Simple Models and Biased Forecasts

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 - all state-space models of a given dimension
- (2) All models in the class are too simple relative to the truth, i.e., they are misspecified.
 - the models are low-dimensional
- (3) Study the long-run limit where agents' estimates have settled.
 - agents settle on pseudo-true models that approximate the true model

The Framework

• Discrete-time economy with a single agent (for now).

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 - for now, assume \mathbb{P} is exogenous (will be endogenous in GE)
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- The agent is attempting to forecast future values of the observables.
 - time-t information set is $\{y_{\tau}\}_{\tau=-\infty}^t$
 - agent uses a model to map past observables to her forecasts:

$$\theta: \{y_{\tau}\}_{\tau=-\infty}^{t} \mapsto E_{t}^{\theta}[\cdot]$$

Main assumption: the agent can only entertain stationary ergodic distributions P^{θ} that can be represented by state-space models with at most d states.

$$\begin{split} z_t &= A z_{t-1} + w_t, & w_t \sim \text{ i.i.d. } \mathcal{N}(0, Q) \\ y_t &= B' z_t + v_t, & v_t \sim \text{ i.i.d. } \mathcal{N}(0, R) \end{split}$$

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- I take d to be (much) smaller than n.
- $\theta \equiv (A, B, Q, R)$ is estimated endogenously by the agent.

Cross-Sectional and Times-Series Complexity

A dichotomy: model θ is unconstrained other than the constraint on d.

- The agent can entertain *any* linear cross-sectional relationship between variables.
- But is constrained in the types of time-series relationships she can perceive.

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Stark assumption, but...

- It allows me to focus on the difficulty of dealing with time-series complexity.
 - Cross-sectional complexity is the focus of rational inattention, sparsity, etc.
- It leads to a useful linear invariance property for expectations.

A Complementary Interpretation: Limited Memory

Models with *d* running statistics

• Running statistics:

$$s_t \in \mathbb{R}^d$$

• The running statistics are updated linearly over time:

$$s_t = Ms_{t-1} + Ky_t$$

• Forecasts are linear functions of the running statistics:

$$E_t[y_{t+\tau}] = \mathbf{v}_{\tau}' \mathbf{s}_t$$

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An equivalence result: d-state models \approx models with d running statistics

Endogenizing the Agent's Model

Two ways of specifying the agent's model $\theta \equiv (A, B, Q, R)$:

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Focus on the limit where the agent has infinite date:

- The agent (generically) ends up with the same model using both approaches.
- The limiting model is a pseudo-true model that minimizes KLDR:

$$\lim_{t\to\infty}\frac{1}{t}\mathbb{E}\left[\log\left(\frac{\mathbb{f}(y_1,\ldots,y_t)}{f^{\theta}(y_1,\ldots,y_t)}\right)\right]$$

The Plan

The rest of the talk...

- 1. (Some) qualitative features of pseudo-true one-state models.
- 2. (Some) implications for agents' forecasts and actions.
- 3. Propagation of TFP shocks in the RBC model.
- 4. Propagation of separation and productivity shocks in the DMP model.

Relation to the Literature

- Misspecified learning: Berk (1966), Huber (1967), White(1982, 1994), Shalizi (2009), Esponda–Pouzo (2016, 2021), ...
 - not about learning foundations
 - characterize properties of pseudo-true models

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- Noisy information/rational inattention/sparsity: Mankiw–Reis (2002), Sims (2003), Woodford (2003), Gabaix (2014), Angeletos–Lian (2018), ...
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 - perfect knowledge of current variables
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 - can only understand simple time-series relationships
- Bounded rationality with pseudo-true models: Sawa (1978), Bray (1982), Bray–Savin (1986), Rabin–Vayanos (2010), Fuster–Laibson–Mendel (2010), Fuster–Hebert–Laibson (2012), Spiegler (2016), Levy–Razin–Young (2021), Molavi–Tahbaz-Salehi–Vedolin (2023), ...

Pseudo-True One-State Models

An Invariance Result

Theorem (linear invariance)

Consider two agents:

- Agent i observes y_t and uses pseudo-true model θ .
- Agent j observes $\tilde{y}_t = Ty_t$ and uses pseudo-true model $\tilde{\theta}$.

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Pseudo-true simple models respect all linear intratemporal relationships...

$$E_t^{\theta}[\alpha y_{1,t+s} + \beta y_{2,t+s}] = \alpha E_t^{\theta}[y_{1,t+s}] + \beta E_t^{\theta}[y_{2,t+s}]$$

• Not always true in non-RE models.

No Misperception in the Cross Section

Theorem

Under any pseudo-true model θ ,

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- The agent correctly perceived all the cross-sectional correlations.
- She only misperceives the serial correlations.

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- The agent correctly perceived all the cross-sectional correlations.
- She only misperceives the serial correlations.
- Different from rational inattention, noisy information, sparsity, etc.
- Intuition: The agent can always match the cross-sectional correlations by an appropriate choice of $\theta = (A, B, Q, R)$. MLE/Bayesian learning leads her to do so.

