

Program 6 - Parallel Cellular Algorithm for Function Optimization :

Design and implement a Parallel Cellular Algorithm (PCA) in Python to optimize a mathematical function. Each cell in a 1D cellular grid represents a potential solution, and cells interact with their neighbors to explore the search space. The objective is to find the maximum value of a mathematical function.

Algorithm:

Algorithm for Parallel Cellular Algorithm

1. **Define the Problem:**
 - Use $f(x) = -x^2 + 8x + 20$ as the objective function.
 - Define the search space as $[0, 10]$.
2. **Initialize Parameters:**
 - Set the grid size NNN (number of cells).
 - Define the number of iterations III .
 - Define the neighborhood structure (e.g., each cell interacts with its immediate neighbors).
3. **Initialize Population:**
 - Generate random initial values for each cell within the search space.
4. **Evaluate Fitness:**
 - Calculate $f(x)$ for each cell to determine its fitness.
5. **Update States:**
 - For each cell, calculate its new state by considering its own value and the values of its neighbors.
6. **Iterate:**
 - Repeat the evaluation and state updating process for III iterations.
7. **Output the Best Solution:**
 - Track and output the value and fitness of the best cell after all iterations.

code:

```
import numpy as np

# Define the fitness function
def fitness_function(x):
    return -x**2 + 8*x + 20

# Parallel Cellular Algorithm implementation
def parallel_cellular_algorithm():
    # Input parameters
    grid_size = int(input("Enter grid size (number of cells): "))
    num_iterations = int(input("Enter number of iterations: "))
    x_min = float(input("Enter minimum value of x: "))
    x_max = float(input("Enter maximum value of x: "))
```

```

# Initialize the cellular grid
cells = np.random.uniform(x_min, x_max, grid_size)
fitness = np.array([fitness_function(x) for x in cells])

# Optimization loop
for _ in range(num_iterations):
    new_cells = np.copy(cells)
    for i in range(grid_size):
        # Get neighbors (handle edge cases)
        left_neighbor = cells[i - 1] if i > 0 else cells[-1]
        right_neighbor = cells[i + 1] if i < grid_size - 1 else cells[0]

        # Update state based on neighbors
        new_cells[i] = (cells[i] + left_neighbor + right_neighbor) / 3
        new_cells[i] = np.clip(new_cells[i], x_min, x_max) # Ensure
within bounds

    # Update fitness values
    cells = new_cells
    fitness = np.array([fitness_function(x) for x in cells])

# Find the best solution
best_index = np.argmax(fitness)
best_solution = cells[best_index]
best_fitness = fitness[best_index]

return best_solution, best_fitness

# Run the Parallel Cellular Algorithm
best_solution, best_fitness = parallel_cellular_algorithm()
print(f"Best Solution: {best_solution}, Fitness: {best_fitness}")
print("Name-pooja Gaikwad(1BM22CS194)")

```

Output:

```
Enter grid size (number of cells): 10
Enter number of iterations: 50
Enter minimum value of x: 0
Enter maximum value of x: 10
Best Solution: 6.856947134091286, Fitness: 27.837853073007587
Name-pooja Gaikwad(1BM22CS194)
```

⑤ Parallel Cellular Algo

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1. Start
2. Initialize grid (rows, col)
initialize grid of x col. with random states.
(0 for dead, 1 for alive)
3. Count neighbours (grid, x, y)
- count the no. of neighbours around the cell (x, y)
4. Apply rules (grid, x, y)
for each cell (x, y) is parallel:
Count neighbours (x, y)

Apply Rules:

If cell (x, y) = 1 & neighbour (grid, x, y) ≥ 2 :
newGrid [x][y] = 1 (cell stays alive)

If cell (x, y) = 0 & neighbour (grid, x, y) = 3
newGrid [x][y] = 1 (cell becomes alive)

ELSE:

newGrid [x][y] = 0 (cell stays dead)

grid [x, y] \leftarrow newGrid [x][y]

5. For iteration 1 to max.

Repeat the above steps

Return the grid after max generation