

## MATB42: Assignment #10

1. Let  $\mathbf{F}$  be a vector field on  $\mathbb{R}^3$  given by  $\mathbf{F} = (F_1, F_2, F_3)$  where  $F_1$ ,  $F_2$ , and  $F_3$  are  $C^1$ -functions from  $\mathbb{R}^3 \rightarrow \mathbb{R}$

- (a) Let  $\eta$  be the 2-form given by

$$\eta = F_3 dx dy + F_1 dy dz + F_2 dz dx$$

Show that  $d\eta = (\operatorname{div} \mathbf{F}) dx dy dz$

(page 489, #6)

$$\begin{aligned}
 \eta &= F_3 dx dy + F_1 dy dz + F_2 dz dx \\
 d\eta &= d(F_3 dx dy + F_1 dy dz + F_2 dz dx) \\
 &= (dF_3) dx dy + (dF_1) dy dz + (dF_2) dz dx \\
 &= \left( \frac{\partial}{\partial x} F_3 dx + \frac{\partial}{\partial y} F_3 dy + \frac{\partial}{\partial z} F_3 dz \right) dx dy + (dF_1) dy dz + (dF_2) dz dx \\
 &= \frac{\partial}{\partial z} F_3 dz dx dy + (dF_1) dy dz + (dF_2) dz dx \\
 &= \frac{\partial}{\partial z} F_3 dx dy dz + \left( \frac{\partial}{\partial x} F_1 dx + \frac{\partial}{\partial y} F_1 dy + \frac{\partial}{\partial z} F_1 dz \right) dy dz + (dF_2) dz dx \\
 &= \frac{\partial}{\partial z} F_3 dx dy dz + \frac{\partial}{\partial x} F_1 dx dy dz + (dF_2) dz dx \\
 &= \frac{\partial}{\partial z} F_3 dx dy dz + \frac{\partial}{\partial x} F_1 dx dy dz + \left( \frac{\partial}{\partial x} F_2 dx + \frac{\partial}{\partial y} F_2 dy + \frac{\partial}{\partial z} F_2 dz \right) dz dx \\
 &= \frac{\partial}{\partial z} F_3 dx dy dz + \frac{\partial}{\partial x} F_1 dx dy dz + \frac{\partial}{\partial y} F_2 dy dz dx \\
 &= \frac{\partial}{\partial z} F_3 dx dy dz + \frac{\partial}{\partial x} F_1 dx dy dz + \frac{\partial}{\partial y} F_2 dx dy dz \\
 &= \frac{\partial}{\partial x} F_1 + \frac{\partial}{\partial y} F_2 + \frac{\partial}{\partial z} F_3 dx dy dz = (\operatorname{div} \mathbf{F}) dx dy dz
 \end{aligned}$$

