

211: Computer Architecture Spring 2021

Instructor: Prof. David Menezes **Assignment Project Exam Help**

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Topics:

- Hardware-Software Interface
- Assembly Programming
 - Reading: Chapter 3

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Programming Meets Hardware

High-Level Language Program

```
#include <stdio.h>
int main() {
    int x, y, temp;
    x=1; y=2;
    temp =x; x=y; y=temp;
    printf("%d %d %d\n",x,y,temp);
}
```

Compiler

Assembly Language Program

Assembler

Machine Language Program

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```
movl    $1, -8(%ebp)
movl    $2, -12(%ebp)
movl    -8(%ebp), %eax
movl    %eax, -16(%ebp)
movl    -12(%ebp), %eax
movl    %eax, -8(%ebp)
movl    -16(%ebp), %eax
movl    %eax, -12(%ebp)
movl    -16(%ebp), %eax
movl    %eax, 12(%esp)
movl    -12(%ebp), %eax
movl    %eax, 8(%esp)
movl    -8(%ebp), %eax
movl    %eax, 4(%esp)
```

```
7f 45 4c 46 01 01 01
00 00 00 00 00 00 00
00 00 02 00 03 00 01
00 00 00 f0 82 04 08
34 00 00 00 c4 0c 00
00 00 00 00 00 34 00
```

ISA

How do you get performance?

Performance with Programs

(1) Program: Data structures + algorithms

(2) Compiler translates code

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(3) Instruction set architecture

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(4) Hardware Implementation

Instruction Set Architecture

(1) Set of instructions that the CPU can execute

- (1) What instructions are available?
- (2) How the instructions are encoded? Eventually everything is binary.

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(2) State of the system (Registers + memory state + program counter)

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- (1) What instruction is going to execute next
- (2) How many registers? Width of each register?
- (3) How do we specify memory addresses?
 - Addressing modes

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(3) Effect of instruction on the state of the system

IA32 (X86 ISA)

There are many different assembly languages because they are processor-specific

- IA32 (x86)
 - x86-64 for new 64-bit processors
 - IA-64 radically different for Itanium processors
 - Backward compatibility instructions added with time
- PowerPC
- MIPS

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We will focus on IA32/x86-64 because you can generate and run on iLab machines (as well as your own PC/laptop)

- IA32 is also dominant in the market although smart phone, eBook readers, etc. are changing this

X86 Evolution

8086 – 1978 – 29K transistors – 5-10MHz

I386 – 1985 – 275K transistors – 16-33 MHz

Pentium4 – 2005 – 230M transistors – 2800-3800 MHz

Haswell – 2013 – > 2B transistors – 3200-3900 MHz

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Added features

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- Large caches
