

# Recomposer: Event-Roll-guided Generative Audio Editing

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Joint work with **Edu Fonseca, Ron Weiss, Kevin Wilson, Pascal Getreuer, Scott Wisdom, Hakan Erdogan, John Hershey, Aren Jansen, Channing Moore, Manoj Plakal**

Mila Conversational AI Reading Group, Jan 29th 2026

<https://arxiv.org/abs/2509.05256>



# The Team



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# Context: Machine Learning for Audio

## Domain

- Speech
- Music
- **Environmental sounds**

## Applications

- Classification / Understanding
- Generation
- **Editing / Modification**

No LLM!

# Scenario: Sound Recomposition

Select clip

Q 0022bc1c4126c0a0\_30000@8008

00080086c5823584_130000@1994	Brief tone; Speech; Music; Explosion; Sneeze
0022bc1c4126c0a0_30000@8008	Generic impact sounds; Speech; Mechanisms; Motorcycle; Sneeze; Traffic noise, roadway noise
00b7026f61c9986f_70000@6786	Music; Singing; Sneeze
020092042b0790c9_60000@6659	Stream, river; Music; Sneeze; Sound effect; Liquid; Bell
020d6108c3f55879_0@4275	Brief tone; Sound effect; Telephone; Sneeze; Noise
02dae3eb9a91ac1a_200000@5556	Sneeze; Bell; Train
03105a88f52883d2_38000@1078	Generic impact sounds; Speech; Breathing; Laughter; Mechanisms; Sneeze; Train
0345d7995b6cd72d_30000@5693	Music; Singing; Sneeze
034720c57c16de65_40000@2938	Speech; Breathing; Sneeze; Mechanisms
034865f16dd11797_0@8331	Engine; Speech; !Human group actions; Steam; Sneeze; Train
036dd4d2829e6c1f_30000@6551	Singing; Whistling; Music; Sneeze; Hands
03e320f85c129225_30000@4292	Music; Stream, river; Sneeze
042f0f2cebe8f2b9_20000@4615	Speech; Music; Sneeze
050f3a218d0cf3ad_30000@6417	Speech; Sneeze; Wind; Boat, Water vehicle
051bb169863609c6_30000@5044	Speech; Singing; Whistling; Music; Sneeze
0599626613d898e4_90000@5317	Speech; Laughter; Dog; Typing; Sneeze
0599626613d898e4_90000@6064	Speech; Laughter; Dog; Explosion; Sneeze
065b1b7b28a65031_30000@4657	Singing; Music; Sneeze; !Human group actions; Hands

