



# Ultra-fast reconstruction using Fourier domain filters

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Mitigate the influence of less accurate but fast backprojection operators

# Introduction

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- + Robust w.r.t. noise and limited angular range
- Computationally expensive

# Iterative reconstruction

$$\begin{aligned} \mathbf{x}^{(k+1)} &= \underbrace{(\mathbf{1} - \mathbf{C}\mathbf{W}^T \mathbf{R}\mathbf{W})}_{A} \mathbf{x}^{(k)} + \underbrace{\mathbf{C}\mathbf{W}^T \mathbf{R}\mathbf{p}}_{B} \\ &= (\mathbf{1} \quad \mathbf{0}) \begin{pmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{0} & 1 \end{pmatrix}^k \begin{pmatrix} \mathbf{0} \\ \mathbf{p} \end{pmatrix} \end{aligned}$$

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Can we approximate iterative reconstruction results with *faster* analytical methods?

## Algebraic filters

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## Filter optimisation

An analytical method  $\mathcal{A}$  such as filtered backprojection (FBP) can be written as

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$\mathbf{h}^*$  is the **minimum-residual** filter

# Advantages

Typical size of projection data is  $N_\theta N_d \sim 10^6$

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## Advantages

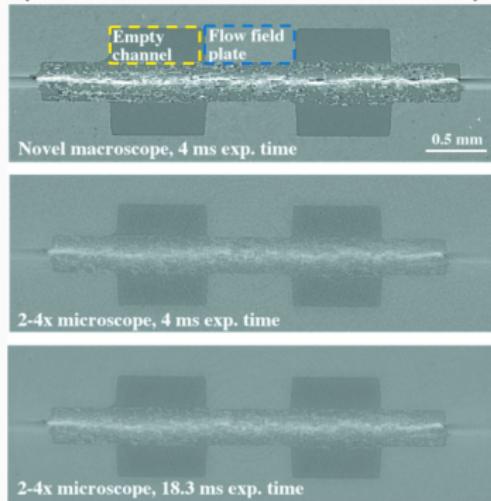
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- Filter dimension can be further reduced to  $\mathcal{O}(\log N_d)$
- Filter can be reused for similar noise experimental geometries and noise statistics

# High-throughput applications

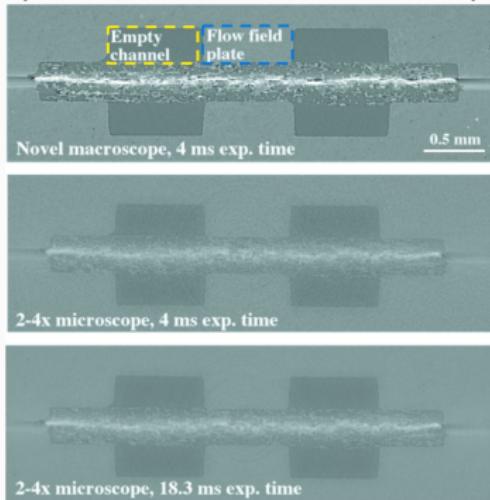
Time-resolved experiments  
(tomography at synchrotrons)



Reconstructions of a fuel cell  
(Bührer et al., 2019)

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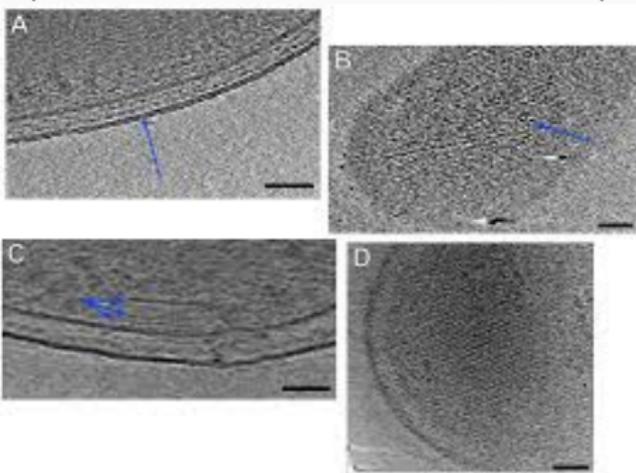
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Data rates  $\sim 10\text{GB s}^{-1}$  →