(b) Show that  $dF_1 \wedge dF_2 \wedge dF_3 = (\det D\mathbf{F}) dx dy dz$

$$df = \sum_{i=0}^n \frac{\partial f}{\partial x_i} dx_i$$

$$\begin{aligned}
dF_1 \wedge dF_2 \wedge dF_3 &= \left( \frac{\partial F_1}{\partial x} dx + \frac{\partial F_1}{\partial y} dy + \frac{\partial F_1}{\partial z} dz \right) \wedge \left( \frac{\partial F_2}{\partial x} dx + \frac{\partial F_2}{\partial y} dy + \frac{\partial F_2}{\partial z} dz \right) \wedge dF_3 \\
&= \left( \frac{\partial F_1}{\partial x} dx \wedge \left( \frac{\partial F_2}{\partial x} dx + \frac{\partial F_2}{\partial y} dy + \frac{\partial F_2}{\partial z} dz \right) \right. \\
&\quad + \frac{\partial F_1}{\partial y} dy \wedge \left( \frac{\partial F_2}{\partial x} dx + \frac{\partial F_2}{\partial y} dy + \frac{\partial F_2}{\partial z} dz \right) \\
&\quad \left. + \frac{\partial F_1}{\partial z} dz \wedge \left( \frac{\partial F_2}{\partial x} dx + \frac{\partial F_2}{\partial y} dy + \frac{\partial F_2}{\partial z} dz \right) \right) \wedge dF_3 \\
&= \left( \left( \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial y} dx dy + \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial z} dx dz \right) \right. \\
&\quad + \left( \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial x} dy dx + \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial z} dy dz \right) \\
&\quad \left. + \left( \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial x} dz dx + \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial y} dz dy \right) \right) \wedge dF_3 \\
&= \left( \left( \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial y} - \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial x} \right) dx dy \right. \\
&\quad + \left( \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial z} - \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial y} \right) dy dz \\
&\quad \left. + \left( \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial z} \right) dz dx \right) \wedge \left( \frac{\partial F_3}{\partial x} dx + \frac{\partial F_3}{\partial y} dy + \frac{\partial F_3}{\partial z} dz \right) \\
&= \left( \frac{\partial F_3}{\partial z} \left( \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial y} - \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial x} \right) dx dy \right. \\
&\quad + \frac{\partial F_3}{\partial x} \left( \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial z} - \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial y} \right) dy dz \\
&\quad \left. + \frac{\partial F_3}{\partial y} \left( \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial z} \right) dz dx \right) \\
&= \frac{\partial F_3}{\partial x} \left( \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial z} - \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial y} \right) dx dy dz \\
&\quad - \frac{\partial F_3}{\partial y} \left( \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial z} - \frac{\partial F_1}{\partial z} \frac{\partial F_2}{\partial x} \right) dx dy dz \\
&\quad + \frac{\partial F_3}{\partial z} \left( \frac{\partial F_1}{\partial x} \frac{\partial F_2}{\partial y} - \frac{\partial F_1}{\partial y} \frac{\partial F_2}{\partial x} \right) dx dy dz \\
&= \frac{\partial F_3}{\partial x} \begin{vmatrix} \frac{\partial F_1}{\partial y} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \end{vmatrix} - \frac{\partial F_3}{\partial y} \begin{vmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial z} \end{vmatrix} + \frac{\partial F_3}{\partial z} \begin{vmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} \end{vmatrix} dx dy dz \\
&= \begin{vmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \\ \frac{\partial F_3}{\partial x} & \frac{\partial F_3}{\partial y} & \frac{\partial F_3}{\partial z} \end{vmatrix} dx dy dz
\end{aligned}$$

2. Let  $\omega$  be a  $k$ -form and let  $\eta$  be a  $\ell$ -form. Find  $d(d\omega \wedge \eta - \omega \wedge d\eta)$ .

$$\begin{aligned}
 d(d\omega \wedge \eta - \omega \wedge d\eta) &= d(d\omega \wedge \eta) - d(\omega \wedge d\eta) \\
 &= (d^2\omega \wedge \eta + (-1)^{k+1}(d\omega \wedge d\eta)) - (d\omega \wedge d\eta + (-1)^k(\omega \wedge d^2\eta)) \\
 &= (-1)^{k+1}d\omega \wedge d\eta - d\omega \wedge d\eta \\
 &= ((-1)^{k+1} - 1)d\omega \wedge d\eta
 \end{aligned}$$

3. Determine if  $\eta = y \, dx \, dy + xz \, dy \, dz - yz \, dz \, dx$  is exact. If  $\eta$  is exact find a 1-form  $\omega$  with  $d\omega = \eta$ . Check if  $d\eta = \mathcal{O}$  to see if  $\eta$  closed.