0022bc1c4126c0a0\_30000@8008

▶ 0:00 / 0:10

3.2 Run ReComPosiTOn

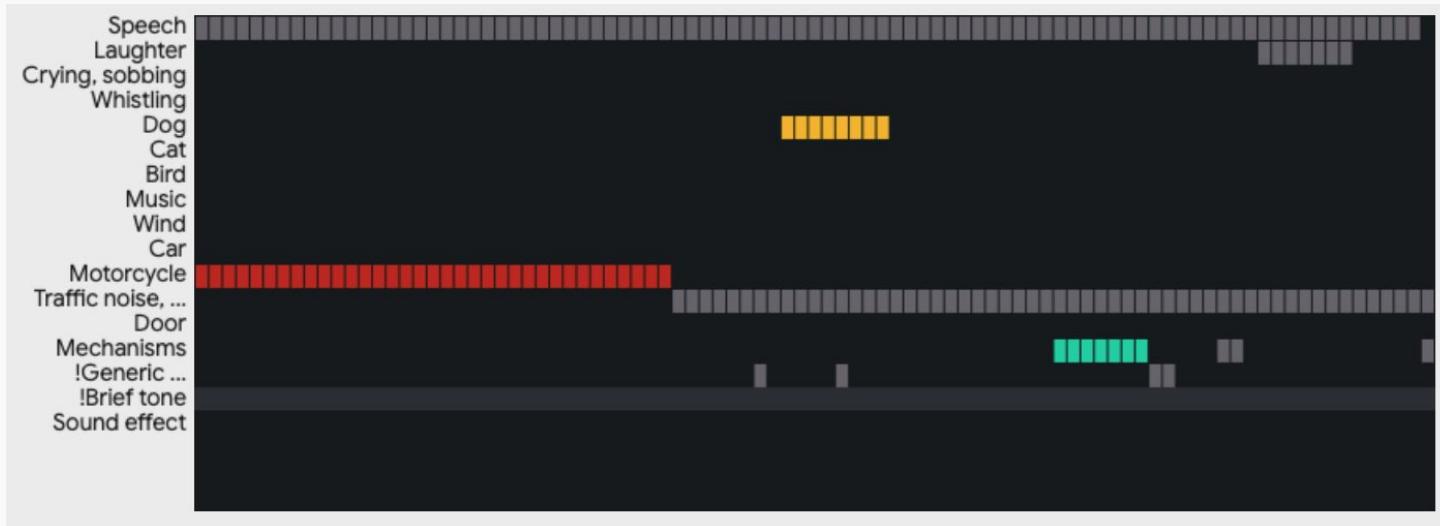
Decoding parameters

This is a screen recording of the refreshed go/recompositron-demo

Be - committed at 13:07 PM

Google

# Contribution: Event Roll

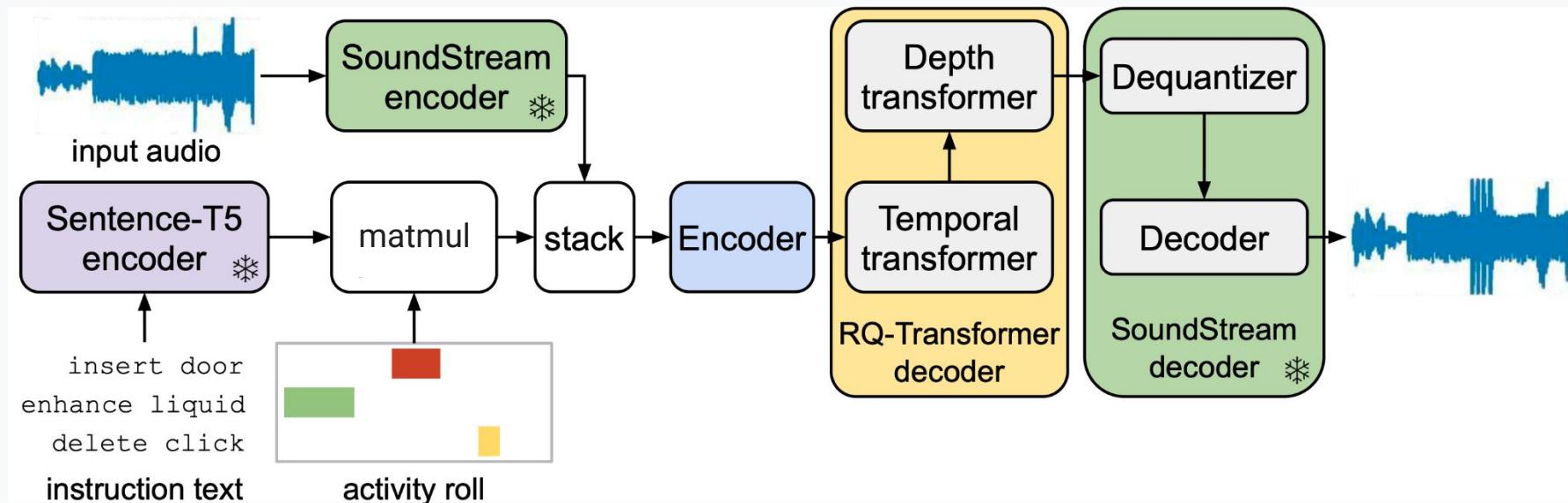


- Represents sound mixture as a collection of **discrete events**
- Each row associated with free-text **label** (Action + Class)
- **Could** be generated by an Audio Event Classifier

# Contribution: Enhancement

- Enhancement combines **sound separation** and **generation**
  - Identify low-level target event in the input
  - Regenerate missing details to synthesize output
- How to specify “Enhancement”?
  - Constant **gain** applied to input?
  - Constant output target **level** (e.g. 10 dB) regardless of input level
  - (allow user to specify)

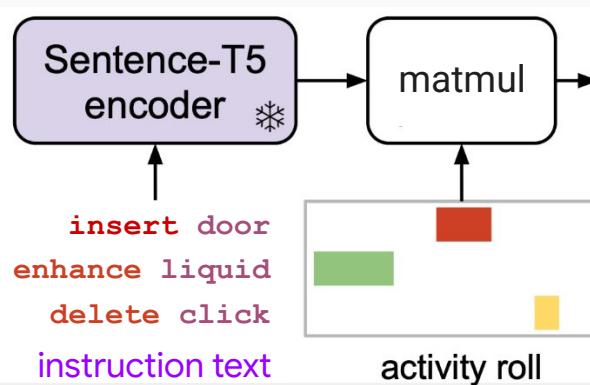
# Recomposer Model



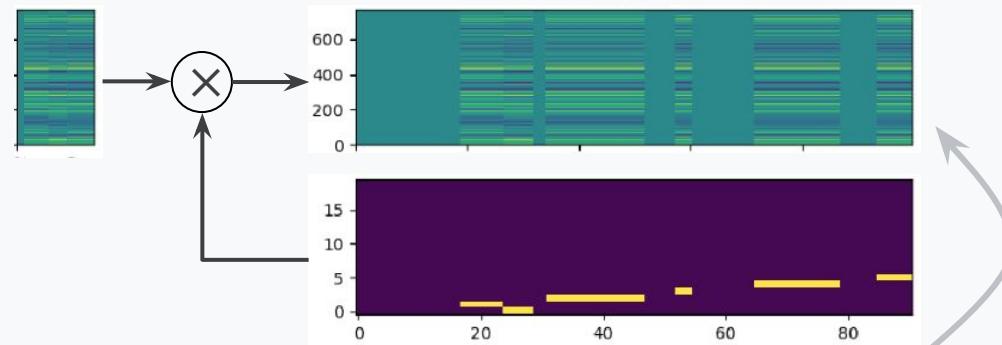
- Input sound **embedding + conditioning** encodes to conditioning **embedding**
- Autoregressive encoder-decoder transformer trained to generate **RVQ tokens**

[Autoregressive Image Generation using Residual Quantization](#), Lee et al, CVPR 2022

