

Applications of DFS

November 12, 2015

Outline

- 1 Topological Sorting
- 2 Bridges/Articulation Points
- 3 Biconnected Components (BCC)
- 4 Strongly Connected Components (SCC)

Applications of DFS

Basic Algorithm

```
1  vector<int> visited(n,0);
2  vector< vector<int> > adj; // adjacency list
3
4  void dfs(int v) {
5      visited[v] = 1;
6      for (int i = 0; i < adj[v].size(); i++) {
7          if (!visited[adj[v][i]]) {
8              dfs(adj[v][i]);
9          }
10     }
11 }
```

I. Topological Sorting

Problem

Given a **directed acyclic graph** (DAG), order the vertices as v_1, \dots, v_n such that for every edge $\overrightarrow{v_i v_j}$, we have $i \leq j$.

I. Topological Sorting

Equivalent formulation:

Problem

Given a **partially ordered set** (V, \preceq) , order the elements as v_1, \dots, v_n such that for every pair $v_i \preceq v_j$, we have $i \leq j$.

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- The resulting order on V is called a **linear extension** of \preceq .

I. Topological Sorting

Equivalent formulation:

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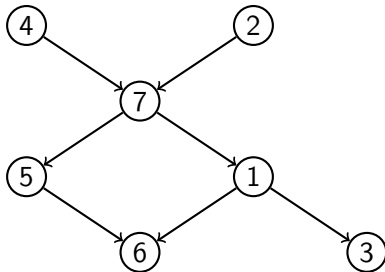
- The resulting order on V is called a **linear extension** of \preceq .
- Application: dependency resolution.

I. Topological Sorting

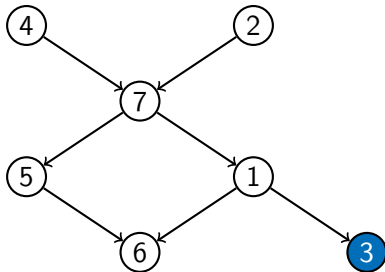
Algorithm (idea):

```
1      vector<int> result;
2
3      while (there is a minimal element v) {
4          result.push_back(v);
5          remove v from the graph;
6      }
```

