

PS5841

Data Science in Finance & Insurance

Support Vector Machines

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SVC

$$L_D = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k \mathbf{x}_i^T \mathbf{x}_k$$

$$\hat{f}(\mathbf{x}) = \mathbf{x}^T \hat{\boldsymbol{\beta}} + \hat{\beta}_0 = \sum_{i=1}^N \hat{\alpha}_i y_i \mathbf{x}^T \mathbf{x}_i + \hat{\beta}_0$$

$$\boldsymbol{\beta} = \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i$$

SVC with Kernel Function (1)

- Generalize the inner products to kernel functions

$$\begin{aligned} L_D &= \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k \mathbf{x}_i^T \mathbf{x}_k \\ &= \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k \langle \mathbf{x}_i, \mathbf{x}_k \rangle \\ \rightarrow L_D &= \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k \langle h(\mathbf{x}_i), h(\mathbf{x}_k) \rangle \\ &= \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k K(\mathbf{x}_i, \mathbf{x}_k) \end{aligned}$$

- For the linear kernel function, $K(\mathbf{x}, \mathbf{x}') = \langle h(\mathbf{x}), h(\mathbf{x}') \rangle = \mathbf{x}^T \mathbf{x}'$

SVC with Kernel Function (2)

- Generalize the inner products to kernel functions

$$\hat{f}(\mathbf{x}) = \mathbf{x}^T \hat{\boldsymbol{\beta}} + \hat{\beta}_0 = \sum_{i=1}^N \hat{\alpha}_i y_i \mathbf{x}^T \mathbf{x}_i + \hat{\beta}_0 = \sum_{i=1}^N \hat{\alpha}_i y_i \langle \mathbf{x}, \mathbf{x}_i \rangle + \hat{\beta}_0$$

$$\rightarrow \hat{f}(\mathbf{x}) = \sum_{i=1}^N \hat{\alpha}_i y_i \langle h(\mathbf{x}), h(\mathbf{x}_i) \rangle + \hat{\beta}_0$$

$$= \sum_{i=1}^N \hat{\alpha}_i y_i K(\mathbf{x}, \mathbf{x}_i) + \hat{\beta}_0$$

- For the linear kernel function, $K(\mathbf{x}, \mathbf{x}') = \langle h(\mathbf{x}), h(\mathbf{x}') \rangle = \mathbf{x}^T \mathbf{x}'$

Feature Space Expansion

- A kernel function can expand the feature space.

- Example – from 2D to 6D

$$\mathbf{x} = (x_1, x_2)^T \rightarrow h(\mathbf{x}) = (h_1(\mathbf{x}), \dots, h_6(\mathbf{x}))^T$$

$$K(\mathbf{x}_i, \mathbf{x}_k) = (1 + \langle \mathbf{x}_i, \mathbf{x}_k \rangle)^2$$

Example – from 2D to 6D (1)

$$\mathbf{x} = (x_1, x_2)^T \rightarrow h(\mathbf{x}) = (h_1(\mathbf{x}), \dots, h_6(\mathbf{x}))^T$$

$$\begin{aligned} K(\mathbf{x}_i, \mathbf{x}_k) &= (1 + \langle \mathbf{x}_i, \mathbf{x}_k \rangle)^2 \\ &= (1 + x_{i1}x_{k1} + x_{i2}x_{k2})^2 \\ &= 1 + (x_{i1}x_{k1})^2 + (x_{i2}x_{k2})^2 \\ &\quad + 2x_{i1}x_{k1} + 2x_{i2}x_{k2} + 2x_{i1}x_{k1}x_{i2}x_{k2} \end{aligned}$$

Example – from 2D to 6D (2)

$$K(\mathbf{x}_i, \mathbf{x}_k) = 1 + (x_{i1}x_{k1})^2 + (x_{i2}x_{k2})^2 + 2x_{i1}x_{k1} + 2x_{i2}x_{k2} + 2x_{i1}x_{k1}x_{i2}x_{k2} = \langle h(\mathbf{x}_i), h(\mathbf{x}_k) \rangle$$

- $h_1(\mathbf{x}) = 1 \rightarrow h_1(\mathbf{x}_i)h_1(\mathbf{x}_k) = 1$
- $h_2(\mathbf{x}) = x_1^2 \rightarrow h_2(\mathbf{x}_i)h_2(\mathbf{x}_k) = (x_{i1}x_{k1})^2$
- $h_3(\mathbf{x}) = x_2^2 \rightarrow h_3(\mathbf{x}_i)h_3(\mathbf{x}_k) = (x_{i2}x_{k2})^2$
- $h_4(\mathbf{x}) = \sqrt{2}x_1 \rightarrow h_4(\mathbf{x}_i)h_4(\mathbf{x}_k) = 2x_{i1}x_{k1}$
- $h_5(\mathbf{x}) = \sqrt{2}x_2 \rightarrow h_5(\mathbf{x}_i)h_5(\mathbf{x}_k) = 2x_{i2}x_{k2}$
- $h_6(\mathbf{x}) = \sqrt{2}x_1x_2 \rightarrow h_6(\mathbf{x}_i)h_6(\mathbf{x}_k) = 2x_{i1}x_{k1}x_{i2}x_{k2}$