(compare with page 461, # 22)

$$\begin{aligned}
 d\eta &= d(y \, dx \, dy + xz \, dy \, dz - yz \, dz \, dx) \\
 &= (dy \, dx \, dy + d(xz) \wedge dy \, dz - d(yz) \wedge dz \, dx) \\
 &= ((z \, dx + x \, dz) \wedge dy \, dz - (z \, dy + y \, dz) \wedge dz \, dx) \\
 &= (z \, dx) \wedge dy \, dz - (z \, dy) \wedge dz \, dx \\
 &= z \, dx \, dy \, dz - z \, dx \, dy \, dz = \mathcal{O}
 \end{aligned}$$

Since the polynomials of  $x$ ,  $y$  and  $z$  defined throughout  $\mathbb{R}^3$  and  $\eta$  closed, it is exact. By inspection,

$$\omega = xy \, dy + xyz \, dz$$

4. Evaluate  $\iint_S \omega$ , where  $\omega = z dx dy + x dy dz + y dz dx$  and  $S$  is the unit sphere, directly and by the Divergence Theorem.

(page 489, #12)

Directly:

Parametrize the sphere  $S$  as

$$\Phi(\varphi, \theta) = (\cos \theta \sin \varphi, \sin \theta \sin \varphi, \cos \varphi) \text{ with } \theta \in [0, 2\pi], \varphi \in [0, \pi]$$

$$\begin{aligned} \iint_S \omega &= \iint_{\Phi} z dx dy + \iint_{\Phi} x dy dz + \iint_{\Phi} y dz dx \\ &= \int_0^{2\pi} \int_0^{\pi} \cos \varphi \begin{vmatrix} \frac{\partial \cos \theta \sin \varphi}{\partial \varphi} & \frac{\partial \cos \theta \sin \varphi}{\partial \theta} \\ \frac{\partial \sin \theta \sin \varphi}{\partial \varphi} & \frac{\partial \sin \theta \sin \varphi}{\partial \theta} \end{vmatrix} d\varphi d\theta + \int_0^{2\pi} \int_0^{\pi} \cos \theta \sin \varphi \begin{vmatrix} \frac{\partial \sin \theta \sin \varphi}{\partial \varphi} & \frac{\partial \sin \theta \sin \varphi}{\partial \theta} \\ \frac{\partial \cos \varphi}{\partial \varphi} & \frac{\partial \cos \varphi}{\partial \theta} \end{vmatrix} d\varphi d\theta \\ &\quad + \int_0^{2\pi} \int_0^{\pi} \sin \theta \sin \varphi \begin{vmatrix} \frac{\partial \cos \varphi}{\partial \varphi} & \frac{\partial \cos \varphi}{\partial \theta} \\ \frac{\partial \cos \theta \sin \varphi}{\partial \varphi} & \frac{\partial \cos \theta \sin \varphi}{\partial \theta} \end{vmatrix} d\varphi d\theta \\ &= \int_0^{2\pi} \int_0^{\pi} \cos \varphi \begin{vmatrix} \cos \theta \cos \varphi & -\sin \theta \sin \varphi \\ \sin \theta \cos \varphi & \cos \theta \sin \varphi \end{vmatrix} d\varphi d\theta + \int_0^{2\pi} \int_0^{\pi} \cos \theta \sin \varphi \begin{vmatrix} \sin \theta \cos \varphi & \cos \theta \sin \varphi \\ -\sin \varphi & 0 \end{vmatrix} d\varphi d\theta \\ &\quad + \int_0^{2\pi} \int_0^{\pi} \sin \theta \sin \varphi \begin{vmatrix} -\sin \varphi & 0 \\ \cos \theta \cos \varphi & -\sin \theta \sin \varphi \end{vmatrix} d\varphi d\theta \\ &= \int_0^{2\pi} \int_0^{\pi} \sin \varphi \cos^2 \varphi d\varphi d\theta + \int_0^{2\pi} \int_0^{\pi} \cos^2 \theta \sin^3 \varphi + \sin^2 \theta \sin^3 \varphi d\varphi d\theta \\ &= \int_0^{2\pi} \int_0^{\pi} \sin \varphi (\cos^2 \varphi + \sin^2 \varphi) d\varphi d\theta \\ &= \int_0^{2\pi} \int_0^{\pi} \sin \varphi d\varphi d\theta \\ &= 2\pi \left[ -\cos \varphi \right]_0^{\pi} = 2\pi \end{aligned}$$

