#### Jaepil Ban

Intelligent Control and System Laboratory Department of Electrical Engineering POSTECH Cheongam-ro 77 Pohang, Nam-gu 37673 South Korea

Phone: +82-54-279-5018 Email: banjp117@postech.ac.kr URL: http://positiveban.github.io/

#### Education

2012-

Pohang University of Science and Technology, Pohang, South Korea

Candidate for integrated MS and PhD in Electrical Engineering

Advisor: Sangwoo Kim

2004-2012 **Ajou University**, Suwon, South Korea

Bachelor of Electronic and Electrical Engineering, February 2012

#### **Research Interests**

My research interests include: control and stability analysis of linear/nonlinear dynamical systems such as hybrid systems, reset control systems, networked control systems, and industrial systems; robust control; adaptive control; intelligent control; machine learning; optimization. I am currently interested in modern power systems including smart grids and microgrids with distributed energy sources.

#### Publications & talks

JOURNAL ARTICLES

1. Improved co-design of event-triggered dynamic output feedback controllers for linear systems

Jaepil Ban, Minseok Seo, Taedong Goh, Hyeyun Jeong, Sang Woo Kim *Automatica* (Under review)

2. Robust  $H_{\infty}$  finite-time control for discrete-time polytopic uncertain switched linear systems

Jaepil Ban, Wookyong Kwon, Sang Woo Kim Nonlinear Analysis: Hybid Systems 20: 348-367, 2018

# 3. Mold Oscillation Feedforward Control Algorithm for Sinusoidal Oscillation of Various Asymmetries

Seung Hoon Kim, Minseok Seo, Jaepil Ban, Nam Woong Kong, Sang Woo Kim ISIJ International 57.11: 2016-2021, 2017

### 4. Multicriteria adaptive observers for singular systems with unknown time-varying parameters

Wookyong Kwon, Jaepil Ban, Soo Hee Han, Changsoo Lee, Sangchul Won Mathematical Problems in Engineering, 2017

Conferences

 Stability and L<sub>2</sub>-gain analysis of Impulsive Switched Systems with Average Dwell Time: Application to Hybrid Control Jaepil Ban, Wookyong Kwon, Sang Woo Kim American Control Conference, 2017.

#### 2. Localization of slab identification numbers using deep learning

Sang Jun Lee, Jaepil Ban, Hyeyeon Choi, Sang Woo Kim 2016 16th International Conference on Control, Automation and Systems (ICCAS), IEEE, 2016.

3. Decentralized  $H_{\infty}$  control of large-scale descriptor systems using proportional-plus-derivative state feedback

Sungbin Kim, Wookyong Kwon, Jaepil Ban, Sangchul Won 2015 15th International Conference on Control, Automation and Systems (ICCAS), IEEE, 2015.

4. Proportional multiple-integral observer based sliding mode control for linear systems with mismatched disturbance

Hyung Woong Lee, Jaepil Ban, Sangchul Won 2015 15th International Conference on Control, Automation and Systems (ICCAS), IEEE, 2015.

5. Fault estimation and fault-tolerant control of vapor compression cycle systems Jaepil Ban, Wookyong Kwon, Sangchul Won 2015 41st Annual Conference of the Industrial Electronics Society, IECON, IEEE, 2015.

6. Generalized complex projective synchronization of chaotic complex systems with unknown parameters

Jaepil Ban, Jinwoo Lee, Sangchul Won 2014 14th International Conference on Control, Automation and Systems (ICCAS), IEEE, 2014.

7. Synchronization of two different chaotic systems using terminal sliding mode with disturbance observer

Jaepil Ban, Jinwoo Lee, Sangchul Won In *Proceedings of SICE Annual Conference 2013*, pp. 2575-2580.

#### Research Experience

## Design of Alpha Grid platform and research on components technology 2018/03-

Collaborated with Korea Electric Power Cooperation Supervisor: Prof. Sang Woo Kim

Developing a distributed optimal energy scheduling algorithm with distributed faulty energy resources.