# Recomposer Model: Edit conditioning



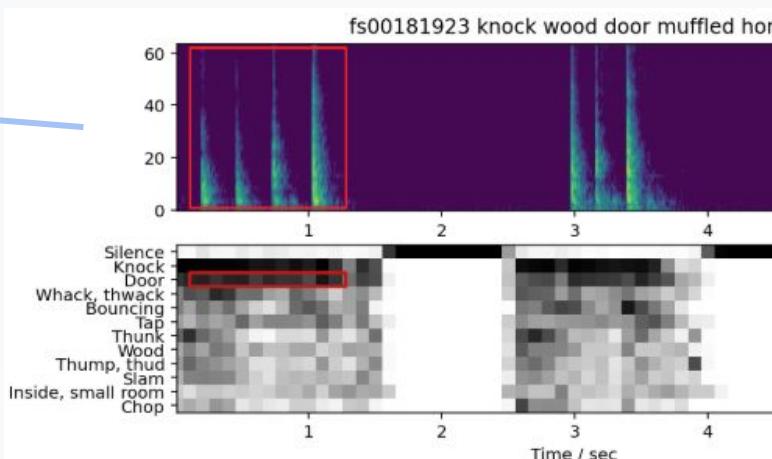
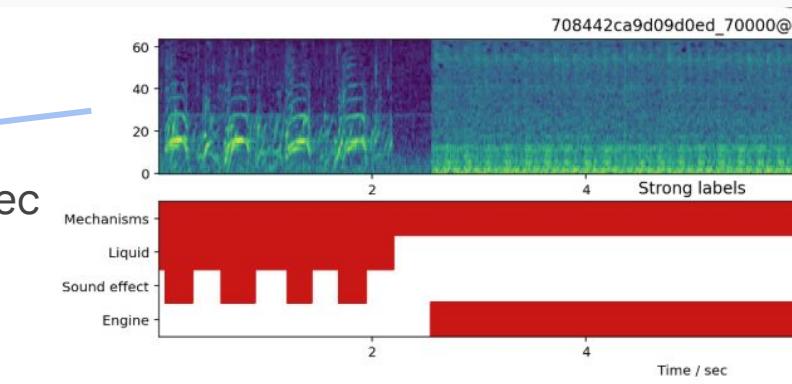
- Instruction text is embedded as **general text**
  - Action and Target class confounded...
  - Permits semantic **adjacency**
- matmul (embedding, event), (event, time) → (embedding, time)
  - All edits summed into a **single edit-conditioning vector** per time step



# Synthetic Target Data

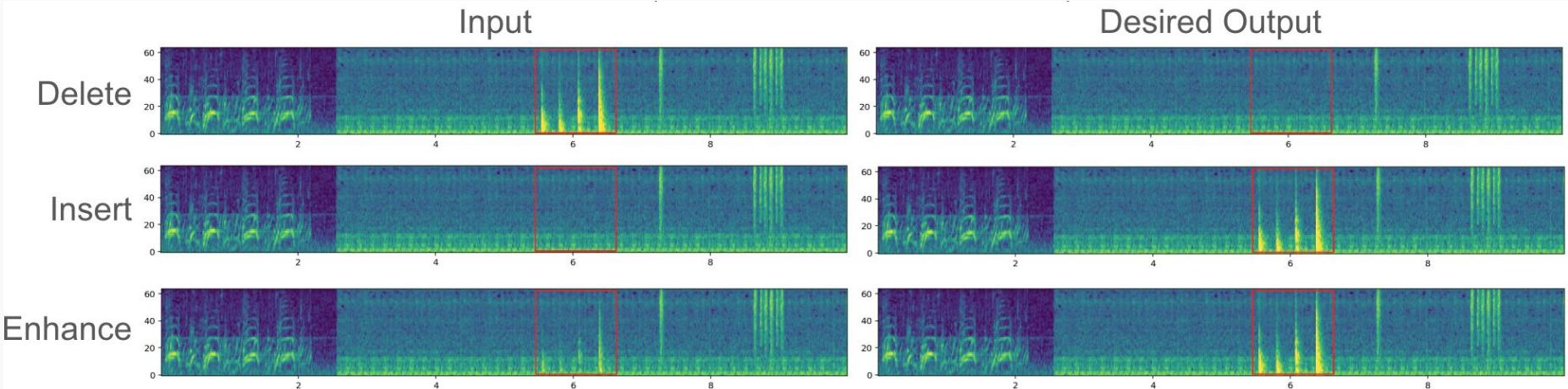
Training examples as Background + Target

- **Background** from [AudioSet](#) (Strong Labeled) (10 sec clips)
  - Selected for Complexity (> 2 classes) and Time coverage (> 9 sec nonsilent)
  - 168k clips
- **Target** events from [Freesound](#)
  - Matched by tags + AudioSet classifier
  - Automatic trimming to isolated events of 0.2 .. 2 sec
  - 16k training events from 40 “event-like” AudioSet classes



# Synthetic Target Data (cont'd)

- Synthetic data  $\{input, output\}$  pairs formed by mixing Target + Background
- Fix **Target-to-Background Ratio (TBR)** vs. the overlapping background



# Synthetic Target Data details

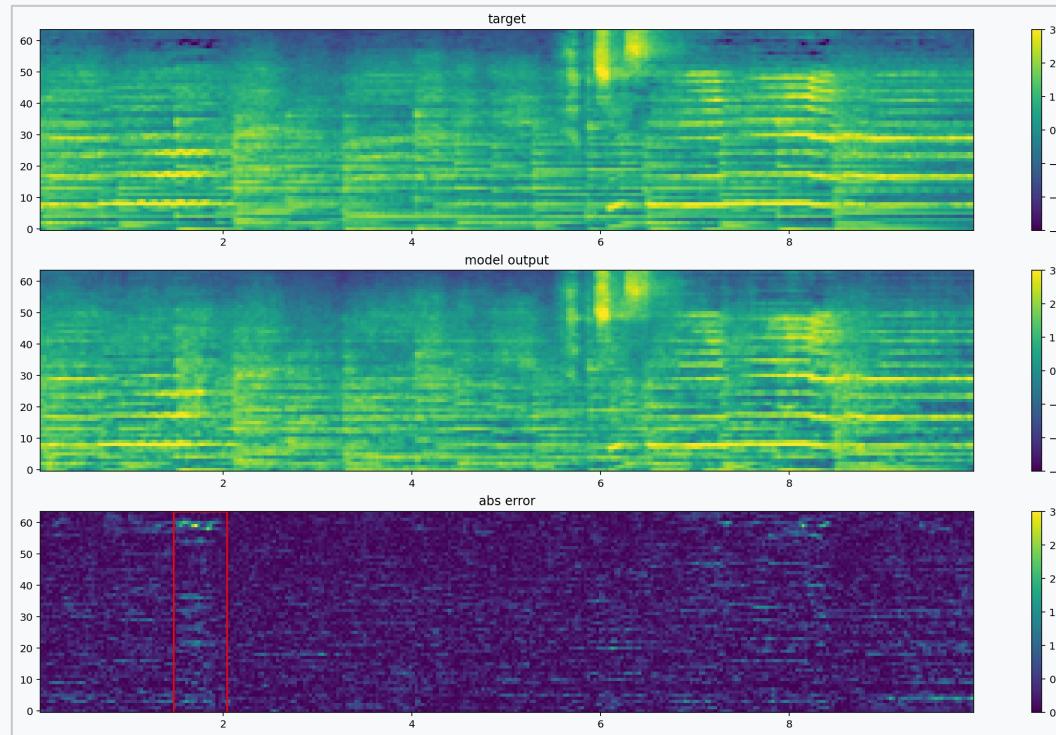
- Training: Generate **on-the-fly**  $\{input, output\}$  pairs
  - Two “Targets” per example
    - Each chosen from Enhance, Delete, Insert, or None (EDIN)
    - No time overlap between targets
  - Targets inserted at 10 ( $\pm 3$ ) dB TBR
    - Loud enough to measure, still plausible
  - Enhancement inputs at -6 ( $\pm 3$ ) dB TBR