- Multiple cores
- Support for data parallelism (SIMD) eg AVX extensions

CISC vs RISC

CISC: complex instructions : eg X86

- Instructions such as strcpy/AES and others
 - Reduces code size
 - Hardware implementation complex?
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RISC: simple instructions: eg Alpha

- Instructions are simple add/ld/st
- Increases code size
- Hardware implementation simple?

Aside About Implementation of x86

About 30 years ago, the instruction set actually reflected the processor hardware

- E.g., the set of registers in the instruction set is actually what was present in the processor

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As hardware advanced, industry faced with choice

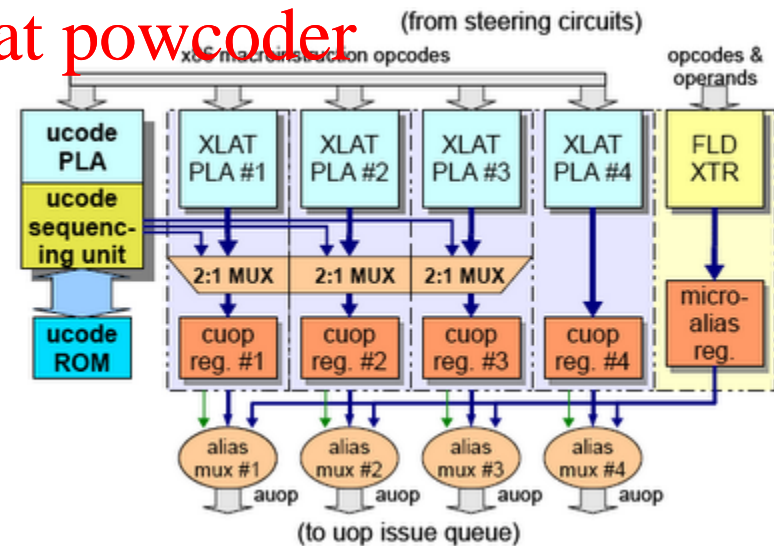
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- Change the instruction set: bad for backward compatibility
- Keep the instruction set: harder to exploit hardware advances
 - Example: many more registers but only small set introduced circa 1980

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Starting with the P6 (PentiumPro), IA32 actually got implemented by Intel using an “interpreter” that translates IA32 instructions into a simpler “micro” instruction set

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Assembly Programming

Brief tour through assembly language programming

Why?

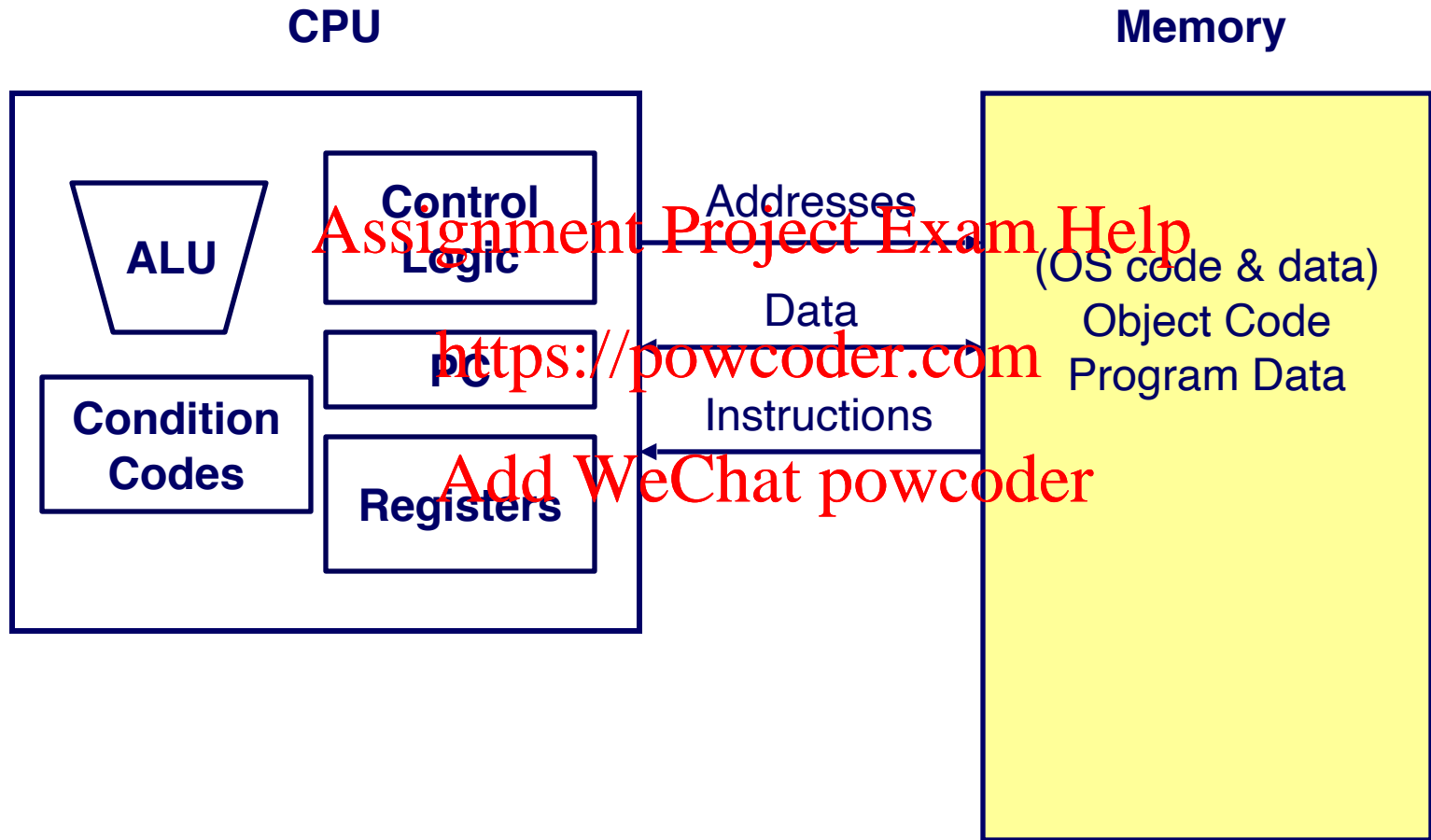
- Machine interface: where software meets hardware
- To understand how the hardware works, we have to understand the interface that it exports

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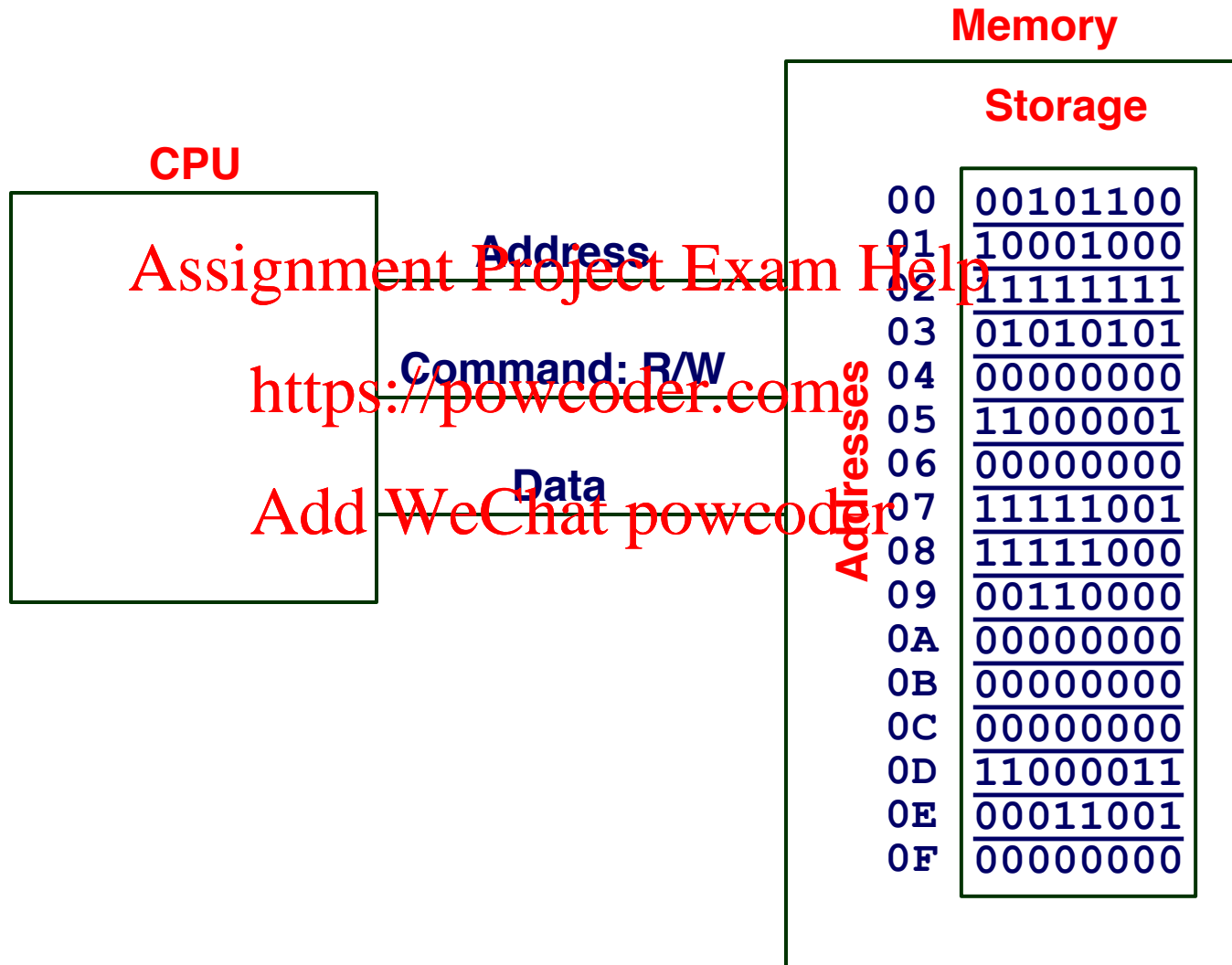
Why not binary language?

- Much easier for humans to read and reason about
- Major differences:
 - Human readable language instead of binary sequences
 - Relative instead of absolute addresses

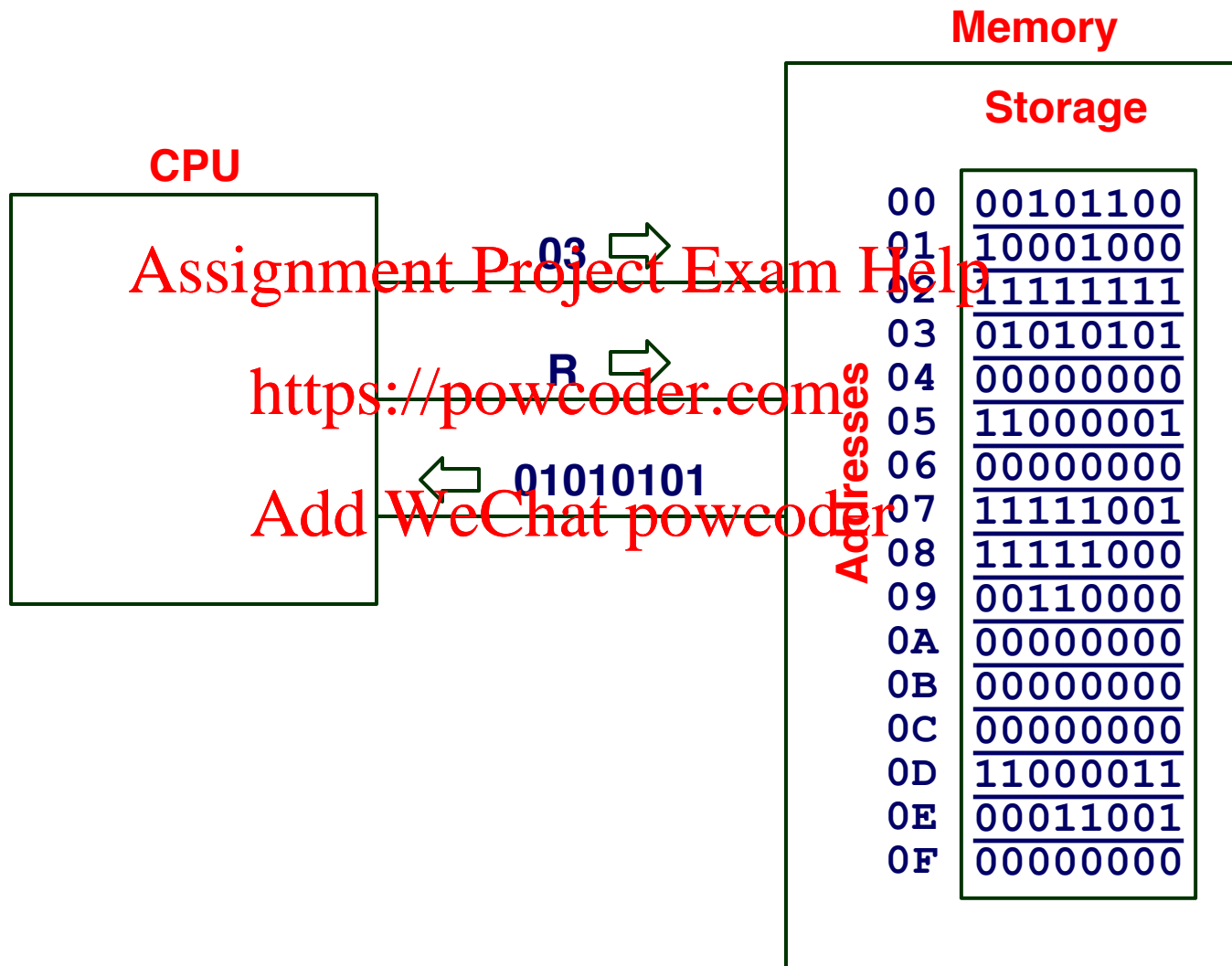
Assembly Programmer's View



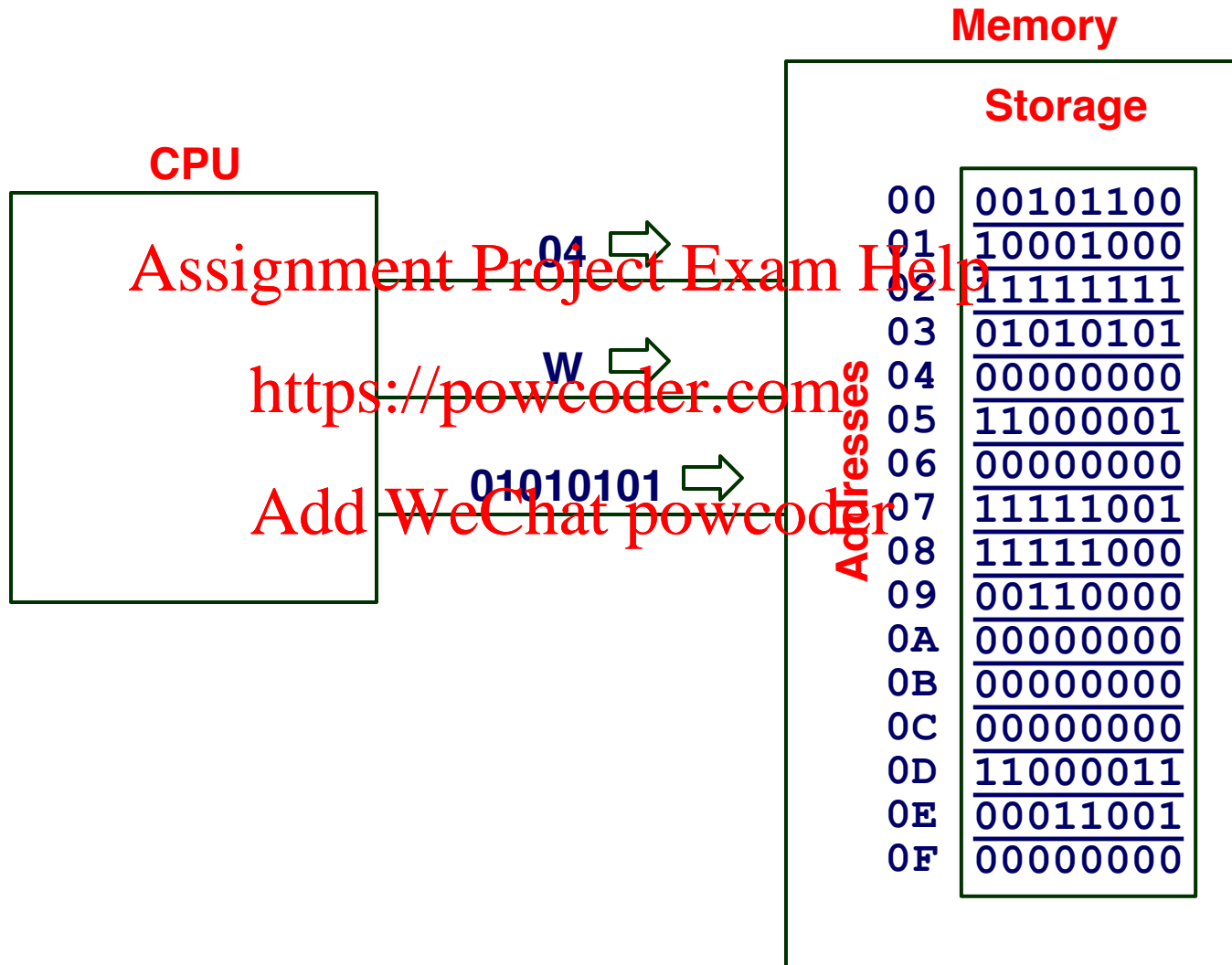
Memory



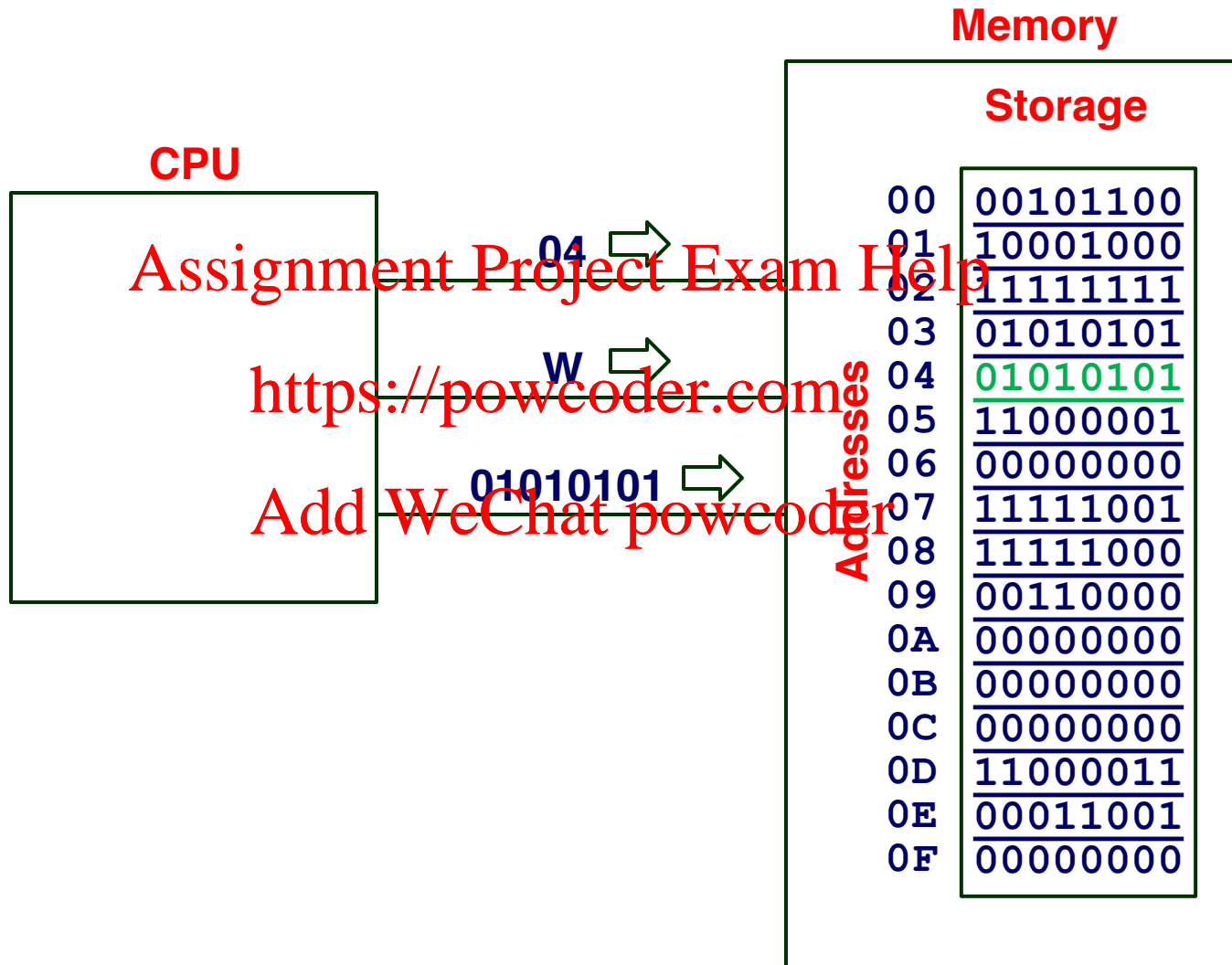
Memory Access: Read



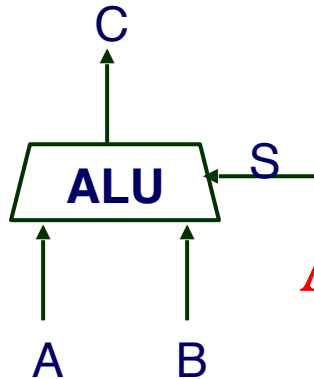
Memory Access: Write



Memory Access: Write



Processor: ALU & Registers



$$C = F_S(A, B)$$

F includes

Arithmetic: +, -, *, /, ~, etc.

Logical: &, |, ^, ~, etc.

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Multiple Ports



Command: R/W

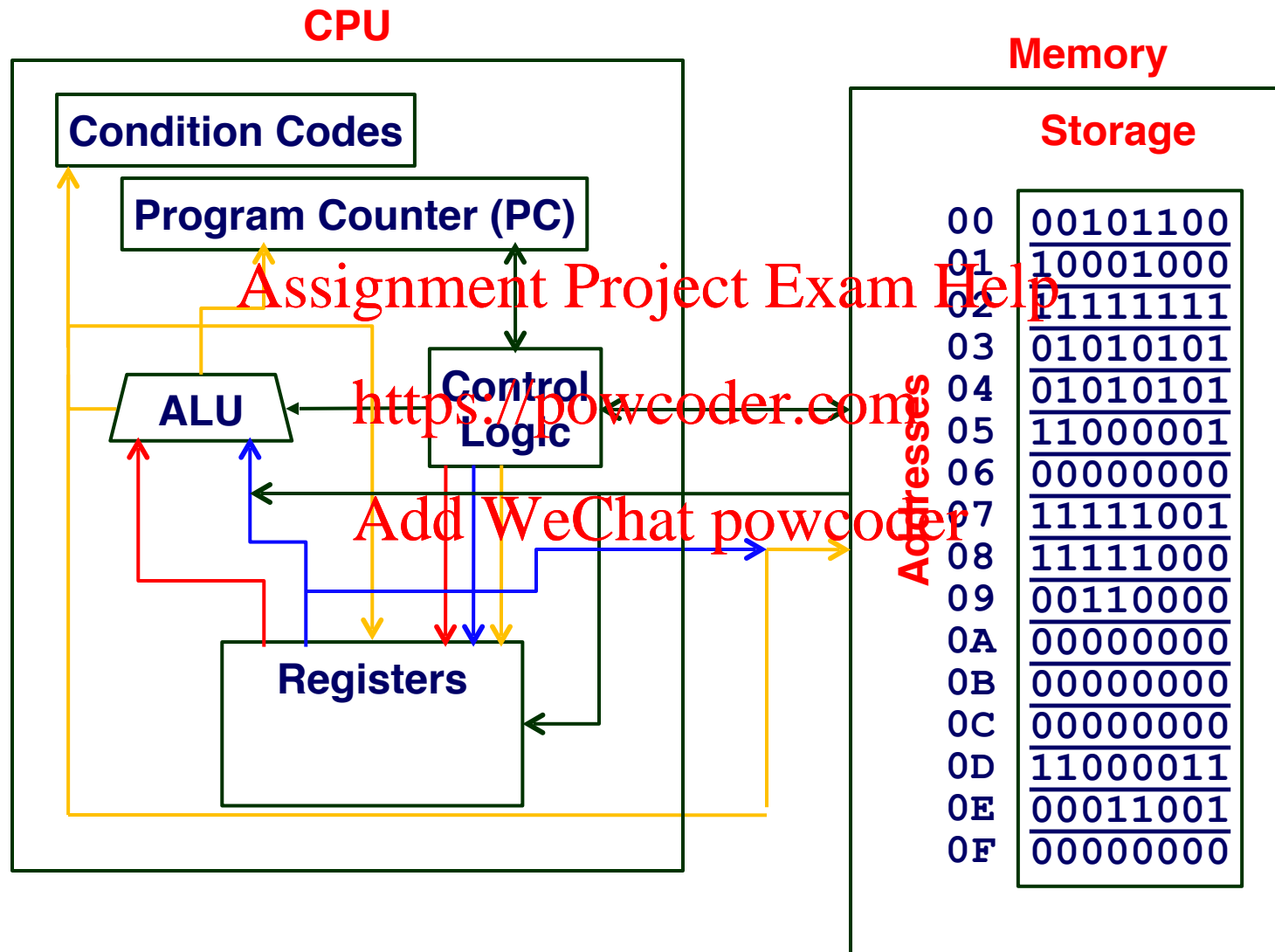
Data

Registers

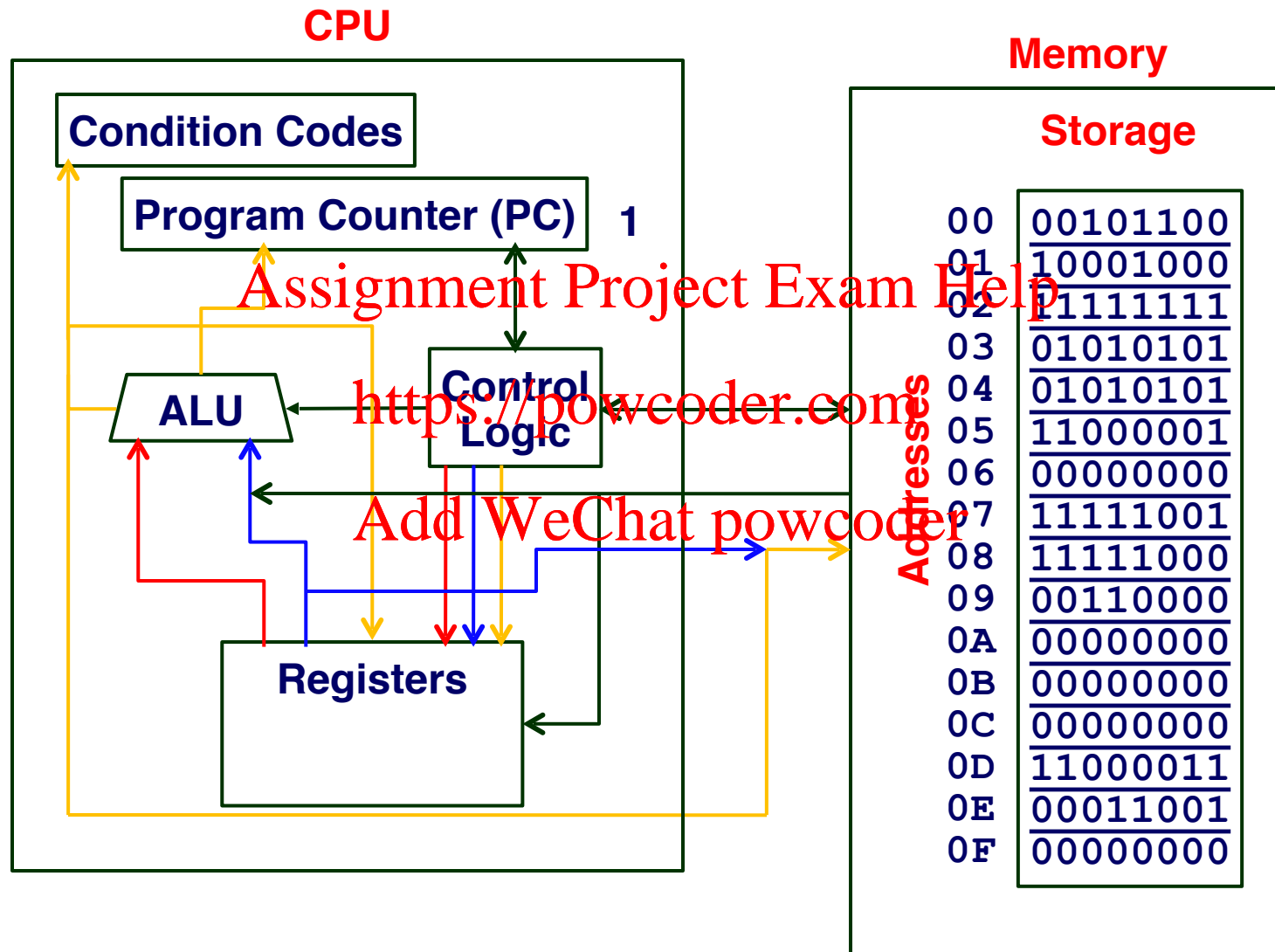
Name Storage

R0	00101100
R1	10001000
R2	11111111
R3	01010101

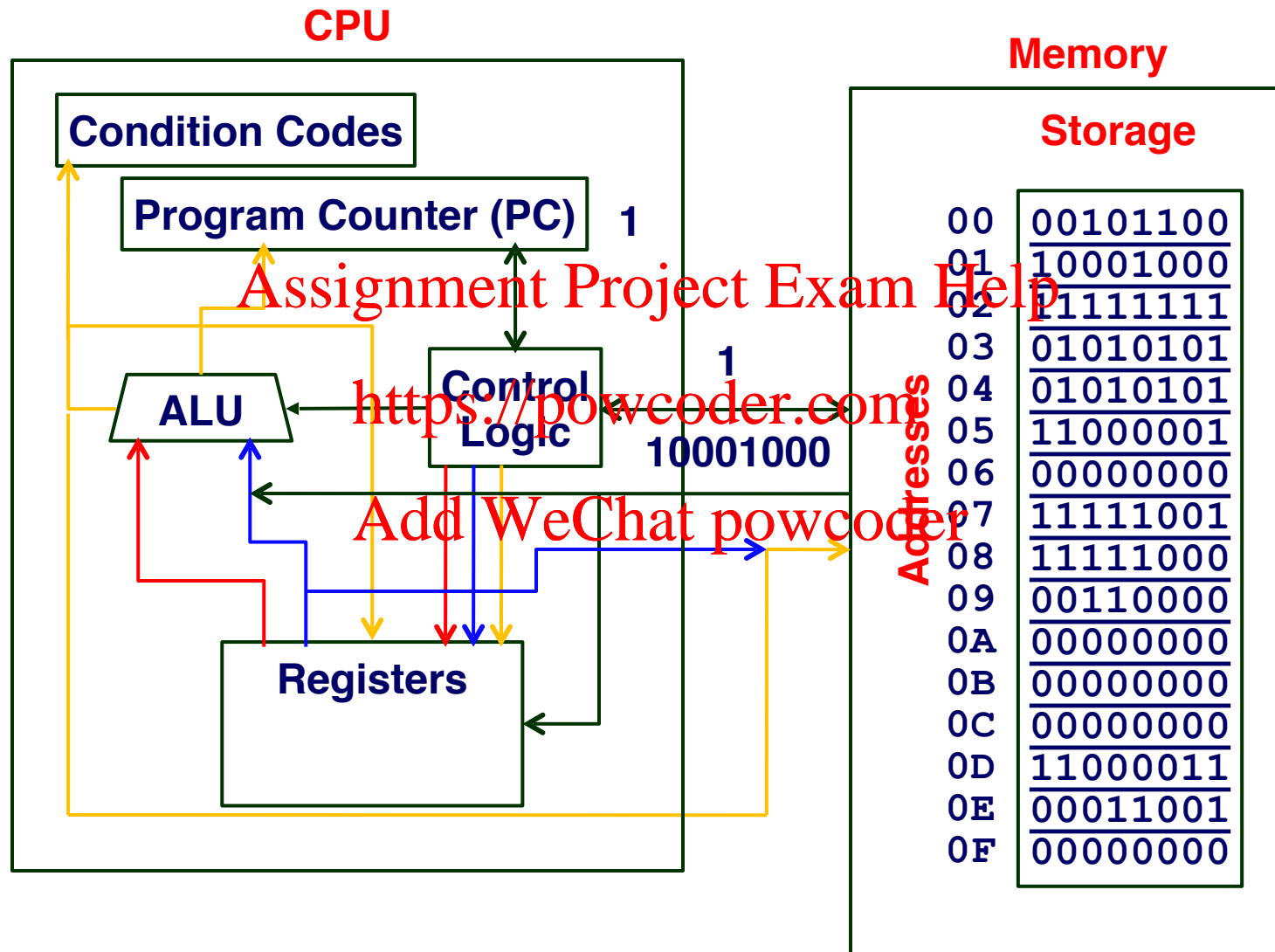
Putting It All Together



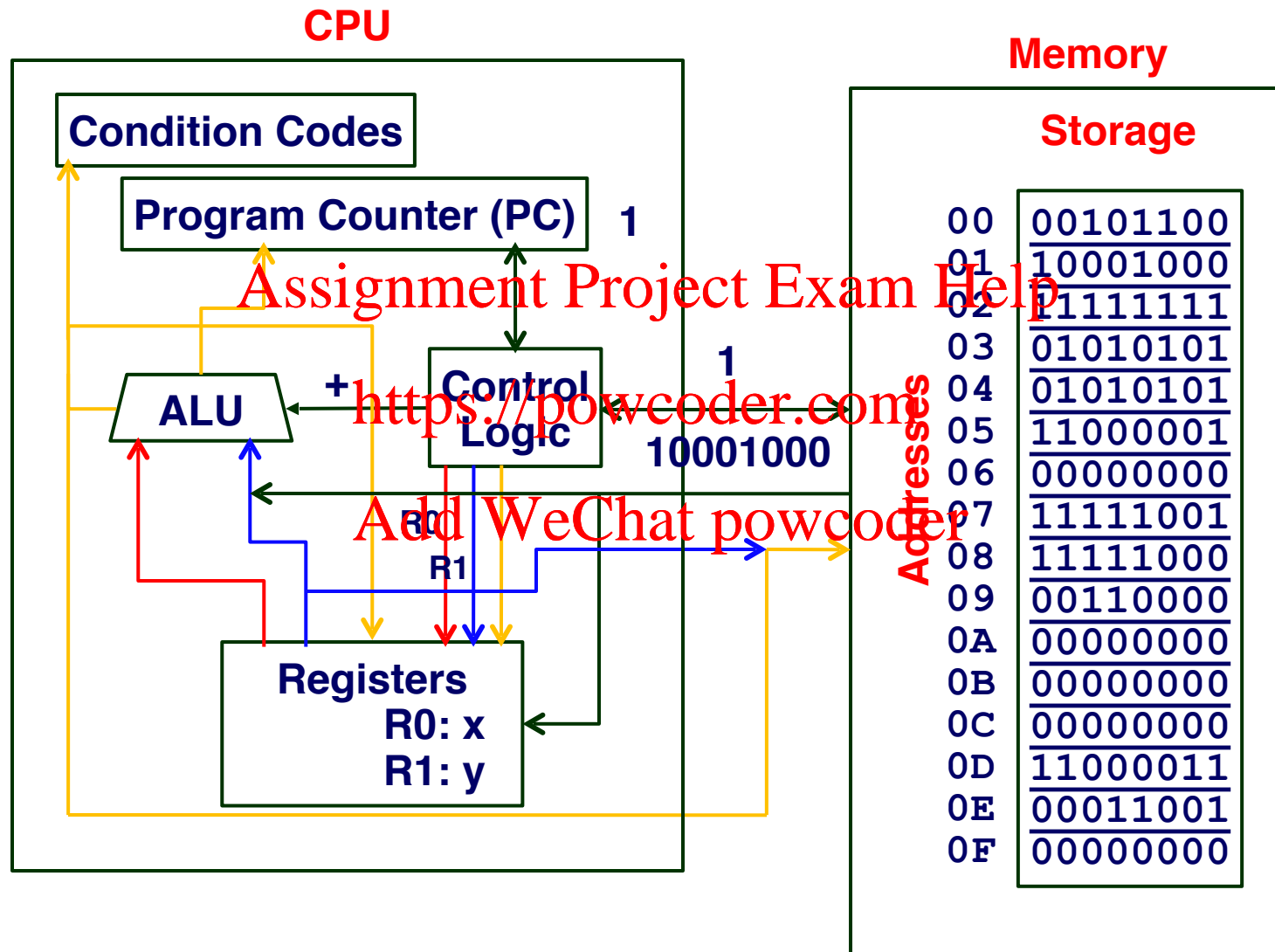
Putting It All Together



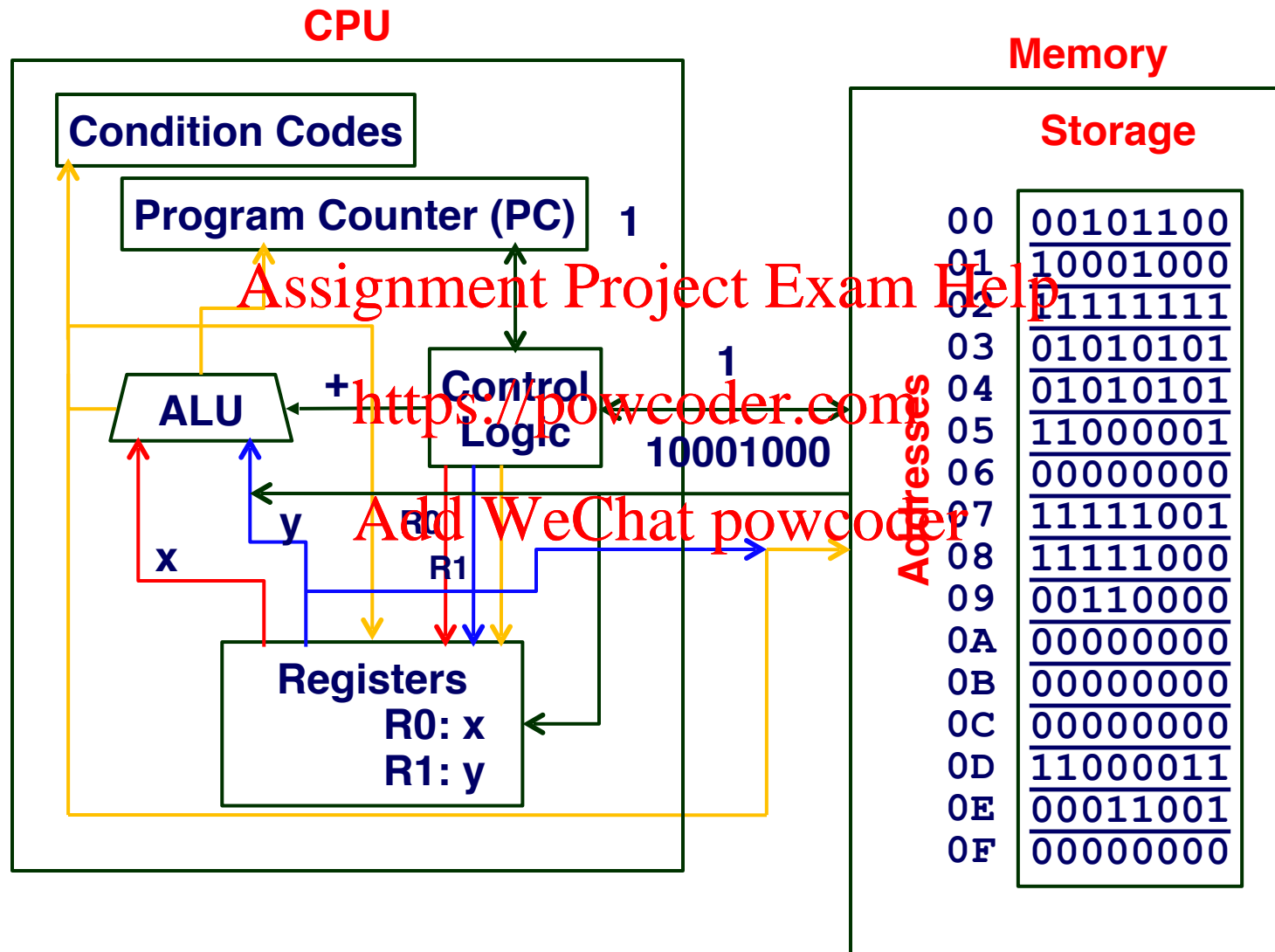
Putting It All Together



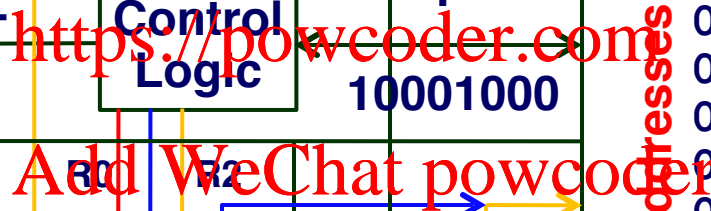
Putting It All Together



Putting It All Together



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C & Assembly Code

Sample C Code

