

First order methods in optimization (homework exercises)

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1 Part 1

For each of the following functions, find an expression for $\text{prox}_{\lambda f}(\mathbf{x})$ for any $\lambda > 0$ and \mathbf{x} .

1. $f(x) = 2x_{[1]} + x_{[2]}$. $\text{prox}_f((2, 1, 4, 1, 2, 1)) = ?$

Solution:

- $f(x) = \sigma_C$ where $C := \{w \in \mathbb{R}^n \mid \sum w_i = 3, 0 \leq w_i \leq 2, \forall i \in [n]\}$
- $\text{prox}_{\lambda f}(x) = x - \lambda P_C(\frac{x}{\lambda})$
- $P_C(x) = H_{a,b} \cap \text{Box}[\ell, u]$ where $\mathbf{a} = \mathbf{e}, b = 3, \ell = \mathbf{0}, \mathbf{u} = \mathbf{2}$
- the code is *ex1-1.py*

2. $f(x) = \begin{cases} \frac{1}{t}, & t > 0 \\ \infty, & \text{else} \end{cases}$

Solution:

- $\text{prox}_{\lambda f}(x) = \text{argmin}_{t>0} \{\frac{\lambda}{t} + \frac{1}{2}\|t - x\|^2\}$
- then: $\text{prox}_{\lambda f}(x) = t_\star : t_\star^3 - xt_\star^2 - \lambda = 0$

3. $F(\mathbf{X}) = \begin{cases} \text{tr}(\mathbf{X}^{-1}), & \mathbf{X} \succ 0 \\ \infty, & \text{else} \end{cases}$

Solution:

- $F = f \circ \lambda : f(\boldsymbol{\lambda}) = \sum_{i=1}^n \frac{1}{\lambda_i}$
-

$$\begin{aligned} \text{prox}_{\alpha F}(\mathbf{X}) &= \mathbf{U} \text{diag}(\text{prox}_{\alpha f}(\boldsymbol{\lambda}(\mathbf{X}))) \mathbf{U}^T \\ &= \mathbf{U} \text{diag}(\text{prox}_{\alpha f_1}(\lambda_1(\mathbf{X})) \times \cdots \times \text{prox}_{\alpha f_n}(\lambda_n(\mathbf{X}))) \mathbf{U}^T \end{aligned}$$

- $f_i(x) = \frac{1}{x} : x > 0$. Hence: $\text{prox}_{\alpha f_i}(x) = t_\star$ from the previous exercise
- $\text{prox}_F(\mathbf{X})$ with $\alpha = 1$ and $\mathbf{X} = \begin{pmatrix} 3 & 1 \\ 1 & 4 \end{pmatrix}$ is calculated using the code
- the code is *ex1-2.py*

4. $f(\mathbf{x}) = (\|\mathbf{x}\|_2 - 1)^2$

Solution:

- $f(\mathbf{x}) = \|\mathbf{x}\|_2^2 - 2\|\mathbf{x}\|_2 + 1$
- $\text{prox}_{\lambda g = -2\lambda\|\cdot\|_2}(\mathbf{x}) = \begin{cases} \left(1 + \frac{2\lambda}{\|\mathbf{x}\|}\right) \mathbf{x}, & \mathbf{x} \neq \mathbf{0}, \\ \{\mathbf{u} : \|\mathbf{u}\| = 2\lambda\}, & \mathbf{x} = \mathbf{0}. \end{cases}$
- $\text{prox}_{\lambda f} = \text{prox}_{\lambda g + \lambda\|\cdot\|^2}(\mathbf{x}) = \text{prox}_{\frac{1}{2\lambda+1}g}(\frac{\mathbf{x}}{2\lambda+1}) = \begin{cases} \left(1 + \frac{2\lambda}{(2\lambda+1)\|\mathbf{x}\|}\right) \frac{\mathbf{x}}{2\lambda+1}, & \mathbf{x} \neq \mathbf{0}, \\ \{\mathbf{u} : \|\mathbf{u}\| = \frac{2\lambda}{2\lambda+1}\}, & \mathbf{x} = \mathbf{0}. \end{cases}$