## Development of the artificial-intelligence-based control algorithm for automation of POSCO EMLPVD process

2017/08-2018/02

Collaborated with PIBEX (R&D Company of POSCO) Supervisor: Prof. Sang Woo Kim

- Developed a physical vapor decomposition process model by using an artificial neural network.
- · Proposed an online-model-learning algorithm to enhance the accuracy of the neural network model in the lacking-data environment.

## Development of simulator for Senzimir mill and improvement on control algorithm 2017/06-2018/03

Collaborated with POSCO

Supervisor: Prof. Sang Woo Kim

- · Derived a mathematical model of the Sendzimir mill (Z-mill) by using its geometry and force transformation.
- · Identified the unknown parameters in the highly nonlinear model of the Z-mill by analyzing real operation data.
- · Identified the linear mill model from data by using least square method.
- Developed an automatic flatness control that improves quality of the still product by using the derived mathematical model.

# Welding point detection algorithm of lighting for vision system for automatic welding in shipbuilding process

2016/05-2016/08

Collaborated with Samsung Heavy Industries

Supervisor: Prof. Sang Woo Kim

- Developed an end point detection algorithm from the noisy image of lighting vision system.
- Proposed a morphological operation based ellipsoid fitting for detecting the welding point and the proposed algorithm is robust and accurate in detecting the points compared to the points-based least square algorithm.

## Real-time control of finishing mill for lateral movement of a strip by using programmable logic controller

2014/12-2015/09

Collaborated with POSCO

Supervisor: Prof. Sangchul Won

- · Designed a hardware in the loop simulator for 7-stand finishing mill with PLC.
- · Proposed active disturbance rejection control for lateral movement of finishing mill to cope with model uncertainty and disturbances and applied it to the real plant.

- · Designed a graphic user interface for the developed hardware in the loop simulator.
- Proposed a sensor fault detection algorithm by using proportional-integral observer and successfully detected the sensor fault of the finishing mill simultaneously.

## Design of an embedded controller and control algorithm for heat pump systems 2013/10-2014/10

Collaborated with BnF Solution

Supervisor: Prof. Sangchul Won

- · Designed an embedded control system with microcontroller unit (MCU) for a two stage heat pump to control superheat temperature of refrigerant and water temperature.
- · Designed a windows API-based monitoring program of a heat pump by using RS232 modbus protocol between PC and MCU.
- · Proposed an optimal energy consumption algorithm for on/off controlled heat pump and reduced electric power consumption achieving satisfied level of water temperature.

## Estimation of 3-dimensional temperature distribution for indoor air-flow control 2013/01-2013/12

Collaborated with LG Electronics

Supervisor: Prof. Sangchul Won

- · Designed a temperature measurement and monitoring system with a thermopile array sensor by using LabVIEW.
- · Proposed an estimation algorithm of temperature distribution in a room by using adaptivenetwork-based fuzzy inference system (ANFIS).
- · Proposed an online human detection algorithm by using temperatures obtained from the thermopile array sensor.

#### Active torque control for 1-Piston rotary compressor

2012/02-2013/07

Collaborated with LG Electronics

Supervisor: Prof. Sangchul Won

- · Designed a disturbance observer-based algorithm for reducing the vibration of 1-piston rotary compressor of air-conditioners.
- · Proposed an adaptive disturbance compensation method to compensate unknown timedelay on phase measurement induced by the sensorless algorithm of the motor.

#### Development of sensing and control algorithm of a quadrotor UAV

2011/03-2011/12

Undergraduate Design Project

Supervisor: Prof. Suk-Kyo Hong

- Designed low cost IMU sensor system by using a 3-axis gyro in Wii MotionPlus and 3-axis accelerometer.
- · Proposed parallel core processors to perform controlling rotors and processing sensor signal simultaneously.

#### Grants, honors & awards

Self-development Scholarship, Ajou University
Honor Scholarships for four semesters, Ajou University

### Computer languages

MATLAB, Simulink, Appdesigner, Python, Tensorflow, OpenAI Gym, C, Windows API, PLC programming, LabView, OrCAD, PSpice,  $\LaTeX$