

# From Systems to Functions Lab session 2 : Digital Filtering

## Make sure to have finished project session 1.

The topic of interest is to study audio signals digitized at a sampling frequency  $f_s$ =44,1 kHz on a 1s time sequence. (Standard frequency in audio following the Shannon criterium)

To validate the digital observations as it relates to the different types of filtering, students will be able to evaluate and appreciate the analysis (for various types of filters) using function soundsc(x,  $f_E$ ) which enables the listening (optional) the sound produced by the values stored in an array (table) using samples spaced by  $1/f_S$  second.

Students may use headphones NB: audible frequencies are between 20Hz and 20KHz.

Student will establish the relationship between the impulse response (time domain) and the frequency response of the filters studied in lab session 1. Data and results should be carefully compiled to be used in the next lab session and included in the final report.

These results are essentially illustrated by the timing diagrams and the spectra of the inputs and outputs to the filters studied. The spectrum of a periodic signal x(t) can be evaluated under MATLAB using a sub-program of the form:

```
Fx=fft(x); Sx=sqrt(power(real(Fx),2)+ power(imag(fx),2));
Or
Fx=fft(x); Sx=sqrt(Fx.*conj(Fx));
```

where fft(x) designate the fast Fourier transform of x, power(.,2), squaring, real(.) et imag(.) real and imaginary part of a complex number and conj(.), the complex conjugate.

NB: a) No report is required but students must save, compile all data and results to include in details in the final project report.

b) in the frequency domain an impulse gives a signal which contains all frequencies of the same amplitude.

c) White noise is a signal that contains all frequencies with random amplitudes

### I. SIGNAL OBSERVATION AND SPECTRAL ANALYSIS

A few computation techniques under MATLAB Q0. Pick two vectors x and y in the command window of MATLAB. Example:  $x = [1 \ 2 \ 3]$  and  $y = [4 \ 5 \ 6]$ .

- Compute one at a time the products x.\*y, x\*y' et x\*y in the command window.
- Which operation correspond to a scalar product? to a term by term product? to nothing?
- In the command window, record all the elements of vector z constructed as : z=x+y\*i.
- Repeat for vector conj(z). Comments.
- How, under MATLAB, can we calculate the magnitude of all vector elements of a complex vector like z?

Q1\*. Assuming that the sampling frequency of the signals is 44,1 kHz

Sampling and time windows of signals

- How many samples N are necessary to represent a signal in a 1s time window?
- Waht should the maximum frequency f<sub>MAX</sub> of the signals we can analyze (process) without losses? (Shannon-Nyquist theorem/criterium). Is the sampling without losses for the sound signal? Explain?

**Applications** 

- Q2. Complete the program **qEcoute.m** (in the dashed fields) to generate a sinusoidal signal at a 50Hz real frequency (lines 3,11).
- Justify the normalization of the frequencies (line 4). (Sampling).
- Plot the timing diagram (lines 24) and its spectrum (line 27).
- Repeat the above steps for frequencies up to 50kHz and for each frequency record (using the cursor) the low frequencies f1 (low) and fh (high) which appear on the signal spectrum. Fill out the table below

v1

<u>validation1</u>																							
	f(Hz)	20		200		1000		10000		15000		16000		17000		18000		20000		40000		50000	
	f <sub>1</sub> (Hz)																						
	F <sub>h</sub> (Hz)																						
1	Audible	Y	N	Y	N	Y	N	Y	N	Y	N	Y	N	Y	N	Y	N	Y	N	Y	Ν	Y	N

- If necessary, adjust the scale of your coordinates to optimize the plots.
- What do fi et fi correspond to? Compare these frequencies to f and to | fi-f | or to | n.fi-f | with n = integer).
- What is the real frequency heard at 40kHz and at 50kHz (ultrasounds !!!)?

