

Machine learning : Sheet 4
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1.

$$\frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{a}} = - \frac{\partial \log a_y}{\partial \mathbf{a}} \quad (1)$$

$$= \left[-\frac{\partial \log a_y}{\partial a_1}, \dots, -\frac{\partial \log a_y}{\partial a_y}, \dots, -\frac{\partial \log a_y}{\partial a_C} \right] \quad (2)$$

$$= \left[0, \dots, -\frac{1}{a_y}, \dots, 0 \right] \quad (3)$$

The equation 1 is a definition of the objective function for a given point. The equation 2 is a definition of a gradient of a scalar function (derivative of scalar by a vector). The equation 3 uses property of derivative of a logarithm function.

$$\frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{z}} = \frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{a}} \cdot \frac{\partial \mathbf{a}}{\partial \mathbf{z}} \quad (4)$$

From the equation 4 we can see that we need to calculate $\frac{\partial \mathbf{a}}{\partial \mathbf{z}}$

$$\frac{\partial \mathbf{a}}{\partial \mathbf{z}} = \frac{\partial \left[\frac{e^{z_1}}{\sum_{l=1}^C e^{z_l}}, \dots, \frac{e^{z_i}}{\sum_{l=1}^C e^{z_l}}, \dots, \frac{e^{z_C}}{\sum_{l=1}^C e^{z_l}} \right]}{\partial \mathbf{z}} \quad (5)$$

$$= \begin{bmatrix} \frac{\partial \frac{e^{z_1}}{\sum_{l=1}^C e^{z_l}}}{\partial z_1} & \frac{\partial \frac{e^{z_1}}{\sum_{l=1}^C e^{z_l}}}{\partial z_2} & \dots & \frac{\partial \frac{e^{z_1}}{\sum_{l=1}^C e^{z_l}}}{\partial z_C} \\ \frac{\partial \frac{e^{z_2}}{\sum_{l=1}^C e^{z_l}}}{\partial z_1} & \frac{\partial \frac{e^{z_2}}{\sum_{l=1}^C e^{z_l}}}{\partial z_2} & \dots & \frac{\partial \frac{e^{z_2}}{\sum_{l=1}^C e^{z_l}}}{\partial z_C} \\ \dots & \dots & \dots & \dots \\ \frac{\partial \frac{e^{z_C}}{\sum_{l=1}^C e^{z_l}}}{\partial z_1} & \frac{\partial \frac{e^{z_C}}{\sum_{l=1}^C e^{z_l}}}{\partial z_2} & \dots & \frac{\partial \frac{e^{z_C}}{\sum_{l=1}^C e^{z_l}}}{\partial z_C} \end{bmatrix} \quad (6)$$

The equation 5 is softmax classifier equation given in the text. The equation 6 is a Jacobian of derivatives of vectors. Let us denote:

$$S_i = \frac{e^{z_i}}{\sum_{l=1}^C e^{z_l}}$$

Then the equation 6 becomes:

$$\begin{bmatrix} \frac{\partial S_1}{\partial z_1} & \frac{\partial S_1}{\partial z_2} & \dots & \frac{\partial S_1}{\partial z_C} \\ \frac{\partial S_2}{\partial z_1} & \frac{\partial S_2}{\partial z_2} & \dots & \frac{\partial S_2}{\partial z_C} \\ \dots & \dots & \dots & \dots \\ \frac{\partial S_C}{\partial z_1} & \frac{\partial S_C}{\partial z_2} & \dots & \frac{\partial S_C}{\partial z_C} \end{bmatrix} \quad (7)$$

In the equation 7 we notice that we have only two "different" type of derivatives, $\frac{\partial S_i}{\partial z_i}, i \in \{1, \dots, C\}$ and $\frac{\partial S_i}{\partial z_j}, i \neq j, i \in \{1, \dots, C\}, j \in \{1, \dots, C\}$.

$$\frac{\partial S_i}{\partial z_i} = \frac{\partial \frac{e^{z_i}}{\sum_{l=1}^C e^{z_l}}}{\partial z_i} \quad (8)$$

$$= \frac{e^{z_i} \cdot \sum_{l=1}^C e^{z_l} - e^{z_i} e^{z_i}}{\left(\sum_{l=1}^C e^{z_l} \right)^2} \quad (9)$$

$$= \frac{e^{z_i} \cdot \left(\sum_{l=1}^C e^{z_l} - e^{z_i} \right)}{\left(\sum_{l=1}^C e^{z_l} \right)^2} \quad (10)$$

$$= \frac{e^{z_i}}{\sum_{l=1}^C e^{z_l}} \frac{\sum_{l=1}^C e^{z_l} - e^{z_i}}{\sum_{l=1}^C e^{z_l}} \quad (11)$$

$$= S_i \cdot (1 - S_i) \quad (12)$$

The equation 8 uses S_i definition. The equation 9 uses derivative of division rule. The equations 10, 11, 12 are the simple transformations of the expressions and usage of definition S_i .

