IRPOS

WatchingIRPOS

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+ start_scene_observation()
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- + stop scene observation()
- + get scene objects()
- + get scene object info()
- + tfg_to_joint_position_with_contact()
- + move_to_synchro_position()
- + move_to_motor_position()
- + move_rel_to_motor_position()
- + move_along_motor_trajectory()
- + move_to_joint_position()
- + move rel to joint position()
- + move_along_joint_trajectory()
- + move to cartesian pose()
- + move_rel_to_cartesian_pose()
- + move_rel_to_cartesian_pose_with_contact()
- + move_along_cartesian_trajectory()
- + move_along_cartesian_circle()