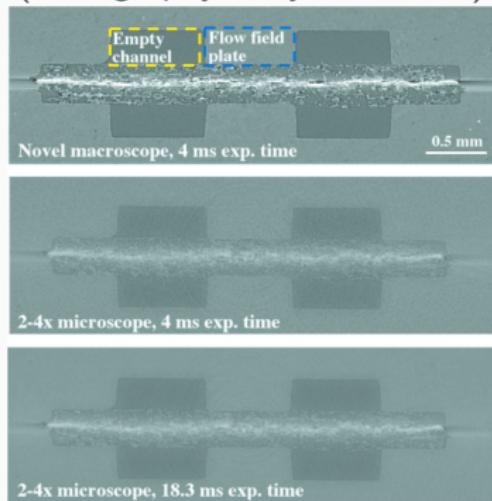
Continuous acquisition  
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Tomograms of *Bdellovibrio bacteriovorus*  
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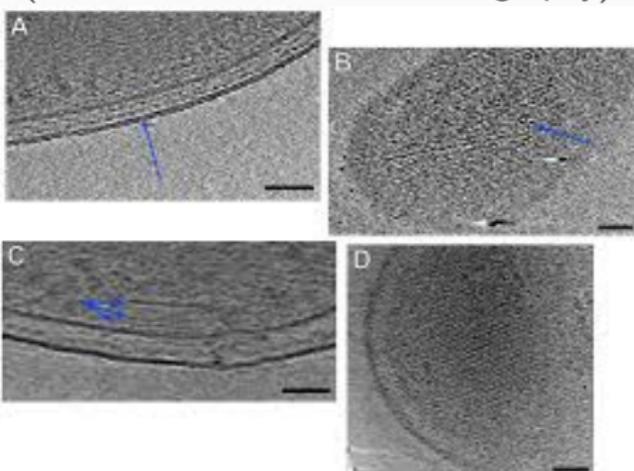
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Data rates  $\sim 10\text{GB s}^{-1}$  → Can we make reconstructions even faster?

Continuous acquisition  
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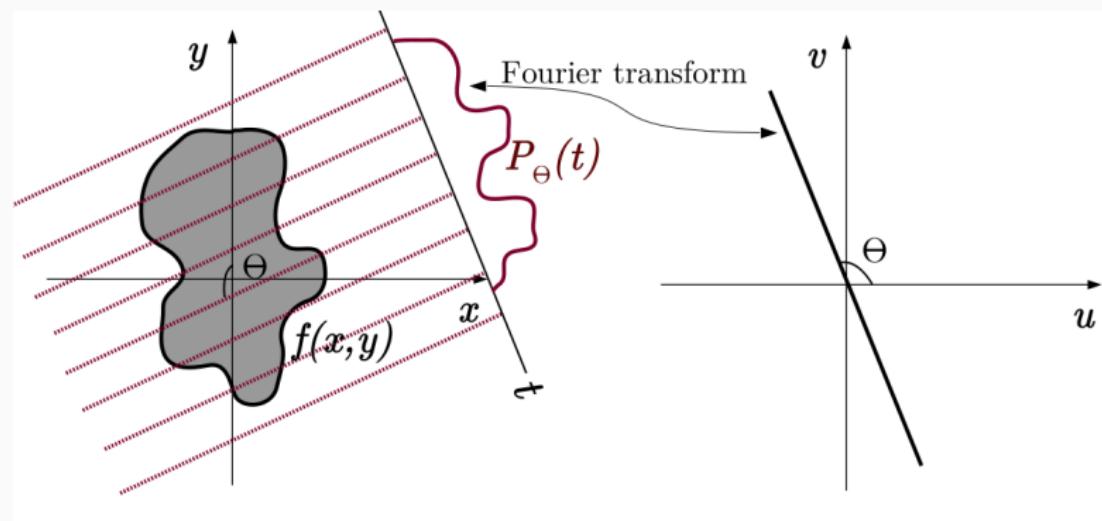


