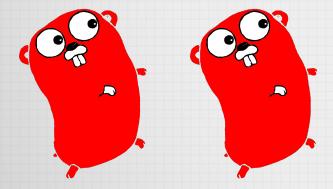
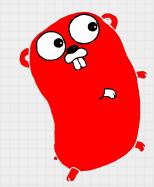
# ALL ABOUT SPEED

# PRESENTED BY SAMUEL PORTMANN

**Parallel Computing and Dynamic Programming** 











# Speed

Parallel computing can be used to run programs on multiple cores. This improves the performance.



#### **World's Behavior**

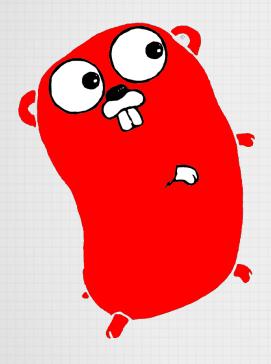
Sequential processing on its own does not model the world's behavior. Out there we see a complex world of interacting and independently behaving pieces.

## **Differences between Parallel Computing and Concurrent Programming:**

Concurrency is not parallelism, although it enables parallelism. If you have only one processor, your program can still be concurrent but it cannot be parallel. On the other hand, a well-written concurrent program might run efficiently in parallel on a multiprocessor.

Parallel Computing is not the same as concurrent programming.

# **GOLANG Some Facts**



#### Google

Go, also called golang, is a programming language initially developed at Google in 2007.

#### **Characteristics**

Go is a statically-typed language with syntax loosely derived from that of C, adding garbage collected memory management, type safety, additional built-in types such as variable-length arrays and key-value maps, and a large standard library.

### **Concurring Programming**

Go's concurrency primitives make it easy to construct streaming data pipelines that make efficient use of I/O and multiple CPUs.

First it was a requirement to program in go. Now I am happy to have seen a new and powerful language.

# **GOLANG Basics I**

# func(parameter) return { }

- 1.anonymous functions closures
- 2.recursive functions (multiple return)
- 3.go functions -> concurrency

# import "fmt"

```
"fmt"
"math"
"runtime"
"sync"
```

"time"

## func main()

```
func main() {
    fmt.Println("Hello World")
}
```

# Data-Types

- 1. integer -> int
- 2. float -> float64
- 3. array -> datatype[]

I have mainly explained these elements as they are used in the show program.



# **GOLANG Basics II**

#### if condition { }

```
if matrix[m][n] > (*maxValue)[m] {
          (*maxValue)[m] = matrix[m][n]
}
```

## pointer

- &variable: get the adress
- 2. \*pointer: operate on the value

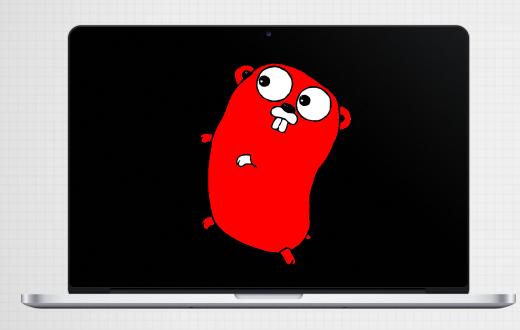
## for condition {}

```
func main() {
    fmt.Println("Hello World")
}
```

# WaitGroup

- 1. var wg sync.WaitGroup
- 2. wg.Add(1)
- 3. wg.Done()
- 4. wg.Wait()





# **Point Of Attack**

Which part of the program should we parallelize?

# Code

A simple value iteration cake eating problem.

Let's go through a simple dynamic programming example.



# **AMDAHL'S LAW Maximum Speed Up**



#### **Formula**

$$T(n) = T(1)\left(B + \frac{1}{n}(1 - B)\right)$$

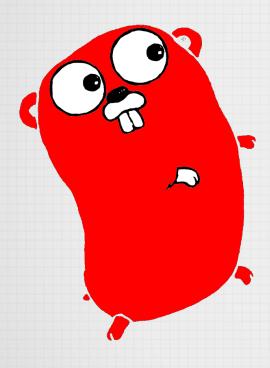
 $n\in\mathbb{N}$  the number of threads of execution,

 $B \in [0,1]$ the fraction of the algorithm that is strictly serial

# How fast can we get? (60% Parallelized)

With 
$$n = 4$$
 and  $B = 40\%$   
->  $T(n) = T(1) \times 0.55$ 





#### Reference

I recommend the ebook available on http://www.golang-book.com/

#### **Matrix Lib**

Skelter John: Parallelized Matrix Library https://github.com/skelterjohn/go.matrix

#### **GITHub**

This presentation and the code: https://github.com/portmann/go.parallelized

This is the last slide.

# THANK YOU FOR YOUR TIME