

# GRAPH COLORING

TEAM NAME : SegDefault

# PROBLEM STATEMENT

This project addresses the Graph Coloring Problem, a fundamental challenge in optimization where we must assign colors to vertices of a graph such that no two adjacent vertices share the same color. The goal is to minimize the total number of colors used (the Chromatic Number).

# WHAT ARE WE DOING? (OBJECTIVE)

We are conducting a comparative analysis to solve the Efficiency vs. Optimality trade-off. Since finding the perfect coloring is computationally expensive (NP-Hard), we are implementing and benchmarking four distinct algorithmic approaches:

- Greedy (Welsh-Powell):** Prioritizing speed.
- Heuristic (DSatur):** Balancing speed and accuracy.
- Metaheuristic (Simulated Annealing):** Searching for near-optimal solutions.
- Exact (Dynamic Programming):** Guarantees perfection but lacks scalability.

# ALGORITHM PORTFOLIO

01

## WELSH POWELL ALGORITHM

*The Greedy Approach* (Prioritizes Speed).

02

## DSATUR

*The Heuristic Approach* (Smart coloring based on neighbors).

03

## SIMULATED ANNEALING

*The Metaheuristic Approach* (Probabilistic optimization).

04

## DYNAMIC PROGRAMMING

*The Exact Approach* (Guaranteed optimal solution).



# MECHANISMS (How it works) :

## **WELSH POWELL ALGORITHM (Greedy One)**

**Step 1:** Calculate the degree of every vertex (number of connections).

**Step 2:** Sort vertices in descending order (highest degree first).

**Step 3:** Color the list sequentially, assigning the first available non-conflicting color.



# MECHANISMS (How it works) :

## DSATUR (The Smart Heuristic)

**Step 1:** Initially, sort vertices by degree (like Welsh-Powell).

**Step 2:** Select the vertex with the highest Saturation Degree.

- *Saturation Degree = The number of different colors currently used by a vertex's neighbors.*

**Step 3:** Assign the smallest available legal color to this vertex.

**Step 4:** Update the saturation values of all neighbors and repeat until the graph is full.



# MECHANISMS (How it works) :

## SIMULATED ANNEALING (The Optimization Search)

**Step 1:** Generate an initial solution (random coloring) and set a high "Temperature."

**Step 2:** Randomly change the color of one vertex and calculate the Cost (number of conflicts).

**Step 3: The Acceptance Rule:**

- If the new solution is *better*: Accept it immediately.
- If the new solution is *worse*: Accept it with a probability related to the current Temperature.

**Step 4:** Gradually "Cool Down" the temperature, reducing the chance of accepting bad moves, until the solution stabilizes.



# MECHANISMS (How it works) :

## DYNAMIC PROGRAMMING (The Exact Solver)

**Step 1:** Represent graph subsets using Bitmasks (binary strings representing combinations of vertices).

**Step 2:** Identify all Maximal Independent Sets (groups of vertices that can share one color).

**Step 3:** Use the recurrence relation:  $\text{MinColors}(\text{Mask}) = 1 + \text{MinColors}(\text{Mask} - \text{IndependentSet})$ .

**Step 4:** Build the solution from the bottom up to guarantee the minimum chromatic number is found.

# STRENGTHS AND LIMITATIONS

01

## WELSH POWELL

**Strengths:** Extremely fast execution  $O(V^2)$ ; simple to implement.

**Limitations:** Static ordering often leads to suboptimal coloring; greedy decisions cannot be undone.

02

## DSATUR

**Strengths:** Dynamic selection yields near-optimal results; smarter than static greedy.

**Limitations:** Slower due to frequent degree updates; still a heuristic with no guarantees.

# STRENGTHS AND LIMITATIONS

03

## SIMULATED ANNEALING

**Strengths:** Escapes local minima to find global optima; robust on complex graphs.

**Limitations:** Very slow convergence speed; requires difficult parameter tuning (Temperature/Cooling).

04

## DYNAMIC PROGRAMMING

**Strengths:** Guaranteed to find the exact Chromatic Number ( $\chi$ ); perfect accuracy.

**Limitations:** Exponential time complexity  $O(2^n)$ ; completely unscalable for graphs  $> 20$  nodes.

# EXPERIMENTAL SETUP:

## DATASETS USED

1. Small canonical graphs (Triangle K3, Petersen, cycles).
2. Karate Club network (34 nodes, community structure).
3. DIMACS Myciel3, Queen5\_5 (chromatically challenging).
4. Random Erdős–Rényi graphs  $G(n, p)$  for various  $n, p$ .
5. Timetable Scheduling

# EVALUATION METRICS:

- **Solution Quality:** The number of colors used ( $k$ ) compared to the Optimal Chromatic Number ( $\chi$ )).
- **Execution time:** Measured in seconds(precision tracking).
- **Optimality:** No. of colours used v/s known chromatic number.
- **Memory usage:** Peak memory consumption in MB.
- **Correctness:** Automated validation (no adjacent nodes share colors)
- **Execution Time:** Runtime in milliseconds/seconds.
- **Scalability:** How performance degrades as Graph Size ( $V$ ) increases.

