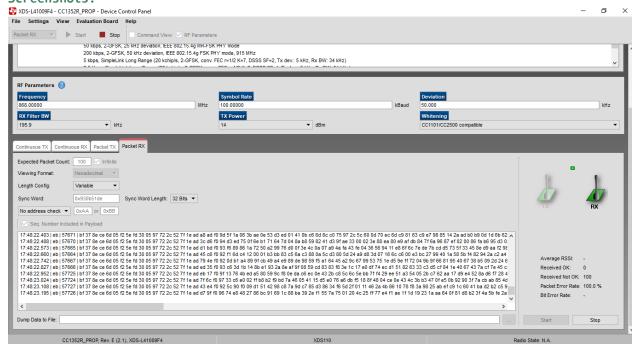
Date Submitted: November 21, 2019

Task 01:

Youtube Link:

Partner had device set to the modified transmit task

Screenshots:



Task 02:

Youtube Link: https://youtu.be/DyW6vjJ6YLI

```
Modified Code:
/***** Includes *****/
/* Standard C Libraries */
#include <stdlib.h>
#include <unistd.h>

/* TI Drivers */
#include <ti/drivers/rf/RF.h>
#include <ti/drivers/PIN.h>
#include <ti/drivers/pin/PINCC26XX.h>
```

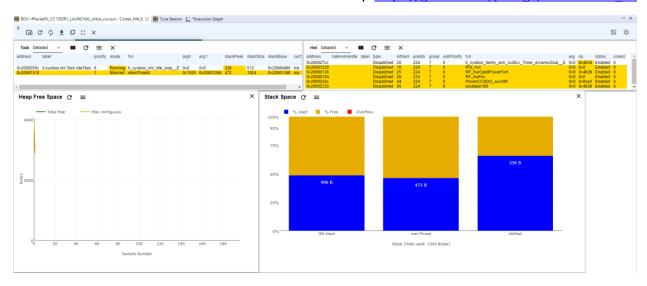
```
/* Driverlib Header files */
#include DeviceFamily constructPath(driverlib/rf prop mailbox.h)
/* Board Header files */
#include "ti drivers config.h"
#include <ti_radio_config.h>
/**** Defines ****/
/* Do power measurement */
//#define POWER_MEASUREMENT
/* Packet TX Configuration */
#define PAYLOAD_LENGTH
#ifdef POWER MEASUREMENT
#define PACKET_INTERVAL 5 /* For power measurement set packet interval to 5s */
#define PACKET INTERVAL 500000 /* Set packet interval to 500000us or 500ms */
#endif
/**** Prototypes *****/
/***** Variable declarations *****/
static RF_Object rfObject;
static RF_Handle rfHandle;
/* Pin driver handle */
static PIN Handle ledPinHandle;
static PIN_State ledPinState;
static uint8 t packet[PAYLOAD LENGTH];
static uint16_t seqNumber;
* Application LED pin configuration table:
* - All LEDs board LEDs are off.
PIN_Config pinTable[] =
   CONFIG PIN RLED | PIN GPIO OUTPUT EN | PIN GPIO LOW | PIN PUSHPULL |
PIN DRVSTR MAX,
#ifdef POWER MEASUREMENT
#if defined(CONFIG CC1350 LAUNCHXL)
   CONFIG DIO30 SWPWR | PIN GPIO OUTPUT EN | PIN GPIO HIGH | PIN PUSHPULL |
PIN_DRVSTR_MAX,
#endif
#endif
   PIN TERMINATE
};
/**** Function definitions *****/
void *mainThread(void *arg0)
```

```
RF Params rfParams;
    RF Params init(&rfParams);
    /* Open LED pins */
    ledPinHandle = PIN open(&ledPinState, pinTable);
    if (ledPinHandle == NULL)
    {
        while(1);
    }
#ifdef POWER MEASUREMENT
#if defined(CONFIG_CC1350_LAUNCHXL)
    /* Route out PA active pin to CONFIG DIO30 SWPWR */
    PINCC26XX_setMux(ledPinHandle, CONFIG_DIO30_SWPWR, PINCC26XX_MUX_RFC_GP01);
#endif
#endif
    RF cmdPropTx.pktLen = PAYLOAD LENGTH;
    RF cmdPropTx.pPkt = packet;
    RF_cmdPropTx.startTrigger.triggerType = TRIG_NOW;
    /* Request access to the radio */
#if defined(DeviceFamily CC26X0R2)
    rfHandle = RF open(&rfObject, &RF prop, (RF RadioSetup*)&RF cmdPropRadioSetup,
&rfParams);
#else
    rfHandle = RF open(&rfObject, &RF prop, (RF RadioSetup*)&RF cmdPropRadioDivSetup,
&rfParams);
#endif// DeviceFamily CC26X0R2
    /* Set the frequency */
    RF_postCmd(rfHandle, (RF_Op*)&RF_cmdFs, RF_PriorityNormal, NULL, 0);
    while(1)
    {
        /* Create packet with incrementing sequence number and random payload */
        packet[0] = (uint8_t)(seqNumber >> 8);
        packet[1] = (uint8_t)(seqNumber++);
        uint8_t i;
        for (i = 2; i < PAYLOAD LENGTH; i++)</pre>
        {
            packet[i] = rand();
        }
        /* Send packet */
        RF EventMask terminationReason = RF_runCmd(rfHandle, (RF_Op*)&RF_cmdPropTx,
                                                    RF PriorityNormal, NULL, 0);
        switch(terminationReason)
        {
            case RF_EventLastCmdDone:
                // A stand-alone radio operation command or the last radio
                // operation command in a chain finished.
                break;
            case RF_EventCmdCancelled:
```