# Metrics: Multi-Scale Spectral Distortion (MSD)

*Desired output*

*Model output*

*Absolute difference*

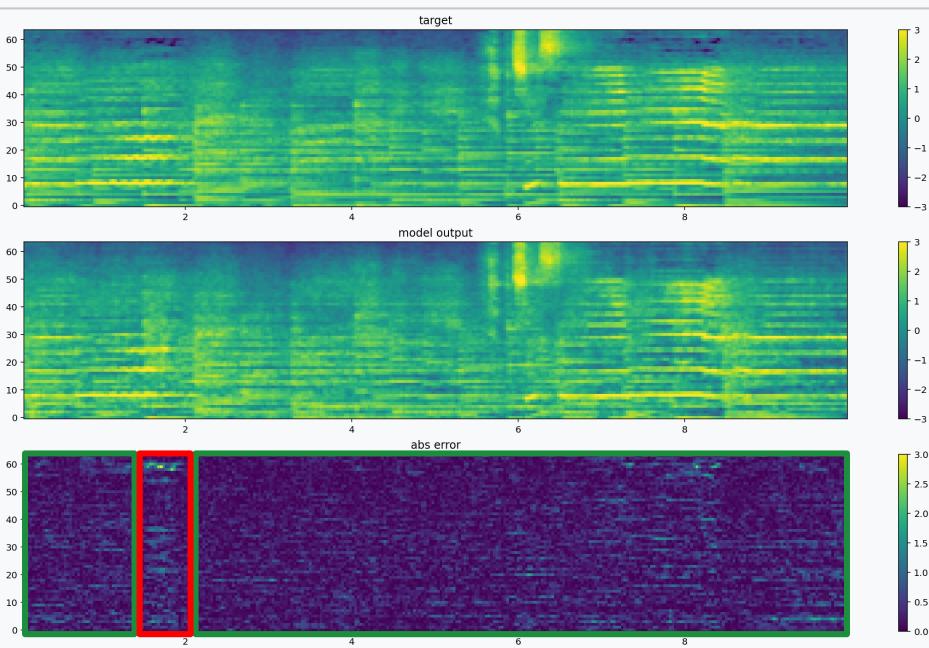


.. sum is  
~MSD

- Constant baseline “**model distortion**” - but differences are not audible

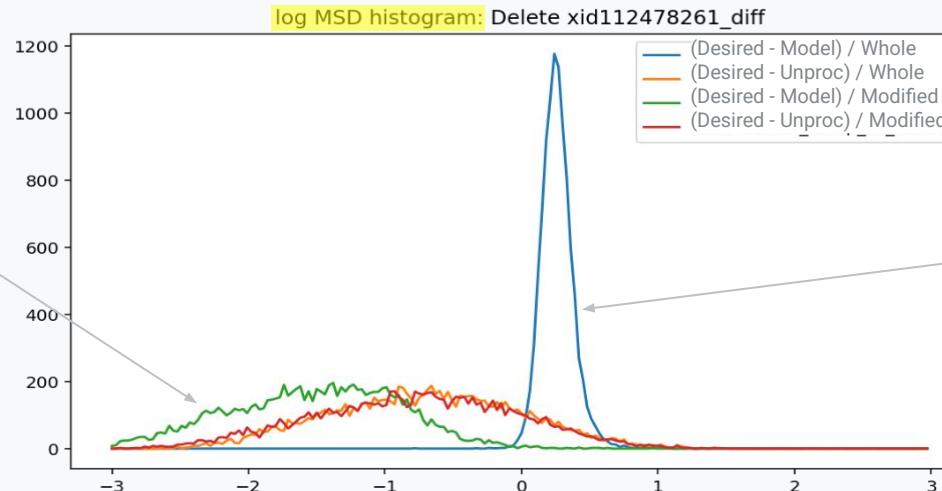
# Metrics: Modified vs. Unmodified regions

- Target event occupies ~10% of time
- “Model distortion” over remainder can dominate metrics
- **Framewise** metrics allow decomposition by time range
  - Use ground-truth target region to calculate separate metrics for **modified** & **unmodified** regions



# Metrics: Modified vs. Unmodified regions

- Look at **histograms** of metrics across eval set
  - Compare  $(\text{Desired} - \text{Model\_output})$  and  $(\text{Desired} - \text{Unprocessed})$
  - Calculate metrics over Whole\_clip vs. Modified\_region
- “Model distortion” overwhelms  $(\text{Desired} - \text{Model\_output}) / \text{Whole\_clip}$   
Restricting to Modified\_region reveals benefit:

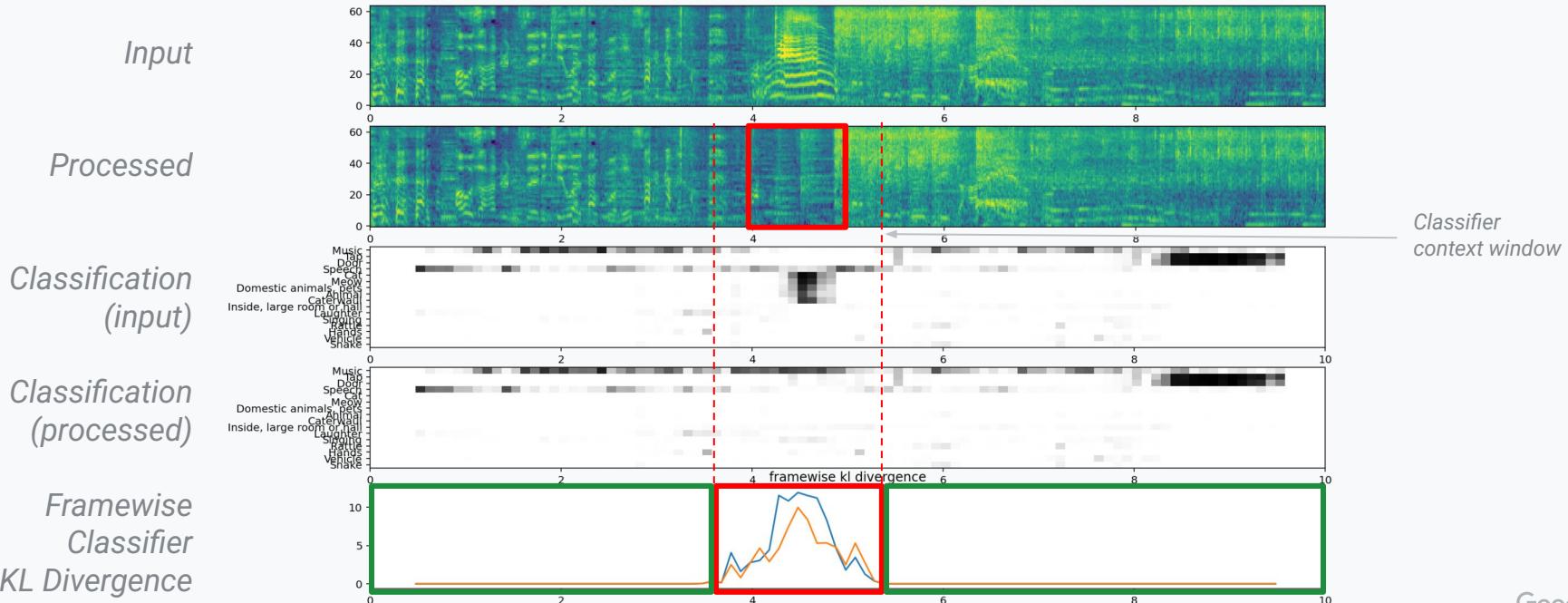


Modified\_region metrics:  
Model\_output **better**  
than Unprocessed

Whole\_clip metrics:  
Model\_output **worse**  
than Unprocessed

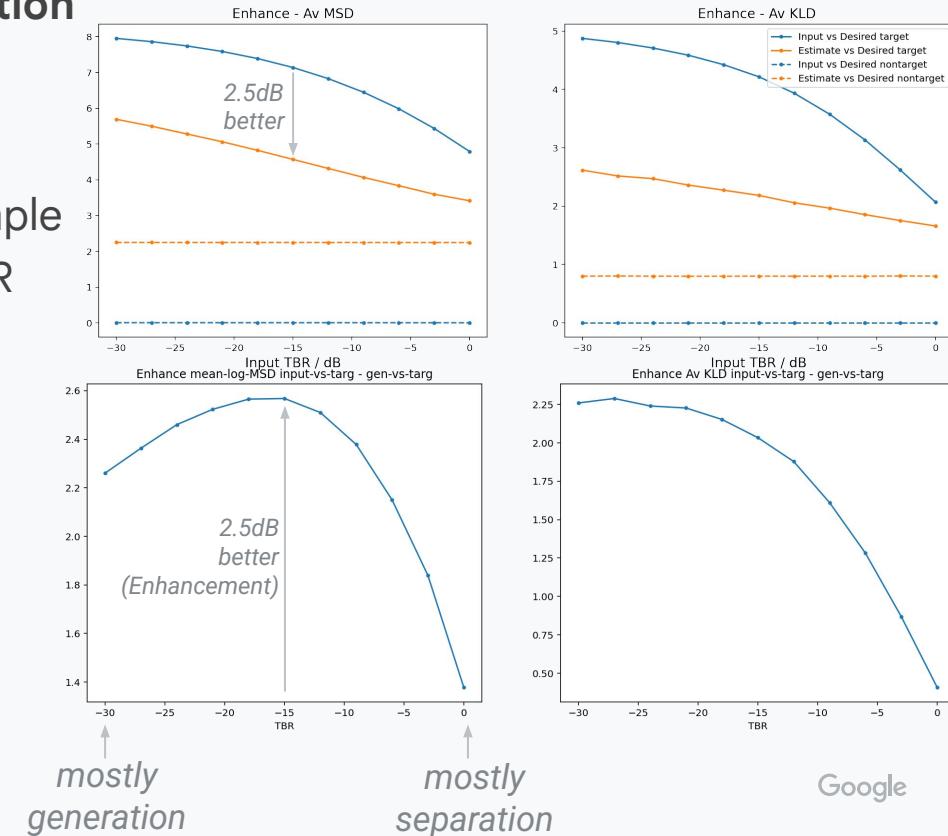
# Metrics: Classifier KL Divergence (KLD)

- KLD compares **framewise classifier** outputs - needed to evaluate **Insert**
  - **YAMNet** AudioSet classifier evaluated every 100 ms
  - Normalize each frame across class, calculate **KL divergence**, average along time



