

Pablo Garcia Arribas (714120290033)

Soohyun Lee (714120290013)

Begaiym Omurkanova (516120990004)

Hannah Rowe (516120990001)

Dastan Yusupov (516120990003)



TABLE OF CONTENTS

PROBLEM

.

FUNCTION

•

B O D E S



PROBLEM WE AIM TO EXPLORE

After studying photo and video simulation and manipulation during our last few classes, we aimed to explore python language and create a program that we would **both enjoy coding and using!**

Our team members were especially interested in what we learnt in lectures on python libraries such as cv3 and machine learning with scikit-learn.









PROBLEM WE AIM TO EXPLORE

FACE DETECTION



MACHINE LEARNING

A PROGRAM THAT <u>IDENTIFIES A PERSON</u>
AFTER TRAINING THE COMPUTER WITH PHOTOS





FUNCTIONS TO BE INCLUDED

- ✓ generate 100 pictures of each of us from a video made with laptop's webcam
- ✓ train the data by using a supervised classifier method called K-Nearest Neighbors (KNN)
- ✓ resize an image to size 150x150 and flatten it into a line of pixels that will then be compared with our data sample
- ✓ capture the faces in the video and compare the face to the 'K' nearest faces of the data we previously gathered
- ✓ print the registered person's name it believes to be in the video
- ✓ avoiding the mirror effect that happens when you take "selfies".
- ✓ change the images into black and white to make them more comparable.
- ✓ a "keyboard command" such as the letter "Q" to stop the video whenever the user wants.





OUR CODES

•

1. CREATE DATASETS 2. WEBCAM





OUR CODES 1. CREATE DATASETS

- This is the first program that runs
- This script takes 100 photos of the face of the front camera of the computer
- We import 2 libraries: numpy and cv2.
 - Numpy is to place the data as an array.
 - Cv2 is a library that help us to work with videos and photos





OUR CODES 1. CREATÉ DATASETS

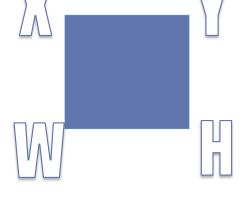
- A face detection algorithm has to be imported from opency. In our case we found that frontal face default is good for this kind of project
- We use the function VideoCapture inside the library cv2 to open the webcam of your computer.
- Then we create a while that will do the following 100 times:
 - If the user presses the letter "q" it will stop running
 - One frame of the video will be taken with with the function cap.read
 - We will flip the picture horizontally (right to left) to avoid the "mirror effect"





OUR CODES: 1. CREATE DATASETS

```
# Put the frame in gray
     gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY
# Detect faces comes next
     faces = face_cascade.detectMultiScale(gray, 1.3, 5)
     if faces != ():
# Get the rectangle representing the first face
     (x,y,w,h) = faces[0]
#Put the face in color into 'roi_color'
     roi_color = frame[y:y+h, x:x+w]
```







OUR CODES: 1. CREATE DATASETS





OUR CODES: 1. CREATE DATASETS

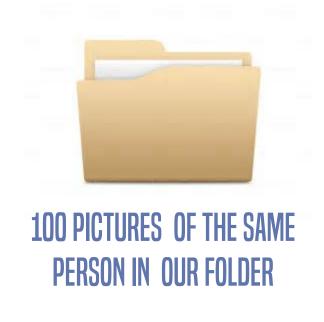
FIXALLY:

Release the webcam cap.release()

Close all the windows

cv2.destroyAllWindows()





YOU HAVE TO REPEAT THE PROCESS AS MANY TIMES PEOPLE YOU WANT TO IDENTIFY





- This code detects faces in front of the camera and tries to match each face based on the faces registered previously
- Define function "img_to_vector"
- Import the face detection algorithm of OpenCV
- Arrays, NumPy used to store the registered images
- Right to left flip to avoid 'mirror effect'
- KNN nearest neighbors machine learning





Function to resize an image in 150x150 and flatten this image into a line of pixels.

Here we have created a function/definition in python's cv2 to resize the image to size 150*150.

We prefer this size because it is not too large or too small. This function also flattens the image (
which makes it easier to be manipulated)

def img_to_vector(img):
 val = cv2.resize(img, (150,150)).flatten()
 return_val.astype(np.float32)

Import the face detection algorithm of OpenCV

face_cascade =cv2.CascadeClassifier('C:₩Users₩Administrator₩Downloads₩TP_Vide o\text{VTP_VideoWhaarcascadesWhaarcascade_frontalface_default.xml')

Arrays to store the registered images and their labels.. Here we make a place to store the images of the registered persons for the program and their names.

train_data = np.empty((900,150*150), dtype=np.float32) labels_data = np.empty(900, dtype=np.float32)





Read all the registered photos and store them into 'train_data'.

Then, here we actually put the data we have saved (the images and their respective names) into the arrays we made.