Divergence Theorem:

$$d\omega = dz dy dx + dx dy dz + dy dz dx = 3 dx dy dz$$

$$\begin{aligned} \iint_S \omega &= \iiint_R d\omega \\ &= 3 \int_0^{2\pi} \int_0^{\pi} \int_0^1 \rho^2 \sin(\varphi) d\rho d\varphi d\theta \\ &= \int_0^{2\pi} \int_0^{\pi} \sin(\varphi) d\varphi d\theta \\ &= 2\pi \left[ -\cos \varphi \right]_0^{\pi} = 2\pi \end{aligned}$$

5. Compute  $\int_S \omega$  and use symbolic algebra software to sketch  $S$  in each of the following.

(a)  $\omega = xz \, dx \, dy + x^2 \, dy \, dz + dy \, dz \, dx$

$S$  is the upper hemisphere  $x^2 + y^2 + z^2 = 4, z \geq 0$  with  $\mathbf{n}$  pointing upward.

Close it with the disk of radius 2 on the  $xy$ -plane to apply divergence theorem

$$\Phi(\theta, r) = (r \cos \theta, r \sin \theta, 0), \quad r \in [0, 2], \quad \theta \in [0, 2\pi]$$

$$dx \, dy = \begin{vmatrix} -r \sin \theta & \cos \theta \\ r \cos \theta & \sin \theta \end{vmatrix} = -2r$$

Which is negative, so correct orientation for normal pointing down.

$$dy \, dz = 0 \quad \text{Since } z \text{ is } 0$$

$$dz \, dx = 0$$

$$\stackrel{\text{Div Thm}}{\implies} \iint_S \omega = \iiint_R d\omega - \iint_{\Phi} \omega$$

$$\text{But } z = 0 \implies xz \, dx \, dy = 0 \implies \iint_{\Phi} \omega = 0$$

$$d\omega = x \, dx \, dy \, dz + 2x \, dx \, dy \, dz = 3x \, dx \, dy \, dz$$

$$\iiint_R d\omega = \int_0^2 \int_0^{2\pi} \int_0^{\frac{\pi}{2}} 3(\rho \sin \varphi \cos \theta) \rho^2 \sin \varphi \, d\varphi \, d\theta \, d\rho$$

$$= 0 \quad \text{Since integrating } \cos \text{ over full period}$$

$$\implies \int_S \omega = 0$$



(b)  $\omega = z \, dx \, dy + x \, dy \, dz + y \, dz \, dx$

$S$  is the part of the plane  $x + y + z = 1$  which lies in the first octant oriented by the unit normal which points upward.

Use the natural parametrization for  $S$ :

$$\Phi(x, y) = (x, y, 1 - x - y), \quad x \in [0, 1], \quad y \in [0, 1 - x]$$

$$dx \, dy = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} > 0 \, \forall x, y \implies \text{Correct orientation}$$

$$\begin{aligned} \int_S \omega &= \int_0^1 \int_0^{1-x} (1 - x - y) + x \begin{vmatrix} 0 & 1 \\ -1 & -1 \end{vmatrix} + y \begin{vmatrix} -1 & -1 \\ 1 & 0 \end{vmatrix} dy \, dx \\ &= \int_0^1 \int_0^{1-x} 1 \, dy \, dx = \int_0^1 1 - x \, dx \\ &= 1 - \frac{1}{2} = \frac{1}{2} \end{aligned}$$