Pseudo-True Forecasts

• Under any pseudo-true one-state model θ ,

$$E_t^{\theta}[y_{t+s}] = a^{s}(1-\eta)qp'\sum_{\tau=0}^{\infty}a^{\tau}\eta^{\tau}y_{t-\tau}$$

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• (a, η, p, q) is the solution to a non-convex optimization problem.

Exponential Ergodicity and Markovian Models

Definition (exponential ergodicity)

The true process is exponentially ergodic if

$$\rho\left(\left(\frac{\Gamma_l + \Gamma_l'}{2}\right)\Gamma_0^{\dagger}\right) \le \rho\left(\left(\frac{\Gamma_1 + \Gamma_1'}{2}\right)\Gamma_0^{\dagger}\right)^l$$

where $\rho(\cdot)$ denotes the spectral radius.

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Theorem

If the true process is exponentially ergodic, then the pseudo-true one-state model:

- (a) is Markovian
- (b) only depends on Γ_0 and Γ_1

So, Which Processes are Exponentially Ergodic?

• A spanning linear combination of independent AR(1) processes:

$$f_{it} = \alpha_i f_{i,t-1} + \epsilon_{it},$$
 $i = 1, ..., m$
 $y_t = H' f_t,$ $H \text{ rank } m$

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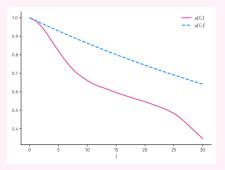
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- The equilibrium processes arising in *all* three macro applications in the paper.
- Estimated (joint) time-series for output gap, inflation rate, and interest rate:



Intuition (1/2)

- Suppose n = 1 and the true process is invertible.
- First, suppose $d = \infty$.
- (Pseudo-)true forecasts are given by

$$\mathbb{E}_t[y_{t+1}] = \sum_{\tau=1}^{\infty} \phi_{\tau} y_{t+1-\tau}$$

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- Coefficients $\{\phi_{\tau}\}_{\tau=1}^{\infty}$ are all generically non-zero.
- But the optimal $\{\phi_{\tau}\}_{\tau=1}^{\infty}$ are fine-tuned to the true autocorrelation function (ACF).
 - · a one-to-one mapping between the two
 - Yule–Walker equations:

the ACF
$$\longleftrightarrow \{\phi_{\tau}\}_{\tau=1}^{\infty}$$

14

Intuition (2/2)

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• Only two degrees of freedom. \Longrightarrow Cannot fine-tune $lpha_{ au}$ to fit the true ACF.

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- Only two degrees of freedom. \Longrightarrow Cannot fine-tune $lpha_{ au}$ to fit the true ACF.
- With exp. ergodicity, y_t is much more informative (than $y_{t+1-\tau}$ for $\tau > 1$) about y_{t+1} .
- Optimal to not distort how one uses y_t . Instead set $\eta=0$, and so, $\alpha_{\tau}=0$ for $\tau>1$.

Persistence Bias

Theorem (persistence bias)

If the true process is exponentially ergodic, under any pseudo-true model θ ,

$$E_t^{\theta}[y_{t+s}] = a^{s}qp'y_t$$

a is the top eigenvalue and p and q are the corresponding left and right eigenvectors of

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• The agent's forecasts only depend on the most persistent component of y_t .

A Diagonal Example

• True data-generating process:

$$y_{t} = \begin{pmatrix} \alpha_{1} & 0 & \dots & 0 \\ 0 & \alpha_{2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \alpha_{n} \end{pmatrix} y_{t-1} + \begin{pmatrix} b_{1} & 0 & \dots & 0 \\ 0 & b_{2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & b_{n} \end{pmatrix} \epsilon_{t}, \qquad \epsilon_{t} \sim i.i.d. \mathcal{N}(0, l)$$

where

$$|\alpha_1| > |\alpha_2| > \cdots > |\alpha_n|$$

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• The autocorrelation matrix at lag l=1:

$$\left(\frac{\Gamma_1 + \Gamma_1'}{2}\right) \Gamma_0^{\dagger} = \begin{pmatrix} \alpha_1 & 0 & \dots & 0 \\ 0 & \alpha_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \alpha_n \end{pmatrix}$$

Pseudo-True One-State Model in the Diagonal Example

• Eigenvalue and eigenvector...

$$a = \alpha_1, \qquad p = q = (1, 0, \dots, 0)'$$

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- Persistence bias:
 - Forecasts of y_1 coincide with the RE.
 - Forecast y_j for $j \neq 1$ as if i.i.d.

Intuition

Agents behave as if only the most persistent component of y_t is relevant.

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- By linear invariance, can scale different components to have the same volatilities!
- Furthermore, the agent can always match the volatilities.

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- Furthermore, the agent can always match the volatilities.

Why focus on the most persistent component?

- Any component that is ignored is approximated as i.i.d.
- Less persistent components are closer to being i.i.d.