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## **Fourier-domain filters**

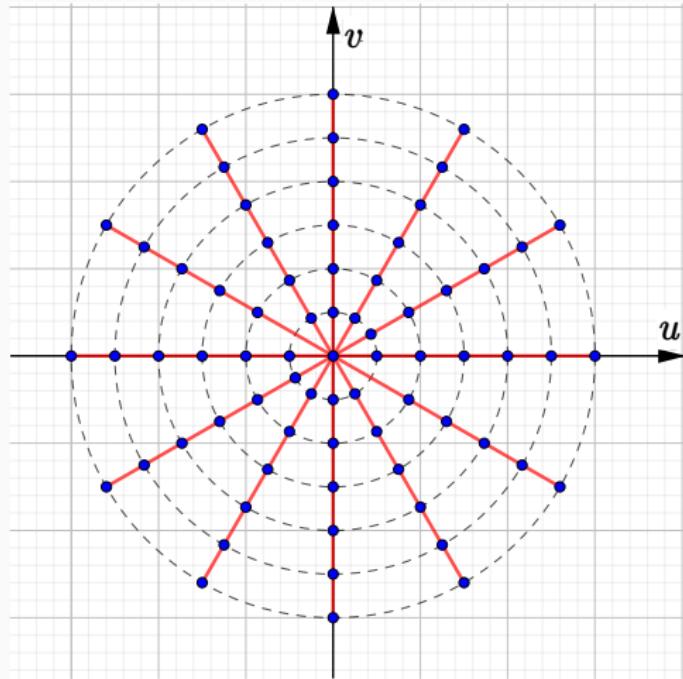
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# Fourier slice theorem



$$\tilde{P}_\theta(\omega) = \tilde{F}(\omega \cos \theta, \omega \sin \theta)$$

# Fourier slice theorem



## Fourier domain algorithms

Marone, F., and M. Stampanoni. "Regridding reconstruction algorithm for real-time tomographic imaging." (2012)

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Steps in Gridrec

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FBP backprojection:  $\mathcal{O}(N^2 N_\theta)$

Gridrec 2D FFT:  $\mathcal{O}(N^2 \log N)$

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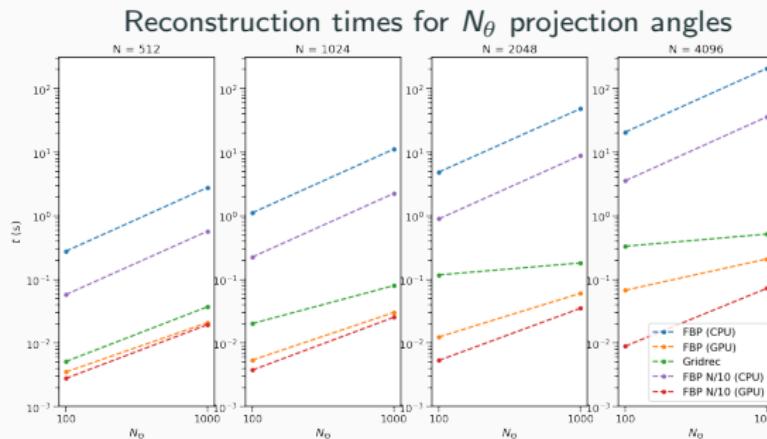
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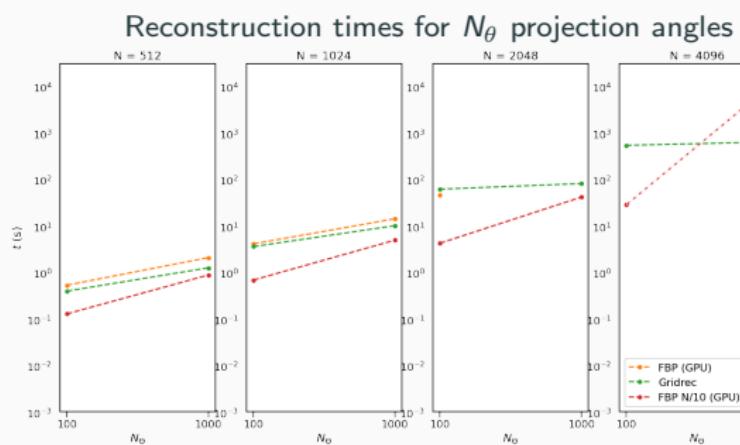


