

MATH 307

CHAPTER 5

SECTION 5.5: SIMILAR MATRICES, DIAGONALIZATION, AND JORDAN CANONICAL FORM

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Motivation

EXAMPLE 1. Let A be the 3×3 matrix

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}.$$

Then, (a) compute A^5 (b) find the eigenvalues of A (c) find a basis for each eigenspace.

$$(a) A \cdot A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} = \begin{bmatrix} 2^2 & 0 & 0 \\ 0 & 3^2 & 0 \\ 0 & 0 & 4^2 \end{bmatrix}$$

$$A^5 = A \cdot A \cdot A \cdot A \cdot A = \begin{bmatrix} 2^5 & 0 & 0 \\ 0 & 3^5 & 0 \\ 0 & 0 & 4^5 \end{bmatrix}$$

$$(b) \det(\lambda I - A) = 0 \iff \begin{vmatrix} \lambda - 2 & 0 & 0 \\ 0 & \lambda - 3 & 0 \\ 0 & 0 & \lambda - 4 \end{vmatrix} = 0 \iff (\lambda - 2)(\lambda - 3)(\lambda - 4) = 0$$

$\iff \lambda = 2, \lambda = 3, \lambda = 4.$

$$(c) \underline{E_2(\lambda=2)} \quad v = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \rightarrow (\lambda I - A) \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -2 & 0 \end{bmatrix} \rightarrow \begin{matrix} x \text{ free} \\ y = 0 \\ z = 0 \end{matrix} \rightarrow \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ 0 \\ 0 \end{bmatrix} = x \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$

basis for E_2

$$\underline{E_3(\lambda=3)}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{bmatrix} \rightarrow \begin{matrix} x = 0 \\ z = 0 \\ y \text{ free} \end{matrix}$$

$$\rightarrow \begin{bmatrix} x \\ y \\ z \end{bmatrix} = y \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \leftarrow \text{basis for } E_3$$

$$\underline{E_4(\lambda=4)}$$

$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{matrix} x = 0 \\ y = 0 \\ z \text{ free} \end{matrix}$$

$$\rightarrow \begin{bmatrix} x \\ y \\ z \end{bmatrix} = z \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \leftarrow \text{basis for } E_4.$$

Remarks

- It is pretty easy to deal with diagonal matrices.
- Our goal is to try to transform a general matrix into a diagonal matrix.

EXAMPLE 2. Let A be the following 3×3 matrix

$$A = \begin{bmatrix} 6 & -4 & -2 \\ 1 & 2 & -1 \\ 1 & 0 & 1 \end{bmatrix}.$$

Find (a) the eigenvalues of A (b) a basis for each eigenspace (c) compute A^5 .

(a) $\det(\lambda I - A) = \lambda^3 - 9\lambda^2 + 26\lambda - 24 = (\lambda - 2)(\lambda - 3)(\lambda - 4) = 0$
 $\rightarrow \lambda = 2, \lambda = 3, \text{ or } \lambda = 4.$

(b) $E_2(\lambda=2)$ $2I - A = \begin{bmatrix} -4 & 4 & 2 \\ -1 & 0 & 1 \\ -1 & 0 & 1 \end{bmatrix}$, solve $(2I - A)v = 0$
 $v = \begin{bmatrix} x \\ y \\ z \end{bmatrix}.$

$\rightarrow v = z \begin{bmatrix} 1 \\ 1/2 \\ 1 \end{bmatrix} \quad (z \text{ free var.})$
 $\rightarrow w_1$

$E_3(\lambda=3)$ $3I - A = \begin{bmatrix} -3 & 4 & 2 \\ -1 & 1 & 1 \\ -1 & 0 & 2 \end{bmatrix}$, solve $(3I - A)v = 0$
 $v = \begin{bmatrix} x \\ y \\ z \end{bmatrix}.$

$\rightarrow v = z \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \quad (z \text{ free var.})$
 $\rightarrow w_2$

$E_4(\lambda=4)$ $4I - A = \begin{bmatrix} -2 & 4 & 2 \\ -1 & 2 & 1 \\ -1 & 0 & 3 \end{bmatrix}$, solve $(4I - A)v = 0$
 $v = \begin{bmatrix} x \\ y \\ z \end{bmatrix}.$

$\rightarrow v = z \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} \rightarrow w_3$

Because eigenvectors associated to different eigenvalues, we have that w_1, w_2, w_3 are lin. independent
 $\rightarrow w_1, w_2, w_3$ form a basis for \mathbb{R}^3 !