$$\frac{\partial S_i}{\partial z_j} = \frac{\partial \frac{e^{z_i}}{\sum_{l=1}^C e^{z_l}}}{\partial z_j} \quad (13)$$

$$= -\frac{e^{z_i} \cdot e^{z_j}}{\left(\sum_{l=1}^C e^{z_l}\right)^2} \quad (14)$$

$$= -S_i \cdot S_j \quad (15)$$

The equation 13 uses S_i definition. The equations 14 and 15 are simple arithmetic transformations of expressions expressions and usage of definition S_i . Finally we have:

$$\begin{aligned} \frac{\partial \mathbf{a}}{\partial \mathbf{z}} &= \begin{bmatrix} \frac{\partial S_1}{\partial z_1} & \frac{\partial S_1}{\partial z_2} & \dots & \frac{\partial S_1}{\partial z_C} \\ \frac{\partial S_2}{\partial z_1} & \frac{\partial S_2}{\partial z_2} & \dots & \frac{\partial S_2}{\partial z_C} \\ \dots & \dots & \dots & \dots \\ \frac{\partial S_C}{\partial z_1} & \frac{\partial S_C}{\partial z_2} & \dots & \frac{\partial S_C}{\partial z_C} \end{bmatrix} \\ &= \begin{bmatrix} S_1 \cdot (1 - S_1) & -S_1 \cdot S_2 & \dots & -S_1 \cdot S_C \\ -S_2 \cdot S_1 & S_2 \cdot (1 - S_2) & \dots & -S_2 \cdot S_C \\ \dots & \dots & \dots & \dots \\ -S_C \cdot S_1 & -S_C \cdot S_2 & \dots & S_C \cdot (1 - S_C) \end{bmatrix} \end{aligned} \quad (16)$$

The equation 16 uses equations 12 and 15. Further we have:

$$\frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{z}} = \frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{a}} \cdot \frac{\partial \mathbf{a}}{\partial \mathbf{z}} \quad (17)$$

$$= \left[0, \dots, -\frac{1}{a_y}, \dots, 0\right] \cdot \begin{bmatrix} S_1 \cdot (1 - S_1) & -S_1 \cdot S_2 & \dots & -S_1 \cdot S_C \\ -S_2 \cdot S_1 & S_2 \cdot (1 - S_2) & \dots & -S_2 \cdot S_C \\ \dots & \dots & \dots & \dots \\ -S_C \cdot S_1 & -S_C \cdot S_2 & \dots & S_C \cdot (1 - S_C) \end{bmatrix} \quad (18)$$

$$= \left[\frac{S_y \cdot S_1}{a_y}, \frac{S_y \cdot S_2}{a_y}, \dots, \frac{S_y \cdot (S_y - 1)}{a_y}, \dots, \frac{S_y \cdot S_C}{a_y}\right] \quad (19)$$

$$= [S_1, S_2, \dots, S_y - 1, \dots, S_C] \quad (20)$$

The equation 17 is just another way to write the same derivative. The equation 18 replaces derivatives using equations 3 and 16. The equation 19 is a matrix multiplication. The equation 20 is a simplification of the equation 19 using the property that $a_i = S_i$ ¹. The Generalizing the formula $\frac{\partial \ell}{\partial w_{ij}^2} = \frac{\partial \ell}{\partial z_i^2} \cdot \frac{\partial z_i^2}{\partial w_{ij}^2} = \frac{\partial \ell}{\partial z_i^2} \cdot x_j$ we get:

$$\begin{aligned} \frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{W}} &= \left(\mathbf{x} \frac{\partial \ell}{\partial \mathbf{z}}\right)^T \\ &= \begin{bmatrix} x_1 \cdot S_1 & x_2 \cdot S_1 & \dots & x_D \cdot S_1 \\ x_1 \cdot S_2 & x_2 \cdot S_2 & \dots & x_D \cdot S_2 \\ \dots & \dots & \dots & \dots \\ x_1 \cdot (S_y - 1) & x_2 \cdot (S_y - 1) & \dots & x_D \cdot (S_y - 1) \\ \dots & \dots & \dots & \dots \\ x_1 \cdot S_C & x_2 \cdot S_C & \dots & x_D \cdot S_C \end{bmatrix} \end{aligned} \quad (21)$$

The equation 21 is a matrix multiplication of matrices.

$$\frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{b}} = \frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{z}} \cdot \frac{\partial \mathbf{z}}{\partial \mathbf{b}} \quad (22)$$

The equation 22 is just another way to write derivative. If we notice that $\frac{\partial \mathbf{z}}{\partial \mathbf{b}}$ is an identity matrix (b_i appears only in equality with the z_i), from the equation 22 we get that $\frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{b}}$ is the same as $\frac{\partial \ell(\mathbf{W}, \mathbf{b}, \mathbf{x}, y)}{\partial \mathbf{z}}$. Using gradient descent for minibatch of B training examples we get the following update equations:

$$\mathbf{W}_{t+1} = \mathbf{W}_t - \frac{1}{B} \sum_{i=1}^B \frac{\partial \ell(\mathbf{x}_i, y_i, \mathbf{W}_t, \mathbf{b}_t)}{\partial \mathbf{W}}$$

¹I saw really late that $S_i = a_i$

$$\mathbf{b}_{t+1} = \mathbf{b}_t - \frac{1}{B} \sum_{i=1}^B \frac{\partial \ell(\mathbf{x}_i, y_i, \mathbf{W}_t, \mathbf{b}_t)}{\partial \mathbf{b}}$$

We just need to adjust orientation of \mathbf{b} and the derivative in the last update rule so the addition is possible.

2. 1.
- 2.
- 3.