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2 Part 2

2.1 exercise 0

1. $g(x) = \lambda_2 \|x\|_1$ then $\text{prox}_g(x) = \mathcal{T}_{\frac{\lambda_2}{L_f}}(x)$
2. $g(x) = \frac{\lambda_1}{2} \|x\|_2^2 + \lambda_2 \|x\|_1$ then $\text{prox}_g(x) = \mathcal{T}_{\frac{\lambda_2}{L_f + \lambda_1}}(\frac{x}{\frac{\lambda_1}{L_f} + 1})$
3. the code is *ex-p2-e0.py*
4. V-FISTA 1, i.e. on $g(x) = \lambda_2 \|x\|_1$, performs the best
5. $x_{PGM}^{sol}(1:4) = (-0.4397, 0.0197, 1.4228, -0.8781)$
 $x_{FISTA}^{sol}(1:4) = (-0.4320, 0.0288, 1.4337, -0.9066)$
 $x_{V-FISTA1}^{sol}(1:4) = (-0.43210748, 0.02959795, 1.43437278, -0.90583604)$
 $x_{V-FISTA2}^{sol}(1:4) = (-0.43210796, 0.02959784, 1.43437041, -0.90583332)$

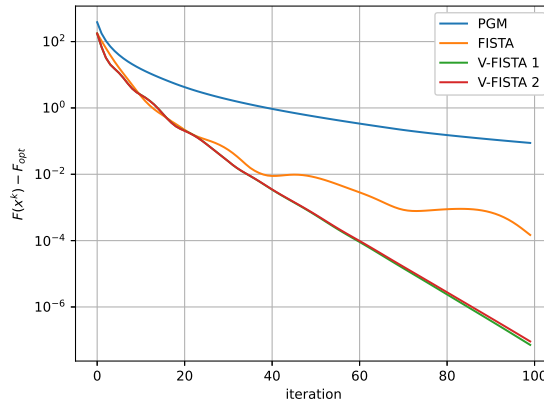


Figure 1: Part 2, exercise 0, V-FISTA 1 is with $g = \lambda_2 \|\cdot\|_1$, and V-FISTA 2 is with $g = \frac{\lambda_1}{2} \|\cdot\|_2^2 + \lambda_2 \|\cdot\|_1$

2.2 exercise 1

1. $H(x) := x^T Q x + 2b^T x + c$
 $\nabla H(x) = 2b + 2Qx = 0$, then $\bar{x} = -Q^{-1}b$
 $H(\bar{x}) = b^T Q^{-T} Q Q^{-1} b - 2b^T Q^{-1} b + c \geq 0$
 $\Rightarrow c \geq b^T Q^{-1} b$
2. as Q is positive definite, one can decompose it to have
 $f(x) = \sqrt{x^T Q x + 2b^T x + c} = \sqrt{\|Px - v\|_2^2 + c'^2} = \left\| \begin{pmatrix} Px - v \\ c' \end{pmatrix} \right\|_2$
 where if $Q = U\Lambda U^T$, $P := \Lambda^{\frac{1}{2}} U^T$, $v := -\Lambda^{-\frac{1}{2}} U^T b$, and $c'^2 := c - b^T Q^{-1} b$. As ℓ_p norm with $p \geq 1$ is convex, and composition of a convex function with an affine mapping is also convex, this norm is convex. Also sum of two convex function is convex, hence, the problem is convex.
3. $f(x) = \sqrt{x^T Q x + 2b^T x + c}$, $g(x) = 0.2 \|Dx\|_1$
 $\nabla f(x) = \frac{2b + 2Qx}{2\sqrt{H(x)}}$
 $\text{prox}_{\frac{0.2}{L_f} \|\cdot\|_1}(x) = \mathcal{T}_{\frac{0.2}{L_f}}(x)$

$$\begin{aligned} \text{prox}_{\frac{g}{L_f}}(x) &= \text{prox}_{\frac{0.2}{L_f} \|\cdot\|_1 \circ D}(x) = x + D^T \text{prox}_{\frac{0.2}{L_f} \|\cdot\|_1}(Dx) - Dx \\ &= \text{prox}_{\frac{0.2}{L_f} \|\cdot\|_1 \circ D}(x) = x + D^T \mathcal{T}_{\frac{0.2}{L_f}}(Dx) - Dx \end{aligned}$$
4. to estimate L_f we upper bound the Hessian of the function f . We have:

$$\nabla^2 f(x) = \frac{1}{\sqrt{\|Px - v\|_2^2 + c'^2}} P^T \left[I - \frac{(Px + b)(Px + b)^T}{\|Px - v\|_2^2 + c'^2} \right] P$$

the eigenvalues of the bracket belong to $\{0, 1\}$, as the matrix inside is a product of one vector by itself. We upper bound the Hessian as: $\nabla^2 f(x) \leq \frac{\|P\|^2}{\sqrt{\|Px-v\|^2 + c'^2}} \leq \frac{\|P\|^2}{c'}$, Hence,

$$L_f = \frac{\|A\|}{\sqrt{c-b^T Q^{-1}b}} = \frac{\|Q\|}{\sqrt{c-b^T Q^{-1}b}}$$