(c) change of basis from $\begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix}, \begin{bmatrix} 6 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 6 \\ 0 \\ 1 \end{bmatrix}$ to $\underbrace{w_1, w_2, w_3}_{\beta}$:

$$P = \begin{bmatrix} 1 & 2 & 3 \\ 1/2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}, \quad P^{-1} = \begin{bmatrix} 0 & -2 & 2 \\ -1 & 4 & -1 \\ 1 & -2 & 0 \end{bmatrix}$$

Now,

$$\begin{aligned} [A]_{\beta}^{\beta} &= P^{-1} A P = \begin{bmatrix} 0 & -2 & 2 \\ -1 & 4 & -1 \\ 1 & -2 & 0 \end{bmatrix} \begin{bmatrix} 6 & -4 & 2 \\ -1 & 2 & -1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 1/2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} \quad \text{diag. matrix!} \end{aligned}$$

So, $A = P [A]_{\beta}^{\beta} P^{-1}$

$$\rightarrow A^5 = \underbrace{(P [A]_{\beta}^{\beta} P^{-1})}_{=I} \underbrace{(P [A]_{\beta}^{\beta} P^{-1})}_{=I} \underbrace{(P [A]_{\beta}^{\beta} P^{-1})}_{=I} \underbrace{(P [A]_{\beta}^{\beta} P^{-1})}_{=I} \underbrace{(P [A]_{\beta}^{\beta} P^{-1})}_{=I}$$

$$= P [A]_{\beta}^{\beta} I [A]_{\beta}^{\beta} I [A]_{\beta}^{\beta} I [A]_{\beta}^{\beta} I [A]_{\beta}^{\beta} P^{-1}$$

$$= P ([A]_{\beta}^{\beta})^5 P^{-1}$$

$$= \begin{bmatrix} 1 & 2 & 3 \\ 1/2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2^5 & 0 & 0 \\ 0 & 3^5 & 0 \\ 0 & 0 & 4^5 \end{bmatrix} \begin{bmatrix} 0 & -2 & 2 \\ -1 & 4 & -1 \\ 1 & -2 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 2586 & -4264 & -422 \\ 781 & -1108 & -211 \\ 781 & -1140 & -179 \end{bmatrix}.$$

Definition

Diagonalizable Matrices:

An $n \times n$ matrix A is *diagonalizable* if there is a matrix $\overset{\text{diagonal matrix.}}{\underset{\uparrow}{D}}$ and an invertible matrix P such that

$$A = P \overset{\text{diagonal matrix.}}{\underset{\uparrow}{D}} P^{-1}$$

Facts:

- Let A be an $n \times n$ matrix.
- Let $\lambda_1, \lambda_2, \dots, \lambda_k$ be the eigenvalues of A .
- Let $E_{\lambda_1}, E_{\lambda_2}, \dots, E_{\lambda_k}$ be the eigenspaces associated to each eigenvalue.

If $\dim(E_{\lambda_1}) + \dim(E_{\lambda_2}) + \dots + \dim(E_{\lambda_k}) = \textcircled{n}$, then A is diagonalizable.

EXAMPLE 3. Is the matrix from Example 2 diagonalizable?

A : was a 3×3 matrix $\rightarrow n=3$

$$\lambda_1 = 2, \quad \lambda_2 = 3, \quad \lambda_3 = 4.$$

Also,

$$\begin{array}{lcl} \begin{bmatrix} 1 \\ 1/2 \end{bmatrix} & \text{basis for } E_2 & \rightarrow \dim(E_2) = 1 \\ \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} & \text{basis for } E_3 & \rightarrow \dim(E_3) = 1 \\ \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} & \text{basis for } E_4 & \rightarrow \dim(E_4) = 1 \end{array}$$

$\underline{\hspace{1cm}} \quad \underline{\hspace{1cm}}$
 3

$$\text{So, } \dim(E_1) + \dim(E_2) + \dim(E_3) = 3 = n$$

$\rightarrow A$ is diagonalizable.