// Command cancelled before it was started; it can be caused

```
// by RF cancelCmd() or RF flushCmd().
                break;
            case RF EventCmdAborted:
                // Abrupt command termination caused by RF cancelCmd() or
                // RF flushCmd().
                break;
            case RF_EventCmdStopped:
                // Graceful command termination caused by RF cancelCmd() or
                // RF flushCmd().
                break:
            default:
                // Uncaught error event
                while(1);
        }
        uint32 t cmdStatus = ((volatile RF Op*)&RF cmdPropTx)->status;
        switch(cmdStatus)
            case PROP DONE OK:
                // Packet transmitted successfully
                break;
            case PROP_DONE_STOPPED:
                // received CMD STOP while transmitting packet and finished
                // transmitting packet
                break;
            case PROP DONE ABORT:
                // Received CMD_ABORT while transmitting packet
                break;
            case PROP_ERROR_PAR:
                // Observed illegal parameter
                break;
            case PROP ERROR NO SETUP:
                // Command sent without setting up the radio in a supported
                // mode using CMD_PROP_RADIO_SETUP or CMD_RADIO_SETUP
                break;
            case PROP_ERROR_NO_FS:
                // Command sent without the synthesizer being programmed
                break;
            case PROP ERROR TXUNF:
                // TX underflow observed during operation
                break:
            default:
                // Uncaught error event - these could come from the
                // pool of states defined in rf mailbox.h
                while(1);
        }
#ifndef POWER MEASUREMENT
        PIN setOutputValue(ledPinHandle,
CONFIG_PIN_RLED, !PIN_getOutputValue(CONFIG_PIN_RLED));
#endif
        /* Power down the radio */
        RF_yield(rfHandle);
```





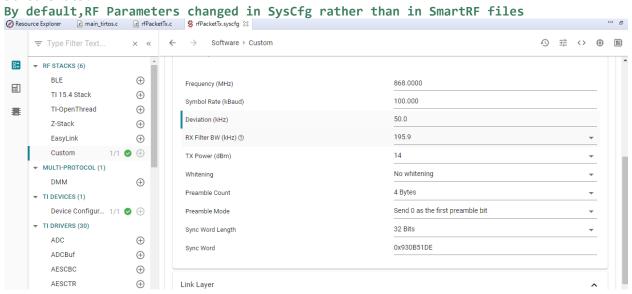
Task 03:

Youtube Link: https://youtu.be/KFcw3kwP4qE

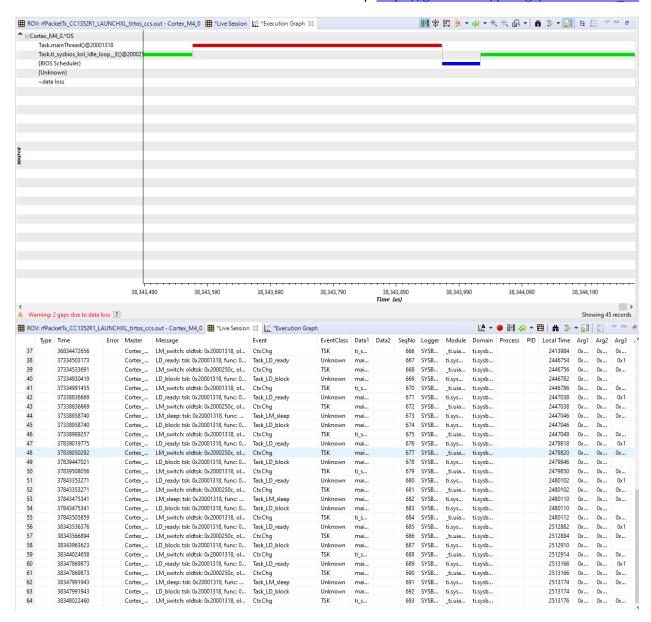
Modified Code:

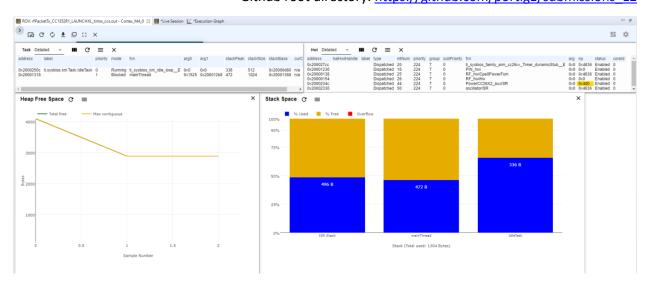
Code is unmodified from previous task

Screenshots:



Github root directory: https://github.com/portig1/submissions E2

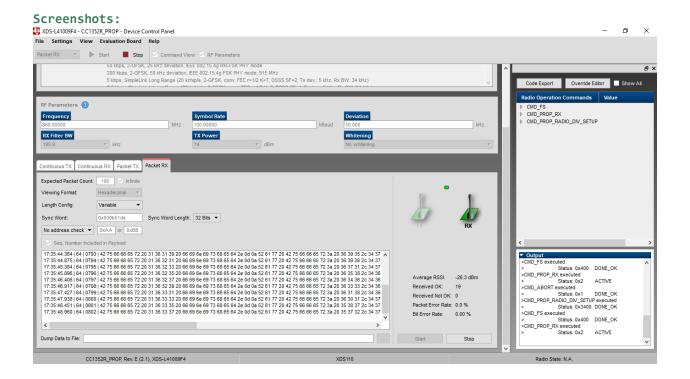




Task 04:

Youtube Link:

Like in Task 1, the TX device is set to transmit a ADC value



Task 05:

```
Youtube Link:
Modified Code:
/**** Includes ****/
/* Standard C Libraries */
#include <stdlib.h>
/* TI Drivers */
#include <ti/drivers/rf/RF.h>
#include <ti/drivers/PIN.h>
/* Driverlib Header files */
#include DeviceFamily constructPath(driverlib/rf prop mailbox.h)
/* Board Header files */
#include "ti_drivers_config.h"
/* Application Header files */
#include "RFQueue.h"
#include <ti radio config.h>
/**** Defines ****/
/* Packet RX Configuration */
#define DATA_ENTRY_HEADER_SIZE 8 /* Constant header size of a Generic Data Entry */
#define MAX_LENGTH 30 /* Max length byte the radio will accept */
#define NUM_DATA_ENTRIES 2 /* NOTE: Only two data entries supported at the
moment */
#define NUM_APPENDED_BYTES 2 /* The Data Entries data field will contain:
                                    * 1 Header byte (RF cmdPropRx.rxConf.bIncludeHdr =
0x1)
                                     * Max 30 payload bytes
                                     * 1 status byte (RF cmdPropRx.rxConf.bAppendStatus
= 0x1) */
/**** Prototypes *****/
static void callback(RF_Handle h, RF_CmdHandle ch, RF_EventMask e);
/***** Variable declarations *****/
static RF_Object rfObject;
static RF_Handle rfHandle;
/* Pin driver handle */
static PIN Handle ledPinHandle;
static PIN_State ledPinState;
```

```
/* Buffer which contains all Data Entries for receiving data.
* Pragmas are needed to make sure this buffer is 4 byte aligned (requirement from
the RF Core) */
#if defined( TI COMPILER VERSION )
#pragma DATA_ALIGN (rxDataEntryBuffer, 4);
static uint8 t
rxDataEntryBuffer[RF_QUEUE_DATA_ENTRY_BUFFER_SIZE(NUM_DATA_ENTRIES,
                                                  MAX LENGTH,
                                                  NUM APPENDED BYTES)];
#elif defined( IAR SYSTEMS ICC )
#pragma data alignment = 4
static uint8 t
rxDataEntryBuffer[RF QUEUE DATA ENTRY BUFFER SIZE(NUM DATA ENTRIES,
                                                  MAX LENGTH,
                                                  NUM_APPENDED_BYTES)];
#elif defined( GNUC )
static uint8 t
rxDataEntryBuffer[RF_QUEUE_DATA_ENTRY_BUFFER SIZE(NUM DATA ENTRIES,
                                                  MAX LENGTH,
                                                  NUM APPENDED BYTES)]
                                                  __attribute__((aligned(4)));
#else
#error This compiler is not supported.
#endif
/* Receive dataQueue for RF Core to fill in data */
static dataOueue t dataOueue;
static rfc_dataEntryGeneral_t* currentDataEntry;
static uint8 t packetLength;
static uint8_t* packetDataPointer;
static uint8 t packet[MAX LENGTH + NUM APPENDED BYTES - 1]; /* The length byte is
stored in a separate variable */
 * Application LED pin configuration table:
   - All LEDs board LEDs are off.
PIN_Config pinTable[] =
    CONFIG PIN RLED | PIN GPIO OUTPUT EN | PIN GPIO LOW | PIN PUSHPULL |
PIN DRVSTR MAX,
      PIN TERMINATE
};
/***** Function definitions *****/
void *mainThread(void *arg0)
{
    RF Params rfParams;
    RF Params init(&rfParams);
    /* Open LED pins */
    ledPinHandle = PIN open(&ledPinState, pinTable);
```

```
if (ledPinHandle == NULL)
    {
        while(1);
    }
    if( RFQueue defineQueue(&dataQueue,
                            rxDataEntryBuffer,
                            sizeof(rxDataEntryBuffer),
                            NUM DATA ENTRIES,
                            MAX LENGTH + NUM APPENDED BYTES))
    {
        /* Failed to allocate space for all data entries */
        while(1);
    }
    /* Modify CMD PROP RX command for application needs */
    /* Set the Data Entity queue for received data */
    RF cmdPropRx.pQueue = &dataQueue;
    /* Discard ignored packets from Rx queue */
    RF cmdPropRx.rxConf.bAutoFlushIgnored = 1;
    /* Discard packets with CRC error from Rx queue */
    RF_cmdPropRx.rxConf.bAutoFlushCrcErr = 1;
    /* Implement packet length filtering to avoid PROP_ERROR_RXBUF */
    RF_cmdPropRx.maxPktLen = MAX_LENGTH;
    RF cmdPropRx.pktConf.bRepeatOk = 1;
    RF cmdPropRx.pktConf.bRepeatNok = 1;
    /* Request access to the radio */
#if defined(DeviceFamily CC26X0R2)
