty

current = open\_set.dequeue()

if heuristic (current) == 0:

return current

for neighbor in neighbors (current):

cost = heuristic (neighbor)

open\_set.enqueue (neighbor, priority = cost)

function heuristic (state):

return no of conflicts queen pairs in state.

\* output:

A\* solution ; [0, 4, 7, 5, 2, 6, 1, 3]

\* Hill climbing Pseudo code :-

function Hill (start)

current = start

while true :

next = best\_neighbor (current)

if heuristic (next)  $\geq$  heuristic (current)

return current if heuristic (current) == 0

else failure

function best\_neighbor (state)

return neighbor of state with the lowest heuristic

function heuristic (state)

return no of conflicting queen pairs in state.

\* output :

Hill climbing solution : [1, 3, 0, 6, 4, 2, 5, 7]

other possible outputs:

~~soln : [0, 2, 4, 6, 1, 3, 5, 7]~~

~~soln : [3, 0, 6, 2, 5, 1, 7, 4]~~

8/29/2024

## LAB 06

A\* Algorithm code for 8 Queens:

Code :

```
import numpy as np
```

```
import heapq
```

```
class Node:
```

```
    def __init__(self, state, g, h):
```

```
        self.state = state # current state of the board
```

```
        self.g = g         # cost to reach this state
```

```
        self.h = h         # heuristic cost to reach goal
```

```
        self.f = g + h     # total cost
```

```
    def __lt__(self, other):
```

```
        return self.f < other.f
```

```
def heuristic(state):
```

```
    # Count pairs of queens that can attack each other
```

```
    attacks = 0
```

```
    for i in range(len(state)):
```

```
        for j in range(i + 1, len(state)):
```

```
            if state[i] == state[j] or abs(state[i] - state[j]) == j - i:
```

```
                attacks += 1
```

```
    return attacks
```

```
def a_star_8_queens():
```

```
    initial_state = [-1] * 8 # -1 means no queen placed
```

```
    open_list = []
```

```
    closed_set = set()
```

```

initial_h = heuristic(initial_state)
heapq.heappush(open_list, Node(initial_state, 0, initial_h))

while open_list:
    current_node = heapq.heappop(open_list)
    current_state = current_node.state
    closed_set.add(tuple(current_state))

    # Check if we reached the goal
    if current_node.h == 0:
        return current_state

    for col in range(8):
        for row in range(8):
            if current_state[col] == -1: # Only place a queen if none is present in this column
                new_state = current_state.copy()
                new_state[col] = row
                if tuple(new_state) not in closed_set:
                    g_cost = current_node.g + 1
                    h_cost = heuristic(new_state)
                    heapq.heappush(open_list, Node(new_state, g_cost, h_cost))

return None

solution = a_star_8_queens()
print("A* solution:", solution)

```

qoutput:

```
⇒ A* solution: [7, 0, 6, 3, 1, -1, 4, 2]
```

Hill Climbing for 8 queens

import random

def heuristic(state):

    attacks = 0

    for i in range(len(state)):

        for j in range(i + 1, len(state)):

            if state[i] == state[j] or abs(state[i] - state[j]) == j - i:

                attacks += 1

    return attacks

def hill\_climbing\_8\_queens():

    state = [random.randint(0, 7) for \_ in range(8)] # Random initial state

    while True:

        current\_h = heuristic(state)

        if current\_h == 0: # Found a solution

            return state

        next\_state = None

        next\_h = float('inf')

        for col in range(8):

            for row in range(8):

                if state[col] != row: # Only consider moving the queen

                    new\_state = state.copy()

```
new_state[col] = row
h = heuristic(new_state)
if h < next_h:
    next_h = h
    next_state = new_state

if next_h >= current_h: # No better neighbor found
    return None # Stuck at local maximum
state = next_state
```

```
solution = hill_climbing_8_queens()
print("Hill Climbing solution:", solution)
```

**Output:**

```
Hill Climbing solution: [4, 2, 7, 3, 6, 0, 5, 1]
```





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                    h_cost = heuristic(new_state)
                    heapq.heappush(open_list, Node(new_state, g_cost, h_cost))

return None

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print("A* solution:", solution)

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qoutput:

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⇒ A* solution: [7, 0, 6, 3, 1, -1, 4, 2]
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Hill Climbing for 8 queens

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    return None # Stuck at local maximum
state = next_state
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```
solution = hill_climbing_8_queens()
print("Hill Climbing solution:", solution)
```

**Output:**

```
Hill Climbing solution: [4, 2, 7, 3, 6, 0, 5, 1]
```