```
int accum;  
int sum(int x, int y)  
{  
    int t = x + y;  
    accum += t;  
    return t;  
}
```

gcc -O1 -m32 -S code.c

Generated Assembly

sum:

```
push %ebp  
movl %esp, %ebp  
movl 12(%ebp), %eax  
addl 8(%ebp), %eax  
addl %eax, accum  
popl %ebp  
ret
```

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C & Machine Code

Sample C Code

```
int accum;

int sum(int x, int y){
    int t = x + y;
    accum += t;
    return t;
}
```

objdump -d code.o

00000000 <sum>:

```
0:      55                push    %ebp
1:      89 e5            mov     %esp,%ebp
3:      8b 45 0c         mov     0xc(%ebp),%eax
6:      03 45 08         add     0x8(%ebp),%eax
9:      03 00 00 00      add     %eax, accum
f:      5d                pop     %ebp
10:     c3                ret
```

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gcc -O1 -m32 -c code.c

gdb code.o

(gdb) x/100xb sum

<sum>: 0x55 0x89 0xe5 0x8b 0x45 0x0c 0x03 0x45

0x8 <sum+8>: 0x08 0x01 0x05 0x00 0x00 0x00 0x00 0x5d

0x10 <sum+16>: 0xc3 Cannot access memory at address 0x11

Assembly Characteristics

Sequence of simple instructions

Minimal Data Types

- “Integer” data of 1, 2, or 4 bytes
 - Data values
 - Addresses (untyped pointers)
- Floating point data of 4, 8, or 10 bytes
- No aggregate types such as arrays or structures
 - Just contiguously allocated bytes in memory

No type checking

- Interpretation of data format depends on instruction
- No protection against misinterpretation of data

Assembly Characteristics

3 types of Primitive Operations

- Perform arithmetic function on register or memory data
- Transfer data between memory and register
 - Load data from memory into register
 - Store register data into memory
- Transfer control
 - Unconditional jumps to/from procedures
 - Conditional branches

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x86 Characteristics

Variable length instructions: 1-15 bytes

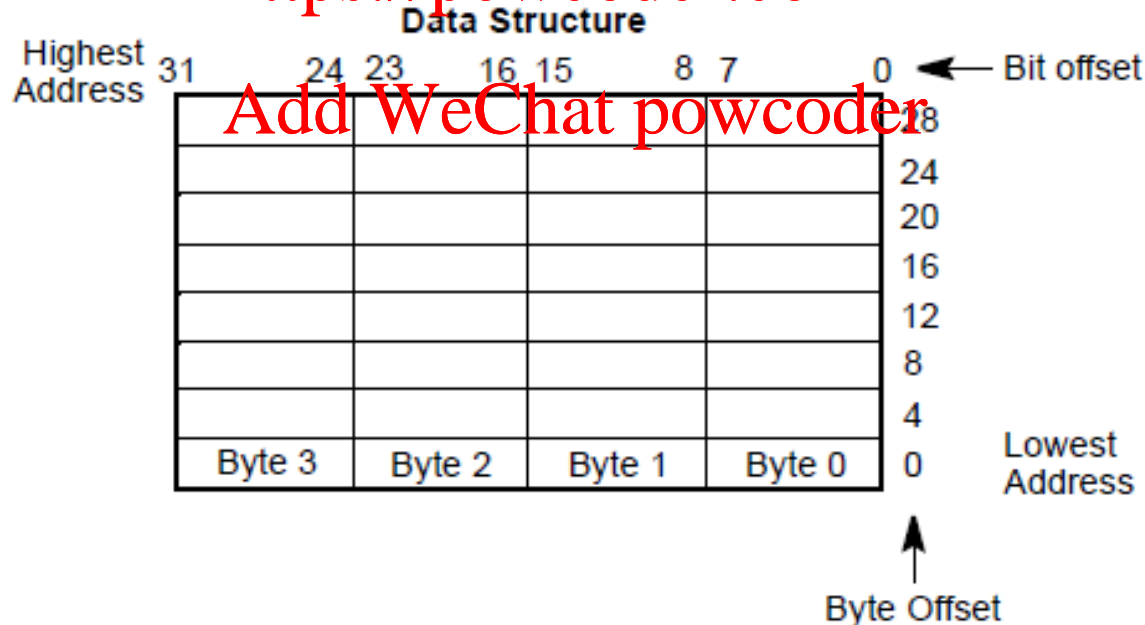
Can address memory directly in most instructions

Uses Little-Endian format (Least significant byte in the lowest address)

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Instruction Format

General format:

opcode operands

Opcode:

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- Short mnemonic for instruction's purpose

- `movb, addl, etc.`

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Operands:

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- Immediate, register, or memory
- Number of operands command-dependent

Example:

- `movl %ebx, (%ecx)`

Machine Representation

Remember, each assembly instruction translated to a sequence of 1-15 bytes



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First, the binary representation of the opcode

Second, instruction specifies the addressing mode

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- The type of operands (registers or register and memory)
- How to interpret the operands

Some instructions can be single-byte because operands and addressing mode are implicitly specified by the instruction

- E.g., pushl

x86 Registers

General purpose registers are 32 bit

- Although operations can access 8-bits or 16-bits portions

Originally categorized into two groups with different functionality

- Data registers (EAX, EBX, ECX, EDX)
 - Holds operands
- Pointer and Index registers (EBP, ESP, EIP,ESI,EDI)
 - Holds references to addresses as well as indexes

Now, the registers are mostly interchangeable

Segment registers

- Holds starting address of program segments
 - CS, DS, SS, ES

x86 Registers

← 16 BITS →
← 8 BITS →

EAX	AX	AH	AL
ECX	CX	CH	CL
EDX	DX	DH	DL
EBX	BX	BH	BL
ESP --Stack Pointer			
EBP --- Base register of current stack frame			
ESI --- Source index for string operations			
EDI --- Destination index for string operations			

← 32 BITS →

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x86 Programming

- Mov instructions to move data from/to memory
 - Operands and registers
- Addressing modes
- Understanding swap
- Arithmetic operations
- Condition codes
- Conditional and unconditional branches
- Loops and switch statements

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Data Format

Byte: 8 bits

- E.g., char

Word: 16 bits (2 bytes)

- E.g., short int

Double Word: 32 bits (4 bytes)

- E.g., int, float

Quad Word: 64 bits (8 bytes)

- E.g., double

Instructions can operate on any data size

- `movl, movw, movb`
 - Move double word, word, byte, respectively
- End character specifies what data size to be used

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MOV instruction

Most common instruction is data transfer instruction

- Mov SRC, DEST: Move source into destination
- SRC and DEST are operands
- DEST is a register or a location
- SRC can be the contents of register, memory location, constant, or a label.
- If you use gcc, you will see `movl <src>, <dest>`
- All the instructions in x86 are 32-bit

Used to copy data:

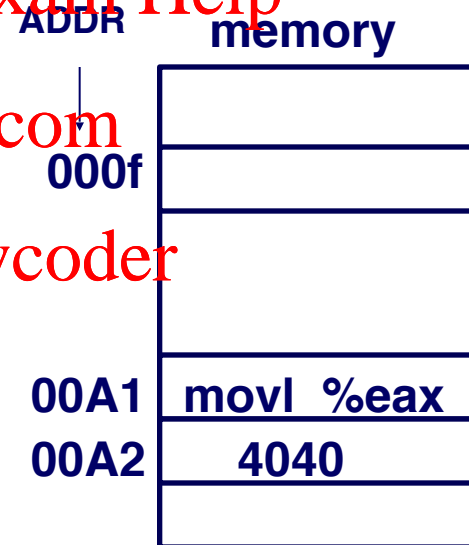
- Constant to register (immediate)
- Memory to register
- Register to memory
- Register to register

**Cannot copy memory to
memory in a single
instruction**

Immediate Addressing

Operand is immediate

- Operand value is found immediately following the instruction
- Encoded in 1, 2, or 4 bytes
- \$ in front of immediate operand
- E.g., `movl $0x4040, %eax`



Register Mode Addressing

Use % to denote register

- E.g., %eax

Source operand: use value in specified register

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Destination operand: use register as destination for value

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Examples:

- `movl %eax, %ebx`
 - Copy content of %eax to %ebx
- `movl $0x4040, %eax` → immediate addressing
 - Copy 0x4040 to %eax
- `movl %eax, 0x0000f` → Absolute addressing
 - Copy content of %eax to memory location 0x0000f

Indirect Mode Addressing

Content of operand is an address

- Designated as parenthesis around operand

Offset can be specified as immediate mode

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Examples:

- `movl (%ebp), %eax`
 - Copy value from memory location whose address is in ebp into eax
- `movl -4(%ebp), %eax`
 - Copy value from memory location whose address is -4 away from content of ebp into eax

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Indexed Mode Addressing

Add content of two registers to get address of operand

- `movl (%ebp, %esi), %eax`
 - Copy value at (address = $\text{ebp} + \text{esi}$) into `eax`
- `movl 8(%ebp, %esi), %eax`
 - Copy value at (address = $8 + \text{ebp} + \text{esi}$) into `eax`

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Useful for dealing with arrays

- If you need to walk through the elements of an array
- Use one register to hold base address, one to hold index
 - E.g., implement C array access in a for loop
- Index cannot be `ESP`

Scaled Indexed Mode Addressing

Multiply the second operand by the scale (1, 2, 4 or 8)

- `movl 0x80 (%ebx, %esi, 4), %eax`
 - Copy value at (address = $\text{ebx} + \text{esi} * 4 + 0x80$) into `eax`

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Where is it useful? <https://powcoder.com>

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Address Computation Examples

<code>%edx</code>	<code>0xf000</code>
-------------------	---------------------

<code>%ecx</code>	<code>0x100</code>
-------------------	--------------------

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Expression	Computation	Address
<code>0x8(%edx)</code>	<code>0xf000 + 0x8</code>	<code>0xf008</code>
<code>(%edx,%ecx)</code>	<code>0xf000 + 0x100</code>	<code>0xf100</code>
<code>(%edx,%ecx,4)</code>	<code>0xf000 + 4*0x100</code>	<code>0xf400</code>
<code>0x80(,%edx,2)</code>	<code>2*0xf000 + 0x80</code>	<code>0x1e080</code>

movl Operand Combinations

	Source	Destination	C Analog
--	--------	-------------	----------

movl	Imm	Reg	movl \$0x4,%eax	temp = 0x4;
		Mem	movl \$-147, (%eax)	*p = -147;
	Reg	Reg	movl %eax,%edx	temp2 = temp1;
		Mem	movl %eax, (%edx)	*p = temp;
	Mem	Reg	movl (%eax), %edx	temp = *p;

- Cannot do memory-memory transfers with single instruction

Stack Operations

By convention, `%esp` is used to maintain a stack in memory

- Used to support C function calls

`%esp` contains the address of top of stack

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Instructions to push (pop) content onto (off of) the stack

- `pushl %eax` <https://powcoder.com>
 - $\text{esp} = \text{esp} - 4$
 - $\text{Memory}[\text{esp}] = \text{eax}$
- `popl %ebx`
 - $\text{ebx} = \text{Memory}[\text{esp}]$
 - $\text{esp} = \text{esp} + 4$

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Where does the stack start? We'll discuss later

Using Simple Addressing Modes

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

swap:

```
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
```

} Set
Up

```
    movl 12(%ebp),%ecx
    movl 8(%ebp),%edx
    movl (%ecx),%eax
    movl (%edx),%ebx
    movl %eax, (%edx)
    movl %ebx, (%ecx)
```

} Body

```
    movl -4(%ebp),%ebx
    movl %ebp,%esp
    popl %ebp
    ret
```

} Finish

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Understanding Swap

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

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Register	Variable
%ecx	yp
%edx	xp
%eax	t1
%ebx	t0

```
movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
```

Offset

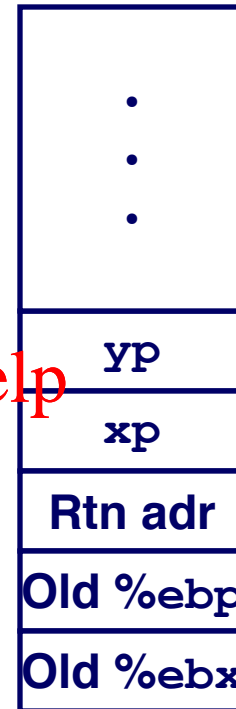
12

8

4

0

-4



Stack

← %ebp

Understanding Swap

%eax	
%edx	
%ecx	
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

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Offset

yp 12
xp 8
Rtn adr 4
%ebp → 0
-4

Address	
123	0x124
456	0x120
	0x11c
	0x118
	0x114
0x120	0x110
0x124	0x10c
Rtn adr	0x108
	0x104
	0x100

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

Understanding Swap

%eax	
%edx	
%ecx	0x120
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

Offset

yp 12
xp 8
Rtn adr 4
%ebp → 0
-4

123	0x124
456	0x120
	0x11c
	0x118
	0x114
0x120	0x110
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	0x104
	0x100

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```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

Understanding Swap

%eax	
%edx	0x124
%ecx	0x120
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

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Offset

yp 12
xp 8
Rtn adr 4
%ebp → 0
-4

Address

123	0x124
456	0x120
	0x11c
	0x118
	0x114
0x120	0x110
0x124	0x10c
Rtn adr	0x108
	0x104
	0x100

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

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Offset

yp 12
xp 8
Rtn adr 4
%ebp → 0
-4

Address	
0x124	123
0x120	456
0x11c	
0x118	
0x114	
0x110	0x120
0x10c	0x124
0x108	Rtn adr
0x104	
0x100	

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```


Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	123
%esi	
%edi	
%esp	
%ebp	0x104

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Offset

yp 12
xp 8
Rtn adr 4
%ebp → 0
-4

Address	
0x124	123
0x120	456
0x11c	
0x118	
0x114	
0x110	0x120
0x10c	0x124
0x108	Rtn adr
0x104	
0x100	

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	123
%esi	
%edi	
%esp	
%ebp	0x104

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Offset

yp 12
xp 8
Rtn adr 4
%ebp → 0
-4

Address	
0x124	456
0x120	456
0x11c	
0x118	
0x114	
0x110	0x120
0x10c	0x124
0x108	Rtn adr
0x104	
0x100	

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	123
%esi	
%edi	
%esp	
%ebp	0x104

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Offset

yp 12
xp 8
Rtn adr 4
%ebp → 0
-4

Address	
0x124	456
0x120	123
0x11c	
0x118	
0x114	
0x110	0x120
0x10c	0x124
0x108	Rtn adr
0x104	
0x100	

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

Swap in x86-64: 64-bit Registers

rax	eax
rcx	ecx
rdx	edx
rbx	ebx
rsp	esp
rbp	ebp
rsi	esi
rdi	edi

r8
r9
r10
r11
r12
r13
r14
r15

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Swap in x86-64 bit

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

swap:

