Pooja Yadav

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Location: Alwar, Rajasthan

Neemrana - In Progress (2023-2027)

Jaipur

CAREER OBJECTIVE

A highly motivated and enthusiastic Computer Science undergraduate with a strong foundation in programming, web development, and problem-solving. Passionate about building real-world applications and continuously exploring new technologies. Eager to contribute to impactful projects in full-stack development, automation, and intelligent systems while gaining practical experience and enhancing my technical and collaborative abilities.

TECHNICAL SKILLS

Frontend : HTML 5, CSS, JavaScript

Backend : Python, Java

Framework: Bootstrap, Node.js, Springboot

Databases : MySQL

Tools & Platforms: Visual Studio Code, Labelbox

EDUCATION

NIIT University Neemrana

BTech in Computer Science Current: 9.62 CGPA

Higher Secondary Education, RBSE

Scored 90 percent marks

Secondary Education, RBSE Jaipur

Scored 95 percent marks

PROJECTS

Gesture-Based Bot

Tech Stack: Spring Boot, SQL, HTML/CSS

Tech Stack: OpenCV, Python

Role: Researcher

- Implemented wireless gesture recognition for hands-free, real-time robotic control.
- Integrated a gesture-sensing module (e.g., accelerometer, gyroscope) for capturing directional input.
- Enabled obstacle avoidance using ultrasonic sensors with real-time feedback and distance measurement.
- Developed a Spring Boot backend API to send directional commands to the ESP32 controller.
- Designed a web-based UI using HTML/CSS for gesture simulation and bot interaction.
- Integrated with a **MySQL database** to log gesture commands, bot responses, and sensor data for monitoring and analytics.

Edge Detection in Medical Imaging

- Implemented Sobel and Scharr operators for gradient-based edge detection in medical and computer vision images.
- Utilized partial derivatives to highlight intensity changes and texture features in diagnostic scans.
- Integrated OpenCV in Python to enable cross-platform analysis.
- Enhanced feature visibility to assist in automated image classification and segmentation workflows.

Autonomous Pollination Rover

- Addressed the critical need for alternative pollination methods due to declining bee and pollinator populations, essential for maintaining crop productivity.
- Designed and developed an IoT-enabled ground-based rover for autonomous navigation and targeted pollination in fields.
- Utilized sensors and real-time environmental data to enhance crop yield.