1. Test Arduino -> done -> is working

2. Test motors and motor driver -> done -> working

3. Battery voltage:

b1: 3.37 V

b2: 3.46 V

b3: 3.45 V

-> To Do: charge battery until 3.7 V each cell and a total voltage of 11.1 V

-> test other battery, to see if can be charged and used

4. Chassis remake

- take protection foil down -> done partially

- remake the circuit and the placement of the components

- buy termocontractil band for a better arrangement of the wires

- WIRE MANAGEMENT!!!

5. Test 2 servo-motors

6. Think about a way to create the "environment" for the lidar sensor

7. Read how lidar sensor works and create a small documentation about it

-> AT WORK

8. Read how wireless connector works and create a small documention about it and

how to connect it to arduino

9. Prepare documentation for university until end of this week

-> send documentation to Brad R.