***Localization and mapping with autonomous robot, based on LIDAR sensor***

Keyword – SLAM; localization; mapping; obstacle detection; LIDAR-SLAM; autonomous mobile robots; real-world autonomous navigation; local map; global map; odometry.

Localization methods - <https://blog.cometlabs.io/teaching-robots-presence-what-you-need-to-know-about-slam-9bf0ca037553>

SLAM - <http://ais.informatik.uni-freiburg.de/teaching/ss12/robotics/slides/12-slam.pdf>

<https://ceit.aut.ac.ir/~shiry/lecture/robotics/Robot%20Navigation/Introduction%20to%20SLAM.pdf>

**Mapping and localization**

Robotic mapping is a discipline related to computer vision and cartography. Mapping robots can now be found in several areas like industry, military, home appliances, exploration and self-driving cars [1]. In most of the cases, these robots are used where humans cannot reach or is very hard for a human to reach those areas.

The goal of this robot is to be able to construct and use a map (indoor or outdoor) and to localize its position in this map. [2]

“*Robotic mapping is that branch which deals with the study and application of ability to localize itself in a map/plan and sometimes to construct the map or floor plan by the autonomous robot*”. [2]

The problem of robot mapping is to acquire information about the robot environment based on a set of data received from a set of sensors. To acquire a map, robots must use a set of multiple sensors, which will allow them to perceive the outside world. Most of the sensors used in this task are cameras, distance sensors (using sonar, laser, and infrared technology), radar, compasses, and GPS. However, all these sensors are subject to errors, like measurement errors or noises, but also some limitations (range limitation, sensor position limitation). [3]

When creating a map, it is very important, the robot localization on the map. “Localization is the problem of using sensor measurements to estimate the robot’s pose relative to some map”. [4] Localization is essential to decide on future actions, to avoid dangerous situations (collisions or unsafe conditions – temperature, radiation, exposure to weather).

“Robot navigation means the robot’s ability to determine its position in its frame of reference and then plan a path toward some goal location”. [5]

The problem with localization and mapping is that each process is based on having data and information from the robot sensor and actuators. The sensor information isn’t 100% accurate, so in order to avoid measurement errors, it will be needed complex algorithms and calculations.

To create an accurate map of the environment, we need information about the robot pose; this means that in order to create the mapping, we need the localization. But to determine the robot pose, we need to have information about the environment, like a map. This problem is known as the “chicken and egg” problem. [6]

There exists a technique which overcomes this problem, which is called: Simultaneous Localization and Mapping (SLAM). [6]

The main principle of SLAM is to detect the outside environment using sensors on the robot and construct the map of the environment while estimating the pose – localization, and orientation – of the robot.

SLAM application can be found in automatic car piloting or unrehearsed off-road terrains, rescue tasks for high-risk or difficult-navigation environment, planetary, aerial, terrestrial and oceanic exploration, medicine and many more.

[1] - LIDAR Application for Mapping and Robot Navigation on Closed Environment – PDF

[2] - <https://en.wikipedia.org/wiki/Robotic_mapping>

[3] - <http://robots.stanford.edu/papers/thrun.mapping-tr.pdf>

[4] - <https://ri.cmu.edu/pub_files/2009/1/thesis_revision_2009_02_13.pdf>

[5] - <https://en.wikipedia.org/wiki/Robot_navigation>

[6] - master\_thesis\_benjamin\_mader%20(3).pdf