EXAMPLE 4. Is the matrix

$$A = \begin{bmatrix} 1 & -2 & -6 \\ -2 & 2 & -5 \\ 2 & 1 & 8 \end{bmatrix}$$

diagonalizable? If so, determine the invertible matrix P such that $P^{-1}AP$ is a diagonal matrix.

1) Eigen values.

$$\det(\lambda I - A) = \lambda^3 - 11\lambda^2 + 39\lambda - 45 = (\lambda - 5)(\lambda - 3)^2$$

$$\Rightarrow \lambda = 5, \lambda = 3 \text{ (mult. is 2)}$$

2) Eigen Spaces.

$$\underline{E_5 (\lambda=5)} \text{ Solve } (5I - A)v = 0 \quad v = \begin{bmatrix} x \\ y \\ z \end{bmatrix}.$$

$$\Rightarrow v = z \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \text{ basis for } E_5.$$

$$\Rightarrow \dim(E_5) = 1$$

$$\underline{E_3 (\lambda=3)} \text{ Solve } (3I - A)v = 0, \quad v = \begin{bmatrix} x \\ y \\ z \end{bmatrix}.$$

$$\Rightarrow v = z \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \text{ basis for } E_3$$

$$\Rightarrow \dim(E_3) = 1$$

So,

$$\dim(E_5) + \dim(E_3) = 2 \neq 3 (=n)$$

$\Rightarrow A$ is not diagonalizable

$1+0i$ $-1+0i$
 $A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$
 $1+0i$ $1+0i$

PAP-1

$$\begin{aligned} \lambda_1 &= 1+i \\ \lambda_2 &= 1-i \end{aligned} \quad \left(\begin{array}{l} \text{Ex. 7} \\ \text{in Sec. 5.4} \end{array} \right)$$

$$\det(\lambda I - A) = \lambda^2 - 2\lambda + 2$$

$$\begin{aligned} \lambda_1 &= 1+i \\ \lambda_2 &= 1-i \end{aligned} \quad \left(\begin{array}{l} \text{Ex. 7} \\ \text{in Sec. 5.4} \end{array} \right)$$

$$\begin{aligned} \lambda_1 &= 1+i \\ \lambda_2 &= 1-i \end{aligned} \quad \left(\begin{array}{l} \text{Ex. 7} \\ \text{in Sec. 5.4} \end{array} \right)$$

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$$\begin{aligned} \lambda_1 &= 1+i \\ \lambda_2 &= 1-i \end{aligned} \quad \left(\begin{array}{l} \text{Ex. 7} \\ \text{in Sec. 5.4} \end{array} \right)$$

$$\begin{aligned} \lambda_1 &= 1+i \\ \lambda_2 &= 1-i \end{aligned} \quad \left(\begin{array}{l} \text{Ex. 7} \\ \text{in Sec. 5.4} \end{array} \right)$$

In general:

An $n \times n$ matrix A is *similar* to an $n \times n$ matrix B if there is an invertible $n \times n$ matrix P such that

$$B = P^{-1}AP.$$

Notation: $A \sim B$ means that A is similar to B .

Facts:

- If A is similar to B and B is similar to C , then A is similar to C .
- If P is the change of bases matrix from α to β and T is a linear transformation, then $[T]_{\beta}^{\beta} = P^{-1}[T]_{\alpha}^{\alpha}P$. So $[T]_{\beta}^{\beta} \sim [T]_{\alpha}^{\alpha}$.

Question:

For non-diagonalizable matrices, can we reduce them to a simple form?

In other words, can we find a matrix B , as simple as possible, such that $B \sim A$?

Answer: Yes! We will replace the diagonal form by the Jordan canonical form.