19

Forward-Looking Decisions

- Consider J agents, with agent j using a pseudo-true d_j -state model θ_j .
- Suppose each agent takes an action of the form

$$x_{jt} = E_{jt}^{\theta_j} \left[\sum_{s=1}^{\infty} c'_{js} y_{t+s} \right]$$

Increased Comovement

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A main shock:

- The economy looks as if it is driven by a single "main shock."
- Angeletos, Collard, and Dellas (2020) find a "main business cycle shock."

TFP Shocks in the RBC Model

The Loglinearized RBC Model

• TFP:

$$a_t = \rho a_{t-1} + \epsilon_t$$

• Capital:

$$k_t = (1 - \delta)k_{t-1} + \delta i_{t-1}$$

Consumption (permanent income hypothesis):

$$c_t = \frac{\chi}{\beta} k_t + \chi r_t + \chi \zeta w_t + (\chi - \beta \sigma) \sum_{s=1}^{\infty} \beta^s E_t[r_{t+s}] + \chi \zeta \sum_{s=1}^{\infty} \beta^s E_t[w_{t+s}]$$

- true for arbitrary expectations that satisfy the LIE.
- the aggregate Euler equation may *not* be valid away from RE (Preston, 2005)
- r_t , w_t , and i_t are linear functions of k_t , a_t , and c_t .

Calibration

Primitives:

- Each period is a quarter.
- Textbook calibration of primitives:

$$\beta = 0.99, \qquad \sigma = \phi = 1, \qquad \delta = 0.012, \qquad \alpha = 0.3, \qquad \rho = 0.95$$

Expectations:

• Agents have full information: perfectly observe everything.

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Expectations:

- Agents have full information: perfectly observe everything.
- *d* is the *only* additional free parameter.
- $d \ge 2 \implies REE$
- So, we only need to consider d = 1.

The (endogenously-determined) main shock:

$$0.947k_t + 0.053a_t$$

- Almost perfectly correlated with the capital stock.
- In equilibrium the capital stock is more persistent than TFP (persistence bias).
- Agents almost ignore innovations to the TFP.

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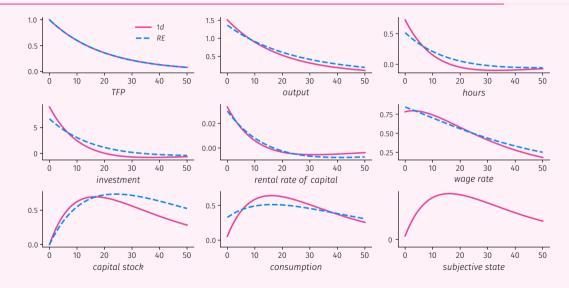
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Sluggishness:

- Expectations move almost one-for-one with capital.
- Capital is sluggish, so expectatations are sluggish.
- Consumption is forward-looking, so it is also sluggish.

Impulse Response Functions



Productivity and Separation Shocks in the DMP Model

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Calibration:

- Almost everything is calibrated as in Shimer (2005).
- Parameters that don't matter under RE:
 - correlation of the two shocks: −0.4
 - SDs of the shocks: ten times larger for productivity

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- Standard undirected labor search model: discrete-time version of Shimer (2005).
- The only interesting decision: firms' vacancy-posting decision.

Calibration:

- Almost everything is calibrated as in Shimer (2005).
- Parameters that don't matter under RE:
 - correlation of the two shocks: -0.4
 - SDs of the shocks: ten times larger for productivity

Expectations:

- Agents have full information.
- Set d = 1 (only other free parameter).

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$$-0.812u_t + 0.010a_t - 0.177s_t$$

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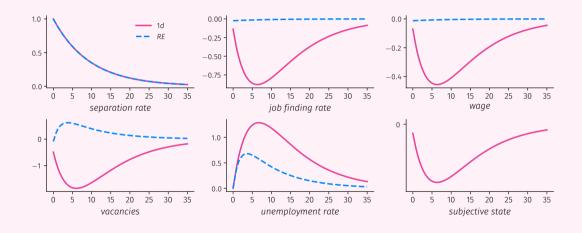
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Intuition: "Keynesian" complementarity between the firms' decisions and models...

- Suppose $u \uparrow + a \downarrow + s \uparrow$ make firms "pessimistic."
- Pessimistic firms post few vacancies. \implies Persistent recession after $u \uparrow + a \downarrow + s \uparrow$.
- In equilibrium, the most persistent combination has $u \uparrow + a \downarrow + s \uparrow$.

Impulse Response Functions to Separation Shock



Concluding Remarks

- I assume agents forecast using simple models that are fit to the DGP.
- Illustration in the context of the RBC and DMP models.
- The framework can be embedded in workhorse macro models.

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- Illustration in the context of the RBC and DMP models.
- The framework can be embedded in workhorse macro models.
- The Julia code is available on my website.
- Paper with Alireza Tahbaz-Salehi and Andrea Vedolin: asset-pricing implications.