#### Q3. Program a white noise.

- Carefully observe its spectrum and its audible perception.
- In a similar way record the spectrum of an impulse. What do you notice?

```
Programme qEcoute.m: Observation des signaux
      clc; clf;
                        %- Nombre d'échantillons=7
      frequence=50;
                        %- Fréquence réelle en Hertz
      f=frequence/...; %- Fréquence normalisée=?
     *---- L'échelle des temps et des fréquences--
 6
      temp=0:(N-1); freq=0:(N-1);
     3 1°) ENTREE SINUSOIDALE
10
     e=sin(2*pi*f*temp);
% 2°) ENTREE BRUIT BLANC
13
            %e=(rend(1.N)-0.5)*2;
15
            %e=geros(1,N); t0=3; e(t0)=N;
16
17
     % 4°) ENTREE INDICIELLE
            %t0=3; e=[zeros(1,t0) ones(1,N-t0)];
18
19 -
     Fe=fft(e); Se=sqrt(Fe.*conj(Fe))/N; %Calcul du Spectre--
20 -
21
                                          &Ecoute du signal --
     soundsc(e,N);
     figure (1); k-----Tracé de Chronogrammes
22 -
     subplot(4,1,1); plot(temp,e,'r'); title('CHRONOGRAMME');
      xlabel('Temps: ; sec'); ylabel ('Amplitide'); grid;
26
                              -Tracé de Spectres-
     subplot(4,1,2); semilogx(freq,Se,'r'); title('SPECTRE');
      xlabel('Fréquence: : Hz'); ylabel('Se'); grid;
     %x1im([20 20000]);
```

```
Programme Q5harmonic.m: Réponse à un sinus
      clc; clf;
      N= . . . . ;
      frequence...:
                                     %Fréquence réelle en Hertz
      frcoupure= . . .
                                     Frèg. de coupure des l'ordre en He
      frcentral=...; deltafreq=...; %Frèq. centrale & LB du passe-bande
           --- Normalisations et calcul des constantes de temps
      f=frequence/..; fc=frcoupure/..; f0=frcentral/..; Df=deltafreq/..;
      k =1/(2*pi*fc); k2=1/(2*pi*Df); k1=Df/(2*pi*f0*f0); %--
     temp=0:(N-1); freq=0:(N-1); %-- L'échelle des temps et des fréquen
12
                             - Initialisation des tableaux
14 -
      s=zeros(1,N); z=zeros(1,N); ss=zeros(1,N); zz=zeros(1,N); y=zeros(
15
16 -
      e=sin(2*pi*f*temp);
                                            %-- Exemple d'entrée sinus
18 -
     Fe=fft(e); Se=sqrt(Fe.*conj(Fe))/N: %-- Calcul du spectre de l'
19
                    -----Programmation des filtres ----
     for t=2:N
21 -
22 -
         s(t)=...; s(t)=...;
                                            % --- filtres du 1er ordre
23 -
24
     for t=3:N
25 -
26
         ss(t)=...; zz(t)=...; y(t)=...; k --- filtres du 2er ordre
27 -
      end;
29 -
                            --- Tracé des Chronogramm
      subplot(4,1,1); plot(temp,e,'r'); grid; ylabel('Entrée'); title('C
```

## II. FILTER SYNTHESIS

Cut-off frequencies, Bandwidth and center frequency. Q4. In the previous session, the relationship between the frequency responses and the time constants k,  $k_1$  et  $k_2$  for each type of filter had been established:

$$k = \frac{1}{\omega_c}$$
  $k1 = \frac{1}{q,\omega_0}$   $k2 = \frac{q}{\omega_0}$   $q = \frac{\omega_0}{\Delta\omega}$ 

where fc ( $\omega_c$ ) is the cut-off frequency of the first order low-pass of high-pass filters, fo ( $\omega_0$ ) the central frequency of the bandpass filter, q its quality factor and  $\Delta f$  its bandwidth .

• Express the different time constants as a function of the frequencies. NB:  $\Delta \omega = 2.\pi \Delta f$ 

Q5. Complete the programming of the 5 filters by filling out the qHarmonic.m. program. Take:

Specifications

- 1 kHz for the first order low pass and high pass filters cut-off frequency
- 2 kHz as the central frequency and a 20Hz bandwidth for the bandpass filter.
- The second order lowpass and high pass filters will be implemented using first order filters in series The output s(t) must be expressed as a function of the inputs e(t), e(t-1) ... and its previous values s(t), s(t-1), s(t-2) ... and eliminating the intermediate output.
- What is the advantage of such programming of the outputs?

## II. APPLICATION TO AUDIO-FREQUENCIES SIGNALS

Q6. Use the composite signal

e(t)=sin  $(2\pi f_1 t)$  + sin  $(2\pi f_2 t)$  with  $f_1$ =50Hz et  $f_2$ =10kHz as the inputs to the lowpass and high pass filters

- Explain the shape and the spectrum of the output signals of each filters.
- Listen to the output signals and note the audible perception of the second-order low-pass and high pass filters and the discrimination of the low and high pitch components of the input signal. Validation2

Q7. Replace the input with a uniform white noise signal: e=(rand(1,N)-0.5)\*2; et record the spectrum of the filter output signals for all the second order filters. (White noise includes all frequencies).

What do you observe?

## III. IMPULSE RESPONSE

Q8. Generate an impulse signal using a command of the form: e=zeros(1,N); e(10)=N as inputs to the filters

V

- Comment on the timing diagrams. Measure the frequency of the pseudo oscillations at the output of the bandpass filter...
- Integrate the command in the next window to observe the spectra on a log scale.
- Record the spectra of the inputs and outputs signals for all filters.

```
figure(2);
subplot(4,1,1); semilogx(freq,Se,'r'); grid;
ylabel('Entrée'); title('SPECTRES');
xlim([20 10000]);
subplot(4,1,2);
semilogx(freq,20*log10(Ss),'b',freq,20*log10(Sss),'c');
grid; ylabel ('Passe-bas I et II'); xlim([20 10000]);
subplot(4,1,3);
semilogx(freq,20*log10(Sz),'b',freq,20*log10(Szz),'c');
grid; ylabel ('Passe-bas I et II'); xlim([20 10000]);
subplot(4,1,4); semilogx(freq,20*log10(Sy),'g'); grid;
ylabel ('Passe-bande'); xlabel('Fréq.(Hs)');
klim([20 10000]);
```

Compare your observations to the Bode plots for each of the filters measuring the cutoff frequencies, the center frequency and bandwidth as well as the slope of the asymptote in low frequencies (LF) and in high frequencies (HF). Validation3