```
movl (%rdi), %edx
movl (%rsi), %eax
movl %eax, (%rdi)
movl %edx, (%rsi)
retq
```

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Arguments passed in registers

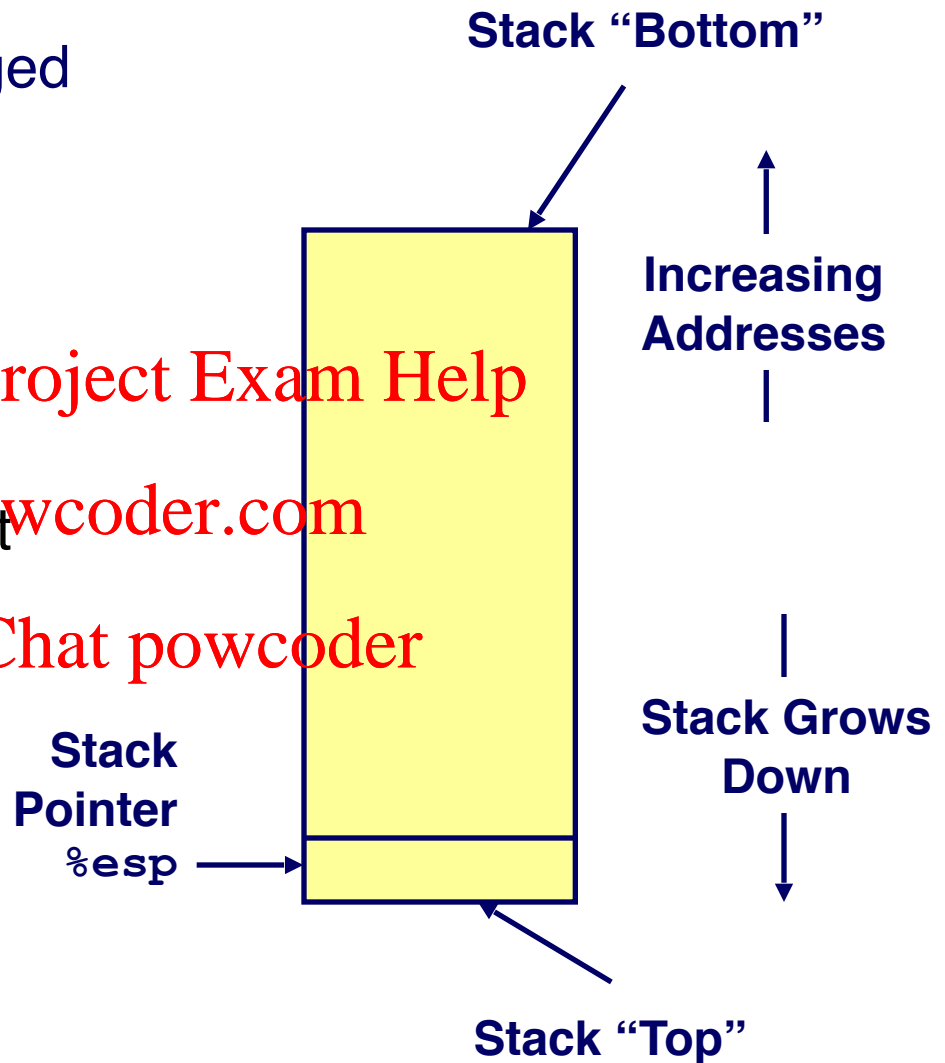
- First, xp in rdi and yp in rsi
- 64-bit pointers, data values are 32-bit ints, so uses eax/edx

No stack operations

What happens with long int?

IA32 Stack

- Region of memory managed with stack discipline
- Grows toward lower addresses
- Register `%esp` indicates lowest stack address
 - address of top element



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IA32 Stack Pushing

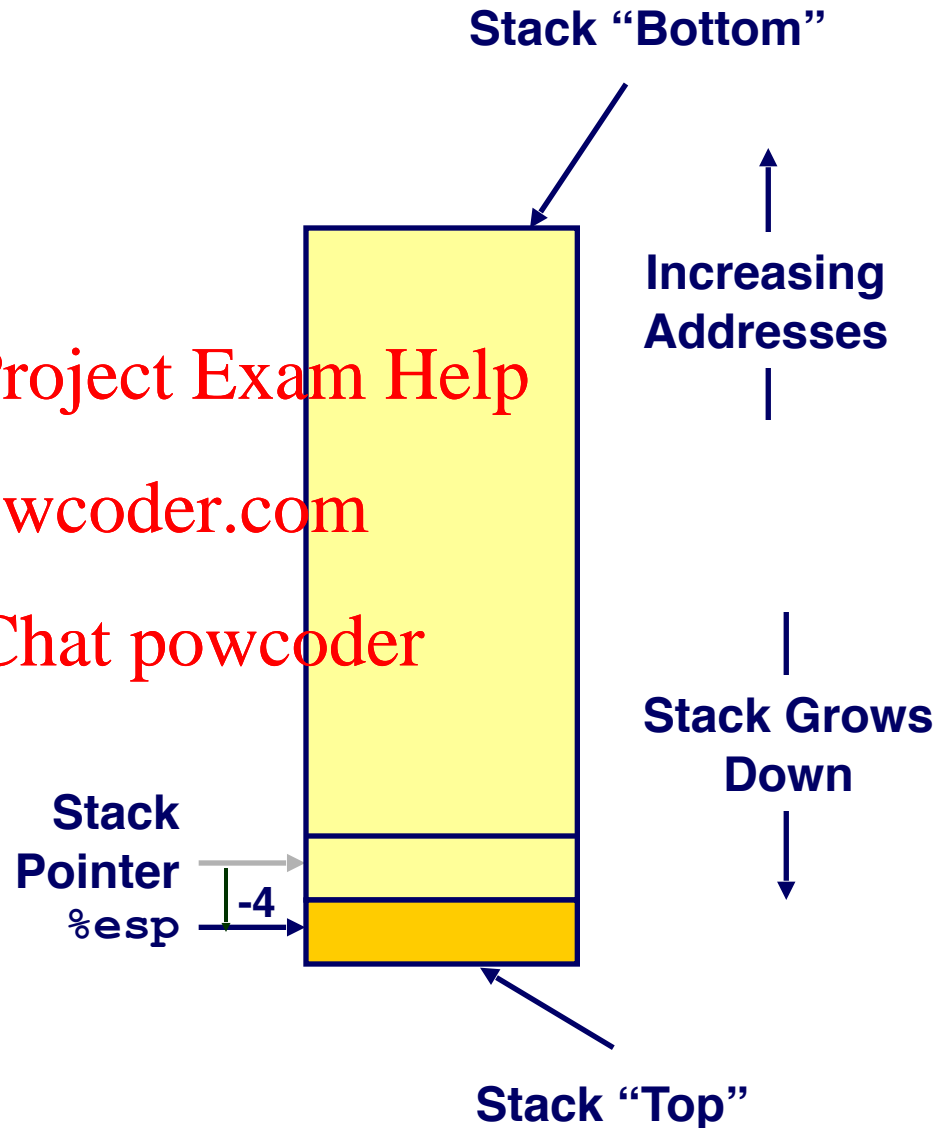
Pushing

- `pushl Src`
- Fetch operand at *Src*
- Decrement `%esp` by 4
- Write operand at address given by `%esp`

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IA32 Stack Popping

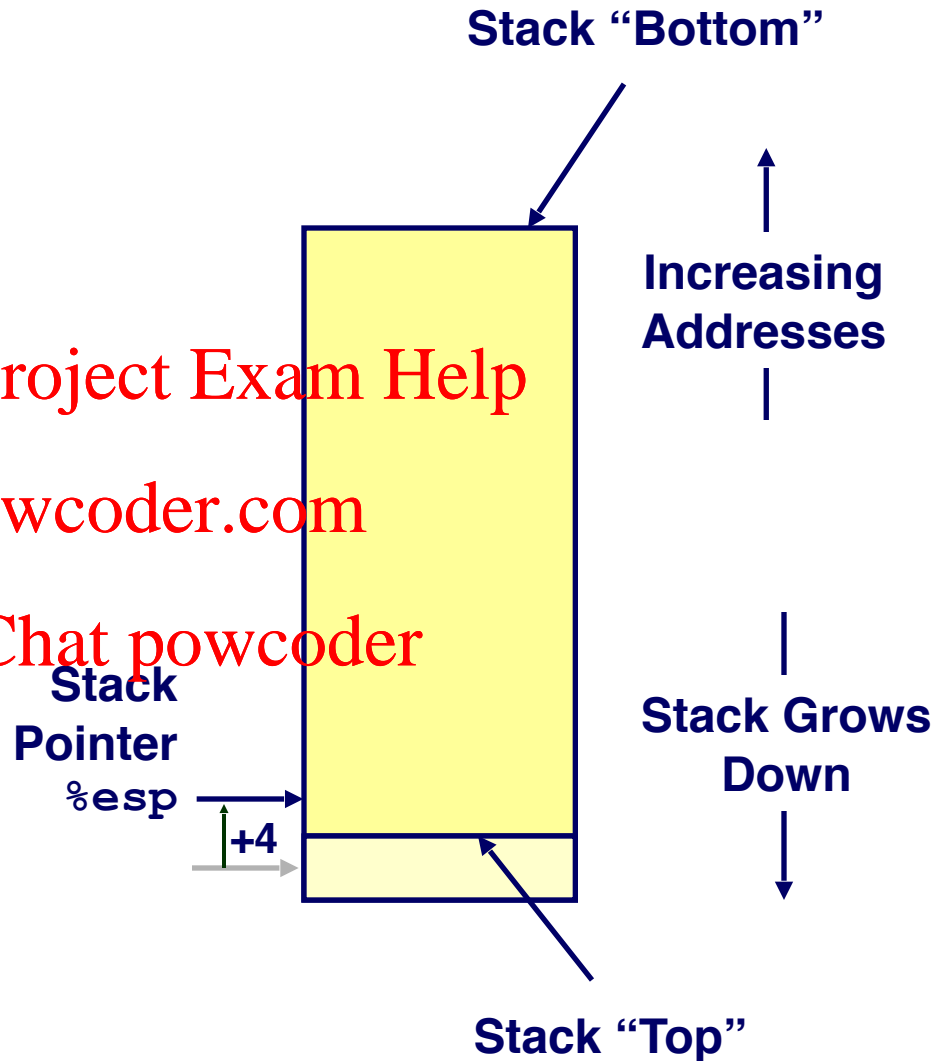
Popping

- `popl Dest`
- Read operand at address given by `%esp`
- Increment `%esp` by 4
- Write to `Dest`

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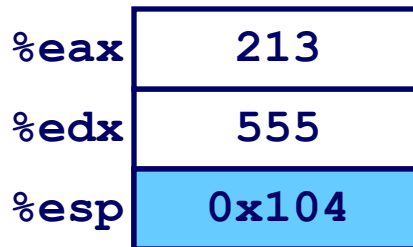
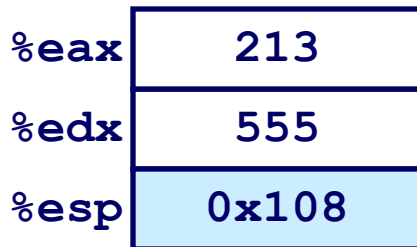
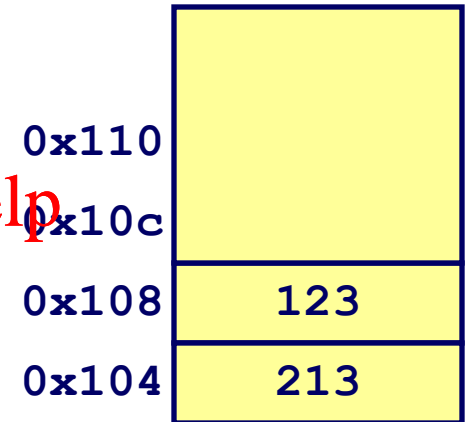
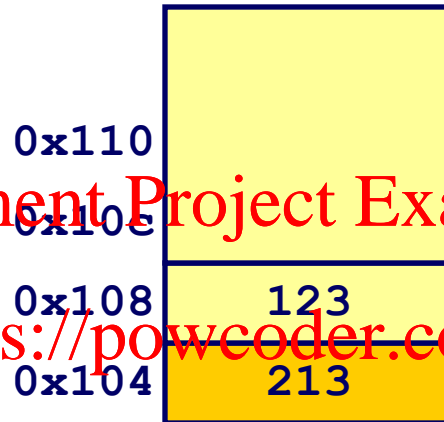
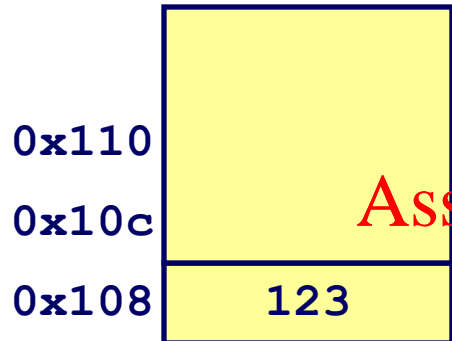
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Stack Operation Examples

`pushl %eax`

`popl %edx`



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Procedure Control Flow

- Use stack to support procedure call and return

Procedure call:

`call label` Push return address on stack; Jump to `label`

Return address value

- Address of instruction beyond `call`
- Example from disassembly

```
804854e: e8 3d 06 00 00      call 8048590 <main>
8048553: 50                 pushl %eax
```

- Return address = 0x8048553

Procedure return:

- `ret` Pop address from stack; Jump to address

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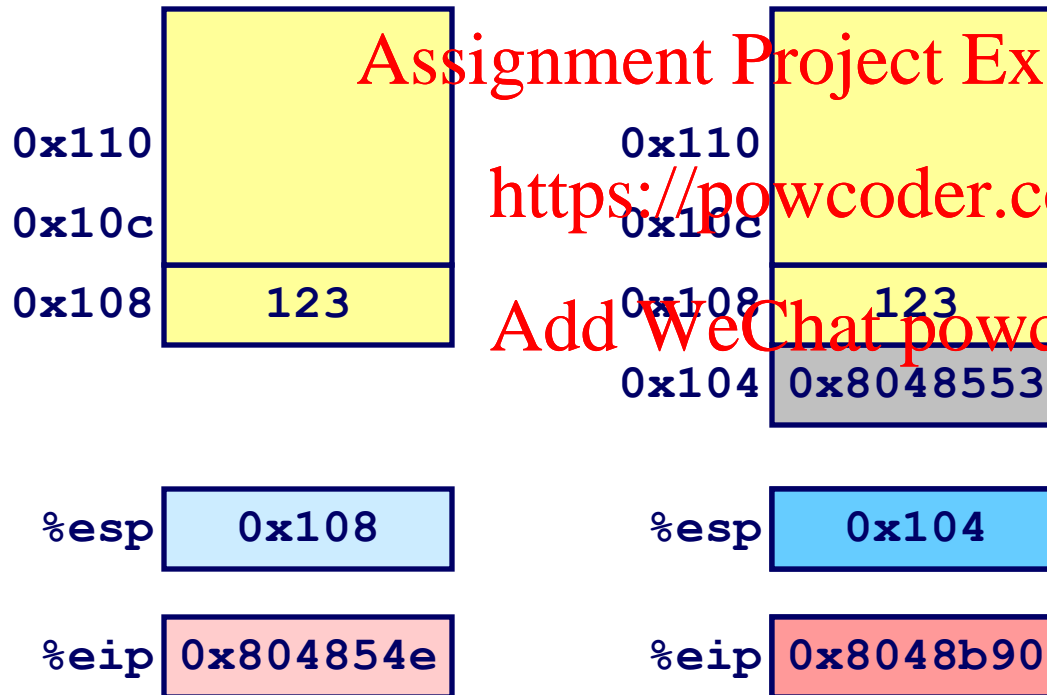
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Procedure Call Example

```
804854e: e8 3d 06 00 00    call    8048b90 <main>
8048553: 50                pushl   %eax
```

call 8048b90



%eip is program counter

Procedure Return Example

8048591: c3

ret

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0x110

0x10c

0x108

0x104

123

0x8048553

%esp

0x104

%eip

0x8048591

ret

0x110

0x10c

0x108

123

0x8048553

%esp

0x108

%eip

0x8048553

%eip is program counter

Address Computation Instruction

leal: compute address using addressing mode without accessing memory

leal src, dest

- src is address mode expression
- Set dest to address specified by src

Use

- Computing address without doing memory reference
 - E.g., translation of $p = \&x[i];$

Example:

- `leal 7(%edx, %edx, 4), %eax`
 - $eax = 4 * edx + edx + 7 = 5 * edx + 7$

Some Arithmetic Operations

Instruction	Computation
<code>addl Src, Dest</code>	$Dest = Dest + Src$
<code>subl Src, Dest</code>	$Dest = Dest - Src$
<code>imull Src, Dest</code>	$Dest = Dest * Src$
<code>sall Src, Dest</code>	$Dest = Dest \ll Src$ (left shift)
<code>sarl Src, Dest</code>	$Dest = Dest \gg Src$ (right shift)
<code>xorl Src, Dest</code>	$Dest = Dest \wedge Src$
<code>andl Src, Dest</code>	$Dest = Dest \& Src$
<code>orl Src, Dest</code>	$Dest = Dest Src$

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Some Arithmetic Operations

Instruction

Computation

`incl Dest`

$Dest = Dest + 1$

`decl Dest`

$Dest = Dest - 1$

`negl Dest`

$Dest = -Dest$

`notl Dest`

$Dest = \sim Dest$

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Using `leal` for Arithmetic Expressions

```
int arith
(int x, int y, int z)
{
    int t1 = x+y;
    int t2 = z+t1;
    int t3 = x+4;
    int t4 = y * 48;
    int t5 = t3 + t4;
    int rval = t2 * t5;
    return rval;
}
```

arith:

```
pushl %ebp
movl %esp,%ebp
```

} Set Up

```
movl 8(%ebp),%eax
movl 12(%ebp),%edx
leal (%edx,%eax),%ecx
leal (%edx,%edx,2),%edx
sal $4,%ecx
addl 16(%ebp),%ecx
leal 4(%edx,%eax),%eax
imull %ecx,%eax
```

} Body

```
movl %ebp,%esp
popl %ebp
ret
```

} Finish

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Understanding arith

```
int arith
  (int x, int y, int z)
{
  int t1 = x+y;
  int t2 = z+t1;
  int t3 = x+4;
  int t4 = y * 48;
  int t5 = t3 + t4;
  int rval = t2 * t5;
  return rval;
}
```

Offset

16

12

8

4

0

·
·
·

z

y

x

Rtn adr

Old %ebp

Stack

← %ebp

movl 8(%ebp), %eax	# eax = x
movl 12(%ebp), %edx	# edx = y
leal (%edx, %eax), %ecx	# ecx = x+y (t1)
leal (%edx, %edx, 2), %edx	# edx = 3*y
sall \$4, %edx	# edx = 48*y (t4)
addl 16(%ebp), %ecx	# ecx = z+t1 (t2)
leal 4(%edx, %eax), %eax	# eax = 4+t4+x (t5)
imull %ecx, %eax	# eax = t5*t2 (rval)

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Understanding arith

```
int arith
(int x, int y, int z)
{
    int t1 = x+y;
    int t2 = z+t1;
    int t3 = x+4;
    int t4 = y * 48;
    int t5 = t3 + t4;
    int rval = t2 * t5;
    return rval;
}
```

```
# eax = x
movl 8(%ebp),%eax
# edx = y
movl 12(%ebp),%edx
# ecx = x+y (t1)
leal (%edx,%eax),%ecx
# edx = 2*y
leal (%edx,%edx,2),%edx
# edx = 48*y (t4)
sall $4,%edx
# ecx = z+t1 (t2)
addl 16(%ebp),%ecx
# eax = 4+t4+x (t5)
leal 4(%edx,%eax),%eax
# eax = t5*t2 (rval)
imull %ecx,%eax
```

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Another Example

```
int logical(int x, int y)
{
    int t1 = x^y;
    int t2 = t1 >> 17;
    int mask = (1<<13) - 7;
    int rval = t2 & mask;
    return rval;
}
```

logical:

```
pushl %ebp
movl %esp,%ebp
```

} Set Up

```
movl 8(%ebp),%eax
xorl 12(%ebp),%eax
sarl $17,%eax
andl $8185,%eax
```

} Body

```
movl %ebp,%esp
popl %ebp
ret
```

} Finish

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$2^{13} = 8192, 2^{13} - 7 = 8185$

```
movl 8(%ebp),%eax
xorl 12(%ebp),%eax
sarl $17,%eax
andl $8185,%eax
```

```
eax = x
eax = x^y      (t1)
eax = t1>>17  (t2)
eax = t2 & 8185
```

Mystery Function

What does the following piece of code do?

- A. Add two variables
- B. Subtract two variables
- C. Swap two variables
- D. No idea

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```
movl 12(%ebp), %ecx
movl 8(%ebp), %edx
movl (%ecx), %eax
movl (%edx), %ebx
movl %eax, (%edx)
movl %ebx, (%ecx)
```

What does this function do?

```
.globl foo
.type   foo, @function
foo:
```

```
    pushl   %ebp
```

```
    movl    %esp, %ebp
```

```
    movl    16(%ebp), %eax
```

```
    imull   12(%ebp), %eax
```

```
    addl    8(%ebp), %eax
```

```
    popl    %ebp
```

```
    ret
```

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Control Flow/Conditionals

How do we represent conditionals in assembly?

A conditional branch can implement all control flow constructs in higher level language

- Examples: if/then, while, for

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A unconditional branch for constructs like break/ continue

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Condition Codes

Single Bit Registers

CF Carry Flag

SF Sign Flag

ZF Zero Flag

OF Overflow Flag

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Can be set either implicitly or explicitly.

- Implicitly by almost all logic and arithmetic operations
- Explicitly by specific comparison operations

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Not Set by `leal` instruction

- Intended for use in address computation only

Jumping

jX Instructions

- Jump to different part of code depending on condition codes

jX	Condition	Description
jmp	1	Unconditional
je	ZF	Equal / Zero
jne	$\sim ZF$	Not Equal / Not Zero
js	SF	Negative
jns	$\sim SF$	Nonnegative
jg	$\sim (SF \wedge OF) \ \& \ \sim ZF$	Greater (Signed)
jge	$\sim (SF \wedge OF)$	Greater or Equal (Signed)
jl	$(SF \wedge OF)$	Less (Signed)
jle	$(SF \wedge OF) \ \ ZF$	Less or Equal (Signed)
ja	$\sim CF \ \& \ \sim ZF$	Above (unsigned)
jb	CF	Below (unsigned)

Condition Codes

Implicitly Set By Arithmetic Operations

`addl Src, Dest`

C analog: `t = a + b`

- CF set if carry out from most significant bit

- Used to detect unsigned overflow

- ZF set if `t == 0`

- SF set if `t < 0`

- OF set if two's complement overflow

`(a > 0 && b > 0 && t < 0) || (a < 0 && b < 0 && t >= 0)`

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Setting Condition Codes (cont.)

Explicit Setting by Compare Instruction

`cmpl Src2,Src1`

- `cmpl b, a` like computing `a-b` without setting destination
- NOTE: The operands are reversed. Source of confusion

- CF set if carry out from most significant bit
 - Used for unsigned comparisons

- ZF set if `a == b`

- SF set if `(a-b) < 0`

- OF set if two's complement overflow

`(a>0 && b<0 && (a-b)<0) || (a<0 && b>0 && (a-b)>0)`

Setting Condition Codes (cont.)

