## MATH 307

## Chapter 6

of ODEs.

SECTION 6.4: NONHOMOGENEOUS LINEAR SYSTEMS

## Contents

What's The Trick?	2
Actually Solving Nonhomogeneous Systems	3

Created by: Pierre-Olivier Parisé Summer 2022

## WHAT'S THE TRICK?

Consider a nonhomogeneous system of ODEs

$$Y' = AY + G.$$

Y = MC

The trick is to use a method called variation of parameter.

Let M be the fundamental matrix of Y' = AY. We suppose we have the matrix M at hand.

Goal: Determine a vector function V such that  $Y_P = MV$  is a particular solution to Y' =

$$\Rightarrow \underbrace{\left(H' - AH\right)}_{=0} V + MV' = G$$

because Histhe

So, 
$$OV + MV' = G_1 \Rightarrow MV' = G_1$$

Because clet(M) =  $\omega(Y_1(x),...,Y_n(x)) \neq 0$ , H is invertible

$$V' = M^{-1}G$$
Integrale
$$V = \int M^{-1}G dx$$

$$\frac{(6.3. \quad y' = ay + ghx)}{y_p(x) = e^{ax} \int e^{-ax} g \, dx}$$

Therefore,

Yp(x) = H(x) V(x) = H(x) (H-1 G) dx

**EXAMPLE 1.** Find the general solution to the system of ODEs

$$Y' = \begin{bmatrix} 1 & 2 \\ -1 & 4 \end{bmatrix} Y + \begin{bmatrix} 2 \\ x \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 2 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 \end{bmatrix}$$

1) Solve Y=AY.

1.2) Find Y.

1.1) Solve diagonal system.

A is diagonalizable 
$$-\infty$$
 $D = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} & P = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$ .

 $Y' = AY$  becomes

 $Z' = DZ$  ( $Z = P'Y$ ).

 $Z' = DZ$  ( $Z = P'Y$ ).

So 
$$V_{H} = PZ = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} c_{1}e^{2x} \\ c_{2}e^{3x} \end{bmatrix} = \begin{bmatrix} 2c_{1}e^{2x} + c_{2}e^{3x} \\ c_{1}e^{2x} + c_{2}e^{3x} \end{bmatrix}$$

$$= \begin{bmatrix} 2e^{2x} & e^{3x} \end{bmatrix} \begin{bmatrix} c_{1} \\ c_{2}e^{2x} \end{bmatrix}$$

$$= \begin{bmatrix} 2e^{2x} & e^{3x} \\ e^{2x} & e^{3x} \end{bmatrix} \begin{bmatrix} c_{1} \\ c_{2}e^{2x} \end{bmatrix}$$

$$A = \begin{bmatrix} 2e^{2x} & e^{3x} \\ e^{2x} & e^{3x} \end{bmatrix}$$

we have 
$$H^{-1}(x) = \frac{1}{\det(H)} \begin{bmatrix} e^{3x} - e^{2x} \\ -e^{3x} - e^{2x} \end{bmatrix}^{-2x} = \frac{1}{e^{5x}} \begin{bmatrix} e^{3x} - e^{3x} \\ -e^{2x} - e^{2x} \end{bmatrix}^{-3x}$$

$$\Rightarrow H^{-1}(x) = \begin{bmatrix} e^{-2x} - e^{-2x} \\ -e^{-3x} - e^{-3x} \end{bmatrix}$$

3) State the result.  

$$\frac{1}{y} = y_{H} + y_{P} = \begin{bmatrix}
2c_{1}e^{2x} + c_{2}e^{3x} & \frac{x}{3} - \frac{19}{18} \\
c_{1}e^{2x} + c_{2}e^{3x} & \frac{x}{3} - \frac{11}{36}
\end{bmatrix}.$$