# Results: Varying Input Level for Enhancement

- Focus on generation-to-separation **transition** in Enhancement
- Training:
  - One Enhancement target per example
  - Inputs ranged over -30 to 0 dB TBR
  - Output always at +15 dB (minimize uncertainty)
- Evaluation:
  - Metrics improve with TBR
  - Improvement-over-unprocessed peaks at ~ -15 dB TBR (for MSD)
  - (KLD has no peak)



# Results: Overall Performance

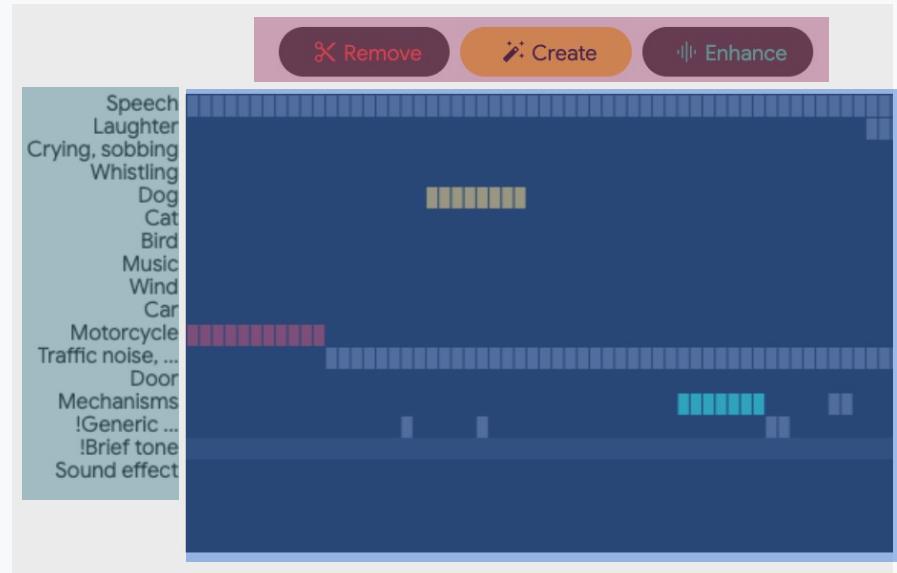
Region	Signal	Delete		Insert		Enhance	
		MSD	KLD	MSD	KLD	MSD	KLD
Target	input	4.8	1.6	4.8	2.8	3.4	1.6
	estimate	2.5	0.5	5.1	1.9	2.6	0.9
Nontarget	input	0.0	0.0	0.0	0.0	0.0	0.0
	estimate	1.3	0.3	1.3	0.3	1.3	0.3

(lower is better)

- Nontarget **input** is perfect - distances of 0
- Nontarget **estimate** is “**model distortion**” - limitation of copying
- Target **estimate** minus **input** gives **improvement** from processing
  - For MSD, **Delete** does well, **Insert** is made worse (specific output is unknown)
  - For KLD, **Insert** reveals benefit (because target class is specified)
  - **Enhance** results are for ~ -6 dB TBR inputs, limited headroom

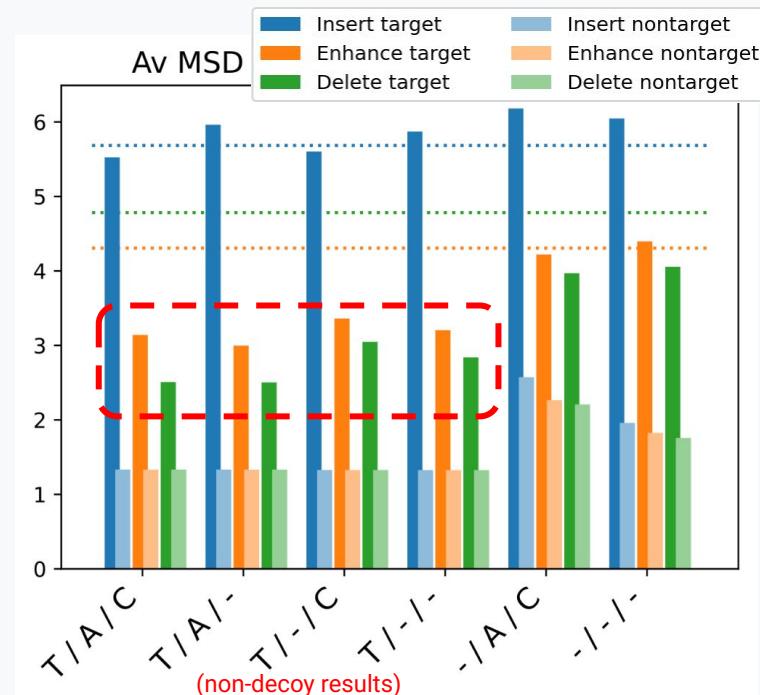
# Conditioning Ablation

- Results show improvement - we're done?
  - Or is there more insight?
- Conditioning has 3 components
  - **Timing** (Event Roll)
  - **Action** (Delete/Insert/Enhance)
  - **Class** (Description of target)
- Train 6 models with partial conditioning
- Evaluate with **Decoy** examples
  - Minimize cues in input