Explicit Setting by Test instruction

`testl Src2,Src1`

- Sets condition codes based on value of *Src1* & *Src2*
 - Useful to have one of the operands be a mask
- `testl b,a` like computing `a&b` without setting destination
- ZF set when `a&b == 0`
- SF set when `a&b < 0`

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Conditional Branch Example

```

_max:
    pushl %ebp
    movl %esp, %ebp
    movl 8(%ebp), %edx
    movl 12(%ebp), %eax
    cmpl %eax, %edx
    jle L9
    movl %edx, %eax
L9:
    movl %ebp, %esp
    popl %ebp
    ret

```

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Set Up

Body

Finish

Conditional Branch Example

```
int max(int x, int y)
{
    if (x <= y)
        return y;
    else
        return x;
}
```

_max:

```
    pushl %ebp
    movl %esp,%ebp
```

} Set
Up

```
    movl 8(%ebp),%edx
    movl 12(%ebp),%eax
    cmpl %eax,%edx
    jle L9
    movl %edx,%eax
```

} Body

L9:

```
    movl %ebp,%esp
    popl %ebp
    ret
```

} Finish

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Conditional Branch Example (Cont.)

```
int goto_max(int x, int y)
{
    int rval = y;
    int ok = (x <= y);
    if (ok)
        goto done;
    rval = x;
done:
    return rval;
}
```

```
int max(int x, int y)
{
    if (x <= y)
        return y;
    else
        return x;
}
```

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- C allows “goto” as means of transferring control
- Closer to machine-level programming style
- Generally considered bad coding style

```
movl 8(%ebp),%edx    # edx = x
movl 12(%ebp),%eax   # eax = y
cmpl %eax,%edx       # x : y
jle L9               # if <= goto L9
movl %edx,%eax       # eax = x
L9:                  # Done: }
```

Skipped when $x \leq y$

Mystery Function

```
.LC0:
.string "%d"
.text
.globl foo
.type   foo, @function
foo:
    pushl   %ebp
    movl    %esp, %ebp
    subl    $40, %esp
    leal    -12(%ebp), %eax
    movl    %eax, 4(%esp)
    movl    $.LC0, (%esp)
    call    scanf
    cmpl    $4, -12(%ebp)
    je      .L3
    call    explode_bomb
.L3:
    leave
    .p2align 4,,3
    ret
```

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“Do-While” Loop Example

C Code

```
int fact_do(int x)
{
    int result = 1;
    do {
        result *= x;
        x = x-1;
    } while (x > 1);
    return result;
}
```

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“Do-While” Loop Example

C Code

```
int fact_do(int x)
{
    int result = 1;
    do {
        result *= x;
        x = x-1;
    } while (x > 1);
    return result;
}
```

Goto Version

```
int fact_goto(int x)
{
    int result = 1;
loop:
    result *= x;
    x = x-1;
    if (x > 1)
        goto loop;
    return result;
}
```

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- Use backward branch to continue looping
- Only take branch when “while” condition holds

“Do-While” Loop Compilation

Goto Version

```
int fact_goto(int x)
{
    int result = 1;
loop:
    result *= x;
    x = x-1;
    if (x > 1)
        goto loop;
    return result;
}
```

Assembly

```
_fact_goto:
    pushl %ebp                # Setup
    movl %esp,%ebp           # Setup
    movl $1,%eax              # eax = 1
    movl 8(%ebp),%edx          # edx = x

L11:
    imull %edx,%eax           # result *= x
    decl %edx                  # x--
    cmpl $1,%edx              # Compare x : 1
    jg L11                     # if > goto loop

    movl %ebp,%esp           # Finish
    popl %ebp                 # Finish
    ret                       # Finish
```

Registers

%edx x

%eax result

General “Do-While” Translation

C Code

```
do  
    Body  
while (Test) ;
```

Goto Version

```
loop:  
    Body  
    if (Test)  
        goto loop
```

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- *Body* can be any C statement
 - Typically compound statement.

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```
{  
    Statement1;  
    Statement2;  
    ...  
    Statementn;  
}
```

- *Test* is expression returning integer
= 0 interpreted as false ≠ 0 interpreted as true

“While” Loop Example #1

C Code

```
int fact_while(int x)
{
    int result = 1;
    while (x > 1) {
        result *= x;
        x = x-1;
    };
    return result;
}
```

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Actual “While” Loop Translation

C Code

```
int fact_while(int x)
{
    int result = 1;
    while (x > 1) {
        result *= x;
        x = x-1;
    };
    return result;
}
```

Goto Version

```
int fact_while_goto2
(int x)
{
    int result = 1;
    if (!(x > 1))
        goto done;
loop:
    result *= x;
    x = x-1;
    if (x > 1)
        goto loop;
done:
    return result;
}
```

- Uses same inner loop as do-while version
- Guards loop entry with extra test

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General “While” Translation

C Code

```
while (Test)  
    Body
```

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Do-While Version

```
if (!Test)  
    goto done;  
do  
    Body  
    while(Test) ;  
done:
```

Goto Version

```
if (!Test)  
    goto done;  
loop:  
    Body  
    if (Test)  
        goto loop;  
done:
```

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Switch Statements

Implementation Options

- Series of conditionals
 - Good if few cases
 - Slow if many
- Jump Table
 - Lookup branch target
 - Avoids conditionals
 - Possible when cases are small integer constants
- GCC
 - Picks one based on case structure
- Bug in example code
 - No default given

```
typedef enum
{ADD, MULT, MINUS, DIV, MOD, BAD}
  op_type;

char unparse_symbol(op_type op)
{
    switch (op) {
    case ADD :
        return '+';
    case MULT:
        return '*';
    case MINUS:
        return '-';
    case DIV:
        return '/';
    case MOD:
        return '%';
    case BAD:
        return '?';
    }
}
```

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Jump Table Structure

Switch Form

```
switch (op) {  
  case val_0:  
    Block 0  
  case val_1:  
    Block 1  
    . . .  
  case val_n-1:  
    Block n-1  
}
```

Jump Table

jtab:	Targ0
	Targ1
	Targ2
	•
	•
	•
	Targn-1

Jump Targets

Targ0: **Code Block 0**

Targ1: **Code Block 1**

Targ2: **Code Block 2**

•
•
•

Targn-1: **Code Block n-1**

Approx. Translation

```
target = JTab[op];  
goto *target;
```

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Switch Statement Example

Branching Possibilities

```
typedef enum
{ADD, MULT, MINUS, DIV, MOD, BAD}
  op_type;

char unparse_symbol(op_type op)
{
    switch (op) {
        . . .
    }
}
```

Enumerated Values

ADD	0
MULT	1
MINUS	2
DIV	3
MOD	4
BAD	5

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Setup:

```
unparse_symbol:
    pushl %ebp                # Setup
    movl %esp,%ebp           # Setup
    movl 8(%ebp),%eax          # eax = op
    cmpl $5,%eax              # Compare op : 5
    ja .L49                   # If > goto done
    jmp *.L57(,%eax,4)         # goto Table[op]
```

Assembly Setup Explanation

Table Structure

- Each target requires 4 bytes
- Base address at `.L57`

Jumping

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```
jmp .L49
```

- Jump target is denoted by label `.L49`

```
jmp *.L57(,%eax,4)
```

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- Start of jump table denoted by label `.L57`
- Register `%eax` holds `op`
- Must scale by factor of 4 to get offset into table
- Fetch target from effective Address $.L57 + op * 4$

Jump Table

Table Contents

```
.section .rodata
    .align 4
.L57:
    .long .L51 #Op = 0
    .long .L52 #Op = 1
    .long .L53 #Op = 2
    .long .L54 #Op = 3
    .long .L55 #Op = 4
    .long .L56 #Op = 5
```

Targets & Completion

```
.L51:
    movl $43,%eax # '+'
    jmp .L49
.L52:
    movl $42,%eax # '*'
    jmp .L49
.L53:
    movl $45,%eax # '-'
    jmp .L49
.L54:
    movl $47,%eax # '/'
    jmp .L49
.L55:
    movl $37,%eax # '%'
    jmp .L49
.L56:
    movl $63,%eax # '?'
    # Fall Through to .L49
```

Enumerated Values

ADD	0
MULT	1
MINUS	2
DIV	3
MOD	4
BAD	5

Switch Statement Completion

<code>.L49:</code>	<code># Done:</code>
<code>movl %ebp,%esp</code>	<code># Finish</code>
<code>popl %ebp</code>	<code># Finish</code>
<code>ret</code>	<code># Finish</code>

Puzzle

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- What value returned when `op` is invalid?

<https://powcoder.com>

Answer

- Register `%eax` set to `op` at beginning of procedure
- This becomes the returned value

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Advantage of Jump Table

- Can do k -way branch in $O(1)$ operations

Reading Condition Codes

SetX Instructions

- Set single byte based on combinations of condition codes

SetX	Condition	Description
sete	ZF	Equal / Zero
setne	$\sim ZF$	Not Equal / Not Zero
sets	SF	Negative
setns	$\sim SF$	Nonnegative
setg	$\sim (SF \wedge OF) \ \& \ \sim ZF$	Greater (Signed)
setge	$\sim (SF \wedge OF)$	Greater or Equal (Signed)
setl	$(SF \wedge OF)$	Less (Signed)
setle	$(SF \wedge OF) \mid ZF$	Less or Equal (Signed)
seta	$\sim CF \ \& \ \sim ZF$	Above (unsigned)
setb	CF	Below (unsigned)

Reading Condition Codes (Cont.)

SetX Instructions

- Set single byte based on combinations of condition codes
- One of 8 addressable byte registers
 - Embedded within first 4 integer registers
 - Does not alter remaining 3 bytes
 - Typically use `movzbl` to finish job

```
int gt (int x, int y) {
    return x > y;
}
```

Body

```
movl 12(%ebp),%eax    # eax = y
cmpl %eax,8(%ebp)     # Compare x : y
setg %al              # al = x > y
movzbl %al,%eax       # Zero rest of %eax
```

%eax	%ah	%al
%edx	%dh	%dl
%ecx	%ch	%cl
%ebx	%bh	%bl
%esi		
%edi		
%esp		
%ebp		

Note
inverted
ordering!

Can you write the C code for this assembly?

```
.globl test
```

```
.type test, @function
```

```
test:
```

What does this function do?

```
    pushl %ebp
```

```
    movl  %esp, %ebp
```

```
    pushl %ebx
```

```
    movl  8(%ebp), %edx
```

```
    movl  12(%ebp), %ecx
```

```
    movl  $1, %eax
```

```
    cmpl  %ecx, %edx
```

```
    jge   .L3
```

What is the C code?

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```
.L6:
```

```
    leal  (%edx,%ecx), %ebx
```

```
    imull %ebx, %eax
```

```
    addl  $1, %edx
```

```
    cmpl  %edx, %ecx
```

```
    jg    .L6
```

```
.L3:
```

```
    popl  %ebx
```

```
    popl  %ebp
```

```
    ret
```

Stack-Based Languages

Languages that Support Recursion

- e.g., C, Pascal, Java
- Code must be “*Reentrant*”
 - Multiple simultaneous instantiations of single procedure
- Need some place to store state of each instantiation
 - Arguments, local variables, return pointer

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Stack Discipline

- State for given procedure needed for limited time
 - From when called to when return
- Callee returns before caller does

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Stack Allocated in *Frames* (*Activation records*)

- state for single procedure instantiation

Call Chain Example

Code Structure

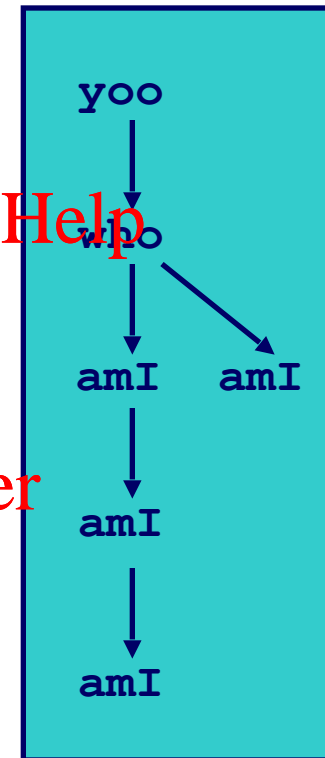
```
yoo (...)  
{  
    .  
    .  
    who () ;  
    .  
    .  
}
```

```
who (...)  
{  
    . . .  
    amI () ;  
    . . .  
    amI () ;  
    . . .  
}
```