The maximum (here 500) needs to be adapted to the number of persons in photos # For example, here the maximum is 500 because we have 5 persons with each 100 photos

for i in range(0, 500): img = cv2.imread('dataset/'+str(i)+'.png', 0) train_data[i] = img_to_vector(img)

#Define the names of the registered persons in the order they were registered.

Order here is very important because if the data is not replicated just like how it was saved the ere will be errors when the program runs as it will not be able to accurately say who is who. The gathered data must correspond with one another. The registered images of the registered persons must correspond with their names.

res_labels = ['Pablo', 'Aimee', Hanna', 'Sue', 'Dastan']





Define for each photo the index corresponding to the name in 'res_labels' For example, from 0 to 100 are the photos of Pablo, which is at the qqindex 0 in 'res_labels' and etc.

```
for i in range(0, 100):
labels_data[i] = 0
for i in range(100, 200):
labels_data[i] = 1
for i in range(200, 300):
labels_data[i] = 2
for i in range(300, 400):
labels_data[i] = 3
for i in range(400, 500):
labels_data[i] = 4
```

Define the font to print the names

font = cv2.FONT_HERSHEY_SIMPLEX









#Create empty NumPy arrays to store detected faces and their positions In our case, number of faces times number of pixels and datatype float32

np.empty((len(faces), 150*150), dtype=np.float32)

#Detect the face and for each face we store its flattened version (img_to_vector) into 'test_data'

test_data[idx] = img_to_vector(roi_gray)

#Execute KNN: Find for each face the 15 nearest registered faces and deduce the matching person (We tried changing the number to other odd numbers check the precision)

ret, results, neighbours, dist = knn.findNearest(test_data, 15)

#Write text on the webcam: cv2.putText

cv2.putText(frame, str, coordinates of the text, font style, font size, font color)

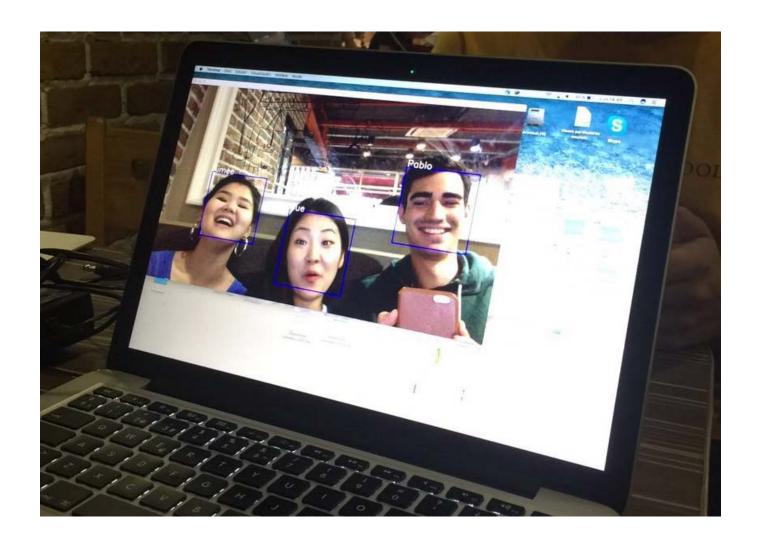
#Show the resulting image

cv2.imshow('frame', frame)





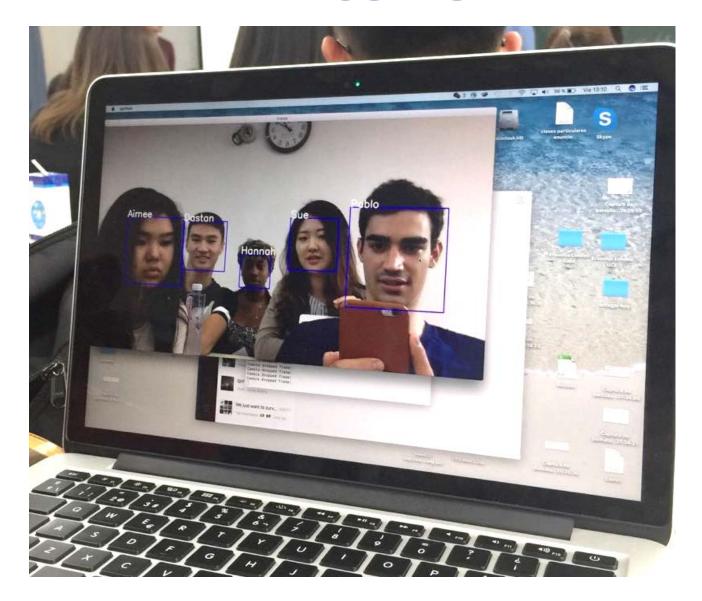
FINAL OUTPUT







FINAL OUTPUT







LET'S TRY IT OUT!



