MATH 307

Chapter 5

SECTION 5.3: MATRICES FOR LINEAR TRANSFORMATIONS

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LINEAR TRANSFORMATION AS A MATRIX

EXAMPLE 1. Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation

$$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} 5x + z \\ 3x + 2y - 3z \\ 5x \end{bmatrix}.$$

Give a matrix representing the linear transformation T.

$$A = \begin{bmatrix} 5 & 0 & 1 \\ 3 & 2 & -3 \\ 5 & 0 & 0 \end{bmatrix} - 0 \qquad T \left(\begin{bmatrix} 7 \\ 2 \end{bmatrix} \right) = \begin{bmatrix} 5 & 0 & 1 \\ 3 & 2 & -3 \\ 5 & 0 & 0 \end{bmatrix} \begin{bmatrix} 7 \\ 2 \end{bmatrix}.$$

$$Identify T with A.$$

Behind the scene:

$$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} 5\pi \\ 3\pi \\ 5\pi \end{bmatrix} + \begin{bmatrix} 0 \\ 2y \\ 0 \end{bmatrix} + \begin{bmatrix} \frac{7}{3}z \\ 0 \end{bmatrix} = \pi \begin{bmatrix} 5 \\ 3 \\ 5 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \overline{z} \begin{bmatrix} 1 \\ -3 \\ 0 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 5 \\ 3 \\ 5 \end{bmatrix}, T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}, T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -3 \\ 0 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$$

(A) The vectors for a basis of 183.

(**)
$$\begin{bmatrix} 5 \\ 3 \\ 5 \end{bmatrix} = 5 \begin{bmatrix} 6 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 6 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The matrix A is t

General Process:

Suppose $T: V \to W$ is a linear transformation.

- Let $v_1, v_2, ..., v_n$ form a basis α for V.
- Let w_1, w_2, \ldots, w_m form a basis β for W.

Since $T(v_1)$, $T(v_2)$, ..., $T(v_n)$ belongs to W and β is a basis for W, we have

$$T(v_{1}) = a_{11}w_{1} + a_{21}w_{2} + \dots + a_{m1}w_{m}$$

$$T(v_{2}) = a_{12}w_{1} + a_{22}w_{2} + \dots + a_{m2}w_{m}$$

$$\vdots$$

$$T(v_{n}) = a_{1n}w_{1} + a_{2n}w_{2} + \dots + a_{mn}w_{m}.$$

We call the **matrix of T with respect to the bases** α **and** β the matrix $[T]^{\beta}_{\alpha}$ formed from the previous coefficients $a_{11}, a_{22}, \ldots, a_{mn}$:

$$[T]_{\alpha}^{\beta} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}.$$

Remarks:

• With the notation introduced in Chapter 2 on basis, we have

$$[T]^{\beta}_{\alpha} = \begin{bmatrix} [T(v_1)]_{\beta} & [T(v_2)]_{\beta} & \cdots & [T(v_n)]_{\beta} \end{bmatrix}.$$

• When $T: V \to V$ is a linear transformation of V into itself and α is used for both the domain and the codomain, then we simply say the matrix of T with respect to α and we denote it by $[T]_{\alpha}^{\alpha}$.

EXAMPLE 2. Let T be the linear transformation in Example 1. Let β be the basis given by

7:
$$\mathbb{R}^3 \longrightarrow \mathbb{R}^3$$

$$V \qquad \beta = \left\{ \begin{bmatrix} 1\\1\\2 \end{bmatrix}, \begin{bmatrix} 1\\-1\\1 \end{bmatrix}, \begin{bmatrix} 1\\1\\1 \end{bmatrix} \right\}.$$

Find

1. the matrix of T with respect to the standard basis α of \mathbb{R}^3 .

 α 2. the matrix of T with respect to the basis β .

$$\int_{3.}^{6} |T|_{\alpha}^{\beta}$$

$$||T|_{\alpha}^{\alpha} = \begin{bmatrix} 5 & 0 & 1 \\ 3 & 2 & -3 \\ 5 & 0 & 0 \end{bmatrix}$$