```
amI (...)  
{  
    .  
    .  
    amI () ;  
    .  
    .  
}
```

- Procedure `amI` recursive

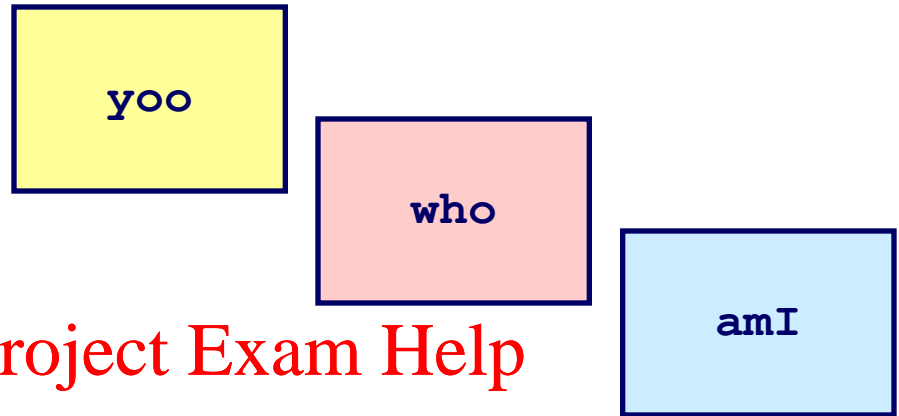
Call Chain



Stack Frames

Contents

- Local variables, return value
- Temporary space

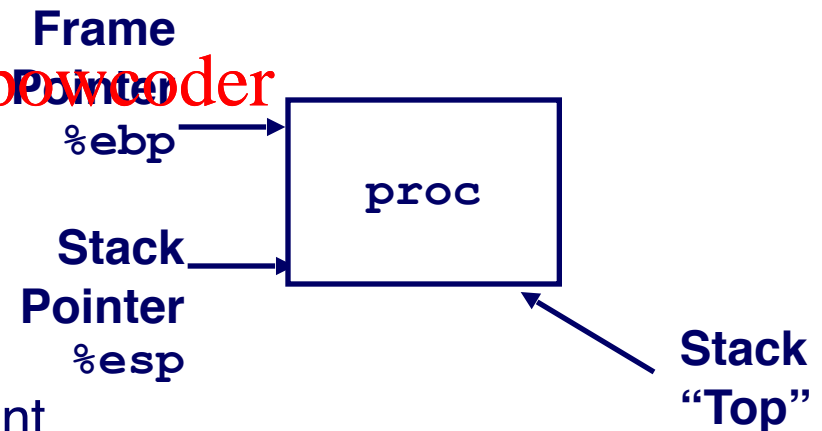


Management

- Space allocated when enter procedure
 - “Set-up” code
- Deallocated when return
 - “Finish” code

Pointers

- Stack pointer `%esp` : stack top
- Frame pointer `%ebp` : start of current frame



Stack Operation

Call Chain



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Stack Operation

Call Chain



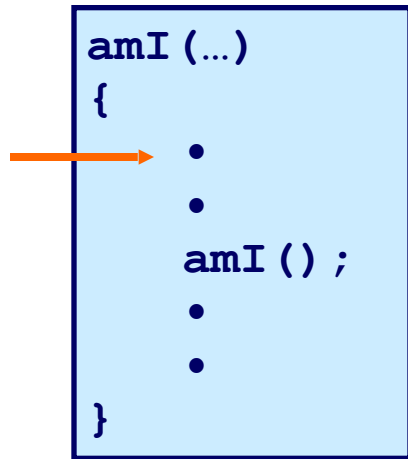
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Stack Operation

Call Chain



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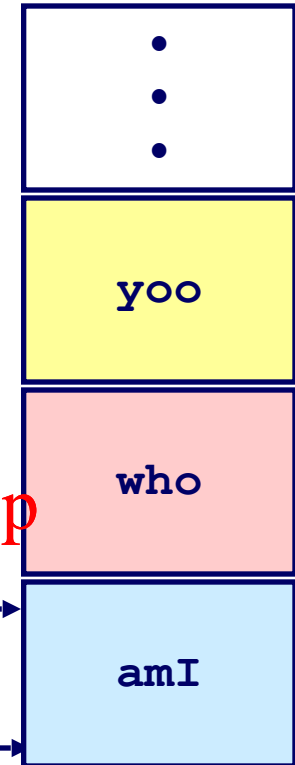
yoo

who

amI

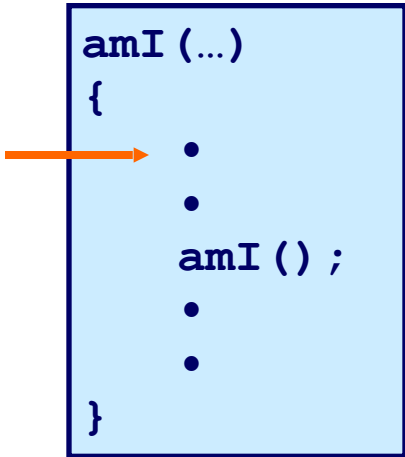
Frame
Pointer
%ebp

Stack
Pointer
%esp



Stack Operation

Call Chain



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yoo

who

amI

amI

Frame

Pointer

%ebp

Stack

Pointer

%esp

•
•
•

yoo

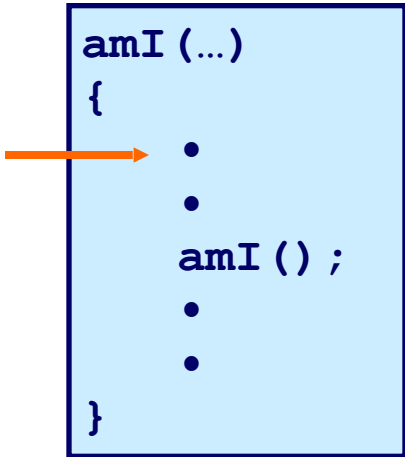
who

amI

amI

Stack Operation

Call Chain



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yoo

who

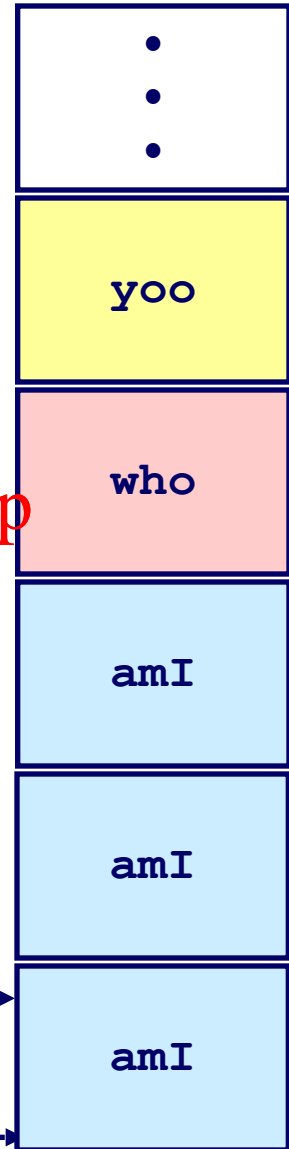
amI

amI

amI

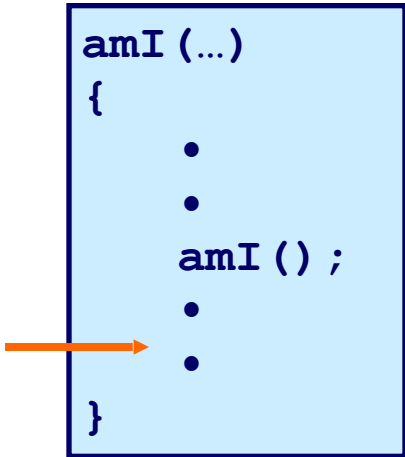
Frame
Pointer
%ebp

Stack
Pointer
%esp



Stack Operation

Call Chain



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yoo

who

amI

amI

amI

Frame

Pointer

%ebp

Stack

Pointer

%esp

•
•
•

yoo

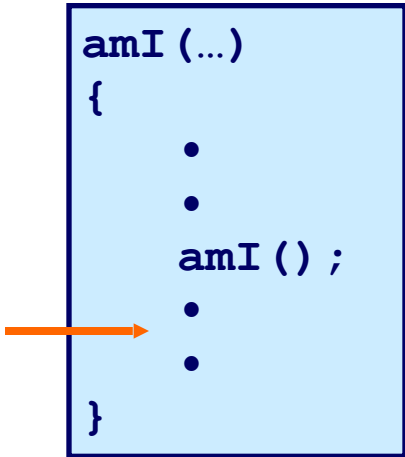
who

amI

amI

Stack Operation

Call Chain



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yoo

who

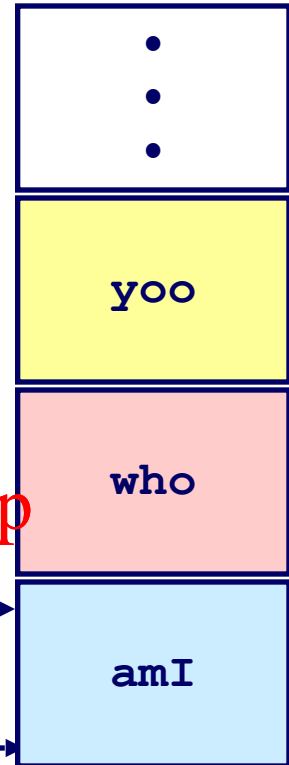
amI

amI

amI

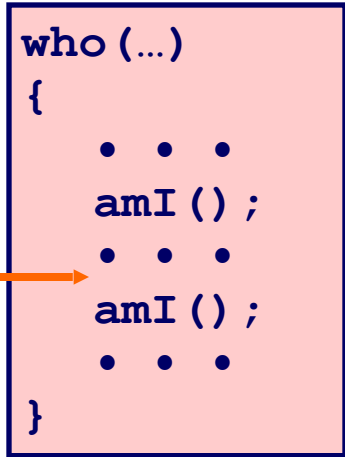
Frame
Pointer
`%ebp`

Stack
Pointer
`%esp`



Stack Operation

Call Chain



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yoo

who

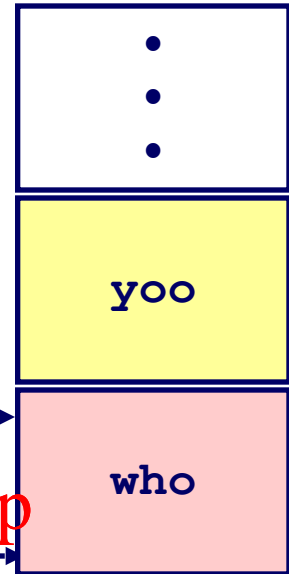
amI

amI

amI

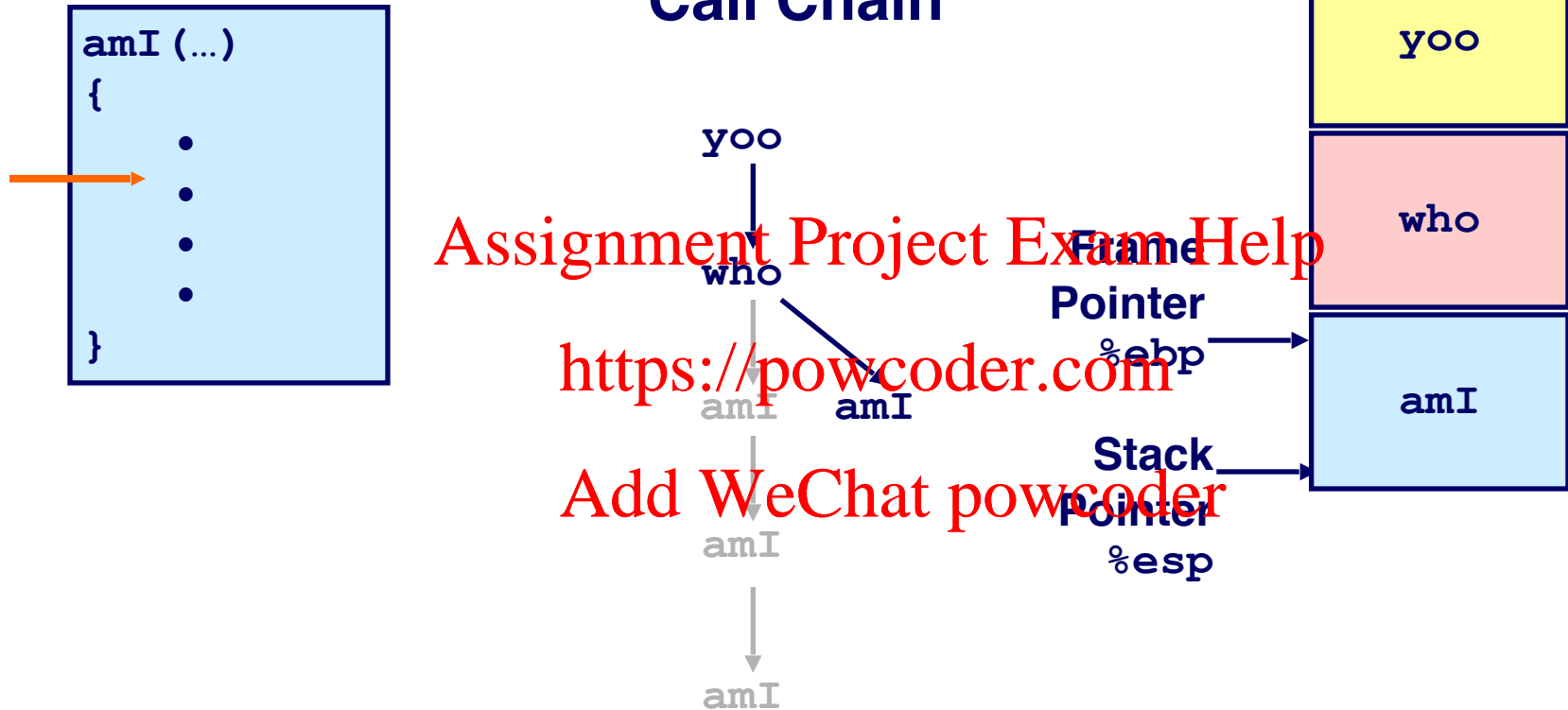
Frame
Pointer
`%ebp`

Stack
Pointer
`%esp`



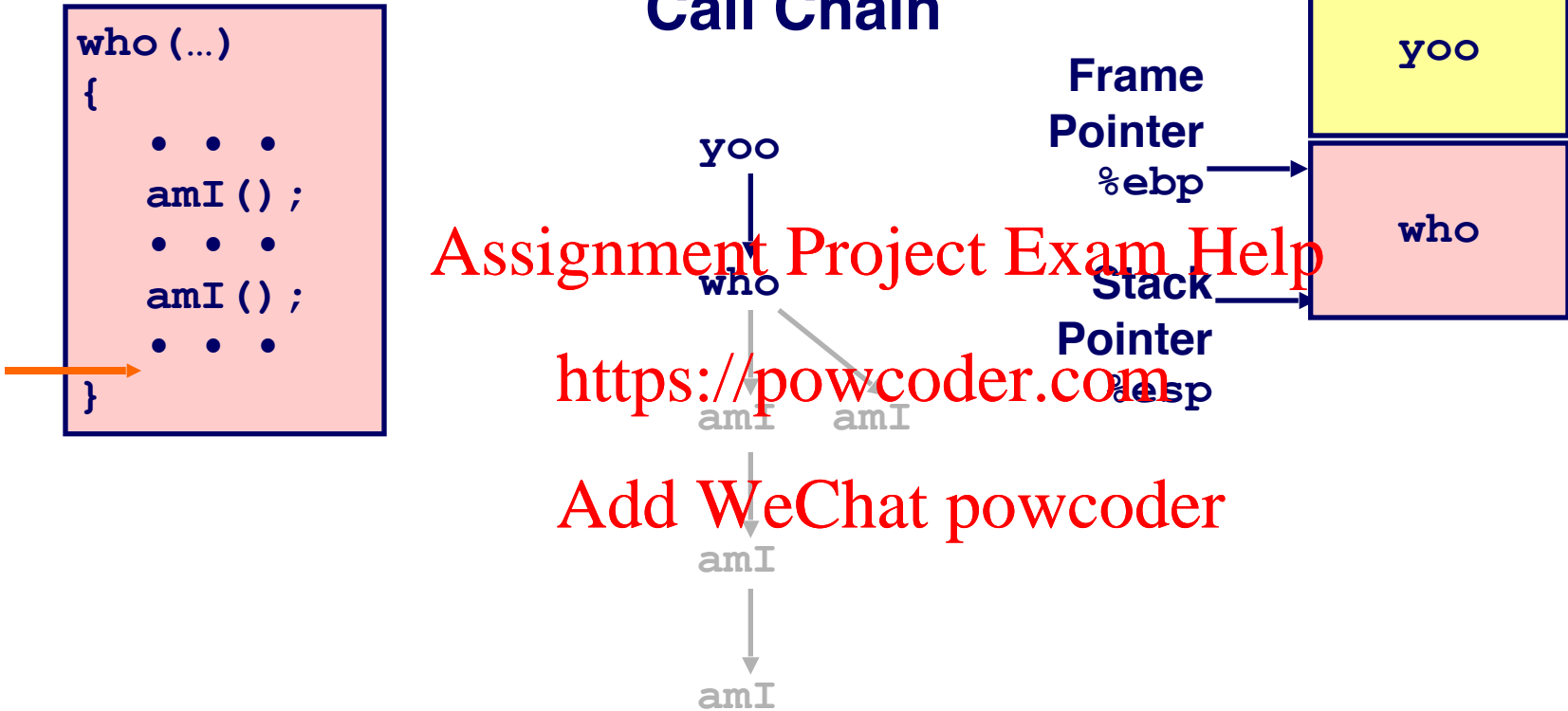
Stack Operation

Call Chain



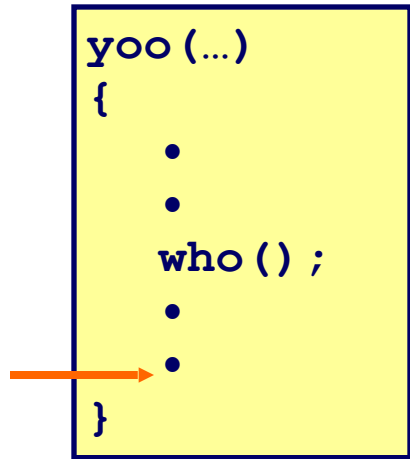
Stack Operation

Call Chain



Stack Operation

Call Chain



Frame

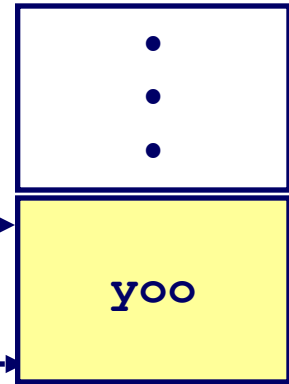
Pointer

`%ebp`

Stack

Pointer

`%esp`



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yoo

who

amI

amI

amI

amI

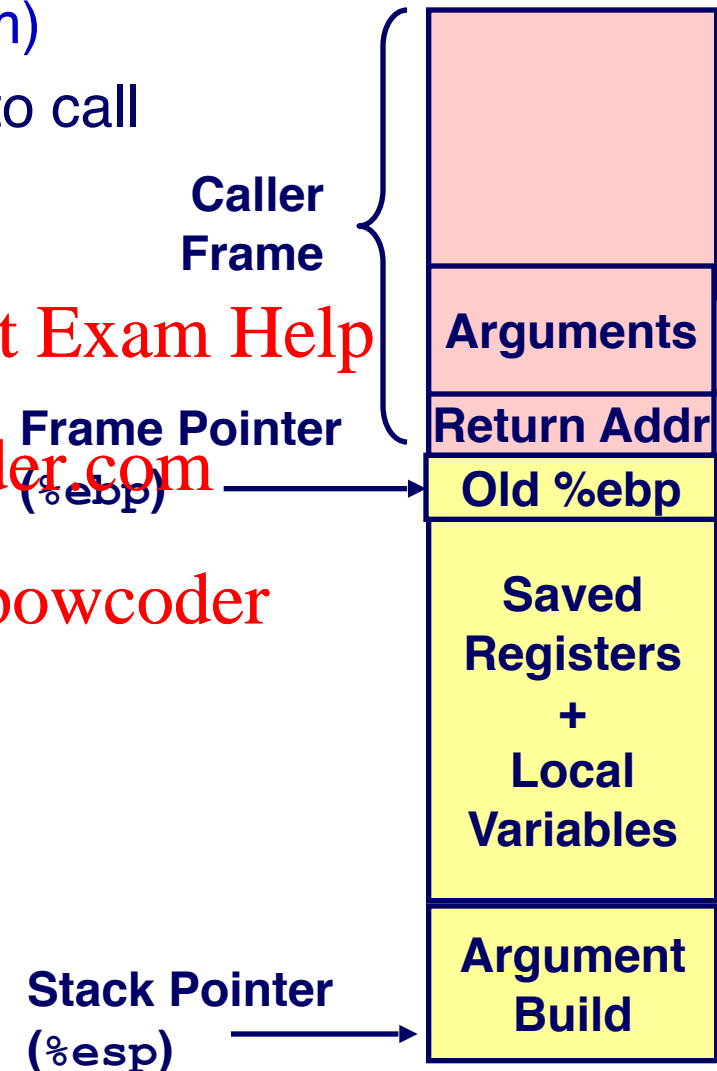
IA32/Linux Stack Frame

Current Stack Frame (“Top” to Bottom)

- Parameters for function about to call
 - “Argument build”
- Local variables
 - If can't keep in registers
- Saved register context
- Old frame pointer

Caller Stack Frame

- Return address
 - Pushed by `call` instruction
- Arguments for this call



Revisiting swap

```
int zip1 = 15213;
int zip2 = 91125;

void call_swap()
{
    swap(&zip1, &zip2);
}
```

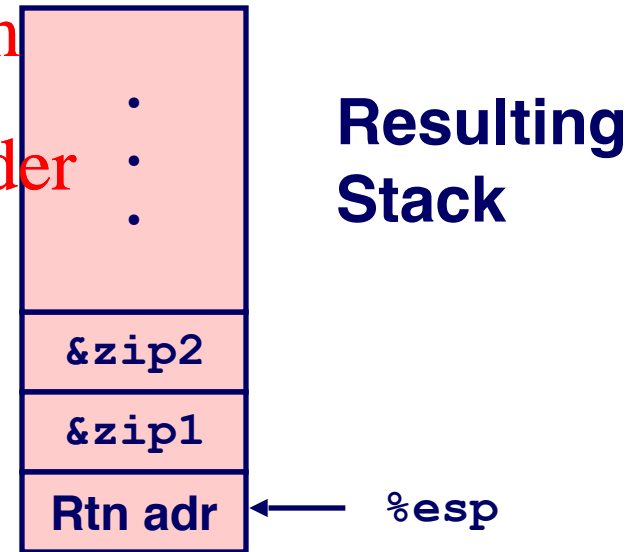
Calling swap from call_swap

```
call_swap:
    . . .
    pushl $zip2    # Global Var
    pushl $zip1    # Global Var
    call swap
    . . .
```

<https://powcoder.com>

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```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```



Revisiting swap

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

swap:

```
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
```

} Set
Up

```
    movl 12(%ebp),%ecx
    movl 8(%ebp),%edx
    movl (%ecx),%eax
    movl (%edx),%ebx
    movl %eax, (%edx)
    movl %ebx, (%ecx)
```

} Body

```
    movl -4(%ebp),%ebx
    movl %ebp,%esp
    popl %ebp
    ret
```

} Finish

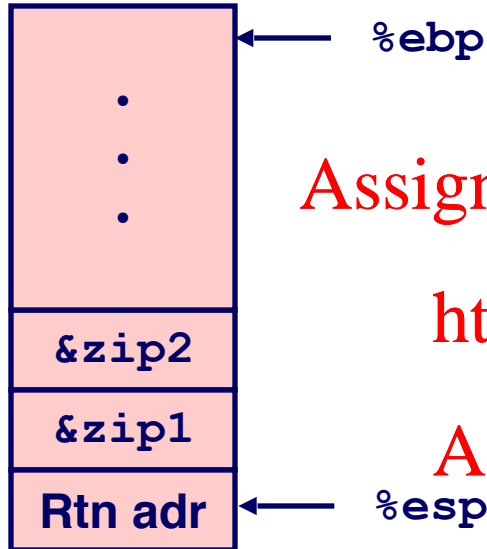
Assignment Project Exam Help

<https://powcoder.com>

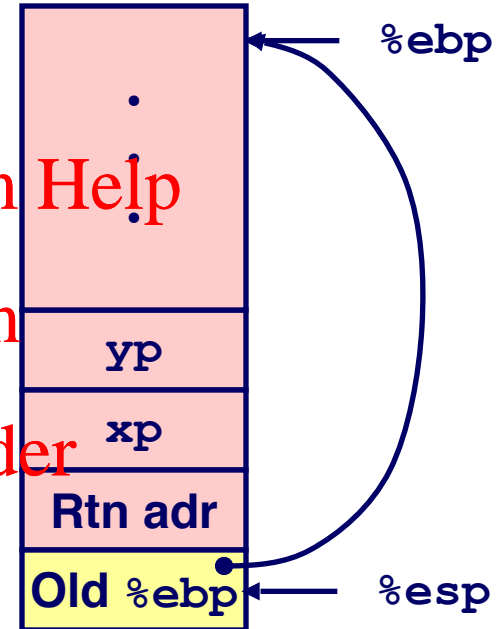
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swap Setup #1

Entering
Stack



Resulting
Stack



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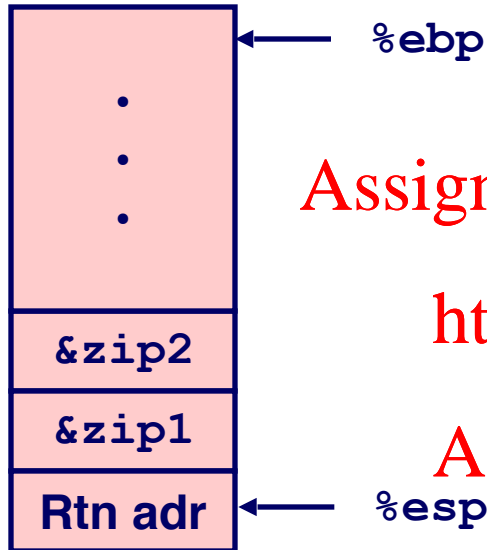
Add WeChat powcoder

`swap:`

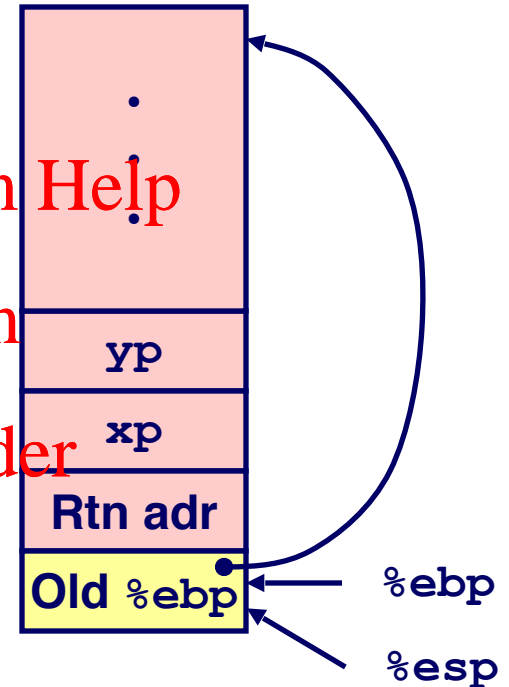
```
pushl %ebp  
movl %esp,%ebp  
pushl %ebx
```

swap Setup #2

Entering Stack



Resulting Stack



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<https://powcoder.com>

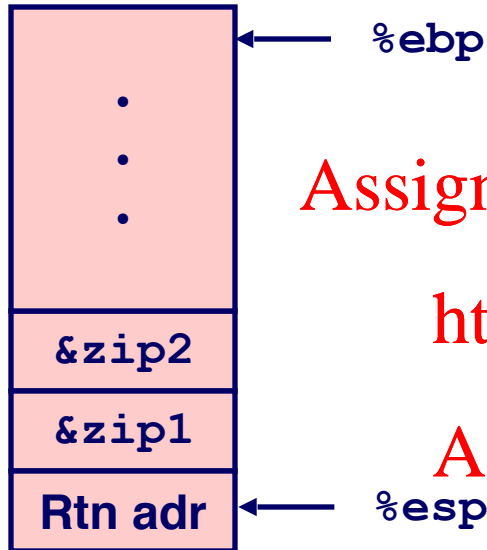
Add WeChat powcoder

`swap:`

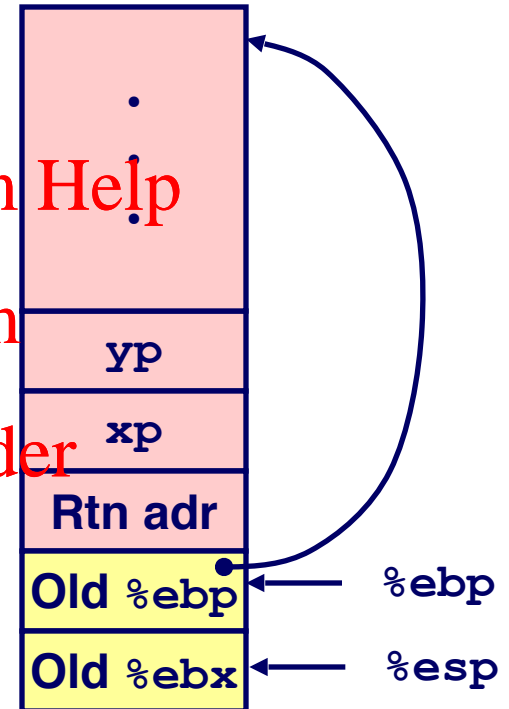
```
pushl %ebp
movl %esp, %ebp
pushl %ebx
```

swap Setup #3

Entering Stack



Resulting Stack



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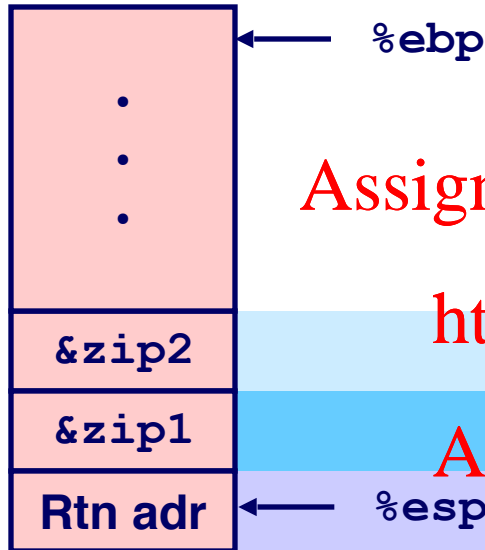
Add WeChat powcoder

`swap:`

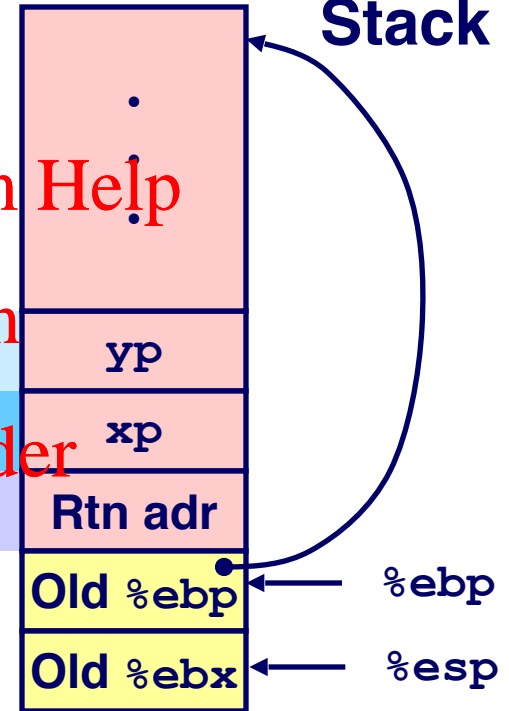
```
pushl %ebp
movl %esp,%ebp
pushl %ebx
```

Effect of swap Setup

Entering
Stack



Resulting
Stack



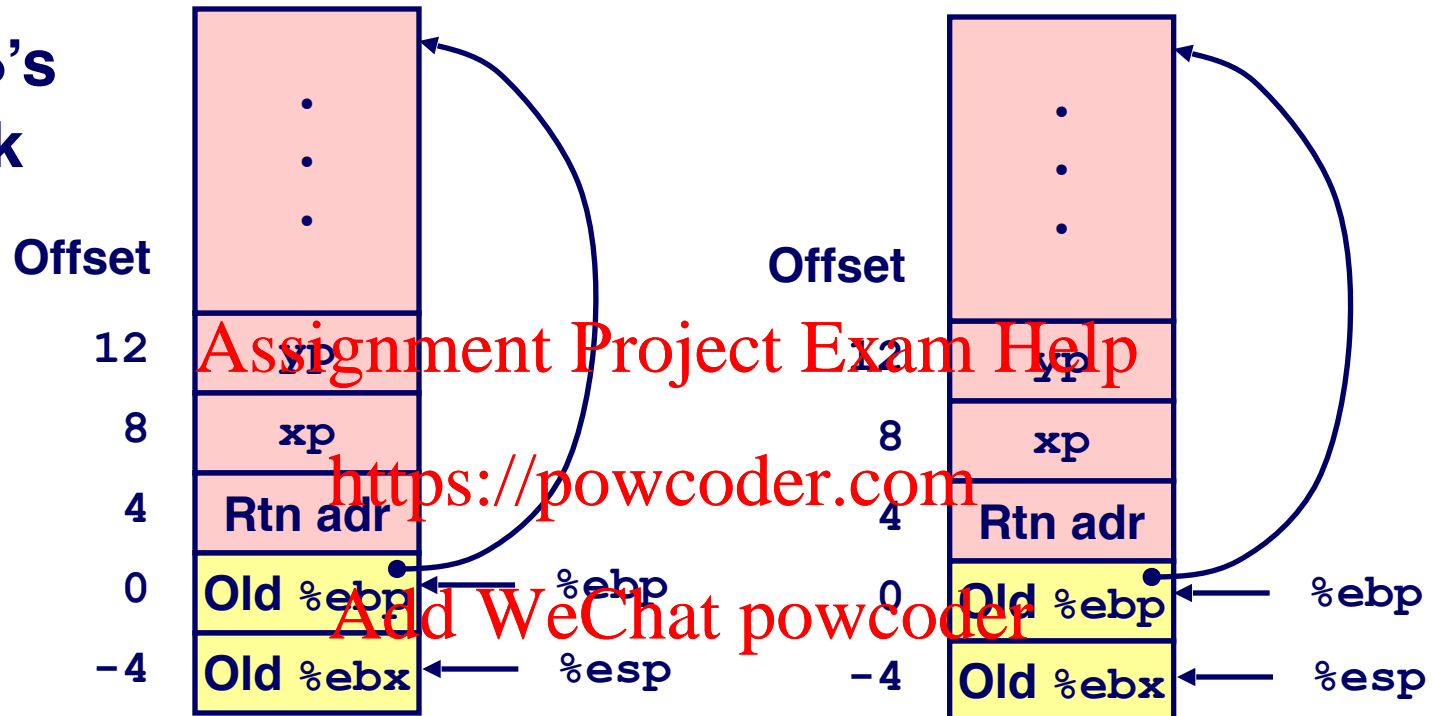
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<https://powcoder.com>

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```
movl 12(%ebp),%ecx # get yp  
movl 8(%ebp),%edx  # get xp  
... } Body
```