    rfHandle = RF_open(&rfObject, &RF_prop, (RF_RadioSetup*)&RF_cmdPropRadioSetup,
&rfParams);
#else
    rfHandle = RF_open(&rfObject, &RF_prop, (RF_RadioSetup*)&RF_cmdPropRadioDivSetup,
&rfParams);
#endif// DeviceFamily_CC26X0R2
    /* Set the frequency */
    RF_postCmd(rfHandle, (RF_Op*)&RF_cmdFs, RF_PriorityNormal, NULL, 0);
    /* Enter RX mode and stay forever in RX */
    RF EventMask terminationReason = RF runCmd(rfHandle, (RF Op*)&RF cmdPropRx,
                                               RF PriorityNormal, &callback,
                                               RF EventRxEntryDone);
    switch(terminationReason)
        case RF EventLastCmdDone:
            // A stand-alone radio operation command or the last radio
            // operation command in a chain finished.
            break:
        case RF_EventCmdCancelled:
            // Command cancelled before it was started; it can be caused
            // by RF_cancelCmd() or RF_flushCmd().
            break;
        case RF_EventCmdAborted:
```

```
// Abrupt command termination caused by RF cancelCmd() or
        // RF_flushCmd().
        break;
    case RF EventCmdStopped:
        // Graceful command termination caused by RF cancelCmd() or
        // RF flushCmd().
        break;
    default:
       // Uncaught error event
       while(1);
}
uint32 t cmdStatus = ((volatile RF Op*)&RF cmdPropRx)->status;
switch(cmdStatus)
{
    case PROP DONE OK:
        // Packet received with CRC OK
        break;
    case PROP DONE RXERR:
        // Packet received with CRC error
        break;
    case PROP_DONE_RXTIMEOUT:
        // Observed end trigger while in sync search
        break;
    case PROP_DONE_BREAK:
        // Observed end trigger while receiving packet when the command is
        // configured with endType set to 1
       break;
    case PROP DONE ENDED:
        // Received packet after having observed the end trigger; if the
        // command is configured with endType set to 0, the end trigger
        // will not terminate an ongoing reception
       break;
    case PROP_DONE_STOPPED:
        // received CMD_STOP after command started and, if sync found,
        // packet is received
        break;
    case PROP_DONE_ABORT:
        // Received CMD_ABORT after command started
       break;
    case PROP ERROR RXBUF:
        // No RX buffer large enough for the received data available at
        // the start of a packet
        break;
    case PROP ERROR RXFULL:
        // Out of RX buffer space during reception in a partial read
        break;
    case PROP ERROR PAR:
        // Observed illegal parameter
        break;
    case PROP_ERROR_NO_SETUP:
        // Command sent without setting up the radio in a supported
        // mode using CMD_PROP_RADIO_SETUP or CMD_RADIO_SETUP
        break;
    case PROP_ERROR_NO_FS:
```

```
// Command sent without the synthesizer being programmed
            break;
        case PROP ERROR RXOVF:
            // RX overflow observed during operation
            break:
        default:
            // Uncaught error event - these could come from the
            // pool of states defined in rf_mailbox.h
            while(1);
    }
    while(1);
}
void callback(RF_Handle h, RF_CmdHandle ch, RF_EventMask e)
    if (e & RF_EventRxEntryDone)
    {
        /* Toggle pin to indicate RX */
        PIN_setOutputValue(ledPinHandle, CONFIG_PIN RLED,
                           !PIN_getOutputValue(CONFIG_PIN_RLED));
        /* Get current unhandled data entry */
        currentDataEntry = RFQueue getDataEntry();
        /* Handle the packet data, located at &currentDataEntry->data:
        * - Length is the first byte with the current configuration
        * - Data starts from the second byte */
        packetLength = *(uint8_t*)(&currentDataEntry->data);
        packetDataPointer = (uint8_t*)(&currentDataEntry->data + 1);
        /* Copy the payload + the status byte to the packet variable */
        memcpy(packet, packetDataPointer, (packetLength + 1));
        RFQueue_nextEntry();
    }
}
Screenshots:
```

Task 06:

Youtube Link:

Modified Code:

Screenshots:		
Task 07:		
Youtube Link:		
Modified Code:		
Screenshots:		