

The Minimal Retroreflective Microfacet Model

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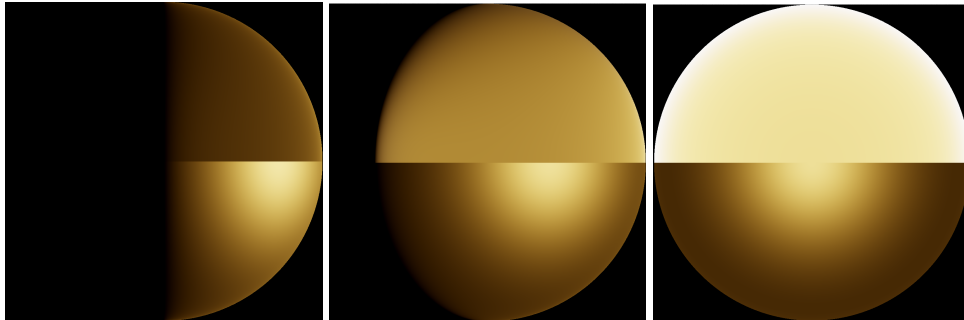


Figure 1. Comparison of our retroreflector model (top) obtained by an almost trivial modification of the equivalent roughness GGX microfacet model (bottom). The lighting varies (left to right) from side-on, quarter-on, and straight-on, exhibiting the strong retro-reflective peak.

Abstract

We introduce the “Minimal Retroreflective Microfacet” (MRM) model, which provides a simple scheme for modifying a pre-existing microfacet BRDF implementation to produce a visually plausible, energy-conserving retroreflective result.

1. Introduction

Rendering of retro-reflective materials is useful in a variety of contexts. A number of CG models have been proposed. For practical purposes in visual effects, we are interested in a model which is a) visually plausible at least, b) provably energy-conserving, c) efficient and easy to implement, ideally a small modification to well-understood microfacet models. We present here a model based on the previously published back-vector formulation [Belcour et al. 2014] which meets these requirements. It is so simple a modification to a regular microfacet model, that we “Minimal Retroreflective Microfacet” (MRM) model which achieves a plausible retro-reflective result.

In this document, we detail the correct usage and derivation of this retro-reflective BRDF model within the microfacet framework [Walter et al. 2007; Heitz 2014]. We first recall some basic principles from microfacets theory (Section 2) and show how to change it to account for retro-reflective microfacets (Section 3). We then detail how to implement this in practice (Section 5). Finally, we discuss how retro-reflection can

\mathbf{v}	normalized vector to viewer
\mathbf{l}	normalized vector to light
\mathbf{n}	surface normal
$\mathbf{t}_1, \mathbf{t}_2$	tangent and bitangent (forming an orthonormal coordinate frame with the normal)
\mathbf{h}	half vector, $\mathbf{h} = \mathbf{h}(\mathbf{v}, \mathbf{l}) = \frac{\mathbf{v} + \mathbf{l}}{\ \mathbf{v} + \mathbf{l}\ }$
$\langle \mathbf{x}, \mathbf{y} \rangle$	dot product of \mathbf{x} and \mathbf{y}
$\text{reflect}(\mathbf{x}, \mathbf{m})$	reflection of vector \mathbf{x} on surface with normal \mathbf{m} , i.e. $\text{reflect}(\mathbf{x}, \mathbf{m}) = -\mathbf{x} + 2 \langle \mathbf{x}, \mathbf{m} \rangle \mathbf{m}$
Ω	hemisphere of directions around the normal

Figure 2. Notations used.

occur at the microfacet level (Section 4).

2. Microfacet BRDF Models

Using the notations from figure 2, a microfacet BRDF [Walter et al. 2007; Heitz 2014] takes the form (Walter et al. [2007] Equation (20))

$$f(\mathbf{v}, \mathbf{l}) = \frac{D(\mathbf{h}) G_2(\mathbf{v}, \mathbf{l}) F(\mathbf{h}, \mathbf{v})}{4 \langle \mathbf{v}, \mathbf{n} \rangle \langle \mathbf{l}, \mathbf{n} \rangle} \quad (1)$$

where D is the distribution of microfacets, normalized to fulfill $\int_{\Omega} D(\mathbf{h}) \langle \mathbf{n}, \mathbf{h} \rangle d\mathbf{h} = 1$, G_2 is the shadowing-masking function, and F is the Fresnel term. The half-vector \mathbf{h} is used as the *selector* for microfacets reflecting light from incident direction \mathbf{l} to outgoing direction \mathbf{v} (i.e. only microfacet with normals aligned with the half-vector will reflect light). In Section 4.1 of their work, Walter et al. [Walter et al. 2007] detail the effect of using the half vector as the microfacet selector and obtain Equation 1.