swap Finish #1

swap's
Stack

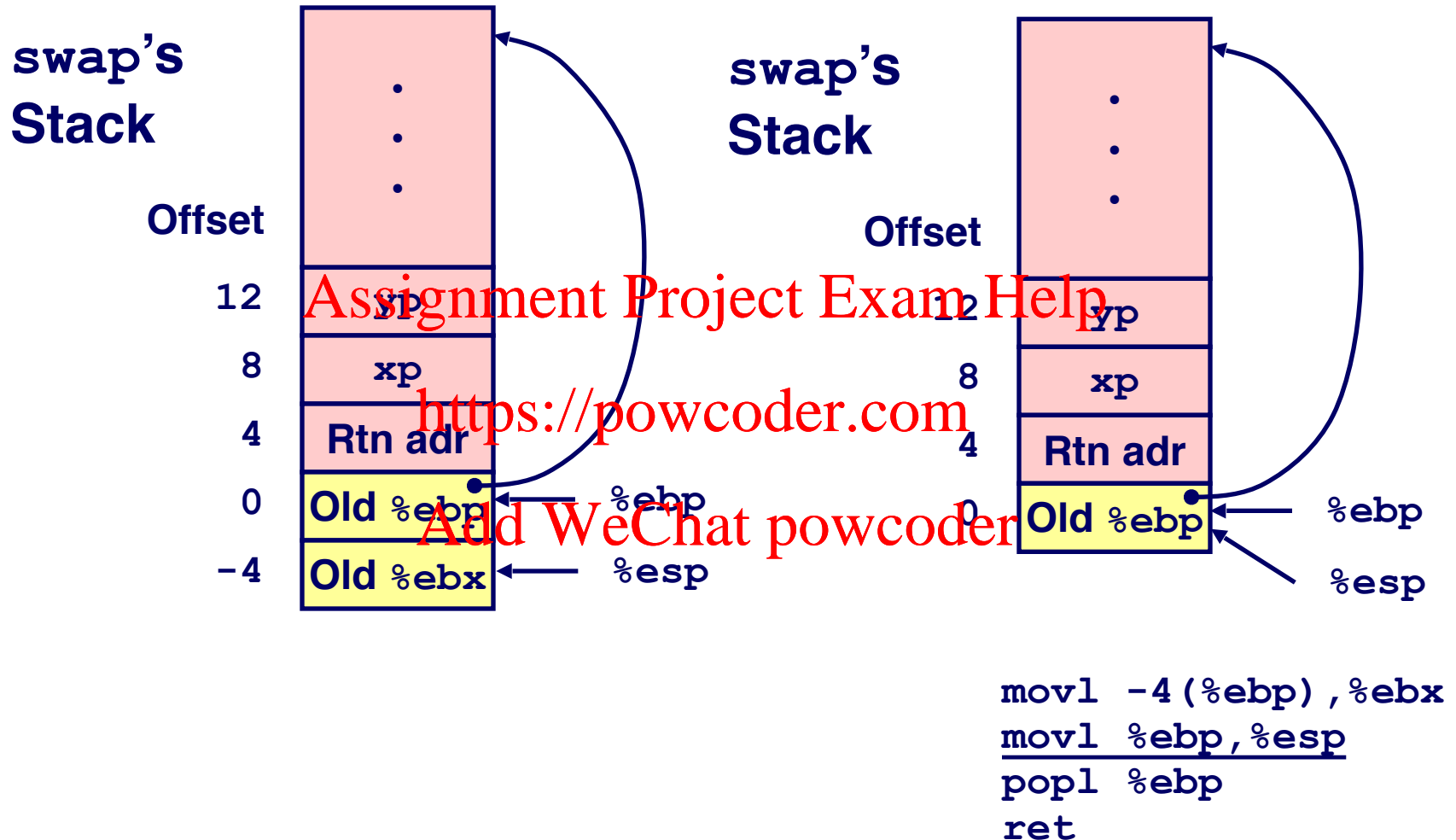


Observation

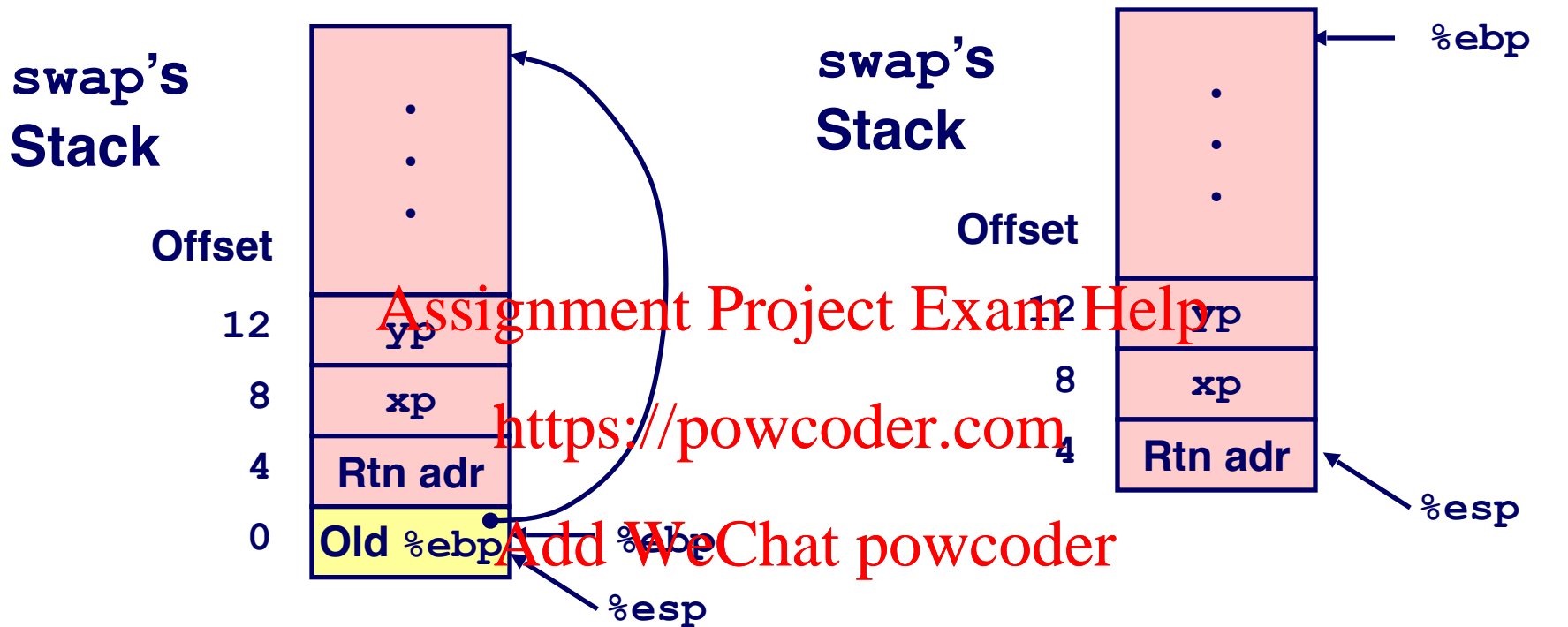
- Saved & restored register `%ebx`

```
movl -4(%ebp), %ebx  
movl %ebp, %esp  
popl %ebp  
ret
```

swap Finish #2

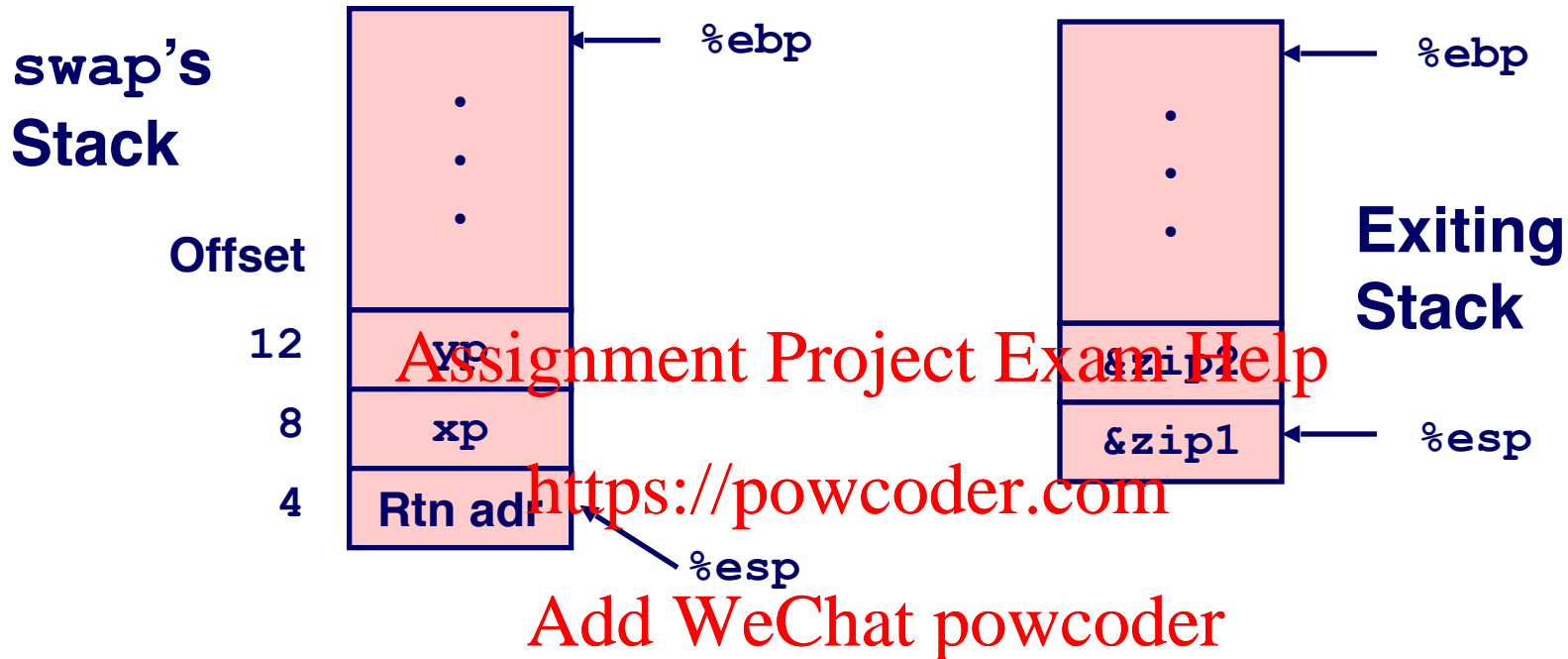


swap Finish #3



```
movl -4(%ebp), %ebx
movl %ebp, %esp
popl %ebp
ret
```

swap Finish #4



Observation

- Saved & restored register `%ebx`
- Didn't do so for `%eax`, `%ecx`, or `%edx`

```
movl    -4(%ebp), %ebx
movl    %ebp, %esp
popl    %ebp
ret
```


Register Saving Conventions

When procedure `yoo` calls `who`:

- `yoo` is the *caller*, `who` is the *callee*

Can Register be Used for Temporary Storage?

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```
yoo:
    . . .
    movl $15213, %edx
    call who
    addl %edx, %eax
    . . .
    ret
```

```
who:
    . . .
    movl 8(%ebp), %edx
    addl $91125, %edx
    . . .
    ret
```

<https://powcoder.com>

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- Contents of register `%edx` overwritten by `who`

Register Saving Conventions

When procedure `yoo` calls `who`:

- `yoo` is the *caller*, `who` is the *callee*

Can Register be Used for Temporary Storage?

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Conventions

- “Caller Save” <https://powcoder.com>
 - Caller saves temporary in its frame before calling
- “Callee Save”
 - Callee saves temporary in its frame before using

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IA32/Linux Register Usage

Two have special uses

- `%ebp`, `%esp`

Three managed as callee-save

- `%ebx`, `%esi`, `%edi`
- Old values saved on stack prior to using

Three managed as caller-save

- `%eax`, `%edx`, `%ecx`
- Do what you please, but expect any callee to do so, as well

Register `%eax` also stores returned value

**Caller-Save
Temporaries**

**Callee-Save
Temporaries**

Special



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Recursive Function

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```
.globl rfact
.type
rfact,@function
rfact:
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
    movl 8(%ebp),%ebx
    cmpl $1,%ebx
    jle .L78
    leal -1(%ebx),%eax
    pushl %eax
    call rfact
    imull %ebx,%eax
    jmp .L79
    .align 4
.L78:
    movl $1,%eax
.L79:
    movl -4(%ebp),%ebx
    movl %ebp,%esp
    popl %ebp
    ret
```

Recursive Factorial

```
int rfact(int x)
{
    int rval;
    if (x <= 1)
        return 1;
    rval = rfact(x-1);
    return rval * x;
}
```

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<https://powcoder.com>

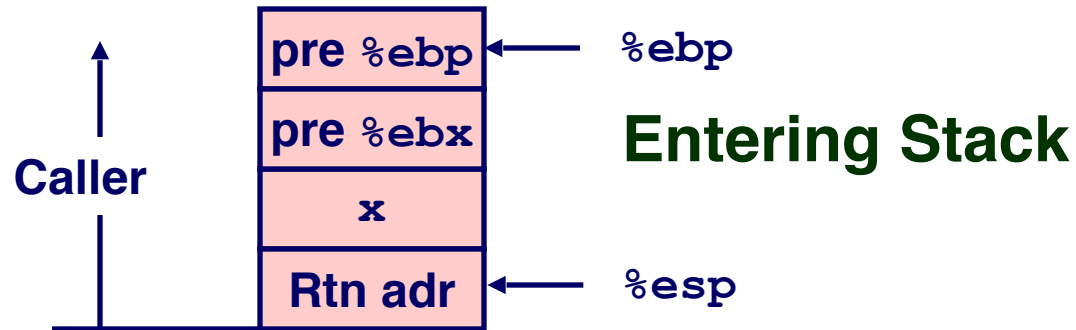
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Registers

- %eax used without first saving
- %ebx used, but save at beginning & restore at end

```
.globl rfact
.type
rfact,@function
rfact:
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
    movl 8(%ebp),%ebx
    cmpl $1,%ebx
    jle .L78
    leal -1(%ebx),%eax
    pushl %eax
    call rfact
    imull %ebx,%eax
    jmp .L79
    .align 4
.L78:
    movl $1,%eax
.L79:
    movl -4(%ebp),%ebx
    movl %ebp,%esp
    popl %ebp
    ret
```

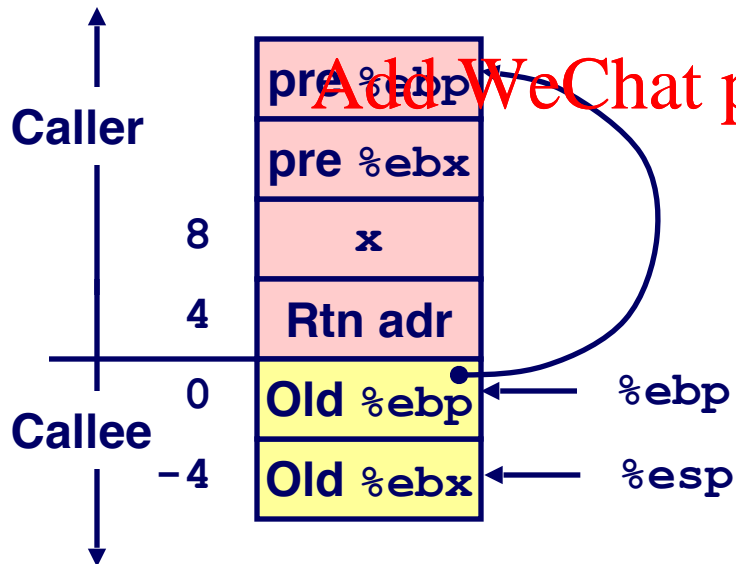
Rfact Stack Setup



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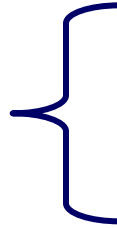
<https://powcoder.com>

```
pushl %ebp  
movl %esp,%ebp  
pushl %ebx
```