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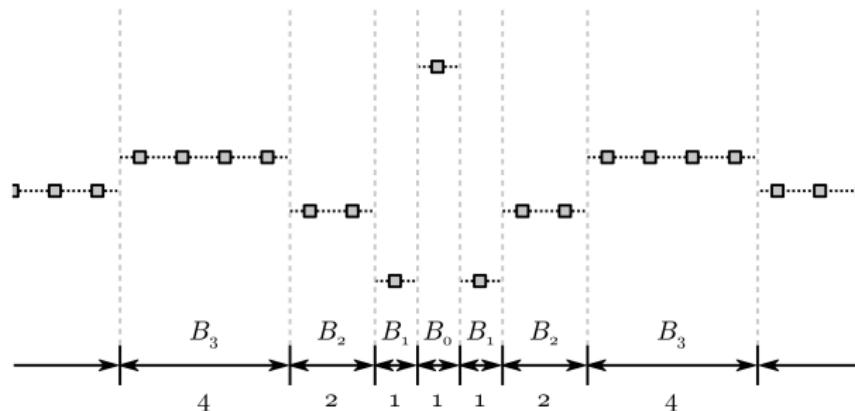
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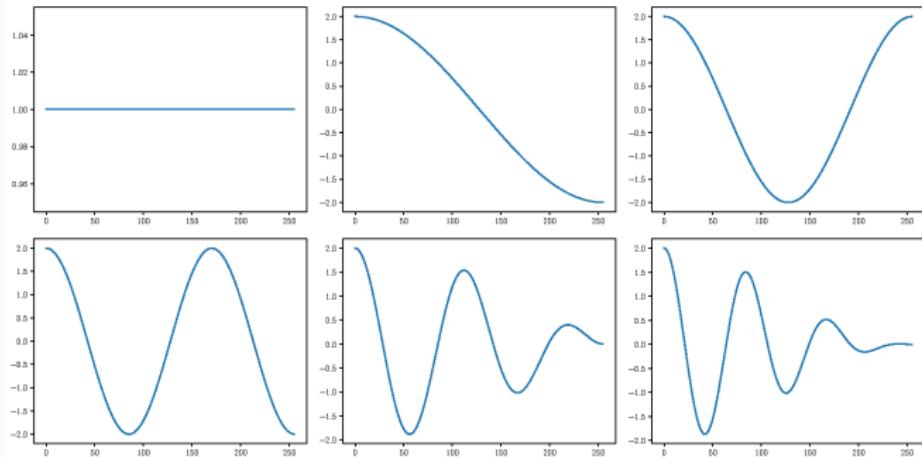
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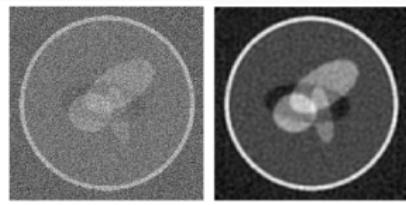
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## Results — 1: phantom