In this work, we show that we can use the back vector [Belcour et al. 2014] used to model retro-reflection as a microfacet selector. Before detailing the impact of such a change, we review some properties of microfacet models.

Shadowing-Masking. The shadowing-masking function combines the visibility masking function $G_1(\mathbf{v}, \mathbf{l})$ for view direction and $G_1(\mathbf{l}, \mathbf{v})$ for light direction:

$$G_2(\mathbf{v}, \mathbf{l}) = G_2(G_1(\mathbf{v}, \mathbf{l}), G_1(\mathbf{l}, \mathbf{v})) \quad (2)$$

Mathematically, the BRDF is plausible if G_2 is symmetric w.r.t. to exchanging \mathbf{v} and \mathbf{l} , fulfills $G_2(\mathbf{v}, \mathbf{l}) \leq G_1(\mathbf{v}, \mathbf{l})$, and if G_1 further establishes the correct projected area of visible micro-surfaces [Heitz 2014]

$$\langle \mathbf{v}, \mathbf{n} \rangle = \int_{\{\mathbf{h} \in \Omega: \langle \mathbf{v}, \mathbf{h} \rangle \geq 0\}} D(\mathbf{h}) G_1(\mathbf{v}, \text{reflect}(\mathbf{v}, \mathbf{h})) \langle \mathbf{v}, \mathbf{h} \rangle d\mathbf{h}. \quad (3)$$

Choices for G_1 with this property are the Smith masking function

$$G_1(\mathbf{v}, \mathbf{l}) = G_{1,\text{Smith}}(\mathbf{v}) = \frac{\langle \mathbf{v}, \mathbf{n} \rangle}{\int_{\{\mathbf{h} \in \Omega: \langle \mathbf{v}, \mathbf{h} \rangle \geq 0\}} D(\mathbf{h}) \langle \mathbf{v}, \mathbf{h} \rangle d\mathbf{h}}, \quad (4)$$

where analytic expressions are available for Beckmann and GGX distributions, and the v-cavity masking function

$$G_1(\mathbf{v}, \mathbf{l}) = G_{1,\text{vc}}(\langle \mathbf{v}, \mathbf{n} \rangle, \langle \mathbf{n}, \mathbf{h} \rangle, \langle \mathbf{v}, \mathbf{h} \rangle) = \min \left\{ \frac{2 \langle \mathbf{v}, \mathbf{n} \rangle \langle \mathbf{n}, \mathbf{h} \rangle}{\langle \mathbf{v}, \mathbf{h} \rangle}, 1 \right\}, \quad (5)$$

which is generally applicable for distributions with symmetry around the normal.

3. Back-vector Modification

If instead of half-vector \mathbf{h} , we use the back-vector \mathbf{b} [Belcour et al. 2014] defined as

$$\mathbf{b}(\mathbf{v}, \mathbf{l}) = \mathbf{h}(\mathbf{v}', \mathbf{l}) = \frac{\mathbf{v}' + \mathbf{l}}{\|\mathbf{v}' + \mathbf{l}\|}, \text{ with } \mathbf{v}' = \text{reflect}(\mathbf{v}, \mathbf{n}), \quad (6)$$

to select the reflecting microfacet, we are to re-derive the microfacet model.

