LET'S SAY WE HAVE A POLICY TA (als) ROLLOUT TO FROM START STATE SO ao S, a, S₂ Q₂ -= (So, Qo, S1, Q1, - - - - S7-1, Q7-1) $P_{\theta}(\mathbf{x}) = P(\mathbf{s}_{0}) T_{\theta}(\mathbf{a}_{0} | \mathbf{s}_{0}) P(\mathbf{s}_{1} | \mathbf{s}_{0}, \mathbf{a}_{0}) T_{\theta}(\mathbf{a}_{1} | \mathbf{s}_{1}) - \mathbf{a}_{0}$ EXPECTED TOTAL REGARD J(0) = - R(3) $\nabla_{\theta}J(\theta)=\nabla_{\theta}E_{\theta}R(z)=\nabla_{\theta}E_{\theta}(z)R(z)$ NAIVE APPROACE: Vo J(0)= 2 (70 Po(2) (R(2) Vere(8) = P(So) Vo To (aclso) P(S, 1 So, ac) -APPLY CHAIN RUE. + P(so) To (ao1so) P(s, s, ao) VTo (a, 1s,) -----

$$P_{\theta}(\vec{z}) = P(s_0) \, T_{\theta}(a_0 \mid s_0) \, P(s_1 \mid s_0, a_0) \, T_{\theta}(a_1 \mid s_1) - \cdots - P(s_1 \mid s_0, a_0) \, T_{\theta}(a_1 \mid s_0) + P(s_1 \mid s_0, a_0) + \cdots - P(s_1 \mid s_0, a_0) + P(s_1 \mid s_0, a_0) + \cdots - P(s_1 \mid s_0, a_0) + P(s_$$

APPROXIMATE THE EXPECTATION BY SAMPLING TRAJECTORIES

SIJN

BY ROLLING OUT POLICY TO IN REAL WORLD

$$\widetilde{V}_{\theta}J(\theta) = \frac{1}{N}\sum_{i=1}^{N} \left[V_{\theta} \log P_{\theta}(3_i) R(3_i) \right]$$

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$$=\frac{1}{N}\sum_{i=1}^{N} \left[\sum_{t=0}^{T-1} V_{\theta} \log T_{\theta} \left(a_{t} | S_{t} \right) \sum_{t=0}^{T-1} \delta(S_{t}, a_{t}) \right]$$

$$\nabla_{\theta} \log T_{\theta} (Q_{t} | S_{t})$$
 $\Sigma_{0} = 0$
 $\Sigma_{2} = 0$
 $\Sigma_{3} = 0$
 $\Sigma_{4} = 0$
 $\Sigma_{4} = 0$