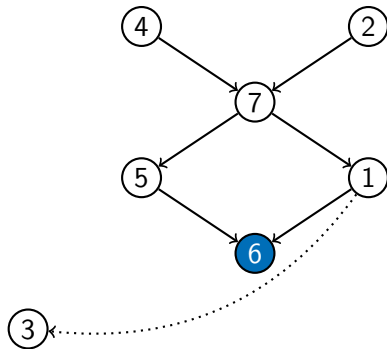
I. Topological Sorting



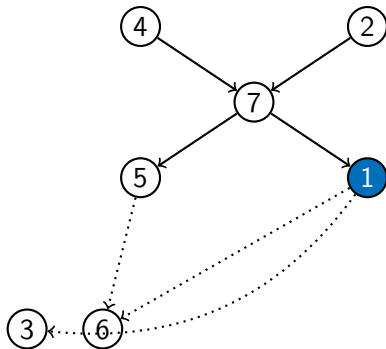
I. Topological Sorting



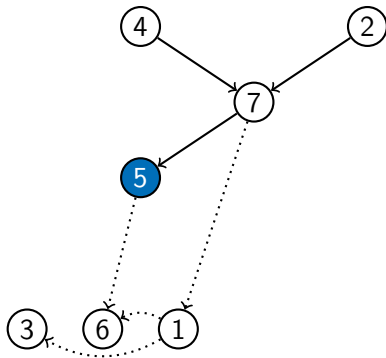
I. Topological Sorting



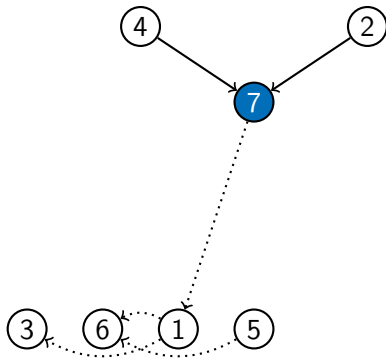
I. Topological Sorting



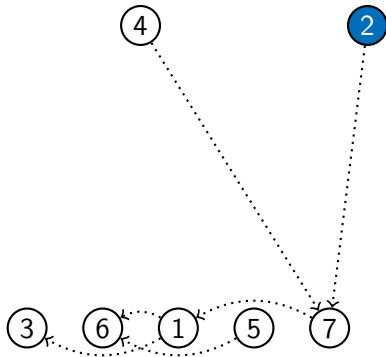
I. Topological Sorting



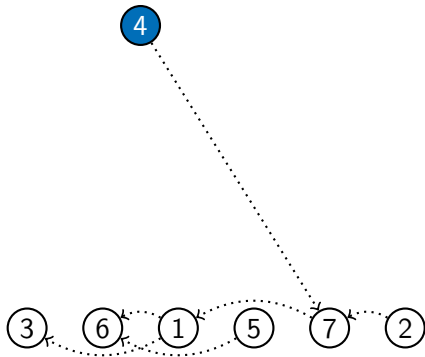
I. Topological Sorting



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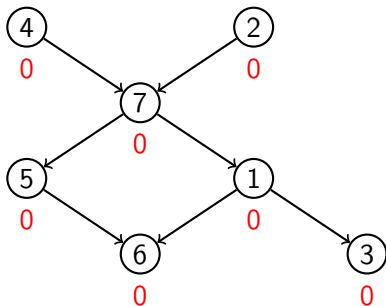


I. Topological Sorting

This idea can be implemented with multiple DFS's:

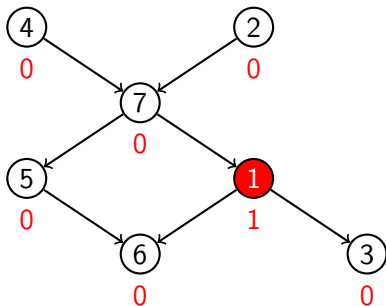
```
1  vector<int> result;
2  vector<int> visited(n,0);
3
4  for (int i = 0; i < n; i++) {
5      if (!visited[i]) dfs(i);
6  }
7
8  void dfs(int v) {
9      if (!visited[v]) {
10         visited[v] = 1;
11         for (int i = 0; i < adj[v].size(); i++) {
12             if (!visited[adj[v][i]]) dfs(m);
13         }
14         result.push_back(v);
15     }
16 }
```

I. Topological Sorting



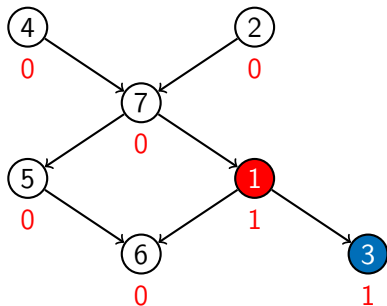
Result:

I. Topological Sorting



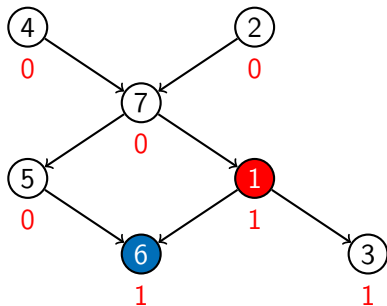
Result:

I. Topological Sorting



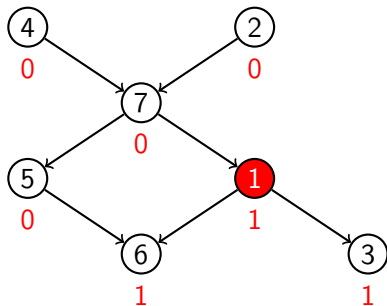
Result:

I. Topological Sorting



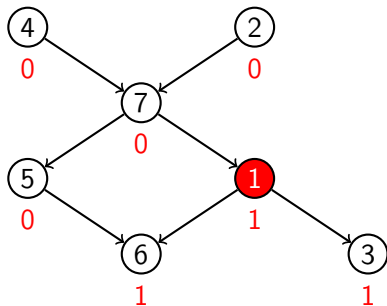
Result: 3

I. Topological Sorting



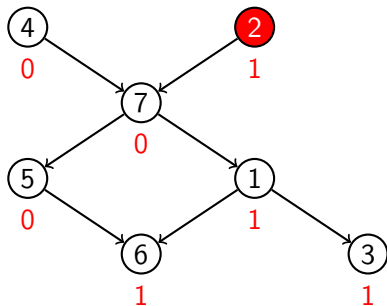
Result: 3 6

I. Topological Sorting



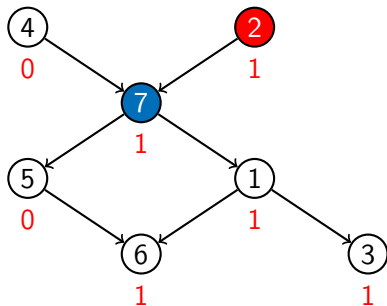
Result: 3 6 1

I. Topological Sorting



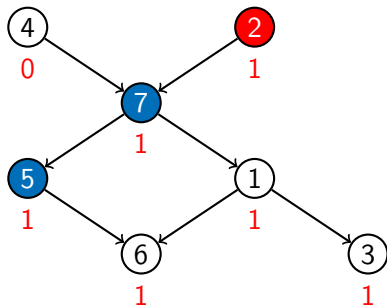
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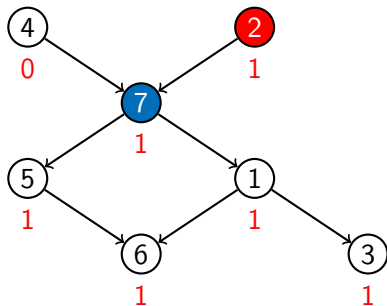
Result: 3 6 1

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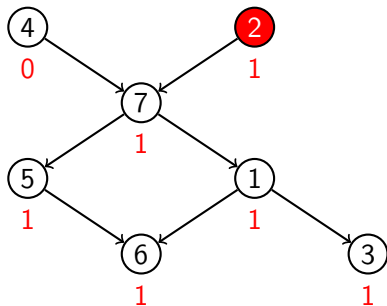
Result: 3 6 1

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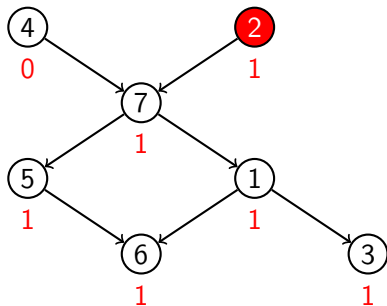
Result: 3 6 1 5

I. Topological Sorting



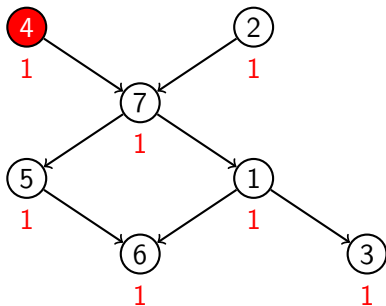
Result: 3 6 1 5 7

I. Topological Sorting



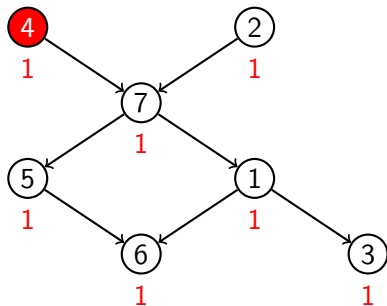
Result: 3 6 1 5 7 2

I. Topological Sorting



Result: 3 6 1 5 7 2

I. Topological Sorting



Result: 3 6 1 5 7 2 4

I. Topological Sorting

- Each vertex and edge is considered only once.
- So the running time of this algorithm is **linear** (more precisely: $O(|V| + |E|)$).

II. BCC/Articulation Points/Bridges

Definition

Let G be a simple graph. An **articulation point** is a vertex of G whose removal separates G into at least two components.

II. BCC/Articulation Points/Bridges

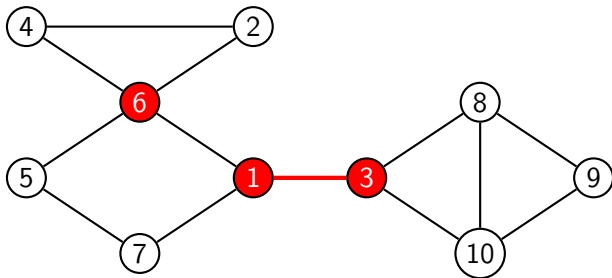
Definition

Let G be a simple graph. An **articulation point** is a vertex of G whose removal separates G into at least two components.

Definition

Let G be a simple graph. A **bridge** is an edge of G whose removal separates G into two components.

