



Outlines

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Statistical Machine Learning

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College of Engineering and Computer Science

The Australian National University

Canberra

Semester One, 2020.

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(Many figures from C. M. Bishop, "Pattern Recognition and Machine Learning")



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Part II

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Introduction

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Polynomial Curve Fitting

Probability Theory

Probability Densities

Expectations and
Covariances

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- Formalise intuitions about problems
- Use language of mathematics to express models
- Geometry, vectors, linear algebra for reasoning
- Probabilistic models to capture uncertainty
- Design and analysis of algorithms
- Numerical algorithms in python
- Understand the choices when designing machine learning methods

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Polynomial Curve Fitting

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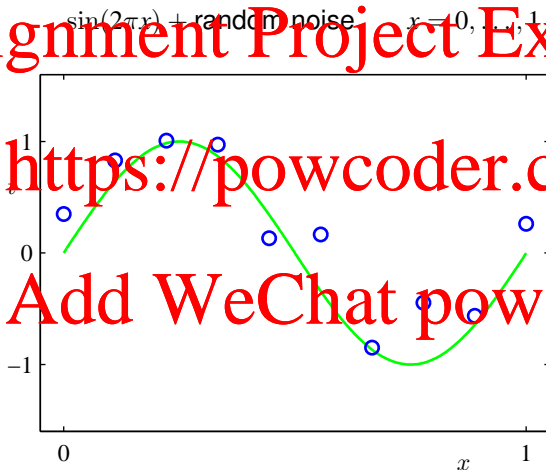
Definition (Mitchell, 1998)

A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P , if its performance at tasks in T , as measured by P , improves with experience E .

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- some artificial data created from the function



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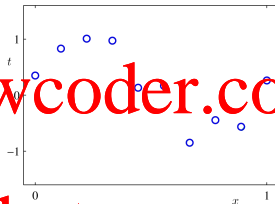


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$N = 10$

$\mathbf{x} \equiv (x_1, \dots, x_N)^T$

$\mathbf{t} \equiv (t_1, \dots, t_N)^T$



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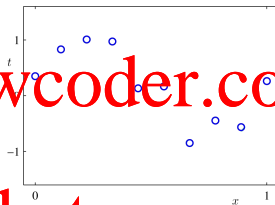
$$N = 10$$

$$\mathbf{x} \equiv (x_1, \dots, x_N)^T$$

$$\mathbf{t} \equiv (t_1, \dots, t_N)^T$$

$$x_i \in \mathbb{R} \quad i = 1, \dots, N$$

$$t_i \in \mathbb{R} \quad i = 1, \dots, N$$



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M order of polynomial

$$y(x, \mathbf{w}) = w_0 + w_1 x + w_2 x^2 + \cdots + w_M x^M$$

$$= \sum_{m=0}^M v_m x^m$$



- nonlinear function of x
- **linear** function of the unknown model parameter \mathbf{w}
- How can we find good parameters $\mathbf{w} = (w_1, \dots, w_M)^T$?

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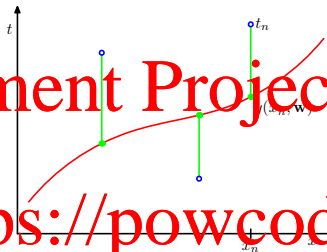
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- Performance measure : Error between target and prediction of the model for the training data

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$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N (y(x_n, \mathbf{w}) - t_n)^2$$

- unique minimum of $E(\mathbf{w})$ for argument \mathbf{w}^* under certain conditions (what are they?)



Polynomial Curve Fitting

Probability Theory

Probability Densities

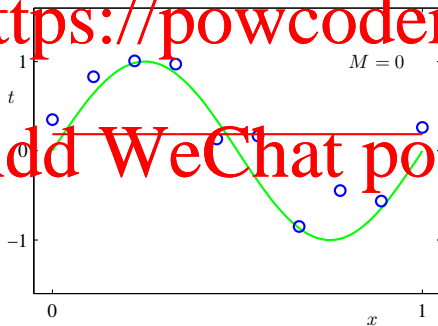
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$$v(x_i, v) = \sum_{m=0}^M v_m x_i^m \Big|_{M=0} \\ = w_0$$