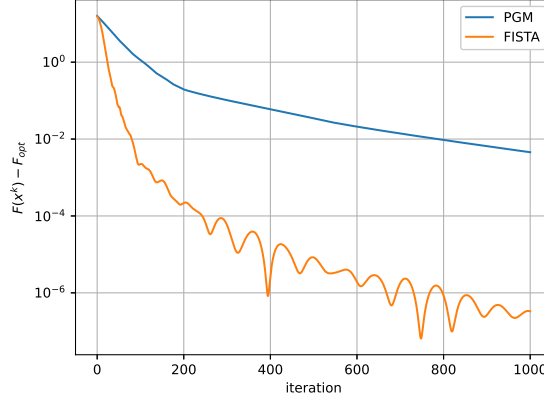


Figure 2: Part 2, exercise 1

5. the stepsize used in PGM is $\gamma = \frac{1}{L_f} = 0.02027373$

6. iterates:

PGM:

iter 1 : $F(x^k) - F_{opt} : 15.969037688894332$
iter 101 : $F(x^k) - F_{opt} : 1.138840371899061$
iter 201 : $F(x^k) - F_{opt} : 0.19536585866318035$
iter 301 : $F(x^k) - F_{opt} : 0.10256671457047162$
iter 401 : $F(x^k) - F_{opt} : 0.05981160382616579$
iter 501 : $F(x^k) - F_{opt} : 0.034541962530351356$
iter 601 : $F(x^k) - F_{opt} : 0.021032280748006116$
iter 701 : $F(x^k) - F_{opt} : 0.013937040643956067$
iter 801 : $F(x^k) - F_{opt} : 0.009469387714531763$
iter 901 : $F(x^k) - F_{opt} : 0.0065280945179999605$
iter 1001 : $F(x^k) - F_{opt} : 0.004544681858035915$

FISTA:

iter 1 : $F(x^k) - F_{opt} : 15.616787710263878$
iter 101 : $F(x^k) - F_{opt} : 0.002229198785176578$
iter 201 : $F(x^k) - F_{opt} : 0.00021635498722005764$
iter 301 : $F(x^k) - F_{opt} : 5.744173655841678e-05$
iter 401 : $F(x^k) - F_{opt} : 2.7570780005703455e-06$
iter 501 : $F(x^k) - F_{opt} : 8.335118572233569e-06$
iter 601 : $F(x^k) - F_{opt} : 1.9008889147187347e-06$
iter 701 : $F(x^k) - F_{opt} : 1.7973270658444562e-06$
iter 801 : $F(x^k) - F_{opt} : 8.541816285401183e-07$
iter 901 : $F(x^k) - F_{opt} : 2.646209011913925e-07$
iter 1001 : $F(x^k) - F_{opt} : 3.302678983629903e-07$

7. solutions:

PGM: $(-0.17302056, -0.13170504, 0.2853231, -0.26288016, -0.53923318,$
 $-0.41890723, 0.34400762, -0.51913402, 0.38304034, -0.8028364,$
 $-0.156584, -0.27559503, 0.06735174, -0.17116589, -0.07071933,$
 $-0.07055706, -0.0558151, -0.13077329, -0.10362827, 0.16621555,$
 $-0.74600957, -0.41574597, 0.62302217, -0.33120591, -0.24841553,$
 $-0.63743909, -0.34855206, 0.2553829, -0.13449554, -0.0940163)$

FISTA: $(-0.23010618, -0.13942272, 0.31427133, -0.27633859, -0.59820196,$
 $-0.49575369, 0.34118456, -0.5456482, 0.38702184, -0.91169326,$
 $-0.17665491, -0.32830946, 0.02846801, -0.10373275, -0.14537967,$
 $-0.07446206, -0.03326546, -0.1831482, -0.08021404, 0.26755059,$
 $-0.84049738, -0.48603082, 0.65971966, -0.25551334, -0.2822796,$
 $-0.75444863, -0.35508949, 0.28620091, -0.20633458, -0.18046632)$