(c)  $\omega = xz \, dx \, dy + y \, dx \, dz + z^2 \, dy \, dz$

$S$  is the part of the cone  $z = \sqrt{x^2 + y^2}$  between  $z = 1$  and  $z = 3$ , oriented by the unit normal with negative  $z$ -component.

$$\Phi(\theta, r) = (r \cos \theta, r \sin \theta, r), \quad r \in [1, 3], \quad \theta \in [0, 2\pi]$$

$$dx \, dy = \begin{vmatrix} -r \sin \theta & \cos \theta \\ r \cos \theta & \sin \theta \end{vmatrix} = -r < 0 \text{ for } r > 1$$

$$dy \, dz = \begin{vmatrix} r \cos \theta & \sin \theta \\ 0 & 1 \end{vmatrix} = r \cos \theta$$

$$dz \, dx = \begin{vmatrix} 0 & 1 \\ -r \sin \theta & \cos \theta \end{vmatrix} = r \sin \theta$$

$$\Rightarrow \omega = (r \cos \theta)(r)(-r) - (r \sin \theta)(r \sin \theta) + (r)^2(r \cos \theta)$$

$$= -r^2 \sin^2 \theta = -r^2 \left( \frac{1}{2} - \frac{\cos(2\theta)}{2} \right)$$

$$\Rightarrow \int_S \omega = \int_1^3 \int_0^{2\pi} -r^2 \left( \frac{1}{2} - \frac{\cos(2\theta)}{2} \right) d\theta \, dr$$

$$= \int_1^3 -r^2 \pi \, dr = -\pi \left[ \frac{r^3}{3} \right]_1^3 = -\frac{26\pi}{3}$$



(d)  $\omega = z \, dx \, dy + y \, dy \, dz$

$S$  is the oriented surface given by the parametrization

$$\Phi(u, v) = (u + v, uv^2, u^2 + v^2), \quad 0 \leq u \leq 1, \quad 0 \leq v \leq 1.$$

$$dx \, dy = \begin{vmatrix} 1 & 1 \\ v^2 & 2uv \end{vmatrix} = 2uv - v^2, \quad dy \, dz = \begin{vmatrix} v^2 & 2uv \\ 2u & 2v \end{vmatrix} = 2v^3 - 4u^2v$$

$$\begin{aligned} \iint_S \omega &= \int_0^1 \int_0^1 (u^2 + v^2)(2uv - v^2) + (uv^2)(2v^3 - 4u^2v) \, du \, dv \\ &= \int_0^1 \int_0^1 (2u^3v - u^2v^2) + (2uv^3 - v^4) + (2uv^5 - 4u^3v^3) \, du \, dv \\ &= \int_0^1 \left( \frac{v}{2} - \frac{v^2}{3} + v^3 - v^4 + v^5 - v^3 \right) \, dv \\ &= \int_0^1 \left( \frac{v}{2} - \frac{v^2}{3} - v^4 + v^5 \right) \, dv \\ &= \frac{1}{4} - \frac{1}{9} - \frac{1}{5} + \frac{1}{6} = \frac{19}{180} \end{aligned}$$





6. Verify Stokes' theorem by direct calculation of both sides when the surface  $S$  is the piece of the paraboloid  $z = x^2 + y^2 - 4$  with  $z \leq 0$ , oriented by the downward pointing unit normal, and  $\omega = (2y - z) dx + (x + y^2 - z) dy + (4y - 3x) dz$ .

As part of your solution, provide a sketch showing the appropriate orientations. (For this question you may draw the sketch by hand or use symbolic algebra software.)