II. BCC/Articulation Points/Bridges



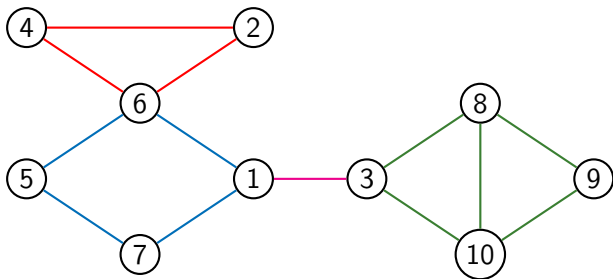
II. BCC/Articulation Points/Bridges

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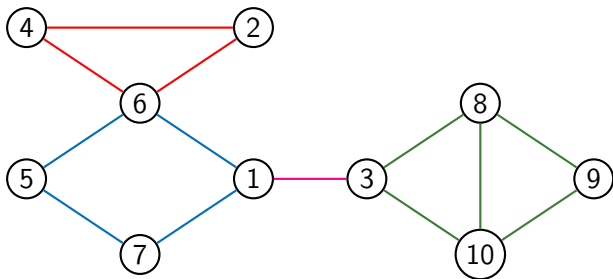
A graph G is **biconnected** if it has no articulation points.

A **biconnected component** of a graph is a maximally biconnected subgraph.

II. BCC/Articulation Points/Bridges

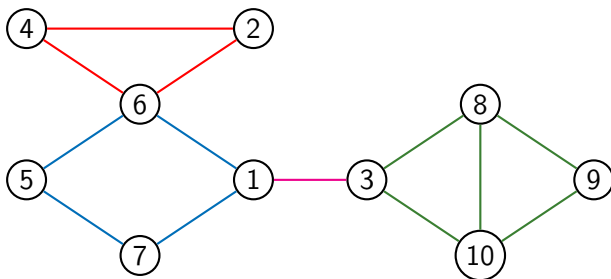


II. BCC/Articulation Points/Bridges



- Biconnected components intersect in articulation points.

II. BCC/Articulation Points/Bridges



- Biconnected components intersect in articulation points.
- Bridges are biconnected components of size two.

II. BCC/Articulation Points/Bridges

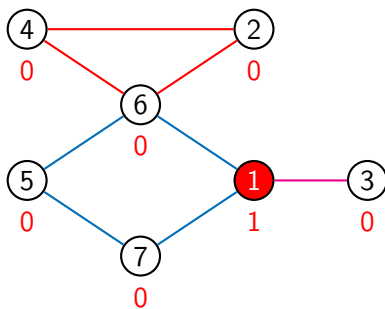
Using DFS, we can find biconnected components, articulation points, and bridges in **linear time**.

II. BCC/Articulation Points/Bridges

First, observe that running a DFS from a node creates a **spanning tree** (the *DFS tree*), as well as some **back-edges**.

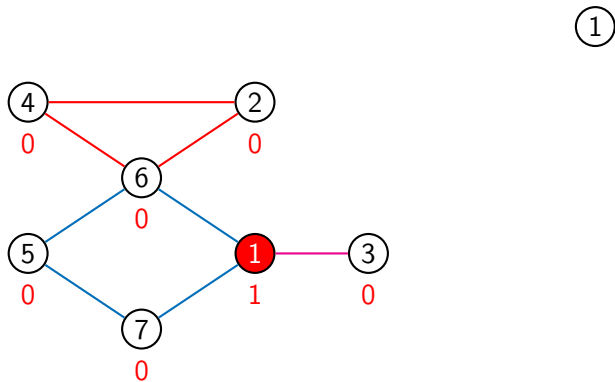
II. BCC/Articulation Points/Bridges

Example:



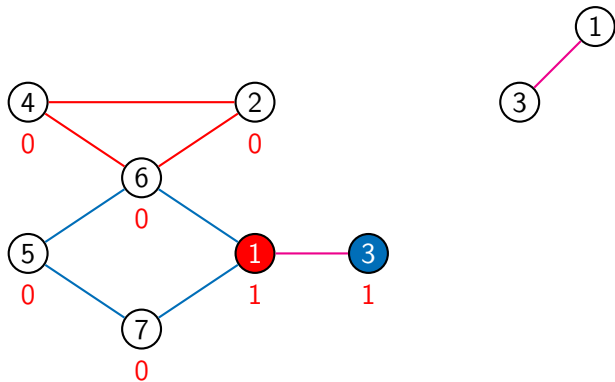
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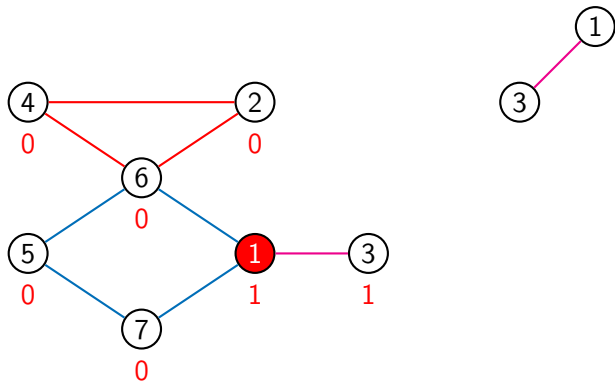
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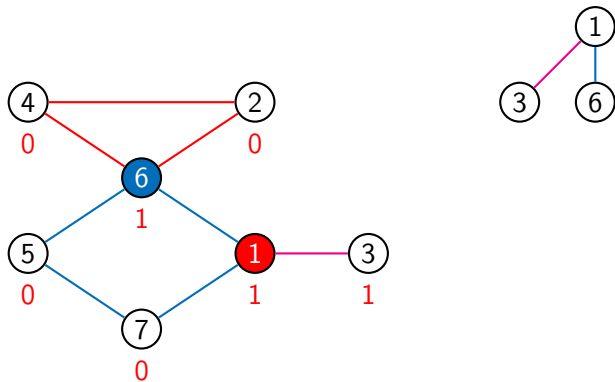
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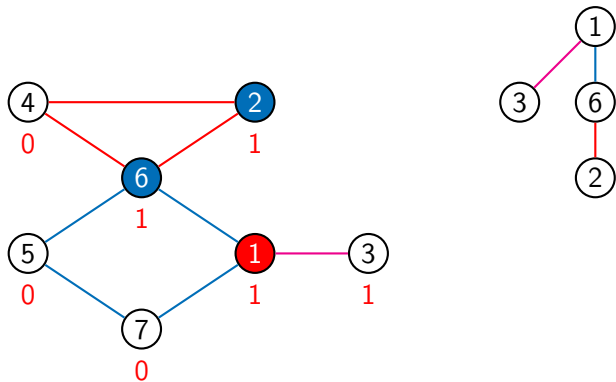
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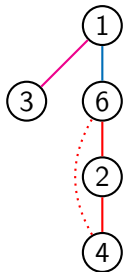
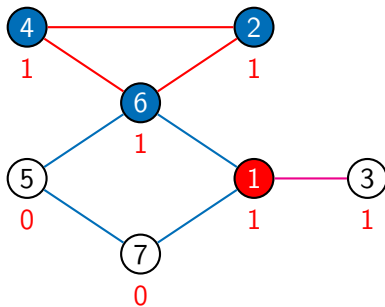
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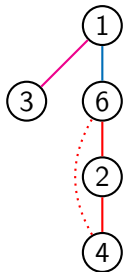
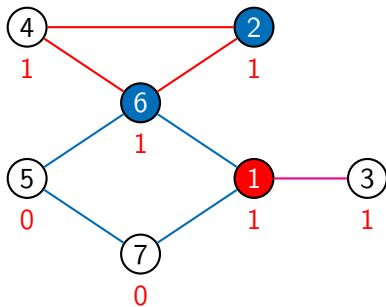
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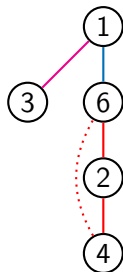
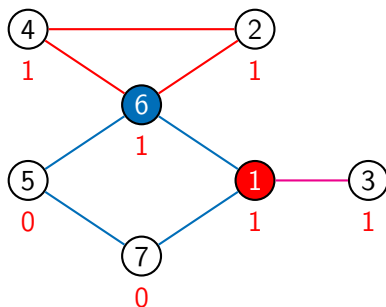
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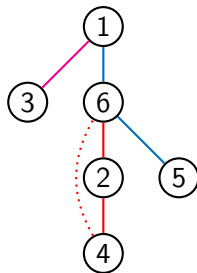
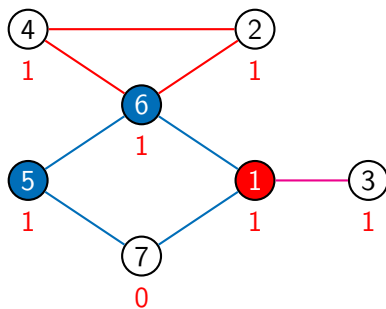
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Example:



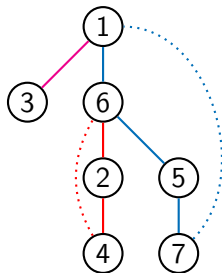
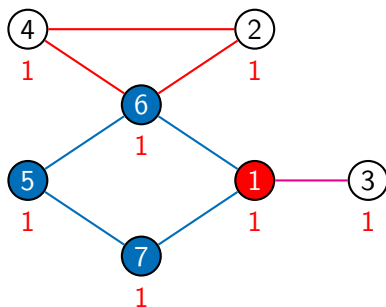
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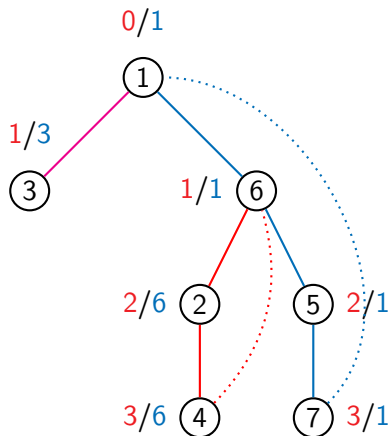
II. BCC/Articulation Points/Bridges

We will compute

- $\text{depth}[v]$: the depth of vertex v in the DFS tree
- $\text{low}[v]$: the lowest-depth neighbor of v or a descendant of v via back-edges in the DFS tree (or v itself if there is no lower-depth neighbor)

II. BCC/Articulation Points/Bridges

In our example, **depth** and **low** are as follows:



II. BCC/Articulation Points/Bridges

We can find articulation points:

- The **root vertex** is an articulation point iff it has more than one child.
- A **non-root vertex** u is an articulation point iff it has a child v with $\text{depth}[\text{low}[v]] \geq \text{depth}[u]$.

II. BCC/Articulation Points/Bridges

We can find bridges:

- All bridges must be edges of the DFS tree.
- A vertex u forms a bridge with a child v iff $\text{depth}[\text{low}[v]] > \text{depth}[u]$.

II. BCC/Articulation Points/Bridges

We can find biconnected components:

- follow the DFS tree from the leaves upwards
- put vertices into the component of the leaf along the way
- stop at articulation points.

II. BCC/Articulation Points/Bridges

It is easy to compute **depth** and **low** during the DFS.

```
1 void dfs(int v, int d) {
2     visited[v] = 1;
3     depth[v] = d; // set depth
4     low[v] = v;
5     for (each child u of v) {
6         if (!visited[u]) {
7             dfs(u, d+1);
8             if (depth[low[u]] <= depth[v]) low[v] = low[u];
9         } else if (depth[u] < depth[v]-1) low[v] = u;
10    }
11 }
12 dfs(0,0); // call like this
```

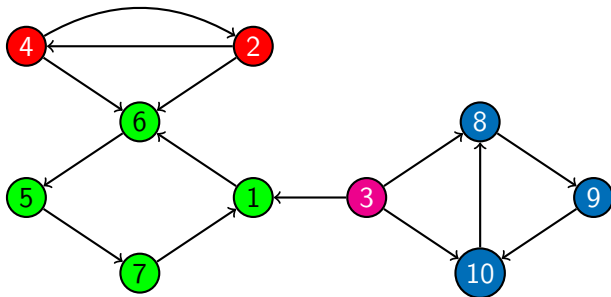
III. Strongly Connected Components

Definition

Let D be a **directed graph**. Write $u \sim v$ if vertex u can be reached from v and vice-versa. Then

- \sim is an **equivalence relation** on $V(D)$, and
- the equivalence classes are called **strongly connected components** of D .

III. Strongly Connected Components (SCC)



- After contracting each SCC, we are left with a DAG!

III. Strongly Connected Components

How to compute strongly connected components?

- Do a DFS and compute finishing times.
- Compute transposed graph, by reverting all edges.
- Do DFS on transposed graph, prioritizing large finishing times.

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To get $\mathcal{O}(|V| + |E|)$ you can use Tarjans algorithm which uses $\text{low}[v]$.

That's all.