

## Ex 6

### Implementation of unification for real-world problems

```
from collections import deque

class Graph:

    def __init__(self, adjacency_list):
        self.adjacency_list = adjacency_list

    def get_neighbors(self, v):
        return self.adjacency_list[v]

    def h(self, n):
        H = {
            'A': 1,
            'B': 1,
            'C': 1,
            'D': 1
        }

        return H[n]

    def a_star_algorithm(self, start_node, stop_node):

        open_list = set([start_node])
        closed_list = set([])

        g = {}

        g[start_node] = 0

        parents = {}
        parents[start_node] = start_node
```

```

while len(open_list) > 0:
    n = None

    for v in open_list:
        if n == None or g[v] + self.h(v) < g[n] + self.h(n):
            n = v;

    if n == None:
        print('Path does not exist!')
        return None

    if n == stop_node:
        reconst_path = []

        while parents[n] != n:
            reconst_path.append(n)
            n = parents[n]

        reconst_path.append(start_node)

        reconst_path.reverse()

        print('Path found: {}'.format(reconst_path))
        return reconst_path

    for (m, weight) in self.get_neighbors(n):

        if m not in open_list and m not in closed_list:
            open_list.add(m)
            parents[m] = n
            g[m] = g[n] + weight

        else:
            if g[m] > g[n] + weight:
                g[m] = g[n] + weight
                parents[m] = n

```



```
        if m in closed_list:
            closed_list.remove(m)
            open_list.add(m)

    open_list.remove(n)
    closed_list.add(n)

    print('Path does not exist!')
    return None

adjacency_list = {
    'A': [('B', 1), ('C', 3), ('D', 7)],
    'B': [('D', 5)],
    'C': [('D', 12)]
}

graph1 = Graph(adjacency_list)
graph1.a_star_algorithm('A', 'D')
```

 Run 

Command: RA1911033010060/exp5/astar.py

Path found: ['A', 'B', 'D']

Process exited with code: 0