Jordan blocks

A Jordan block is a square matrix A taking the following shape:

$$A = \begin{bmatrix} \mu & 1 & 0 & \cdots & 0 & 0 \\ 0 & \mu & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \mu & 1 \\ 0 & 0 & 0 & \cdots & 0 & \mu \end{bmatrix}.$$

Why are these type of matrices important?

EXAMPLE 6. Let A be the matrix

$$A = \begin{bmatrix} \mu & 1 & 0 \\ 0 & \mu & 1 \\ 0 & 0 & \mu \end{bmatrix}.$$

(a) Compute $\det(\lambda I - A)$. (b) Find the dimension of the eigenspaces.

$$(a) \det(\lambda I - A) = \begin{vmatrix} \lambda - \mu & -1 & 0 \\ 0 & \lambda - \mu & -1 \\ 0 & 0 & \lambda - \mu \end{vmatrix} = (\lambda - \mu)^3 = 0$$

$\Rightarrow \lambda = \mu \quad (\text{alg. mult.} = 3)$

$$(b) \underline{E_\mu}. \quad (\mu I - A)v = 0, \quad v = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$\mu I - A = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{bmatrix} 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{matrix} y=0 \\ z=0 \\ x \text{ free} \end{matrix}$$

$$\Rightarrow v = x \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \rightarrow \dim(E_\mu) = 1.$$

Remark:

- a $n \times n$ Jordan block associated to a number μ has only one eigenvalue.
- The algebraic multiplicity of this eigenvalue is necessarily equal to n .

4 We always have $\dim(E_\mu) = 1$ for an $n \times n$ Jordan block.

- Jordan blocks are the building blocks for the set of matrices that can't be diagonalizable.

Reduction to Jordan Blocks

EXAMPLE 7. We know that the matrix

$$A = \begin{bmatrix} 1 & -2 & -6 \\ -2 & 2 & -5 \\ 2 & 1 & 8 \end{bmatrix} \quad \setminus$$

is not diagonalizable. Find a matrix B , not necessarily a diagonal matrix, such that A is similar to B .

General Procedure: Suppose A is an $n \times n$ matrix.

- Express $\det(\lambda I - A)$ as

$$\det(\lambda I - A) = (\lambda - \lambda_1)^{m_1} (\lambda - \lambda_2)^{m_2} \cdots (\lambda - \lambda_k)^{m_k}$$

where m_1 is the multiplicity of λ_1 , m_2 is the multiplicity of λ_2 , ..., m_k is the multiplicity of λ_k .

- For each λ_j , write

$$A_j = \begin{bmatrix} J_{m_{j-1}+1} & 0 & \cdots & 0 \\ 0 & J_{m_{j-1}+2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & J_{m_j} \end{bmatrix}.$$

where each J_p , for $p = m_{j-1} + 1, \dots, m_j$, is a Jordan block

$$J_p = \begin{bmatrix} \lambda_j & 1 & 0 & \cdots & 0 & 0 \\ 0 & \lambda_j & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_j & 1 \\ 0 & 0 & 0 & \cdots & 0 & \lambda_j \end{bmatrix}.$$

- Then the Jordan Canonical Form (JCF) is

$$B = \begin{bmatrix} A_1 & 0 & 0 & \cdots & 0 \\ 0 & A_2 & 0 & \cdots & 0 \\ 0 & 0 & A_3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & A_k \end{bmatrix}$$

- The invertible matrix P such that $B = P^{-1}AP$ is more complicated to find. In theory, the method to find P uses the notion of a **generalized eigenvector**. In our situation, we will use Python to find this matrix P .

If you want to know more on the generalized eigenvectors and the Jordan Canonical Form, I suggest to take a look at the following references:

- A more math article: *Down With Determinants!* by Sheldon Axler, <https://www.maa.org/sites/default/files/pdf/awards/Axler-Ford-1996.pdf>.
- A Youtube video: <https://www.youtube.com/watch?v=GVixvieNnyc>.

EXAMPLE 8. Let A be an 7×7 matrix with the following eigenvalues:

$$\{1, 1, 1, 1, 2, 2, 3\}.$$

Give the possible Jordan canonical form B of the matrix A .