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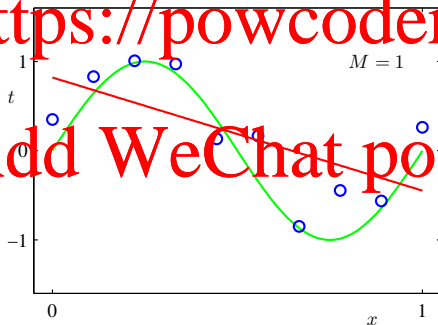
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$$\begin{aligned} y/x, v &= \sum_{m=0}^M v_m x^m \\ &= w_0 + w_1 x \end{aligned} \quad \Bigg|_{M=1}$$

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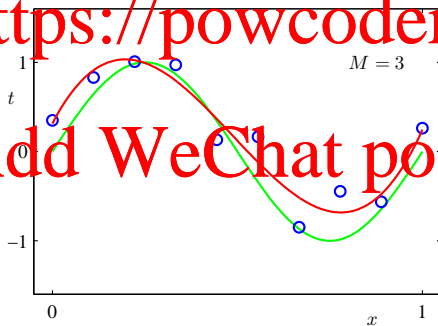
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$$\begin{aligned} f(x; w) &= \sum_{m=0}^M w_m x^m \\ &= w_0 + w_1 x + w_2 x^2 + w_3 x^3 \end{aligned}$$

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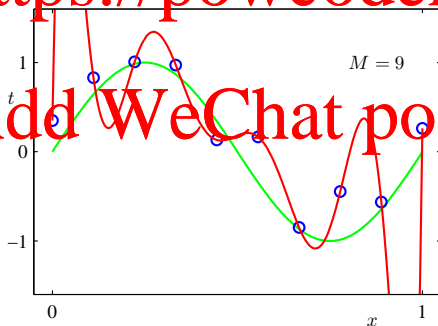
Probability Theory

Probability Densities

Expectations and
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$$y(x, \mathbf{w}) = \sum_{m=0}^M w_m x^m \\ = w_0 + w_1 x + \cdots + w_8 x^8 + w_9 x^9$$

- overfitting



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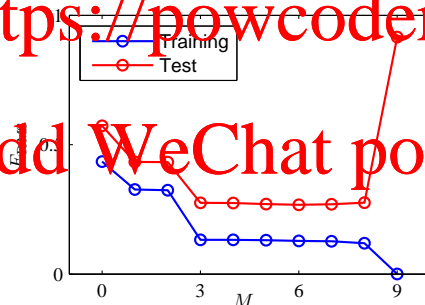
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Expectations and
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- Train the model and get \mathbf{w}^*
- Get 100 new data points
- Root mean-square (RMS) error

$$E_{\text{RMS}} = \sqrt{2E(\mathbf{w}^*)/N}$$



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Probability Theory

Probability Densities

Expectations and
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	M = 0	M = 1	M = 3	M = 9
w_0^*	0.19	0.82	0.31	0.35
w_1^*		-1.27	7.99	232.37
w_2^*			-25.43	-5321.83
w_3^*			17.37	48568.31
w_4^*				231639.30
w_5^*				640042.26
w_6^*				-1061800.52
w_7^*				1042400.18
w_8^*				-557682.99
w_9^*				125201.43

Table: Coefficients w^* for polynomials of various order.



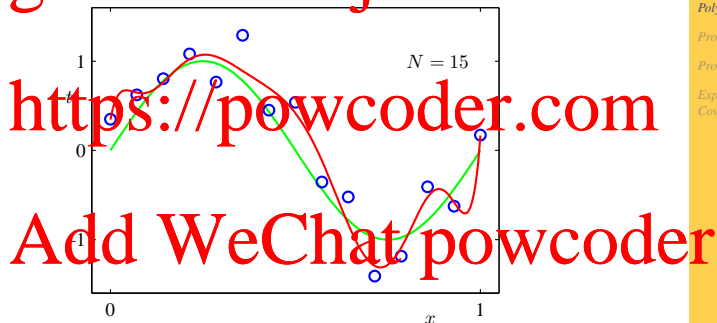
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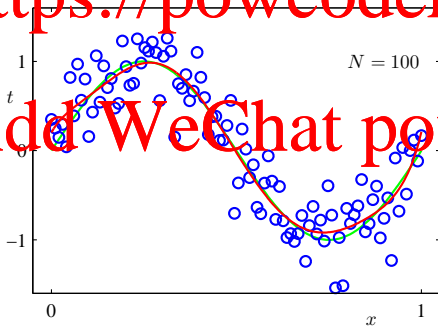