3) (*)
$$T([3]) = [3], T([3]) = [3], T([3]) = [3].$$

$$\begin{bmatrix}
1 & 1 & 1 & 5 \\
1 & -1 & 1 & 3 \\
7 & 1 & 1 & 5
\end{bmatrix}
\sim
\begin{bmatrix}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 4 \\
0 & 0 & 1 & 1
\end{bmatrix}
\rightarrow
\begin{bmatrix}
6 \\
7 \\
0 \\
0
\end{bmatrix}
=
\begin{bmatrix}
6 \\
-1 \\
1
\end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -3 \\ 0 & 0 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 \\ -3 \\ 0 \end{bmatrix}_{\beta} = \begin{bmatrix} -1 \\ z \\ 0 \end{bmatrix}$$

$$-b \left[T\right]_{\alpha}^{\beta} = \begin{bmatrix} 0 & 0 & -1 \\ 4 & -1 & 2 \\ 1 & 1 & 0 \end{bmatrix}$$

$$\begin{pmatrix} 7 \\ -1 \\ 5 \end{pmatrix} = C_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + (2 \begin{bmatrix} -1 \\ -1 \end{bmatrix} + (3 \begin{bmatrix} -1 \\ 2 \end{bmatrix})$$

2) Goal: Hind List
(x)
$$T\left(\begin{bmatrix} 1\\2 \end{bmatrix}\right) = \begin{bmatrix} 7\\-1\\5 \end{bmatrix}$$
, $T\left(\begin{bmatrix} -1\\1 \end{bmatrix}\right) = \begin{bmatrix} 6\\-2\\5 \end{bmatrix}$, $T\left(\begin{bmatrix} -1\\2\\0 \end{bmatrix}\right) = \begin{bmatrix} 6\\2\\5 \end{bmatrix}$

$$\begin{bmatrix} T \end{bmatrix}_{\beta}^{\beta} = \begin{bmatrix} -2 & -1 & -1 \\ 4 & 4 & 2 \\ 3 & 3 & 5 \end{bmatrix}.$$

MATRIX OF THE COMPOSITION

ST: V -> U.

Let $T: V \to W$ and $S: W \to U$ be linear transformations. Suppose that

- α is a basis for V;
- β is a basis for W;
- γ is a basis for U.

Then we have

$$[ST]^{\gamma}_{\alpha} = [S]^{\gamma}_{\beta} [T]^{\beta}_{\alpha}.$$

MATRIX AND EVALUATION OF TRANSFORMATIONS

Given a transformation $T: V \to W$, a basis α for V and a basis β for W, we then have

$$[T(v)]_{\beta} = [T]_{\alpha}^{\beta}[v]_{\alpha}.$$

<u>Remark</u>: The last equality means that the vector T(v) is obtained by multiplying the matrix of T with respect to α and β by the vector of the coordinates of v in the basis α .

EXAMPLE 3. Let T, α and β be as in Example 2.

- 1. Find the coordinate vector of $v = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}^{\top}$ with respect to the basis α .
- 2. Find coordinate vector of T(v) with respect to the basis β .
- 3. Use the result in part (b) to find T(v) in the standard basis.

1)
$$\begin{bmatrix} \frac{1}{2} \\ \frac{2}{3} \end{bmatrix}_{\alpha} = \begin{bmatrix} \frac{1}{2} \\ \frac{2}{3} \end{bmatrix}$$
2)
$$\begin{bmatrix} T(\begin{bmatrix} \frac{1}{2} \\ \frac{7}{3} \end{bmatrix}) \end{bmatrix}_{\beta} = \begin{bmatrix} T \end{bmatrix}_{\alpha} \begin{bmatrix} x \end{bmatrix}_{\alpha}$$

$$= \begin{bmatrix} 0 & 0 & -1 \\ 4 & -1 & 2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{2}{3} \end{bmatrix} = \begin{bmatrix} -\frac{3}{8} \\ \frac{8}{3} \end{bmatrix}$$
3)
$$T(\begin{bmatrix} \frac{1}{2} \\ \frac{7}{3} \end{bmatrix}) = -3 \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} + 8 \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} + 3 \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$

$$= \begin{bmatrix} 8 \\ -8 \end{bmatrix}$$

Matrix of a Change of Basis

EXAMPLE 4. Let α be the standard basis for \mathbb{R}^3 and let β be the basis in Example 2. Find a matrix that will send each vector in the basis α to the vectors in the basis β .

$$\alpha = \{ \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \}$$
 $\beta = \{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \}$

Goal: Find a matrix A s.t. Finding a linear transformation.

 $A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

(2)
$$-b$$
 $\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} b \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a_{12} \\ a_{22} \\ a_{32} \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$ coordinate vector w.r.t. the Standard burns.