Support Vector Machine

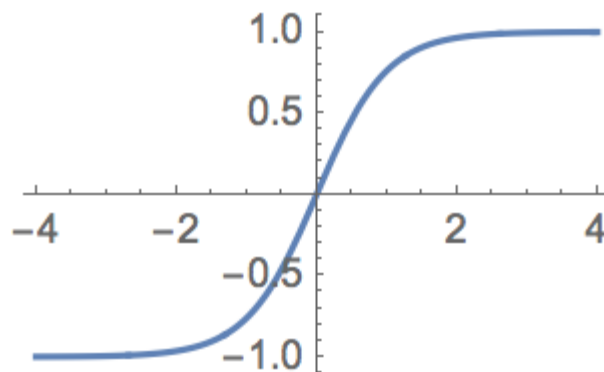
- The support vector machine is an extension of the support vector classifier, expanding the feature space using kernels
- Linear $K(\mathbf{x}, \mathbf{x}') = \langle \mathbf{x}, \mathbf{x}' \rangle = \mathbf{x}^T \mathbf{x}'$
- Polynomial $K(\mathbf{x}, \mathbf{x}') = (1 + \langle \mathbf{x}, \mathbf{x}' \rangle)^d$
- Radial basis $K(\mathbf{x}, \mathbf{x}') = \exp(-\gamma \|\mathbf{x} - \mathbf{x}'\|^2)$
- Neural Network

$$K(\mathbf{x}, \mathbf{x}') = \tanh(\kappa_1 \langle \mathbf{x}, \mathbf{x}' \rangle + \kappa_2)$$

tanh

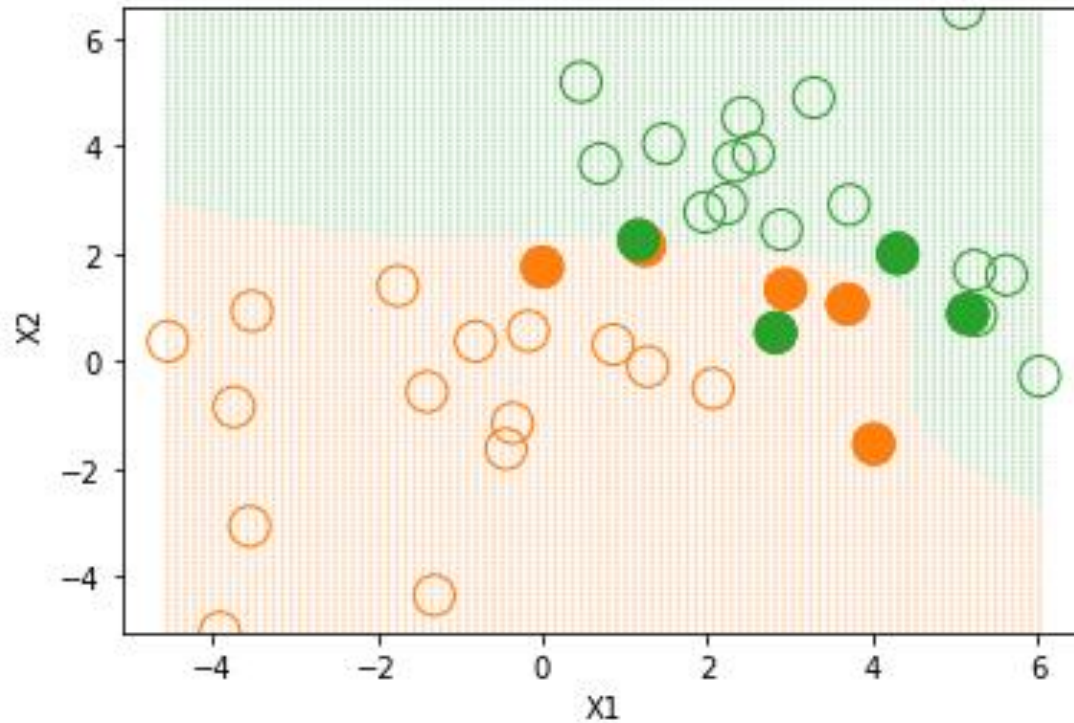
- Neural Network

$$K(\mathbf{x}, \mathbf{x}') = \tanh(\kappa_1 \langle \mathbf{x}, \mathbf{x}' \rangle + \kappa_2)$$



Decision Boundary (SVM) non-separable case

- Poly3, C=1



That was

