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- Precision and thoroughness are both appreciated. Reaching the correct answer without the appropriate justification or incorrect reasoning will be penalized.
- We have proof-read the problem set multiple times to ensure there are no bugs. Some details are however left out intentionally and are for you to figure out. So, if you really think some piece of information is missing and need to make an assumption to solve the problem please go ahead; there is no need to run it by the instructors. Do not forget to mention the assumption made for solving the problem. Needless to say, unreasonable assumptions are, by definition, unreasonable.

1. Suppose that image f(x, y) has radon transform $r(\alpha, \theta)$. Given a > 0, find the radon transform of $f(\frac{x}{a}, \frac{y}{a})$.

2. Consider the image inpainting problem where we are given the following input-output equation:

$$y[m, n] = x[m, n]a[m, n],$$

where a[m,n]=1 when $(m,n)\in\Omega$ and zero otherwise. The set Ω is known. Hence, given Ω , the image formation model above is linear.

Let $\widehat{x}[m,n]$ be the pseudoinverse solution. Show that $\widehat{x}[m,n]=y[m,n].$

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3. Let A be an $N \times N$ orthonormal matrix, i.e., $A^{\top}A = AA^{\top} = \mathbb{I}_N$, where \mathbb{I}_N is the N-dimensional identity matrix.

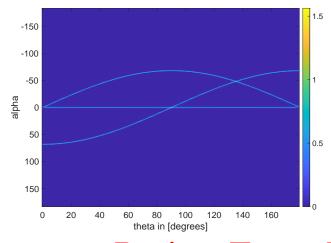
Given positive integer K and $\mathbf{y} \in \mathbb{R}^N$, find the solution (as a closed form expression) to

$$\min_{\mathbf{x}} \|\mathbf{y} - A\mathbf{x}\|^2 \quad \text{s.t.} \quad \|\mathbf{x}\|_0 \le K.$$

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4. You are given the radon transform of an image. Derive an analytical expression for the image. It is ok if the values in your expression are approximate.



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5. A corrupted image is given below. Devise a strategy for restoring it.



You are given the following information (that you can also readily observe from the image). 1) A small number of squares have been added to the image intensities. 2) Each square is 10 pixels wide. Project Exam Help

Your answer is expected to contain the following three components:

- a) A mathematical possibility of the property image to the observed corrupted image,
- b) An optimization-based formulation for the solution. Specifically, we want to see something a the driver chart powcoder
- c) A brief description on how you would solve the optimization in (b).

6. We will study a different approach to derive DCT-II in this problem. Let x[n], n = 0, ..., N-1 be a N-length signal and let d[k] be its DCT-II coefficients. Lets construct a new signal y[n], of length 2N such that

$$y[n] = \begin{cases} x[n] & 0 \le n < N \\ x[2N - 1 - n] & N \le n < 2N \end{cases}$$

Let Y[k] be the 2N-length DFT of y[n], given as $Y[k] = \sum_{n=0}^{2N-1} y[n] e^{-j2\pi kn/(2N)}$.

(Part a) Relate Y[k] to d[k].

(Part b) Derive expressions to invert the DCT-II coefficients using Y[k] as an intermediary.

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Finals

7. Let f(x) be given as

$$f(x) = \begin{cases} -x & x \le 0\\ 0 & x > 0 \end{cases}$$

(Part a) Sketch f(x)

(Part b) Is f(x) differentiable? Justify.

(Part c) Derive the sub-differential of f(x).

(Part d) Derive an expression for the proximal operator:

$$\min_{x} \beta f(x) + \frac{1}{2}(y-x)^{2}.$$

(Part e) What does this proximal operator become as $\lim \beta \to \infty$?

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8. Let A be an $M \times N$ matrix with unit-norm columns \mathbf{a}_i . Let $\mathbf{x}_0 \in \mathbb{R}^N$ be some 1-sparse signal. Suppose we obtain linear measurements

$$\mathbf{y} = A\mathbf{x}_0$$

where A is an $M \times N$ matrix.

(Part a) What property must A satisfy so that OMP recovers \mathbf{x}_0 from \mathbf{y} ? Now, lets assume that we obtain noisy linear measurements of the form

$$z = Ax_0 + n$$

We only know that the noise is bounded in energy and specifically,

$$\|\mathbf{n}\| \leq \epsilon$$
.

(Part A set graph the type type of the support of \mathbf{x}_0 correctly?

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