ACM Lab - HS 2015

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Weighted Graphs

• If each edge is equipped with a weight, how do we store the graph?

```
Adjacency matrix: store weight in matrix
 for (int i = 0; i < m; ++i) {
        int a,b,c; cin >> a >> b >> c;
        graph[a][b] = c;
      graph[b][a] = c;
Adjacency list: store weight with neighbor
 vector < vector < pair < int , int > > > graph(n);
 for (int i = 0; i < m; ++i) {
        int a,b,c; cin >> a >> b >> c;
```

Weighted Graphs

• If each edge is equipped with a weight, how do we store the graph?

```
Adjacency list: store weight with neighbor
vector<vector<pair<int,int> > graph(n);
for(int i = 0; i < m; ++i){
    int a,b,c; cin >> a >> b >> c;
    graph[a].push_back(make_pair(b,c));
    graph[b].push_back(make_pair(a,c));
}
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Single Source Shortest Paths (SSSP)

- Task: given a weighted graph G and a source s, compute the shortest path from s to t for all $t \in V(G)$.
- If all weights are 1: BFS
- If weights are non-negative: Dijkstra's algorithm
- (Otherwise Bellman-Ford)

Dijkstra's Algorithm

```
Input: (G, w, s)
begin
      d[v] \longleftarrow \infty \qquad \forall v \in V(G)
      d[s] \leftarrow 0
      S \longleftarrow \emptyset
      Q \leftarrow V(G)
      while Q \neq \emptyset do
            u \longleftarrow min(Q)
            S \longleftarrow S \cup \{u\}
            foreach v \in Adi[u] do
                  if d[v] > d[u] + w[(u,v)] then
                       d[v] \longleftarrow d[u] + w[(u,v)]
                   decreaseKey(Q, v)
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How can we sort vectors of our own structs or have priority queues of our own structs?

```
Define struct with "<" operator

1    struct s{
2       int a;
3       int b;

4       friend bool operator < (const s &x, const s &y) {
6         return x.a < y.a || (x.a == y.a && x.b < y.b)
7       }
8    };</pre>
```

- The structs are sorted lexicographically increasing
 vector <s > v; sort (v.begin(), v.end());
- The priority queue returns the lexicographical maximum priority_queue <s>;

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Dijkstra's Algorithm with STL

- Unfortunately, the STL priority queue does not have a decreaseKey operation
- We can implement a "Lazy Deletion" variant of Dijkstra
- In this version, there can be duplicates in the priority queue

- \blacksquare Task: given a weighted graph G, compute a spanning tree such that the sum of edge weights of the spanning tree is minimal
- Prim's algorithm (similar to Dijkstra's algorithm)
- Kruskal's algorithm

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Q \leftarrow E(G)
while Q \neq \emptyset do

\{u, v\} \leftarrow min(Q)
if \{u, v\} does not close a cycle in T then

T \leftarrow E \cup \{\{u, v\}\}
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- Data structure to represent a partition $\{S_1, \ldots, S_i\}$ of $\{1, \ldots, n\}$
- Each subset S_j has some representative $r \in S_j$
- find(x): returns the representative of the set x is contained in
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Kruskal's Algorithm Revisited

- The Union Find Disjoint Set data structure will keep track of the components of *T*
- If u and v are in the same component (i.e., find(u) == find(v)), then adding the edge $\{u, v\}$ would close a cycle