2.3 exercise 3

1. $f(x) = \frac{1}{2}\|x\|_2^2$, and it is strongly convex with $\sigma = 1$
2. $g(Ax) := C \sum_{i=1}^n \max\{0, 1 - y_i \mathbf{w}^T \mathbf{x}_i\}$, take $C = 1$
 $A = \text{diag}(\mathbf{y})\mathbf{X}$, where $\mathbf{y} = (y_1, \dots, y_n)$ and \mathbf{X} has rows equal to \mathbf{x}_i
 $L_f = \|A\|^2/\sigma$
 $g(z) = h(1 - z)$ where we define:
 $h(z) := \sum_{i=1}^n \{0, z_i\} = \sigma_{\text{Box}[0,1]}(z)$
 $\text{prox}_{L_f h}(x) = z - L_f P_{\text{Box}[0,1]}(\frac{x}{L_f})$
 $\text{prox}_{L_f g}(x) = 1 - \text{prox}_{L_f h}(1 - x) = x + L_f P_{\text{Box}[0,1]}(\frac{1-x}{L_f})$

3. DPG iterates:

$$x^k = A^T y^k$$

$$y^{k+1} = y^k - \frac{1}{L_f} A x^k + \frac{A x^k - L_f y^k}{L_f} + P_{\text{Box}[0,1]}(\frac{1 - A x^k + L_f y^k}{L_f})$$

4. solutions:

by DPG: $(2.04031854, -0.91262279)$
by FDPG: $(2.13382443, -1.01718168)$

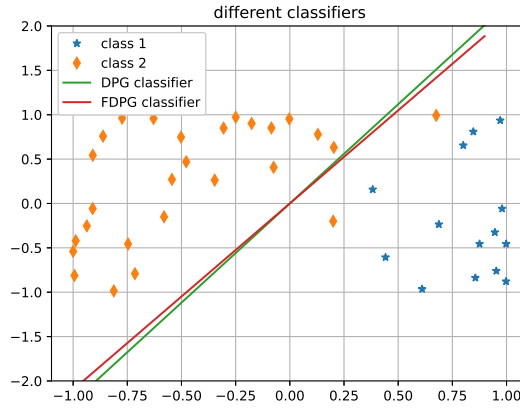


Figure 3: Part 2, exercise 3

3 Part 3

3.1 exercise 2 - part 1

1. ADLPMM: $f(x) + g(z)$ where $x + Bz = 0$ and $g = 0$
with $B = (-A, -A, -D1, -D2)$

A is a matrix with rows equal to a_i

$$D_1 = \begin{bmatrix} 1 & -1 & \cdots & 0 & 0 \\ 0 & 1 & -1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \cdot & 1 & -1 & 0 \end{bmatrix} \text{ and } D_2 = \begin{bmatrix} 0 & 1 & -1 & \cdots & 0 \\ 0 & 0 & 1 & -1 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdot & 1 & -1 \end{bmatrix}$$

$$f(z, w, v, u) = -\sum_{i=1}^m \log(a_i^T z - b_i) + \delta_{C:Aw \geq b}(w) + \sum_{i=1}^{n-2} \sqrt{v_i^2 + u_i^2}$$

$$\begin{aligned} \text{prox}_{\lambda f}(z, w, v, u) &= \left(\frac{z_j - b_j + \sqrt{(z_j - b_j)^2 + 4\lambda}}{2} + b_j \right)_{j=1}^n \\ &\quad \times (\max\{w_j, b_j\})_{j=1}^n \\ &\quad \times \left(\left(1 - \frac{\lambda}{\max\{\sqrt{v_j^2 + u_j^2}, \lambda\}} \right) v_j \right)_{j=1}^n \\ &\quad \times \left(\left(1 - \frac{\lambda}{\max\{\sqrt{v_j^2 + u_j^2}, \lambda\}} \right) u_j \right)_{j=1}^n \end{aligned}$$

$$\text{prox}_{\lambda g}(z) = z$$

In the algorithm, $\alpha = \rho$ and $\beta = \rho \lambda_{\max}(B^T B)$

2. CP: $f(Qx) + g(x)$ where $g = 0$ and f is defined as above with $Q = (A, A, D1, D2)$

In the algorithm, using Moreau Decomposition, $\text{prox}_{\sigma f^*}(x) = x - \sigma \text{prox}_{\frac{1}{\sigma} f}(\frac{x}{\sigma})$