# Conditioning Ablation

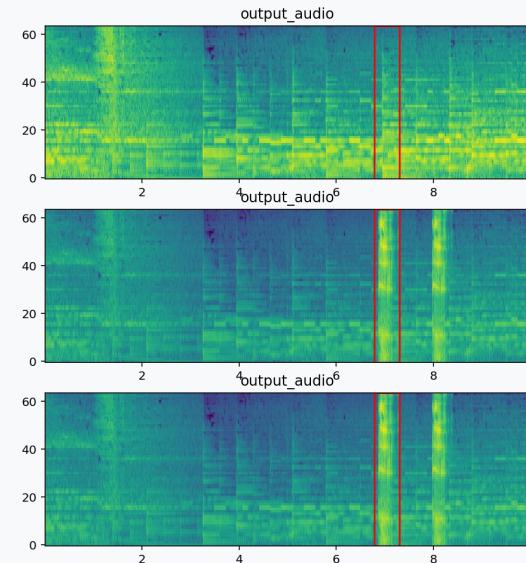
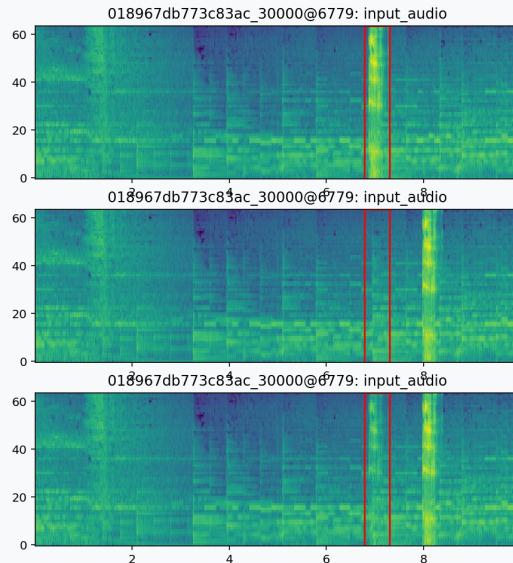
- Initial results: **Action** (and **Class**) have little impact
  - Model can infer them from input?



# Decoy Data

Each sample input has **one event** (or decoy) at 10 dB TBR

- **Delete:** Output has no event
- **Insert:** Output has a second event (event in input is **decoy**)
- **Enhance:** Input has decoy plus -6dB TBR target event



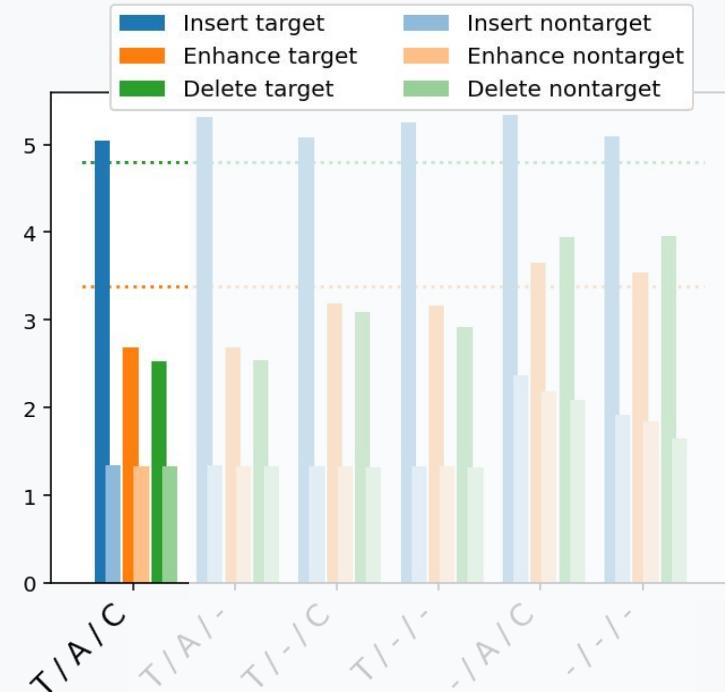
- ⇒ Model cannot guess action from input
- Model was trained with 0 .. 2 edits per sample