Jacobian of Back-Vector. The first step is to write the Jacobian of the change of variable from the back-vector to the light vector \mathbf{l} (Equation (11) and (14) of Walter et al. [2007]). Fortunately, this jacobian has the same form as the half-vector one:

$$\left\| \frac{\partial \omega_{\mathbf{b}}}{\partial \omega_{\mathbf{l}}} \right\| = \left\| \frac{\partial \omega_{\mathbf{h}(\mathbf{v}', \mathbf{l})}}{\partial \omega_{\mathbf{l}}} \right\| = \frac{1}{4 |\mathbf{l} \cdot \mathbf{h}(\mathbf{v}', \mathbf{l})|} = \frac{1}{4 |\mathbf{l} \cdot \mathbf{b}|} \quad (7)$$

Microfacet reflection term. We do not know for sure how the retro-reflective microfacet interacts with incident light. However, we have experimental evidence [Belcour et al. 2014] that it behaves similarly to a Fresnel term. We opted to reuse the Fresnel as well in the $(\mathbf{v}', \mathbf{l})$ configuration. As such, we update the formulation of $\rho(\mathbf{v}, \mathbf{m})$ (Equation (11) of Walter et al. [2007]) to use the reflected view vector instead. It follows that the reflection microsurface BRDF (Equation (15) of Walter et al. [2007]) becomes

$$f_r^m(\mathbf{v}, \mathbf{l}, \mathbf{m}) = F(\mathbf{v}', \mathbf{m}) \frac{\delta(\mathbf{b}, \mathbf{m})}{4 |\mathbf{v}' \cdot \mathbf{b}|^2}. \quad (8)$$

We used the fact that $|\mathbf{l} \cdot \mathbf{b}| = |\mathbf{v}' \cdot \mathbf{b}|$.

Shadowing & Masking. [TODO: Laurent: I think we could extract the shadowing from Matthias derivation here. The other way to justify the derivation of the full model is to highlight that Smith's shadowing/masking does not depend on the microfacet (apart from the sidedness). Hence, whatever the microfacet selector (as long as the sidedness matches), the shadowing/masking is the same. Since \mathbf{v} and \mathbf{v}' share the same slope, we can exchange them in the equation.]

Final form.

$$f_R(\mathbf{v}, \mathbf{l}) = \frac{D(\mathbf{h}) G_2(\mathbf{v}', \mathbf{l}) F(\mathbf{b}, \mathbf{v}')}{4 \langle \mathbf{v}', \mathbf{n} \rangle \langle \mathbf{l}, \mathbf{n} \rangle} \quad (9)$$

4. Plausibility of the Back-vector Modification

In analogy to \mathbf{v}' we let $\mathbf{l}' := \text{reflect}(\mathbf{l}, \mathbf{n})$. First we observe

$$\begin{aligned} \langle \mathbf{v}', \mathbf{n} \rangle &= \langle \mathbf{v}, \mathbf{n} \rangle \text{ and} \\ \langle \mathbf{l}, \mathbf{n} \rangle &= \langle \mathbf{l}', \mathbf{n} \rangle. \end{aligned} \quad (10)$$

For the back-vector we show $\mathbf{h}(\mathbf{v}', \mathbf{l}) = \text{reflect}(\mathbf{h}(\mathbf{l}', \mathbf{v}), \mathbf{n})$, as

$$\begin{aligned} \mathbf{v}' + \mathbf{l} &= (-\mathbf{v} + 2 \langle \mathbf{v}, \mathbf{n} \rangle \mathbf{n}) + \mathbf{l} \\ &= (-\mathbf{v} + 2 \langle \mathbf{v}, \mathbf{n} \rangle \mathbf{n}) + (-\mathbf{l}' + 2 \langle \mathbf{l}', \mathbf{n} \rangle \mathbf{n}) \\ &= -(\mathbf{l}' + \mathbf{v}) + 2 \langle \mathbf{l}' + \mathbf{v}, \mathbf{n} \rangle \mathbf{n} = \text{reflect}(\mathbf{l}' + \mathbf{v}, \mathbf{n}) \end{aligned} \quad (11)$$

and therefore $\|\mathbf{v}' + \mathbf{l}\| = \|\mathbf{l}' + \mathbf{v}\|$ as well. From that we can conclude

$$\begin{aligned} \langle \mathbf{n}, \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle &= \langle \mathbf{n}, \mathbf{h}(\mathbf{l}', \mathbf{v}) \rangle \\ \langle \mathbf{t}_1, \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle &= -\langle \mathbf{t}_1, \mathbf{h}(\mathbf{l}', \mathbf{v}) \rangle \\ \langle \mathbf{t}_2, \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle &= -\langle \mathbf{t}_2, \mathbf{h}(\mathbf{l}', \mathbf{v}) \rangle. \end{aligned} \quad (12)$$

