

→ what is Dirichlet dist.?

→ start with Beta dist:

flip a coin w. prob.  $q$  turning up head  
prob. of  $x$  heads in  $n$  flips → Binomial dist.

$$P(x|q, n) = \binom{n}{x} q^x (1-q)^{n-x}$$

what if you don't know  $q$ ?

→ Bayesians represent uncertainty about  $q$   
with a prior dist. (i.e. Beta dist.)

$$P(q|\alpha_1, \alpha_2) = \frac{\Gamma(\alpha_1 + \alpha_2)}{\Gamma(\alpha_1)\Gamma(\alpha_2)} q^{\alpha_1-1} (1-q)^{\alpha_2-1}$$

hyperparameters  $\alpha_1, \alpha_2 > 0$  are pseudocounts

Why Beta?

- it is defined over interval  $[0, 1]$

- Beta and Binomial are conjugate  
(a Beta prior and Binomial likelihood result in a posterior Beta)

posterior  $\propto$  likelihood  $\times$  prior

$$P(q|x, \alpha_1, \alpha_2) \propto P(x|q, n) P(q|\alpha_1, \alpha_2)$$

$$\propto q^x (1-q)^{n-x} q^{\alpha_1-1} (1-q)^{\alpha_2-1}$$

$$= q^{\alpha_1+x-1} (1-q)^{\alpha_2+n-x-1}$$

$$= \text{Beta}(\alpha_1+x, \alpha_2+n-x)$$



DP-03

# Dirichlet (Multinomial conjugacy)

- Multinomial extends binomial to more than 2 classes

(instead of flipping a coin, roll a die)

Let  $Z$  be the multinomial random var. with  $p(Z_k=1) = q_k$

- Dirichlet dist. is conjugate prior to multinomial

- It is defined as an exponential family dist. on the simplex (generalizes the Beta)

$$p(q|\alpha) = \frac{\prod_{i=1}^m \Gamma(\alpha_i)}{\Gamma(\sum_{i=1}^m \alpha_i)} q_1^{\alpha_1-1} \dots q_m^{\alpha_m-1}$$

where  $q = (q_1, q_2, \dots, q_m)$  is a point on  $(m-1)$ -simplex

(i.e.  $0 < q_i < 1$  and  $\sum_{i=1}^m q_i = 1$ )

and  $\alpha = (\alpha_1, \dots, \alpha_m)$  is a set of parameters ( $\alpha_i > 0$ )

posterior  $\propto$  likelihood  $\times$  prior

$$p(q|Z, \alpha) \propto p(Z|q) p(q|\alpha)$$

$$\propto (q_1^{z_1} \dots q_m^{z_m}) (q_1^{\alpha_1-1} \dots q_m^{\alpha_m-1})$$

$$\propto q_1^{\alpha_1+z_1-1} \dots q_m^{\alpha_m+z_m-1}$$

$$= \text{Dir}(\alpha_1+z_1, \dots, \alpha_m+z_m)$$

Simplex:

generalization of a triangle to arbitrary dimension

K-simplex is a K-dim. polytope

which is convex hull of its

K+1 vertices.



## Properties of Dirichlet:

①  $\rightarrow$  Any Dir. dist. can be represented as a normalized set of indep. Gamma Random Var.

$$\text{Dir}(\alpha_1, \dots, \alpha_m) \equiv \left( \frac{\text{Gam}(\alpha_1)}{\text{Gam}(\alpha_1) + \dots + \text{Gam}(\alpha_m)}, \dots, \frac{\text{Gam}(\alpha_m)}{\text{Gam}(\alpha_1) + \dots + \text{Gam}(\alpha_m)} \right)$$

②  $\rightarrow$  Sum of Gamma RVs (with common Scale Parameters) is also a Gamma R.V.

$$\text{Gam}(\alpha_1 + \alpha_2) = \text{Gam}(\alpha_1) + \text{Gam}(\alpha_2)$$

~~$$\text{Gam}(\alpha_1 + \alpha_2 + \dots + \alpha_m)$$~~

$\Rightarrow$  The aggregation of any subset of Dir. variables yield a Dir, with corresponding agg. of parameters.

$$q = (\underbrace{q_1, \dots, q_i}_{\text{subset}}, \underbrace{q_{i+1}, \dots, q_m}_{\text{rest}}) \sim \text{Dir}(\underbrace{\alpha_1, \dots, \alpha_i}_{\text{subset}}, \underbrace{\alpha_{i+1}, \dots, \alpha_m}_{\text{rest}})$$

$$q = (q_1 + q_2 + \dots + q_i, q_{i+1} + \dots + q_m) \sim \text{Dir}(\alpha_1 + \dots + \alpha_i, \alpha_{i+1} + \dots + \alpha_m)$$