- $N = 100$
- heuristics : have no less than 5 to 10 times as many data points than parameters
- but number of parameters is not necessarily the most appropriate measure of model complexity !
- later: Bayesian approach

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- How to constrain the growing of the coefficients \mathbf{w} ?
- Add a **regularisation** term to the error function

$$\tilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N (y(x_n, \mathbf{w}) - t_n)^2 + \frac{\lambda}{2} \|\mathbf{w}\|^2$$

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- Squared norm of the parameter vector \mathbf{w}

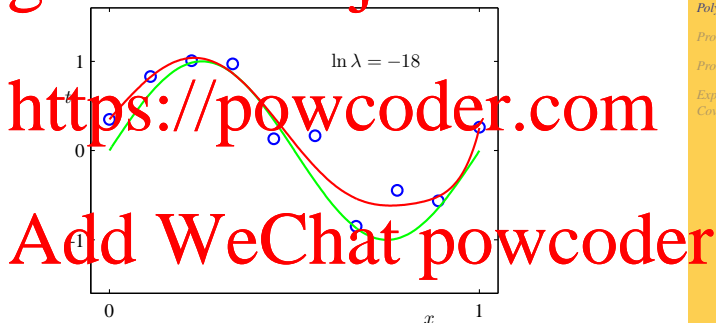
$$\|\mathbf{w}\|^2 = \mathbf{w}^T \mathbf{w} = w_0^2 + w_1^2 + \dots + w_M^2$$

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- unique minimum of $E(\mathbf{w})$ for argument \mathbf{w}^* under certain conditions (what are they for $\lambda = 0$? for $\lambda > 0$?)



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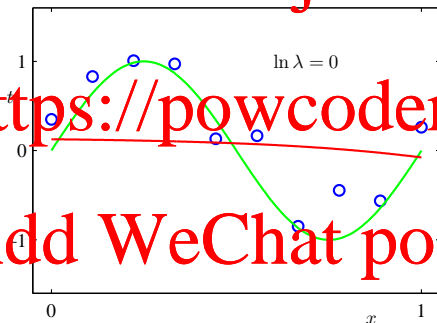
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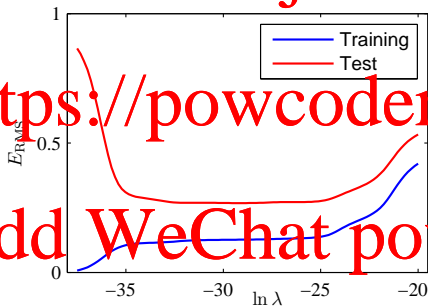
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What is Machine Learning?



Definition (Mitchell, 1998)

A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P , if its performance at tasks in T , as measured by P , improves with experience E .

- Task: regression
- Experience: x input examples, t output labels
- Performance: squared error
- Model choice
- Regularisation
- **do not train on the test set!**

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Probability Theory

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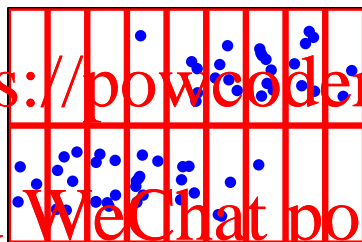
$p(X, Y)$

$Y = 2$

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$Y = 1$

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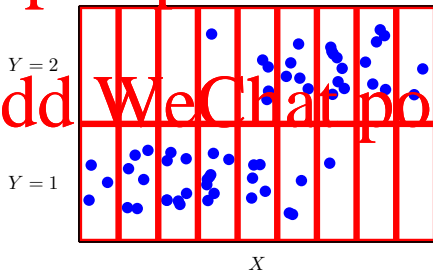




