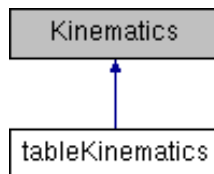


# tableKinematics Class Reference

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Inheritance diagram for tableKinematics:



## Public Member Functions

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public void **forwardKinematic** ()

---

## Public Attributes

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double **A1**

double **A2**

---

## Detailed Description

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Author: Poulastya Mukherjee Description: Class Implementation for Forward Kinematics Calculation of Table  
Inputs: Joint Angle Values of Table Output: New Position of Table

## Member Function Documentation

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### ◆ forwardKinematic()

public void tableKinematics::forwardKinematic ( )

inline

Author: Poulastya Mukherjee Description: Function for Forward Kinematics Calculation of Table Inputs:  
Current value of the Workpiece position and Selected Edge coordinates Output: Transformed Position of  
Selected Edge

The documentation for this class was generated from the following file:

- ClassTable.cpp