As anisotropic Phong, Beckmann, and GGX distributions are reflection-symmetric around the normal, i.e. they take the form $D(\mathbf{h}) = D(\langle \mathbf{n}, \mathbf{h} \rangle, |\langle \mathbf{t}_1, \mathbf{h} \rangle|, |\langle \mathbf{t}_2, \mathbf{h} \rangle|)$, we can thus infer that using them with the back-vector obeys symmetry. Further, the reflection symmetry of D along with equation (10) gives

$$\begin{aligned} G_{1,\text{Smith}}(\mathbf{v}) &= \frac{\langle \mathbf{v}, \mathbf{n} \rangle}{\int_{\{\mathbf{h} \in \Omega: \langle \mathbf{v}, \mathbf{h} \rangle \geq 0\}} D(\mathbf{h}) \langle \mathbf{v}, \mathbf{h} \rangle d\mathbf{h}} \\ &= \frac{\langle \mathbf{v}', \mathbf{n} \rangle}{\int_{\{\mathbf{h} \in \Omega: \langle \mathbf{v}', \mathbf{h} \rangle \geq 0\}} D(\mathbf{h}) \langle \mathbf{v}', \mathbf{h} \rangle d\mathbf{h}} = G_{1,\text{Smith}}(\mathbf{v}') \end{aligned} \quad (13)$$

for Smith-masking. Next we show

$$\langle \mathbf{v}', \mathbf{l} \rangle = -\langle \mathbf{v}, \mathbf{l} \rangle + 2 \langle \mathbf{v}, \mathbf{n} \rangle \langle \mathbf{l}, \mathbf{n} \rangle = \langle \mathbf{v}, -\mathbf{l} + 2 \langle \mathbf{l}, \mathbf{n} \rangle \mathbf{n} \rangle = \langle \mathbf{v}, \mathbf{l}' \rangle \quad (14)$$

and therefore

$$\langle \mathbf{v}', \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle = \frac{1 + \langle \mathbf{l}, \mathbf{v}' \rangle}{\|\mathbf{v}' + \mathbf{l}\|} = \frac{1 + \langle \mathbf{l}', \mathbf{v} \rangle}{\|\mathbf{l}' + \mathbf{v}\|} = \langle \mathbf{l}', \mathbf{h}(\mathbf{l}', \mathbf{v}) \rangle. \quad (15)$$

Using this along with equations (12) and (10) we get

$$\begin{aligned} G_1(\mathbf{v}', \mathbf{l}) &= G_{1,\text{vc}}(\langle \mathbf{v}', \mathbf{n} \rangle, \langle \mathbf{n}, \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle, \langle \mathbf{v}', \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle) \\ &= G_{1,\text{vc}}(\langle \mathbf{v}, \mathbf{n} \rangle, \langle \mathbf{n}, \mathbf{h}(\mathbf{l}', \mathbf{v}) \rangle, \langle \mathbf{l}', \mathbf{h}(\mathbf{l}', \mathbf{v}) \rangle) \\ &= G_{1,\text{vc}}(\langle \mathbf{v}, \mathbf{n} \rangle, \langle \mathbf{n}, \mathbf{h}(\mathbf{v}, \mathbf{l}') \rangle, \langle \mathbf{l}', \mathbf{h}(\mathbf{v}, \mathbf{l}') \rangle) \\ &= G_1(\mathbf{v}, \mathbf{l}') \end{aligned} \quad (16)$$

and similarly $G_1(\mathbf{l}, \mathbf{v}') = G_1(\mathbf{l}', \mathbf{v})$ for the v-cavity masking function. In summary, we can conclude the symmetry of the BRDF

$$\begin{aligned} f_{\text{retro}}(\mathbf{v}, \mathbf{l}) = f(\mathbf{v}', \mathbf{l}) &= \frac{D(\mathbf{h}(\mathbf{v}', \mathbf{l}))G_2(G_1(\mathbf{v}', \mathbf{l}), G_1(\mathbf{l}, \mathbf{v}'))}{4 \langle \mathbf{v}', \mathbf{n} \rangle \langle \mathbf{l}, \mathbf{n} \rangle} \\ &= \frac{D(\mathbf{h}(\mathbf{l}', \mathbf{v}))G_2(G_1(\mathbf{v}, \mathbf{l}'), G_1(\mathbf{l}', \mathbf{v}))}{4 \langle \mathbf{v}, \mathbf{n} \rangle \langle \mathbf{l}', \mathbf{n} \rangle} = f(\mathbf{l}', \mathbf{v}) = f_{\text{retro}}(\mathbf{l}, \mathbf{v}). \end{aligned} \quad (17)$$