Y vs. X	a	b	c	d	e	f	g	h	i	sum
2	0	0	0	1	4	5	8	6	2	26
1	3	6	8	8	5	3	4	0	0	34
sum	3	6	8	9	9	8	9	6	2	60

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Y vs. X	a	b	c	d	e	f	g	h	i	sum
2	0	0	0	1	4	5	8	6	2	26
1	3	6	8	8	9	3	1	0	0	34
sum	3	6	8	9	9	8	9	6	2	60

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$$p(X = d, Y = 1) = 8/60$$

$$p(X = d) = p(X = d, Y = 2) + p(X = d, Y = 1)$$

$$= 1/60 + 8/60$$

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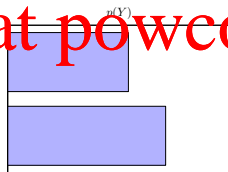
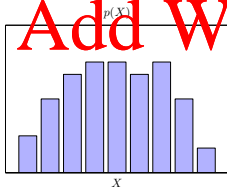
$$p(X = d) = \sum_Y p(X = d, Y)$$

$$p(X) = \sum_Y p(X, Y)$$



Y vs. X	a	b	c	d	e	f	g	h	i	sum
2	0	0	0	1	4	5	8	6	2	26
1	3	6	8	8	5	3	1	0	0	34
sum	3	6	8	9	9	8	9	6	2	60

$$p(X) = \sum_Y p(X, Y) \quad p(Y) = \sum_X p(X, Y)$$





Y vs. X	a	b	c	d	e	f	g	h	i	sum
2	0	0	0	1	4	5	8	6	2	26
1	3	6	8	8	5	3	1	0	0	34
sum	3	6	8	9	9	8	9	6	2	60

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Conditional Probability

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Calculate $p(Y=1)$:

$$p(Y=1) = \sum_x p(X, Y=1) = 34/60$$

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$$p(X=d, Y=1) = p(X=d | Y=1) p(Y=1)$$

$$p(X, Y) = p(X | Y) p(Y)$$

Another intuitive view is **renormalisation** of relative frequencies:

$$p(X | Y) = \frac{p(X, Y)}{p(Y)}$$

Sum and Product Rules



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Probability Theory

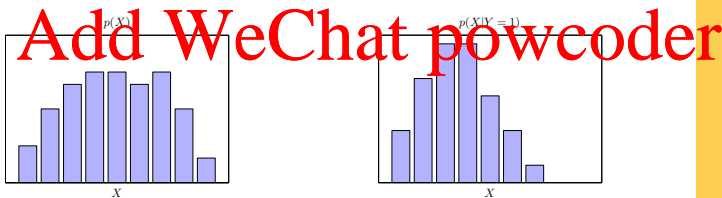
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Y vs. X	a	b	c	d	e	f	g	h	i	sum
2	0	0	0	1	4	5	8	6	2	26
1	3	6	8	8	5	3	1	0	0	34
sum	3	6	8	9	9	8	9	6	2	60

$$p(X) = \sum_Y p(X, Y) \quad p(X | Y) = \frac{p(X, Y)}{p(Y)}$$





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- Sum Rule

$$p(X) = \sum_Y p(X, Y)$$

- Product Rule

$$p(X, Y) = p(X | Y) p(Y)$$

These rules form the basis of Bayesian machine learning, and this course!

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Use product rule

$$p(X, Y) = p(X | Y) p(Y) = p(Y | X) p(X)$$

Bayes Theorem

$$p(Y | X) = \frac{p(X | Y) p(Y)}{p(X)} \quad \text{only defined for } p(X) > 0$$

and

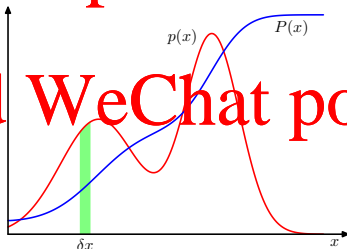
$$\begin{aligned} p(X) &= \sum_Y p(X, Y) && \text{(sum rule)} \\ &= \sum_Y p(X | Y) p(Y) && \text{(product rule)} \end{aligned}$$