Stokes' Theorem states that:

$$\int_{\partial S} \omega = \int_S d\omega$$

Calculation of  $\int_{\partial S} \omega$

The boundary curve of the plane is the circle at  $z = 0$  with radius 2. Since the normal vector is downward pointing, the curve is parametrized clockwise. So parametrize the curve as  $\gamma(\theta) = (-2 \cos \theta, 2 \sin \theta, 0)$

$$\begin{aligned} & \int_0^{2\pi} (2(2 \sin \theta) - 0)(2 \sin \theta) + ((-2 \cos \theta) + (2 \sin \theta)^2 - 0)(2 \cos \theta) d\theta \\ &= \int_0^{2\pi} 8 \sin^2 \theta - 4 \cos^2 \theta + 8 \sin^2 \theta \cos \theta d\theta \\ &= \int_0^{2\pi} 4(1 - \cos(2\theta)) - 2(1 + \cos(2\theta)) + 8 \sin^2 \theta \cos \theta d\theta \\ &= \int_0^{2\pi} 2 + 8 \sin^2 \theta \cos \theta d\theta \\ &= 4\pi + \left[ \frac{8 \sin^3 \theta}{3} \right]_0^{2\pi} = 4\pi \end{aligned}$$

Calculation of  $\int_S d\omega$

(Using the parametrization  $\Phi(\theta, r) = (r \cos \theta, r \sin \theta, r^2 - 4)$ ,  $r \in [0, 2]$ ,  $\theta \in [0, 2\pi]$ )

$$dx dy = \begin{vmatrix} -r \sin \theta & \cos \theta \\ r \cos \theta & \sin \theta \end{vmatrix} = -r$$

So the orientation is in the correct direction.

$$\begin{aligned} d\omega &= d(2y - z) dx + d(x + y^2 - z) dy + d(4y - 3x) dz \\ &= (2 dy - dz) \wedge dx + (dx - dz) \wedge dy + (4 dy - 3 dx) \wedge dz \\ &= -2 dx dy - dz dx + dx dy + dy dz + 4 dy dz + 3 dz dx \\ &= -dx dy + 5 dy dz + 2 dz dx \\ \Rightarrow \int_S d\omega &= \int_0^{2\pi} \int_0^2 \begin{vmatrix} -r \sin \theta & \cos \theta \\ r \cos \theta & \sin \theta \end{vmatrix} + 5 \begin{vmatrix} r \cos \theta & \sin \theta \\ 0 & 2r \end{vmatrix} + 2 \begin{vmatrix} 0 & 2r \\ -r \sin \theta & \cos \theta \end{vmatrix} dr d\theta \\ &= \int_0^{2\pi} \int_0^2 r + 5(2r^2 \cos \theta) + 2(2r^2 \sin \theta) dr d\theta \\ &= 2\pi \int_0^2 r dr = 4\pi \end{aligned}$$

7. Let  $\omega = yz \, dx - xz \, dy + xy \, dz$  and let  $\gamma(t) = (2 \cos t, 2 \sin t, 4)$ ,  $0 \leq t \leq 2\pi$ .

$$\begin{aligned} d\omega &= d(yz) \wedge dx - d(xz) \wedge dy + d(xy) \wedge dz \\ &= (z \, dy + y \, dz) \wedge dx - (z \, dx + x \, dz) \wedge dy + (y \, dx + x \, dy) \wedge dz \\ &= z \, dy \, dx + y \, dz \, dx - z \, dx \, dy - x \, dz \, dy + y \, dx \, dz + x \, dy \, dz \\ &= -2z \, dx \, dy + 2x \, dy \, dz \end{aligned}$$

- (a) Let  $S$  be the piece of the surface  $z = x^2 + y^2$  with  $z \leq 4$ . Use Stokes' theorem to give an integral over  $S$  which is equivalent to  $\int_{\gamma} \omega$ . Verify by directly computing both integrals.

Note that the boundary of  $S$  at  $z = 4$  is  $\gamma$ . This means that, if the orientation is compatible, Stokes' theorem will apply. Since the orientation of the curve is counter clockwise, the normal vector should be pointing up for the surface.