For the albedo we simply have

$$\rho_{\text{retro}}(\mathbf{v}) = \int_{\Omega} f_{\text{retro}}(\mathbf{v}, \mathbf{l}) \langle \mathbf{l}, \mathbf{n} \rangle d\mathbf{l} = \int_{\Omega} f(\mathbf{v}', \mathbf{l}) \langle \mathbf{l}, \mathbf{n} \rangle d\mathbf{l} = \rho(\mathbf{v}') \quad (18)$$

i.e. we get the albedo of the regular microfacet BRDF for the reflected direction. Which, using equation (3) and $\frac{d\mathbf{h}(\mathbf{v}', \mathbf{l})}{d\mathbf{l}} = \frac{1}{4\langle \mathbf{l}, \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle} = \frac{1}{4\langle \mathbf{v}', \mathbf{h}(\mathbf{v}', \mathbf{l}) \rangle}$ [Walter et al. 2007], can be shown to fulfill energy conservation

$$\begin{aligned} \rho(\mathbf{v}') &= \int_{\Omega} \frac{D(\mathbf{h}(\mathbf{v}', \mathbf{l}))G_2(\mathbf{v}', \mathbf{l})}{4 \langle \mathbf{v}', \mathbf{n} \rangle \langle \mathbf{l}, \mathbf{n} \rangle} \langle \mathbf{l}, \mathbf{n} \rangle d\mathbf{l} \\ &\leq \int_{\{\mathbf{h} \in \Omega: \langle \mathbf{v}', \mathbf{h} \rangle \geq 0\}} \frac{D(\mathbf{h})G_1(\mathbf{v}', \text{reflect}(\mathbf{v}', \mathbf{h}))}{\langle \mathbf{v}', \mathbf{n} \rangle} \langle \mathbf{v}', \mathbf{h} \rangle d\mathbf{h} = 1. \end{aligned} \quad (19)$$

5. Implementation Notes

Given an implementation of a regular microfacet BRDF, extending it to retro-reflection is straightforward:

- Evaluation merely needs to replace \mathbf{v} with \mathbf{v}' upfront.
- Similarly, importance sampling of \mathbf{l} given \mathbf{v} can be realized by replacing \mathbf{v} with \mathbf{v}' upfront and then importance sampling the regular microfacet BRDF. This may include low variance sampling using the domain of visible microfacets [Heitz and d'Eon 2014].
- As the albedos of standard BRDF and retro-reflective BRDF are essentially identical, compensating for energy loss in the sense of [Kelemen and Szirmay-Kalos 2001] can be realized using the same data tables.
- Pseudo-code is provided in Listing 1.

```
vec3 brdf_retro(vec3 L, vec3 V, vec3 N, vec3 X, vec3 Y)
{
    vec3 Vp = -reflect(V,N); // jp - is this wrong? Why the minus sign

    // The following could all be replaced with:
    // We could give the simplified form of brdf_ggx, but not essential.
    return brdf_ggx(L, Vp, N, X, Y);

    /*
    float NdotL = dot(N, L);
    float NdotV = dot(N, Vp);
    if (NdotL < 0 || NdotV < 0) return vec3(0);

    vec3 B = normalize(L+Vp);
    float NdotH = dot(N, B);
    vec3 wB = vec3(dot(B,X), dot(B,Y), dot(B,N));
    vec3 wL = vec3(dot(L,X), dot(L,Y), dot(L,N));
    vec3 wV = vec3(dot(Vp,X), dot(Vp,Y), dot(Vp,N));

    float D = D_GGX(wB, ax, ay);
    float G = G2_GGX(wV, wL, ax, ay);

    float c = dot(L, B);
    float F = schlick(f0, c); // I don't think we need to give the form of
    the Fresnel

    float val = Ks * D * G * F / (4 * NdotL * NdotV);
    return vec3(val);
    */
}
```

Listing 1. Pseudo code to implement the retro-reflective microfacet model.

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