- Real valued variable $x \in \mathbb{R}$

- Probability of x to fall in the interval $(x, x + \delta x)$ is given by $p(x)\delta x$ for infinitesimal small δx .

$$p(x \in (a, b)) = \int_a^b p(x) dx.$$

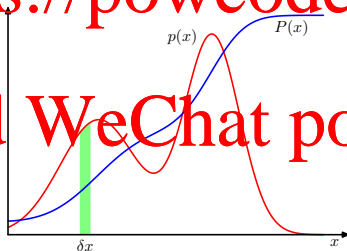


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Constraints on $p(x)$

- Nonnegative
- Normalisation

$$\int_{-\infty}^{\infty} p(x) dx = 1.$$



Cumulative distribution function $P(x)$

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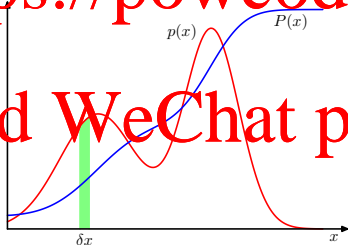
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or

$\frac{d}{dx}P(x) = p(x)$
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- Vector $\mathbf{x} \in (x_1, \dots, x_D)^T = \begin{bmatrix} x_1 \\ \vdots \\ x_D \end{bmatrix}$

- Nonnegative

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- Normalisation

$$\int_{-\infty}^{\infty} p(\mathbf{x}) \, d\mathbf{x} = 1.$$

- This means

$$\int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} p(\mathbf{x}) \, dx_1 \dots dx_D = 1.$$

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- Sum Rule

$$p(x) = \int_{-\infty}^{\infty} p(x, y) dy$$

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- Product Rule

$$p(x, y) = p(y | x) p(x)$$

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- Weighted average of a function $f(x)$ under the probability distribution $p(x)$

$$\mathbb{E}[f] = \sum_x p(x) f(x) \quad \text{discrete distribution } p(x)$$

$$\mathbb{E}[f] = \int p(x) f(x) dx \quad \text{probability density } p(x)$$

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- Given a finite number N of points x_n drawn from the probability distribution $p(x)$.
- Approximate the expectation by a finite sum:

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$$\mathbb{E}[f] \simeq \frac{1}{N} \sum_{n=1}^N f(x_n)$$

- How to draw points from a probability distribution $p(x)$?
Lecture coming about "Sampling"

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- arbitrary function $f(x, y)$

$$\mathbb{E}_x [f(x, y)] = \sum_x p(x) f(x, y) \quad \text{discrete distribution } p(x)$$

$$\mathbb{E}_x [f(x, y)] = \int p(x) f(x, y) dx \quad \text{probability density } p(x)$$

- Note that $\mathbb{E}_x [f(x, y)]$ is a function of y .

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- arbitrary function $f(x)$

$$\mathbb{E}_x [f | y] = \sum_x p(x | y) f(x) \quad \text{discrete distribution } p(x)$$

$$\mathbb{E}_x [f | y] = \int p(x | y) f(x) \, dx \quad \text{probability density } p(x)$$

- Note that $\mathbb{E}_x [f | y]$ is a function of y .
- Other notation used in the literature: $\mathbb{E}_{x|y} [f]$.
- What is $\mathbb{E} [\mathbb{E} [f(x) | y]]$? Can we simplify it?
- This must mean $\mathbb{E}_y [\mathbb{E}_x [f(x) | y]]$. (Why?)

$$\begin{aligned} \mathbb{E}_y [\mathbb{E}_x [f(x) | y]] &= \sum_y p(y) \mathbb{E}_x [f | y] = \sum_y p(y) \sum_x p(x|y) f(x) \\ &= \sum_{x,y} f(x) p(x, y) = \sum_x f(x) p(x) \\ &= \mathbb{E}_x [f(x)] \end{aligned}$$

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- arbitrary function $f(x)$

$$\text{var}[f] = \mathbb{E} [(f(x) - \mathbb{E} [f(x)])^2] = \mathbb{E} [f(x)^2] - \mathbb{E} [f(x)]^2$$

- Special case: $f(x) = x$

$$\text{var}[x] = \mathbb{E} [(x - \mathbb{E} [x])^2] = \mathbb{E} [x^2] - \mathbb{E} [x]^2$$