3 ->
$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} 0 \\ 6 \end{bmatrix} = \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
 = the matrix A .

the matrix
$$A$$
: change of basis from α to β

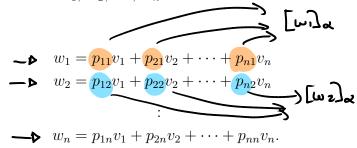
$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 0 \\ 2 & 1 & 1 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

General Procedure:

Let α and β be two bases of V:

- α be a basis with vectors v_1, v_2, \ldots, v_n .
- β be a basis with vectors w_1, w_2, \ldots, w_n .

Write



Then the matrix

is called the **change of basis matrix from** α **to** β .

Fact:

• If we define I(v) = v to be the identity transformation, then in fact $P = I[I]^{\alpha}_{\beta}$ So, $[v]_{\alpha} = P[v]_{\beta}$.

$$\hat{I}(\omega_1) = \omega_1 = P_{11}v_1 + P_{21}v_2 + \cdots + P_{n1}v_n$$

$$I(\omega_2) = \omega_2 = P_{12}v_1 + P_{22}v_2 + \cdots + P_{n2}v_n$$

$$\vdots$$

$$I(\omega_n) = \omega_n = P_{1n}v_1 + P_{2n}v_2 + \cdots + P_{nn}v_n$$

• If P is the change of basis matrix from a basis α to a basis β of a vector space, then the change of basis from β to α is P^{-1} . So $P^{-1} = \underline{[I]_{\alpha}^{\beta}}$ and $[v]_{\beta} = P^{-1}[v]_{\alpha}$.

Consequence on the Matrix of a Linear Transformation

EXAMPLE 5. Let α be the standard basis and let β be the basis in Example 2. Suppose that a linear transformation T has the following matrix with respect to α :

$$[T]^{\alpha}_{\alpha} = \begin{bmatrix} 1 & 3 & -1 \\ 2 & -1 & 2 \\ 1 & 3 & -1 \end{bmatrix}.$$

Find $[T(v)]_{\beta}$ where $[v]_{\beta} = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}^{\top}$.

Trick. Use P found in Example 4:

$$(I)_{\beta}^{\alpha} = P = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \end{bmatrix}$$
 (change of basis $\alpha \longrightarrow \beta$).

(*) becomes
$$[T(v)]_{\alpha} = [T]_{\alpha}^{\alpha} P [I]_{\beta}$$
. (**)
$$[T(v)]_{\beta} = [I]_{\alpha}^{\beta} [T(v)]_{\alpha} = P^{-1} [T(v)]_{\alpha}$$

*non (HH) :

<u>Facts</u>:

• If $T:V\to V$ is a linear transformation, α and β are bases for V, and P is the change of basis matrix from α to β , then

$$[\underline{T}]^{\beta}_{\beta} = \underline{P}^{-1}[T]^{\alpha}_{\alpha}\underline{P}.$$

• If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation and A is the matrix of T with respect to the standard basis of \mathbb{R}^n and \mathbb{R}^m , then

$$T(X) = AX.$$

EXAMPLE 6 (Extra).

$$\alpha = \{\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \end{bmatrix} \}$$

$$\beta = \{\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \}$$

$$w_{2}$$

Change of bosin a -> B => Find the matrix [I]B

$$I(w_1) = w_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} = C_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + C_2 \begin{bmatrix} 2 \\ 0 \end{bmatrix} + C_3 \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} C_1 + C_2 + C_3 \\ C_1 + C_2 - C_3 \\ C_1 + C_3 \end{bmatrix}$$

(2)
$$I(\omega_z) = \omega_z = \begin{bmatrix} -2 \\ 3 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$-0 \begin{bmatrix} 1 & 1 & 1 & -2 \\ 1 & 2 & -1 & 3 \\ 1 & 0 & 7 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 20 \\ 0 & 10 & -13 \\ 0 & 0 & 1 & -9 \end{bmatrix} - 0 \begin{bmatrix} \omega_z \\ \omega_z \\ -9 \end{bmatrix}$$

(3)
$$I(\omega_3) = \omega_3 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = C_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + C_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + C_3 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$-D \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 2 & -1 & 1 \\ 1 & 0 & 2 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 5 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & -2 \end{bmatrix} - D \begin{bmatrix} \omega_3 \\ \omega_4 \end{bmatrix} \alpha = \begin{bmatrix} 5 \\ -3 \\ -2 \end{bmatrix}$$

Now,
$$P = [J]_{\beta}^{\alpha} = \begin{bmatrix} 1 & 20 & 5 \\ 0 & -13 & -3 \\ 0 & -9 & -2 \end{bmatrix}$$