---



## NB Methods

Dirichlet process/  
Chinese Restaurant process

Latent class models

(Often used in clustering)

Beta  
process/  
Indian buffet  
process

(Latent feature)  
models

Gaussian  
process  
(Regression)

### \* Gaussian process:

Defines a distribution  $p(f)$  over functions  $f$   
where  $f$  is a function mapping some  
input space  $X$  to  $\mathbb{R}$   $f: X \rightarrow \mathbb{R}$

( $X$  could be infinite dimensional quantity.  
(e.g.  $X = \mathbb{R}$ )

Let  $\mathbf{f} = (f(x_1), f(x_2), \dots, f(x_n))$   $n$ -dim. vector of  
function values  
evaluated at  $n$  points  $x_i \in X \Rightarrow \mathbf{f}$  is a R.V.

then:  $p(f)$  is a Gaussian process if for  
any finite subset  $\{x_1, \dots, x_n\} \subset X$   
the marginal dist. over that  
finite subset  $p(f)$  has a  
multivariate Gaussian dist.



GPs are parametrized by a mean function  $\mu(x)$  and Cov. function  $C(x, x')$

$$p(f(x), f(x')) = N(\mu, \Sigma)$$

$$\mu = \begin{bmatrix} \mu(x) \\ \mu(x') \end{bmatrix}, \Sigma = \begin{bmatrix} C(x, x) & C(x, x') \\ C(x', x) & C(x', x') \end{bmatrix}$$

$$C(x_i, x_j) = \nu_0 \exp \left\{ - \left( \frac{\|x_i - x_j\|^\alpha}{\lambda} \right)^2 \right\} + \nu_1 + \nu_2 \delta_{ij}$$

with parameters  $(\nu_0, \nu_1, \nu_2, \lambda, \alpha)$

Dirichlet dist.

is a distribution over  $K$ -dimensional prob. simplex.

Let  $p$  be a  $K$ -dim vector s.t.  $\forall j$

$$p_j \geq 0 \text{ \& } \sum_{j=1}^K p_j = 1$$

$$p(p|\alpha) = \text{Dir}(\alpha_1, \alpha_2, \dots, \alpha_K) \triangleq \frac{\Gamma(\sum_j \alpha_j)}{\prod_j \Gamma(\alpha_j)} \prod_{j=1}^K p_j^{\alpha_j - 1}$$

normalization const.

$$E(p_j) = \frac{\alpha_j}{\sum_k \alpha_k}$$

Dir is conjugate to multinomial dist.

Let  $C|P \sim \text{multinomial}(\cdot|P)$

$p(C=j|P) = p_j$  Then posterior is Dirichlet

$$p(P|C=j, \alpha) = \frac{p(C=j|P) p(P|\alpha)}{p(C=j|\alpha)} = \text{Dir}(\alpha')$$

$n$  integer  
 $\Gamma(n) = (n-1)!$

$$\alpha'_i = \alpha_i + 1 \quad \forall i \neq j$$

$$\alpha'_j = \alpha_j$$



$p(f) \sim \text{Gauss. process (GP)}$

parametrized by a mean function  $\mu(x)$   
and cov. function  $C(x, x')$

$$p(f(x), f(x')) = N(\mu, \Sigma)$$

where

$$\mu = \begin{bmatrix} \mu(x) \\ \mu(x') \end{bmatrix}; \Sigma = \begin{bmatrix} C(x, x) & C(x, x') \\ C(x', x) & C(x', x') \end{bmatrix}$$

for  $p(f(x_1), \dots, f(x_n)) \Rightarrow \mu$  is  $n \times 1$  vector &  $\Sigma$   $n \times n$  matrix.

$$C(x_i, x_j) = V_0 \exp\left\{-\left(\frac{\|x_i - x_j\|}{\lambda}\right)^\alpha\right\} + V_1 + V_2 \delta_{ij}'$$

with parameters  $(V_0, V_1, V_2, \lambda, \alpha)$

Once the mean & cov. functions are defined then  
everything can be derived easily from mv Gaussian.