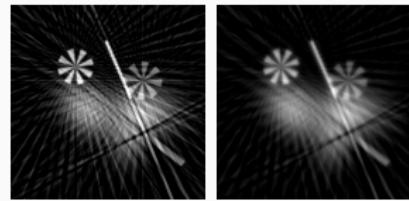
Noisy sinogram



ramp filter

our filter

Sinogram with few angles

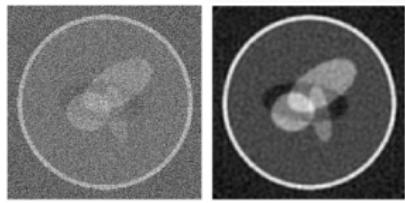


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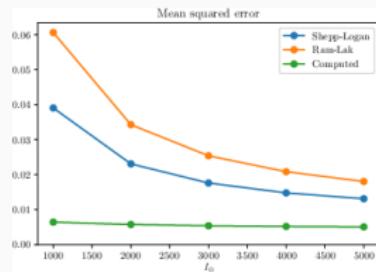
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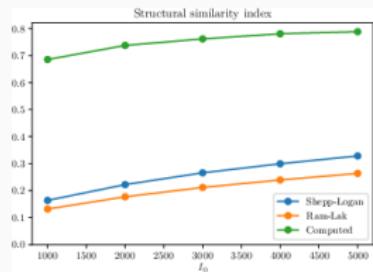
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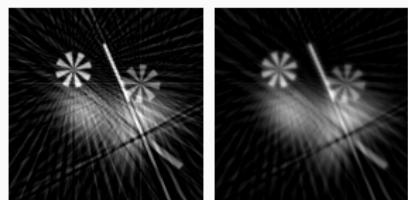
Mean squared error



Structural similarity

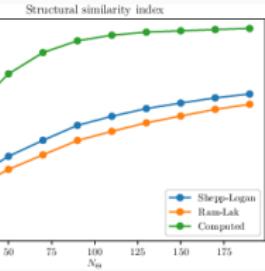
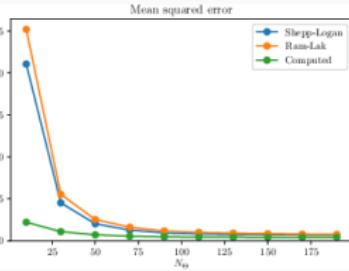


Sinogram with few angles

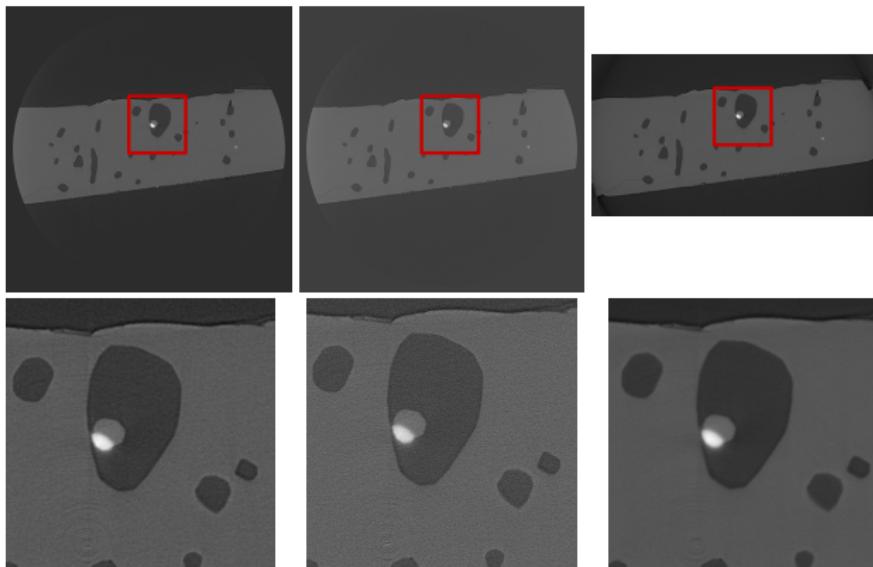


ramp filter

our filter



## Results — 2: synchrotron data



(left to right) Gridrec reconstructions using a minimum-residual filter, the Parzen filter, and additional phase retrieval