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- Two random variables $x \in \mathbb{R}$ and $y \in \mathbb{R}$

$$\begin{aligned}\text{cov}[x, y] &= \mathbb{E}_{x, y}[(x - \mathbb{E}[x])(y - \mathbb{E}[y])] \\ &= \mathbb{E}_{x, y}[xy] - \mathbb{E}[x] \mathbb{E}[y]\end{aligned}$$

- With $\mathbb{E}[x] = a$ and $\mathbb{E}[y] = b$

$$\begin{aligned}\text{cov}[x, y] &= \mathbb{E}_{x, y}[(x - a)(y - b)] \\ &= \mathbb{E}_{x, y}[xy] - \mathbb{E}_{x, y}[xb] - \mathbb{E}_{x, y}[ay] + \mathbb{E}_{x, y}[ab] \\ &= \mathbb{E}_{x, y}[xy] - b \underbrace{\mathbb{E}_{x, y}[x]}_{=\mathbb{E}[x]} - a \underbrace{\mathbb{E}_{x, y}[y]}_{=\mathbb{E}[y]} + ab \underbrace{\mathbb{E}_{x, y}[1]}_{=1}\end{aligned}$$

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$$\begin{aligned}&= \mathbb{E}_{x, y}[xy] - ab - ab + ab = \mathbb{E}_{x, y}[xy] - ab \\ &= \mathbb{E}_{x, y}[xy] - \mathbb{E}[x] \mathbb{E}[y]\end{aligned}$$

- Expresses how strongly x and y vary together. If x and y are independent, their covariance vanishes.



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- Two random variables $\mathbf{x} \in \mathbb{R}^D$ and $\mathbf{y} \in \mathbb{R}^D$

$$\begin{aligned}\text{cov}[\mathbf{x}, \mathbf{y}] &= \mathbb{E}_{\mathbf{x}, \mathbf{y}} [(\mathbf{x} - \mathbb{E}[\mathbf{x}])(\mathbf{y} - \mathbb{E}[\mathbf{y}])^T] \\ &= \mathbb{E}_{\mathbf{x}, \mathbf{y}} [\mathbf{x} \mathbf{y}^T] - \mathbb{E}[\mathbf{x}] \mathbb{E}[\mathbf{y}^T]\end{aligned}$$

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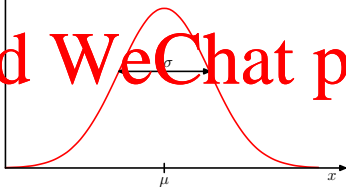
- $x \in \mathbb{R}$

- Gaussian Distribution with mean μ and variance σ^2

$$\mathcal{N}(x | \mu, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{\frac{1}{2}}} \exp\left\{-\frac{1}{2\sigma^2}(x - \mu)^2\right\}$$

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$\mathcal{N}(x | \mu, \sigma^2)$



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- $\mathcal{N}(x | \mu, \sigma^2) > 0$

- $\int_{-\infty}^{\infty} \mathcal{N}(x | \mu, \sigma^2) dx = 1$

- Expectation over x

$$\mathbb{E}[x] = \int_{-\infty}^{\infty} \mathcal{N}(x | \mu, \sigma^2) x dx = \mu$$

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- Expectation over x^2

$$\mathbb{E}[x^2] = \int_{-\infty}^{\infty} \mathcal{N}(x | \mu, \sigma^2) x^2 dx = \mu^2 + \sigma^2$$

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- Variance of x

$$\text{var}[x] = \mathbb{E}[x^2] - \mathbb{E}[x]^2 = \sigma^2$$



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- Estimate best predictor = training = learning

Given data $(x_1, y_1), \dots, (x_n, y_n)$, find a predictor $f_{\mathbf{w}}(\cdot)$.

- 1 Identify the type of input x and output y data
- 2 Propose a (linear) mathematical model for $f_{\mathbf{w}}$
- 3 Design an objective function or likelihood
- 4 Calculate the optimal parameter (\mathbf{w})
- 5 Model uncertainty using the Bayesian approach
- 6 Implement and compute (the algorithm in python)
- 7 Interpret and diagnose results

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