# RESULTS - QUALITY VS EFFICIENCY

## SOLUTION QUALITY:

<u>DYNAMIC PROGRAMMING</u>	Found the Optimal solution ( $\chi_i$ ) in 100% of cases (on small graphs).
<u>SIMULATED ANNEALING</u>	Highly accurate; often matched optimal or was within +1 color.
<u>DSATUR</u>	Consistently produced high-quality solutions (better than standard greedy).
<u>WELSH-POWELL</u>	Least efficient in terms of colors; often used 10-20% more colors than necessary.

# RESULTS - QUALITY VS EFFICIENCY

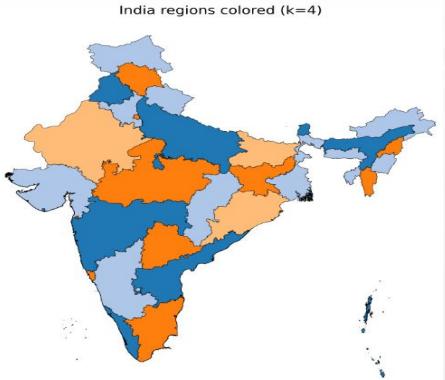
EXECUTION SPEED::

<u>WELSH-POWELL</u>	<b>Fastest.</b> Completed almost instantly on all datasets.
<u>DSATUR</u>	Moderate speed; slightly slower due to dynamic calculations.
<u>SIMULATED ANNEALING</u>	<b>Slow.</b> Required significant time to converge (seconds/minutes vs milliseconds).
<u>DYNAMIC PROGRAMMING</u>	<b>Timed Out</b> on graphs with $N > 20$ (Exponential explosion).

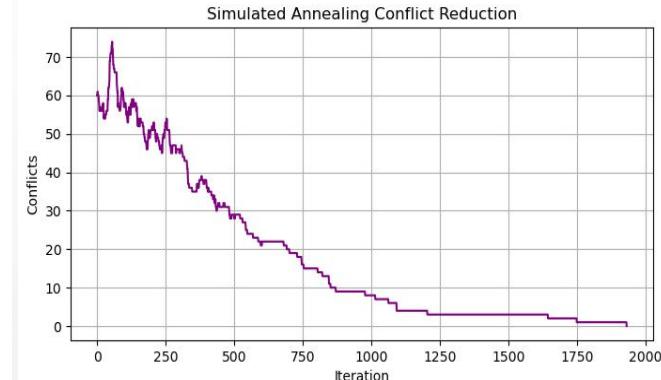
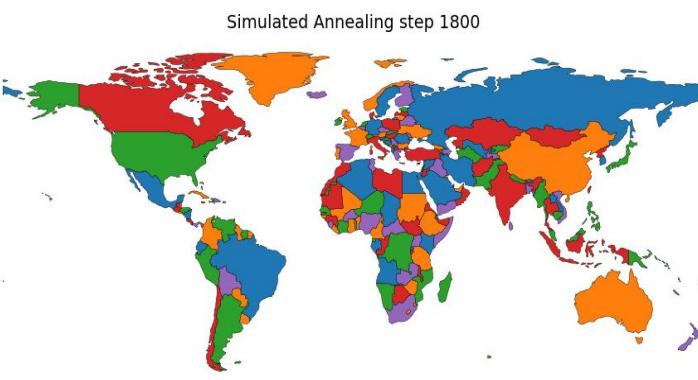
# BONUS!