## High performance implementations

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→ Compute minimum-residual filters for standard implementations  
! Does not require knowledge of the implementation

## **Implementation-specific filters**

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# Results

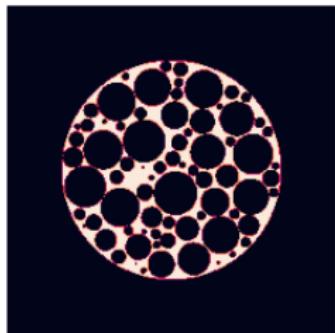
Minimum-residual filters *reduce* the mismatch between operators

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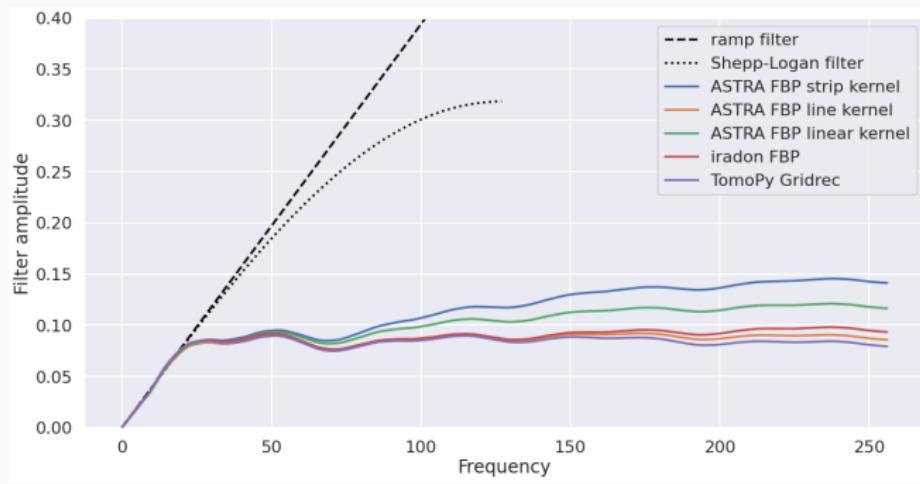
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Foam phantom



Minimum-residual filter shapes

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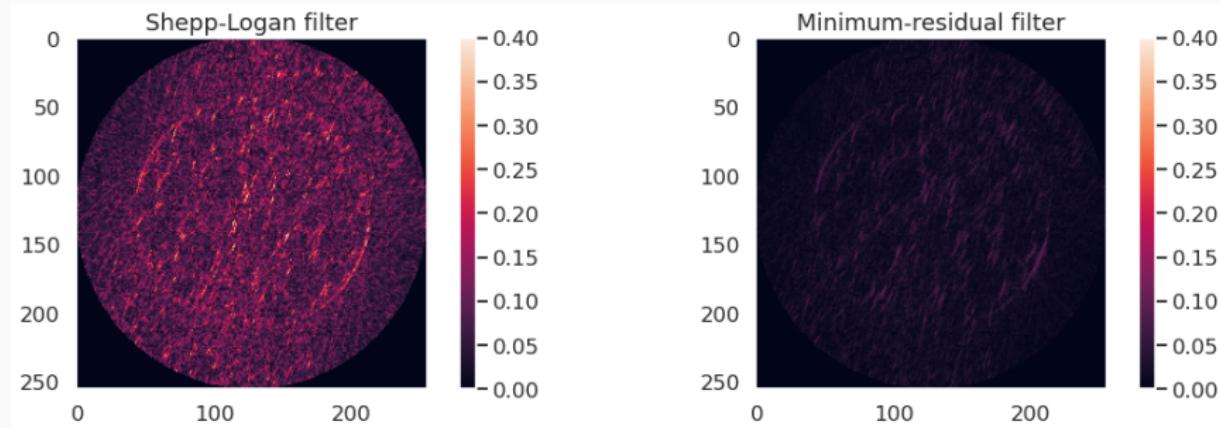
Pixelwise standard deviation in reconstructions

$$\text{std}\{\mathbf{x}_r^{\text{strip}}, \mathbf{x}_r^{\text{line}}, \mathbf{x}_r^{\text{linear}}, \mathbf{x}_r^{\text{iradon}}, \mathbf{x}_r^{\text{gridrec}}\}$$