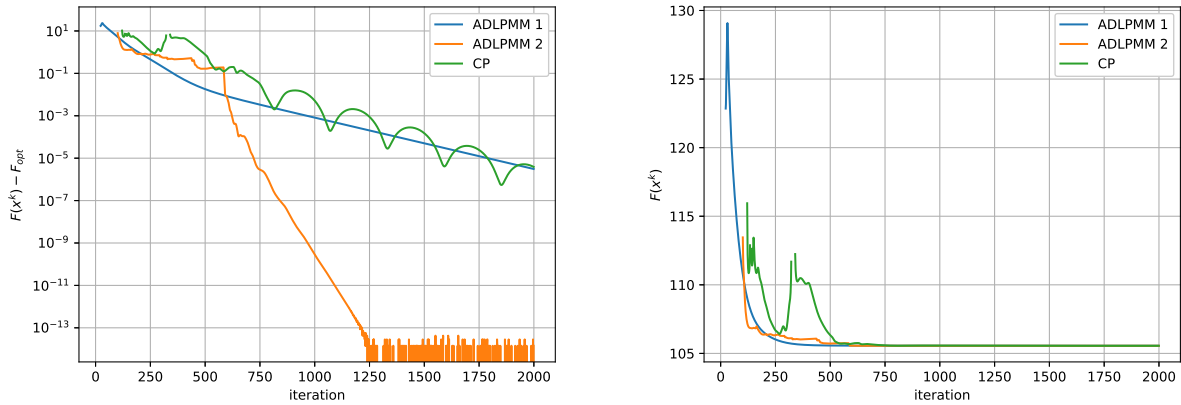


Figure 4: Part 3, exercise 2, section (c), ADLPM1 is with $\rho = 1$, ADLPM2 is with $\rho = \frac{1}{\|A\|_2}$, and CP is with $\tau = \sigma = \frac{1}{\|A\|_2}$

3. Solutions:

ADLPM1: $(-5.2156251, 1.41843662, 1.40372643)$

ADLPM2: $(-5.2148905, 1.41837664, 1.40349131)$

CP: $(-5.21427958, 1.41827063, 1.40324038)$

3.2 exercise 2 - part 2

1. ACP: $f(Qx) + g(x)$ where $g(x) = \frac{1}{2} \|x\|_2^2$, Q and f is defined as above
 $\text{prox}_{\lambda g}(x) = \frac{x}{1+\lambda}$
the strong convexity parameter $\gamma = 1$

2. FDPG: $L_f = \frac{\|Q\|_2^2}{\gamma}$ where $\gamma = 1$ is the strong convexity parameter
The update: $u^k = \arg\max_u \{\langle u, Q^T w^k \rangle - g(u)\} = Q^T w^k$

3. Solutions:

ACP: $(-4.26504195, 1.15973671, 1.98584402)$

FDPG: $(-4.264957, 1.1596312, 1.98584261)$

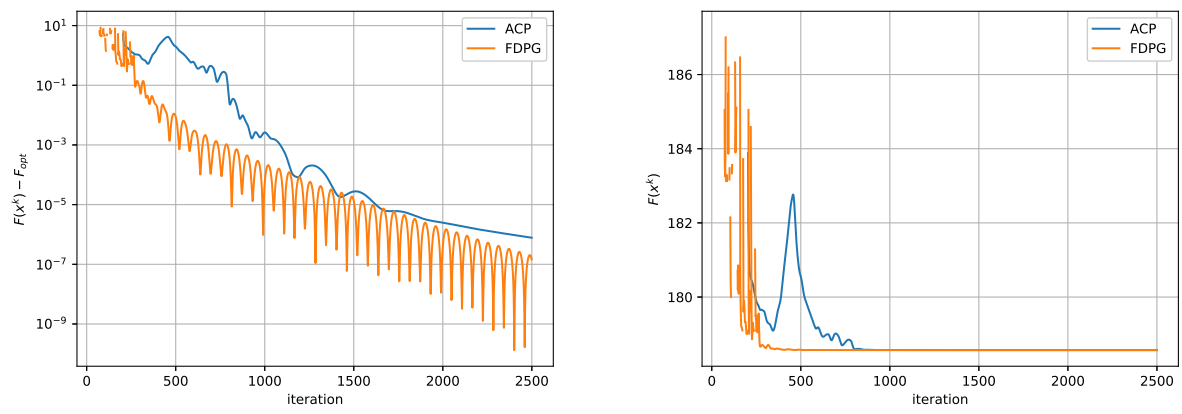


Figure 5: Part 3, exercise 2, section (e)