How to use GP for nonlinear regression:

observing Data set  $D = \{(x_i, y_i)\}_{i=1}^n = (X, Y)$

Model

$$y_i = f(x_i) + \epsilon_i$$

$$f \sim \text{GP}(\cdot | \mu, C)$$

$$\epsilon_i \sim N(0, \sigma^2)$$

prior on  $f$  is a GP  
likelihood is Gaussian  $\Rightarrow$  posterior on  $f$   
is also GP

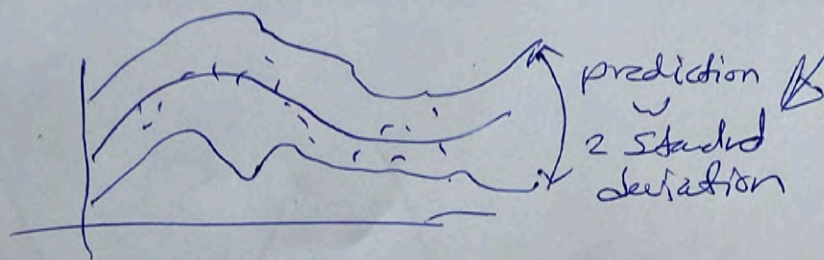


$$\rightarrow p(y' | x', D) = \int p(y' | x', f, D) p(f | D) df$$

prediction

compute  
marginal  
likelihood  
to tune  
Cov. function

$$\Rightarrow p(y | x) = \int p(y | f, x) p(f) df$$



Consider Linear regression with input  $x_i$  and output  $y_i$  :  $y_i = \beta_0 + \beta_1 x_i + \epsilon_i$

Linear regression with  $K$  basis functions

$$y_i = \sum_{k=1}^K \beta_k \phi_k(x_i) + \epsilon_i$$

Bayesian linear regression with basis function

$$\beta_k \sim N(0, \lambda_k) \text{ (indep. of } \beta_0; \forall k \neq 0); \epsilon_i \sim N(0, \sigma^2)$$

Integrating Coef.  $\beta_j$  we find:

$$E[y_i] = 0 \quad \text{Cov.}(y_i, y_j) = C_{ij} \triangleq \sum_k \lambda_k \phi_k(x_i) \phi_k(x_j) + \delta_{ij} \sigma^2$$

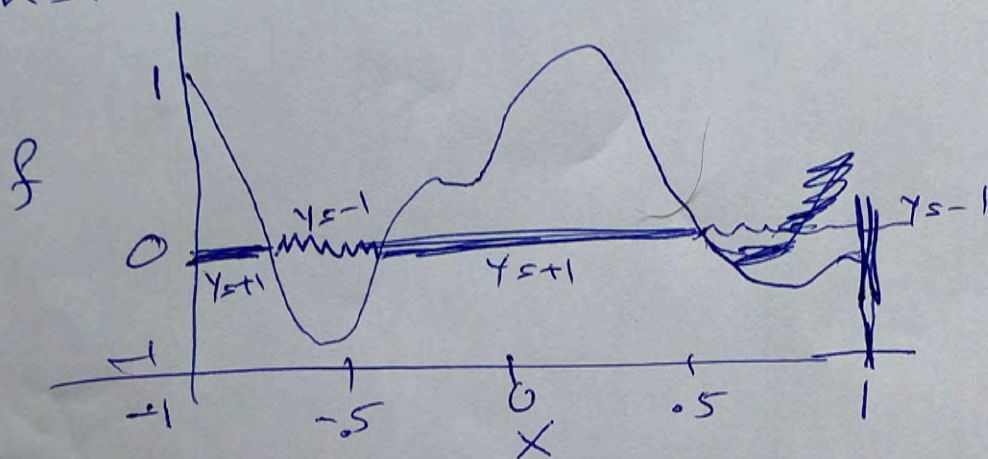
$\{y_i\}$  This is a Gaussian process with cov. function  $C(x_i, x_j) = C_{ij}$

~~This is a Gaussian process with cov. function~~  
this GP has finite # of basis functions ( $K$ )



# Using GP for Classification (2-class problem) - Binary

Given a data set  $D = \{(x_i, y_i)\}_{i=1}^n$   
with binary class labels  $y_i \in \{-1, +1\}$   
infer class label probabilities at new  
points.



Relate  $f(x_i)$  to class probabilities

$$p(y|f) = \begin{cases} \frac{1}{1 + \exp(-yf)} & \rightarrow \text{Sigmoid (logistic)} \\ \Phi(yf) & \rightarrow \text{Cumulative normal (probit)} \\ H(yf) & \rightarrow \text{threshold} \\ \epsilon + (1 - 2\epsilon)H(yf) & \rightarrow \text{robust threshold} \end{cases}$$