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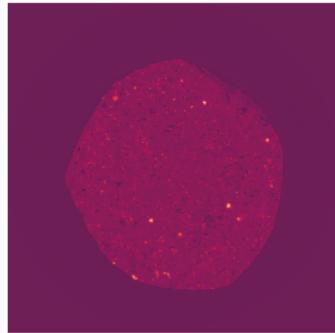
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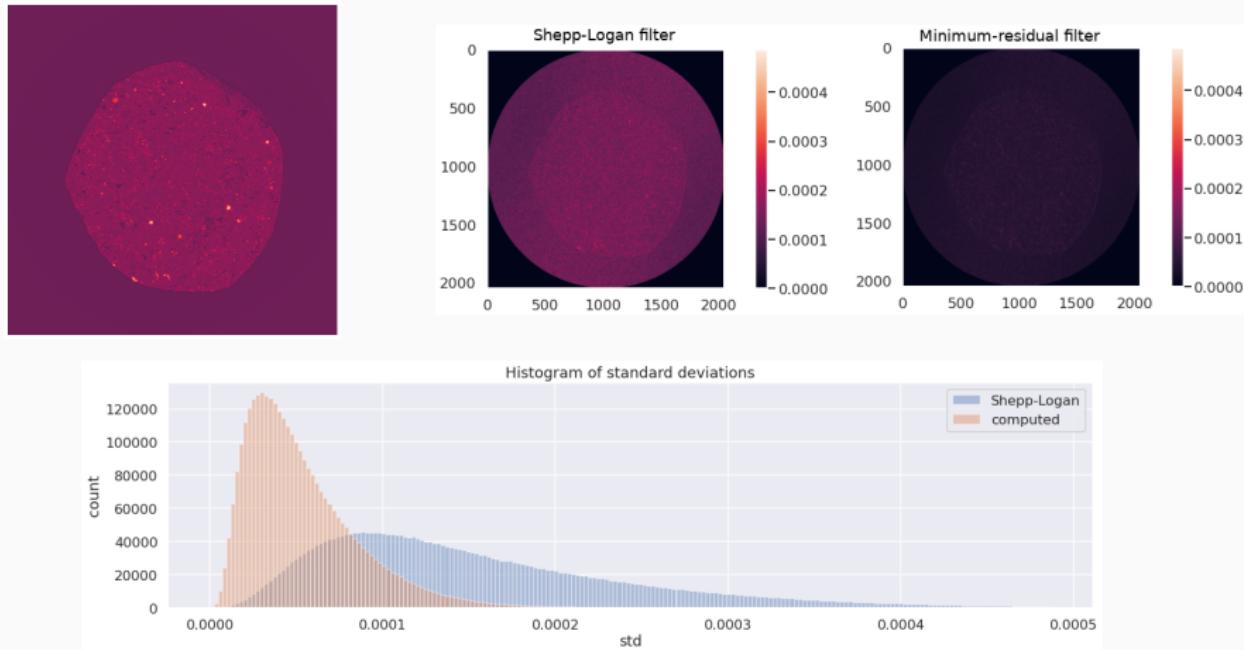
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Round-robin dataset from Tomobank



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## Conclusions

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## Summary and outlook

- Analytical algorithms despite their inability to handle imperfect data are **widely used** in practice because they are **fast**
- One way to **improve reconstruction quality** of these algorithms is by computing a **minimum-residual filter** for the available data
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- Learn filter by optimising to more than one dataset
- More general approach for learning corrections to the backprojection operator from data

**Thank you for your attention!**