# Results: MSD



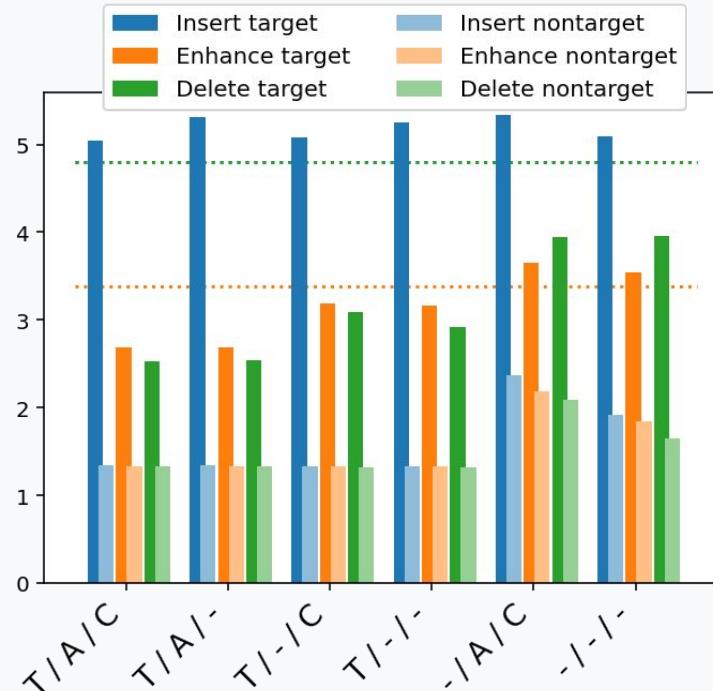
←  
*Timing  
Action  
Class*

# Results: MSD - Full-Conditioning



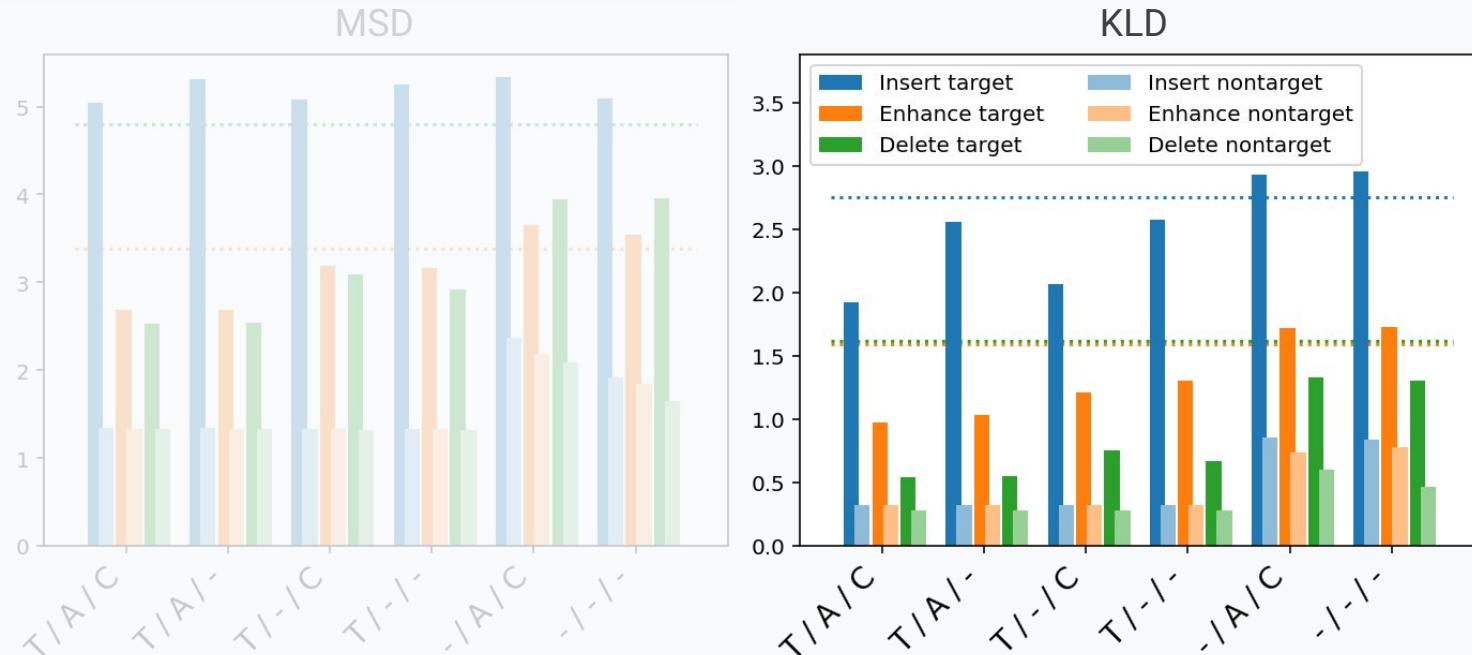
- Unprocessed baseline (dotted): **Insert & Delete same (4.8)**, **Enhance better (3.3)**
- Unmodified region (nontarget, pale bars): “Model distortion” floor (1.3)
- Modified region (target, dark bars): **Delete ~ Enhance (2.5)**, **Insert much worse (5.0)**

# Results: MSD - Conditioning Ablation



- Remove Class (T / A / -) → **Insert** worse, **Delete & Enhance** unchanged?
- Remove Action (T / - / C) → **Delete & Enhance** worse (confused?)
- Remove Timing (- / A / C) → **Delete, Enhance** (and nontarget) worse

# Results: KLD



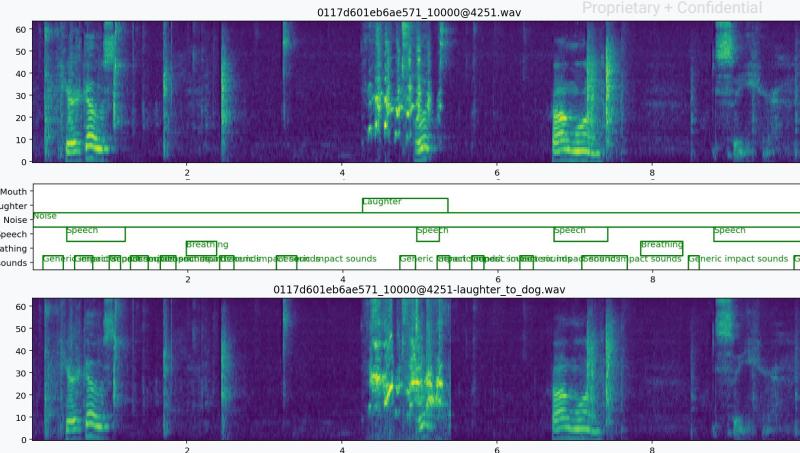
- Unprocessed baseline (dotted): **Delete** ≈ **Enhance**, but **Insert** much worse
- Processed: **Delete** better than **Enhance**
- **Insert** benefits from Class

# Future Work

- Richer **control** of generation
  - More structured attributes (loudness, pitch, reverberation)
  - Richer text-to-audio generation
    - training data?
- Broader conditioning e.g. **Video**
  - Audio-Video joint generation
- Sound **Transformation** ...

# Sound Transformation via Cross-Class Enhancement

- Input audio contains a given source\_class
- Run an enhancement-only Recomposer model to `enhance <destination\_class>` at times when the **source\_class** occurs.
  - The model was never trained to do this



<i>Clip ID</i>	<i>0239dc6ce0480dc9_30000@4598</i>	<i>0253eef2c4b4f68_230000@5512</i>	<i>0117d601eb6ae571_10000@4251</i>	<i>33ad41049a6fbf1f_30000@3207</i>
Source class	Human locomotion	Cough	Laughter	Ring
Destination class	Digestive	Dog	Dog	Bird
Input audio				
Output audio				Google

# Conclusions

- Autoregressive Encoder-Decoder models can **edit scene details**
  - **Event roll** as a precise way to specify timing
- **Ablations** reveal complex interactions
  - Each part of the conditioning has a different effect
- Future work:
  - Richer **control** of generated sound events
  - Additional conditioning, e.g. **video**