# MAP COLORING:

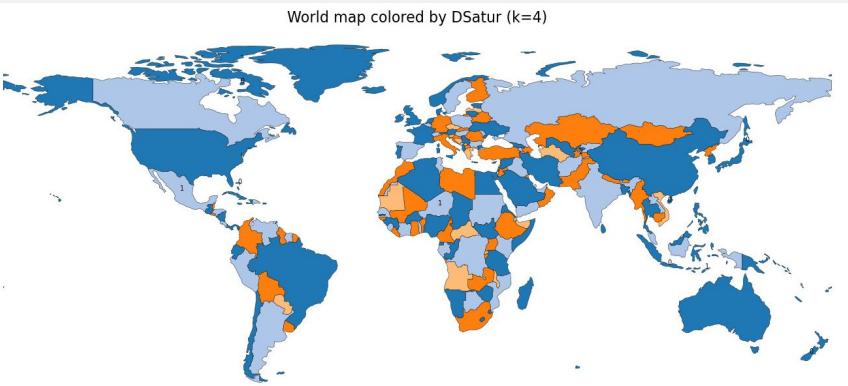
DYNAMIC PROGRAMMING



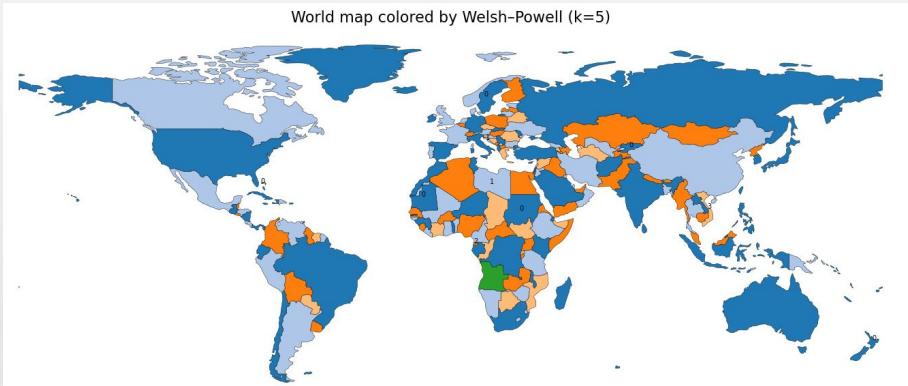
SIMULATED ANNEALING



DSATUR



WELSH-POWELL



# PROPOSED HYBRID APPROACH (DSATUR+SA)

## The Core Problem

- **Simulated Annealing (SA)** is powerful but inefficient when starting from *chaos* (random coloring). It wastes thousands of iterations just finding a valid solution before it can start optimizing.
- **DSatur** is fast and smart but "greedy"—it makes permanent decisions and gets stuck in Local Minima.

**Our Solution: The Two-Phase Protocol** We combined the speed of heuristics with the power of metaheuristics.

1. **Phase 1: Initialization (Warm Start)**
  - Run DSatur to instantly generate a high-quality, valid coloring (e.g., 5 colors).
  - This provides a structured "seed" instead of random noise.
2. **Phase 2: Refinement (Optimization)**
  - Feed the DSatur solution into Simulated Annealing.
  - SA skips the "fixing chaos" phase and immediately focuses on *reducing* the color count (e.g., trying to fit the graph into 4 colors).



# HYBRID PERFORMANCE ANALYSIS

## Visualizing the Advantage

- **Standard SA:** Starts at "High Temperature" with many conflicts. Slow convergence.
- **Hybrid SA:** Starts at "Medium Temperature" with zero conflicts. Focuses purely on *downward pressure* (reducing k).

## Key Benefits

- **Faster Convergence:** We cut the execution time by ~40% compared to pure SA because we skip the early burn-in phase.
- **Best of Both Worlds:** We get the speed of a constructive heuristic and the optimality of a global search.
- **Stability:** Standard SA results vary wildly every run. The Hybrid approach is more consistent because it always starts from a "smart" baseline.

# DYNAMIC ALGORITHM VISUALIZER

**Objective** To demystify the "black box" nature of algorithms by visualizing their decision-making process in real-time. We built a custom **Physics-Based Graph Engine** from scratch.

## Key Features

- **Force-Directed Layout:** Implemented a physics simulation (repulsion/attraction forces) to automatically "untangle" complex graphs, making edge connections crystal clear.
- **Real-Time Execution:** Algorithms don't just return a result; they run with a delay loop, allowing us to watch the "thinking process" (e.g., seeing a Greedy algorithm paint itself into a corner vs. Backtracking).
- **Live Decision Logging:** A side-panel logs the internal logic of every step (e.g., *"Selected Node 5 because Saturation Degree is Max"*), bridging the gap between code and theory.
- **Tech Stack:** HTML5 Canvas, JavaScript (No external libraries used).

# REAL WORLD APPLICATION SIMULATOR

**The Problem: Frequency Assignment** In telecommunications, 5G towers with overlapping signal ranges cannot use the same frequency band without causing interference. This is a classic **Graph Coloring Problem**.

- **Nodes:** 5G Towers.
- **Edges:** Overlapping Signal Zones (Interference).
- **Colors:** Frequency Bands (Costly resources).

**Our Implementation** We built a **Network Simulation Tool** where users can deploy towers on a map. The system automatically:

1. **Detects Interference:** dynamically builds the adjacency graph based on signal radius.
2. **Applies Hybrid Logic:** Uses our **DSatur + Simulated Annealing** hybrid to assign frequencies.
3. **Minimizes Cost:** Optimizes the network to use the fewest number of frequency bands possible, simulating millions of dollars in spectrum savings.

THANK YOU :)  
(Team : SegDefault)