Note that the disk  $S$  can be parametrized as  $\Phi(r, \theta) = (r \cos \theta, r \sin \theta, 4)$ ,  $r \in [0, 2]$ ,  $\theta \in [0, 2\pi]$  as we have that

$$dx \, dy = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \geq 0$$

$$\xRightarrow{\text{Stokes' Thm}} \int_{\partial S = \gamma} \omega = \int_S d\omega$$

$$\begin{aligned} \int_{\gamma} \omega &= \int_0^{2\pi} (2 \sin t)(4)(-2 \sin t) - (2 \cos t)4(2 \cos t) \, dt \\ &= \int_0^{2\pi} -16(\sin^2 t + \cos^2 t) \, dt \\ &= \int_0^{2\pi} -16 \, dt = -32\pi \\ \int_S d\omega &= \int_0^2 \int_0^{2\pi} -2(4)(r) + 0 \, d\theta \, dr \\ &= \int_0^2 -16r \, d\theta \, dr \\ &= -16 \left[ \frac{r^2}{2} \right]_0^2 \end{aligned}$$

- (b) Let  $S'$  be the part of the plane  $z = 4$  with  $x^2 + y^2 \leq 4$ . Use Stokes' theorem to give an integral over  $S'$  which is equivalent to  $\int_{\gamma} \omega$ . Verify by direct computation.

- (c) Can you give another explanation as to why the integrals you get over  $S$  and  $S'$  should have the same value?

8. Let  $\mathbf{F}(x, y, z) = (e^{z^2}, 4z - y, 8x \sin y)$ . Find  $\int_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S}$  where  $S$  is the unit sphere oriented with the outward normal.

9. (a) Marsden & Tromba, page 451, # 13.

Let  $S$  be the capped cylindrical surface shown in Figure 1.  $S$  is the union of two surfaces,  $S_1$  and  $S_2$ , where  $S_1$  is the set of  $(x, y, z)$  with  $x^2 + y^2 = 1$ ,  $0 \leq z \leq 1$ , and  $S_2$  is the set of  $(x, y, z)$  with  $x^2 + y^2 + (z - 1)^2 = 1$ ,  $z \geq 1$ . Set  $\mathbf{F}(x, y, z) = (zx + z^2y + x)\mathbf{i} + (z^3yx + y)\mathbf{j} + z^4x^2\mathbf{k}$ . Compute

$$\iint_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S}. \quad (\text{HINT: Stokes' theorem holds for this surface.})$$

- (b) Marsden & Tromba, page 451, # 15.

Evaluate the integral  $\iint_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S}$ , where  $S$  is the portion of the surface of a sphere defined by  $x^2 + y^2 + z^2 = 1$  and  $x + y + z \geq 1$ , and where  $\mathbf{F} = \mathbf{r} \times (\mathbf{i} + \mathbf{j} + \mathbf{k})$ ,  $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ .

- (c) Use symbolic algebra software to sketch the surfaces in parts (a) and (b).

10. (a) Let  $\mathbf{F}$  and  $\mathbf{G}$  be vector fields on  $\mathbb{R}^3$  and let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ . Verify the following identities.
- (i)  $\operatorname{div}(\mathbf{F} \times \mathbf{G}) = \mathbf{G} \cdot \operatorname{curl} \mathbf{F} - \mathbf{F} \cdot \operatorname{curl} \mathbf{G}$ .
  - (ii)  $\operatorname{curl}(f\mathbf{F}) = f\operatorname{curl} \mathbf{F} + (\operatorname{grad} f) \times \mathbf{F}$ .
- (b) Let  $R$  be a closed region in  $\mathbb{R}^3$  with boundary  $\partial R$ . Prove the identity

$$\int_{\partial R} (\mathbf{F} \times \operatorname{curl} \mathbf{G}) \cdot d\mathbf{S} = \int_R (\operatorname{curl} \mathbf{F}) \cdot (\operatorname{curl} \mathbf{G}) dV - \int_R \mathbf{F} \cdot \operatorname{curl}(\operatorname{curl} \mathbf{G}) dV$$

(page 490, #2)