Rfact Body

Recursion



```
movl 8(%ebp),%ebx    # ebx = x
cmpl $1,%ebx         # Compare x : 1
jle .L78             # If <= goto Term
leal -1(%ebx),%eax   # eax = x-1
pushl %eax           # Push x-1
call rfact           # rfact(x-1)
imull %ebx,%eax      # rval * x
jmp .L79             # Goto done
.L78:                # Term:
movl $1,%eax         # return val = 1
.L79:                # Done:
```

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Registers

```
int rfact(int x)
{
    int rval;
    if (x <= 1)
        return 1;
    rval = rfact(x-1) ;
    return rval * x;
}
```

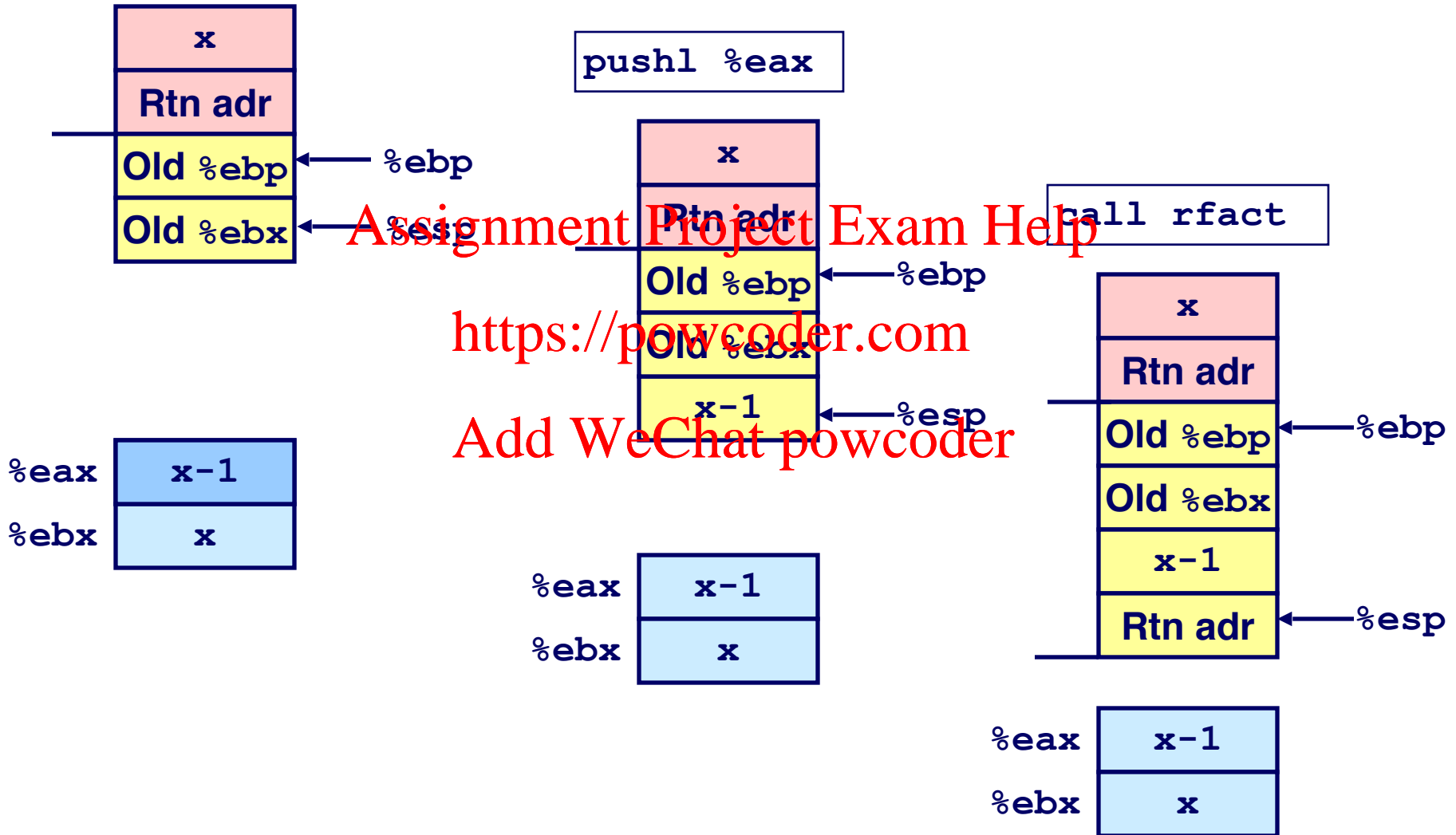
%ebx Stored value of x

%eax

- Temporary value of $x-1$
- Returned value from `rfact(x-1)`
- Returned value from this call

Rfact Recursion

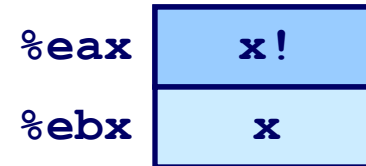
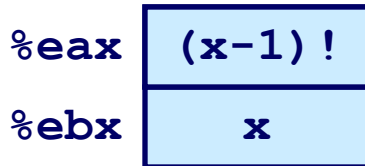
```
leal -1(%ebx), %eax
```



Rfact Result

Return from Call

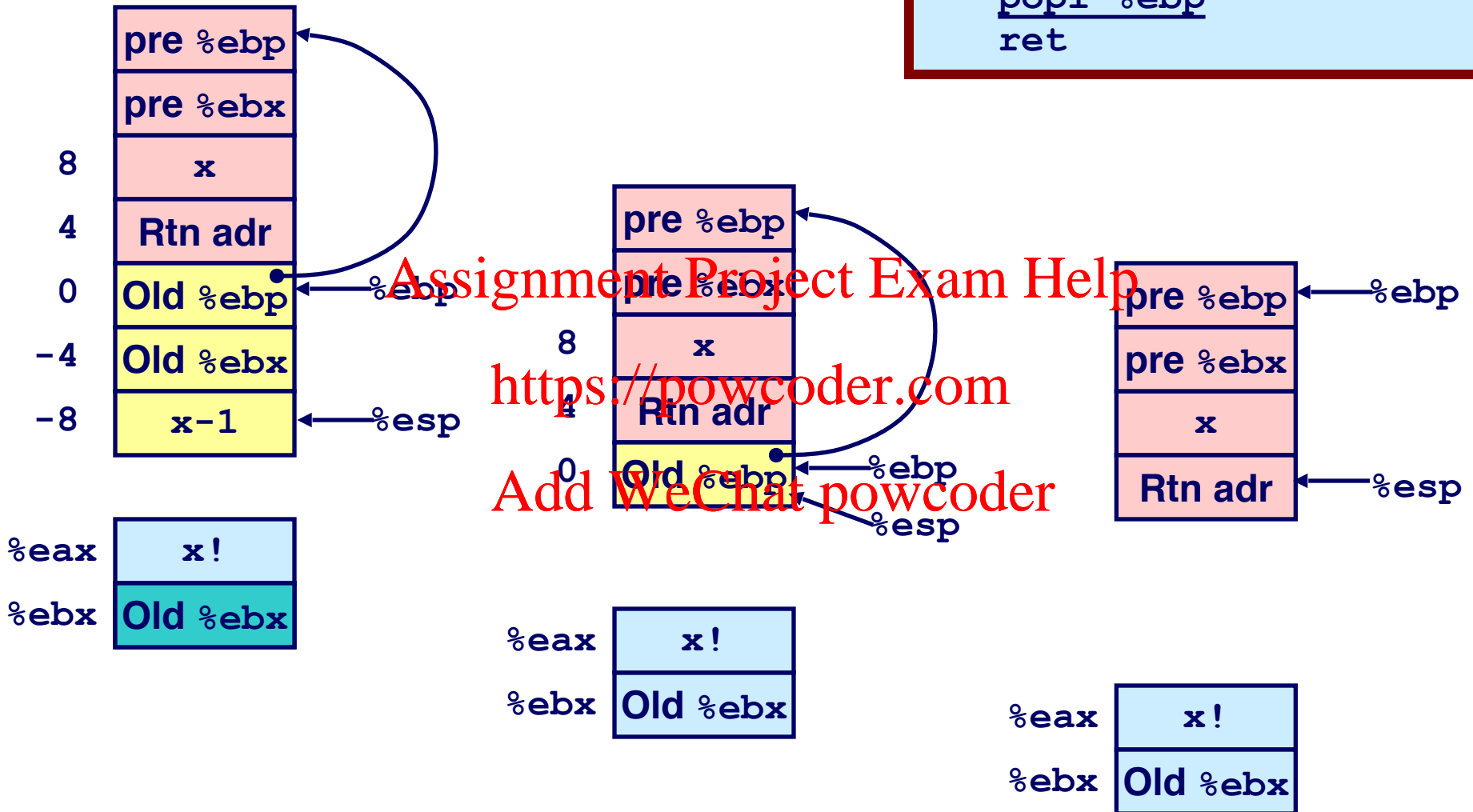
```
imull %ebx,%eax
```



Assume that `rfact(x-1)`
returns `(x-1) !` in register
`%eax`

Rfact Completion

```
movl -4(%ebp), %ebx
movl %ebp, %esp
popl %ebp
ret
```



Basic Data Types

Integral

- Stored & operated on in general registers
- Signed vs. unsigned depends on instructions used

Intel	GAS	Bytes	C
byte	b	1	[signed] char
word	w	2	[unsigned] short
double word	l	4	[unsigned] int

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Floating Point

- Stored & operated on in floating point registers

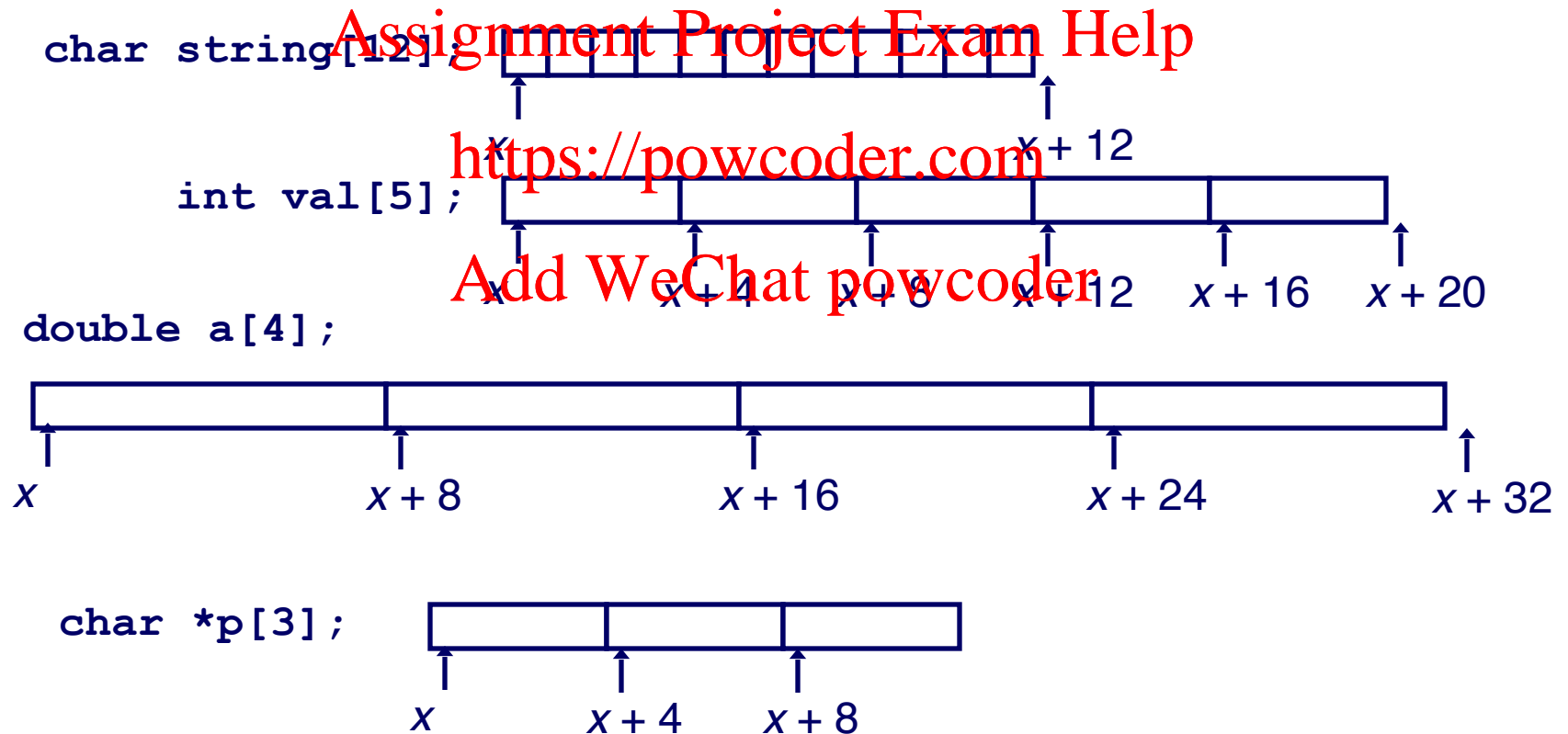
Intel	GAS	Bytes	C
Single	s	4	float
Double	l	8	double
Extended	t	10/12	long double

Array Allocation

Basic Principle

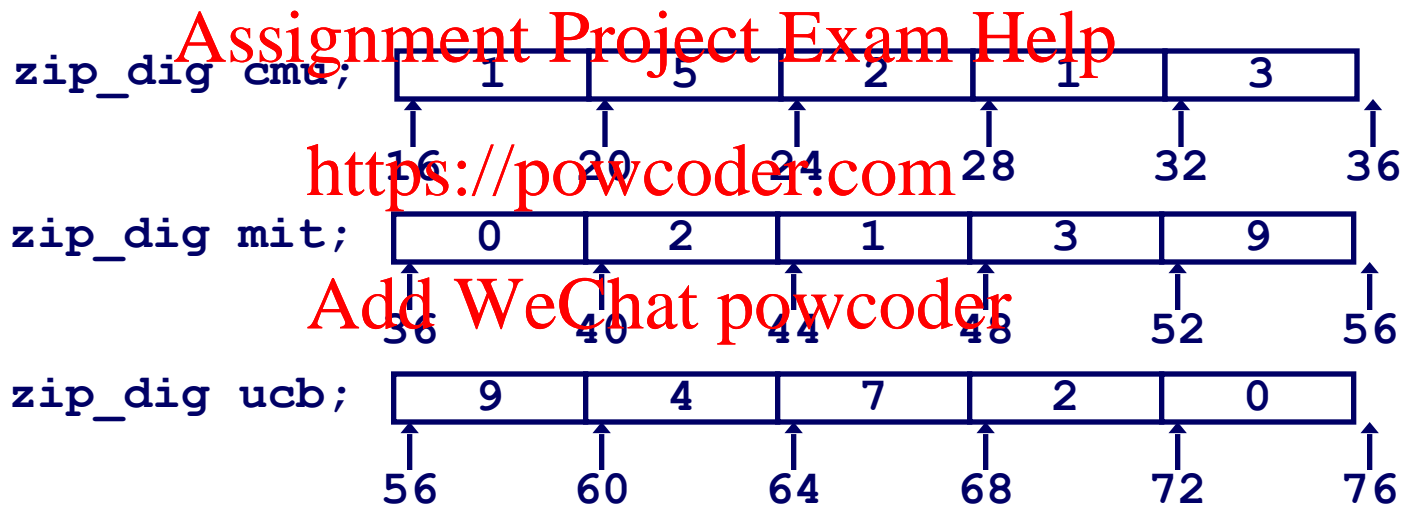
$T \ A[L];$

- Array of data type T and length L
- Contiguously allocated region of $L * \text{sizeof}(T)$ bytes



Array Example

```
typedef int zip_dig[5];  
  
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```



Notes

- Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”
- Example arrays were allocated in successive 20 byte blocks
 - Not guaranteed to happen in general

Array Accessing Example

Computation

- Register `%edx` contains starting address of array
- Register `%eax` contains array index
- Desired digit at $4 * \%eax + \%edx$
- Use memory reference (`%edx, %eax, 4`)

```
int get_digit
(zip_dig z, int dig)
{
    return z[dig];
}
```

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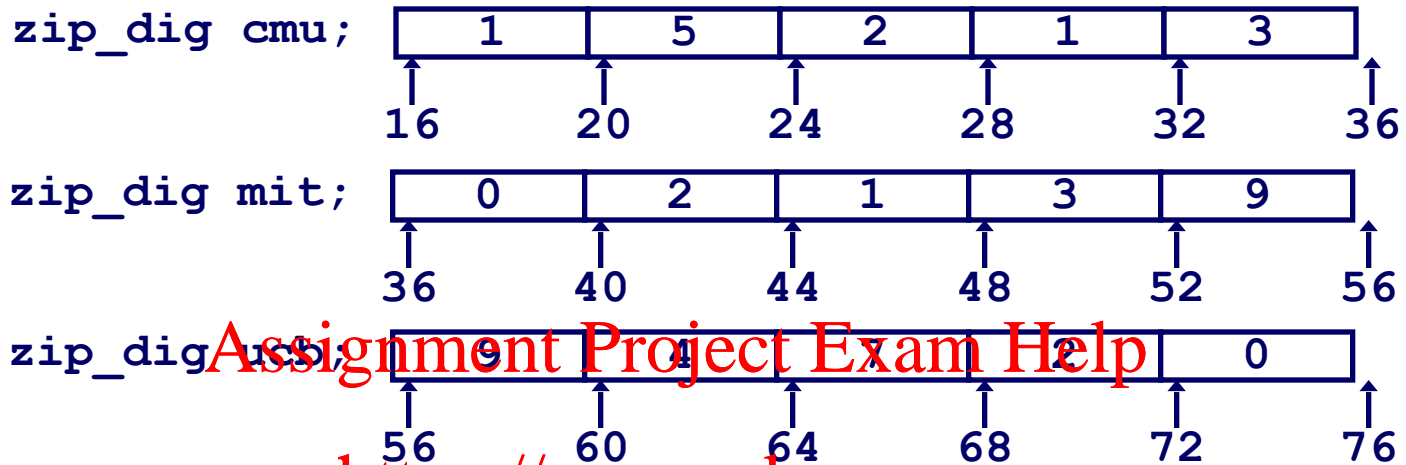
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Memory Reference Code

```
# %edx = z
# %eax = dig
movl (%edx,%eax,4),%eax # z[dig]
```

Referencing Examples



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Code Does Not Do Any Bounds Checking!

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Reference	Address	Value	Guaranteed?
mit[3]	$36 + 4 * 3 = 48$	3	Yes
mit[5]	$36 + 4 * 5 = 56$	9	No
mit[-1]	$36 + 4 * -1 = 32$	3	No
cmu[15]	$16 + 4 * 15 = 76$??	No

- Out of range behavior implementation-dependent
 - No guaranteed relative allocation of different arrays

Array Loop Example

Original Source

```
int zd2int(zip_dig z)
{
    int i;
    int zi = 0;
    for (i = 0; i < 5; i++) {
        zi = 10 * zi + z[i];
    }
    return zi;
}
```

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Transformed Version

- As generated by GCC
- Eliminate loop variable `i`
- Convert array code to pointer code
- Express in do-while form
 - No need to test at entrance

```
int zd2int(zip_dig z)
{
    int zi = 0;
    int *zend = z + 4;
    do {
        zi = 10 * zi + *z;
        z++;
    } while(z <= zend);
    return zi;
}
```


Array Loop Implementation

Registers

%ecx z
%eax zi
%ebx zend

Computations

- $10 * zi + *z$ implemented as $*z + 2 * (zi + 4 * zi)$
- $z++$ increments by 4

```
int zd2int(zip_dig z)
{
    int zi = 0;
    int *zend = z + 4;
    do {
        zi = 10 * zi + *z;
        z++;
    } while(z <= zend);
    return zi;
}
```

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```
# %ecx = z
xorl %eax,%eax          # zi = 0
leal 16(%ecx),%ebx       # zend = z+4
.L59:
leal (%eax,%eax,4),%edx  # 5*zi
movl (%ecx),%eax        # *z
addl $4,%ecx            # z++
leal (%eax,%edx,2),%eax  # zi = *z + 2*(5*zi)
cmpl %ebx,%ecx          # z : zend
jle .L59                # if <= goto loop
```

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Multi-Level Array Example

- Variable `univ` denotes array of 3 elements
- Each element is a pointer
 - 4 bytes
- Each pointer points to array of `int`'s

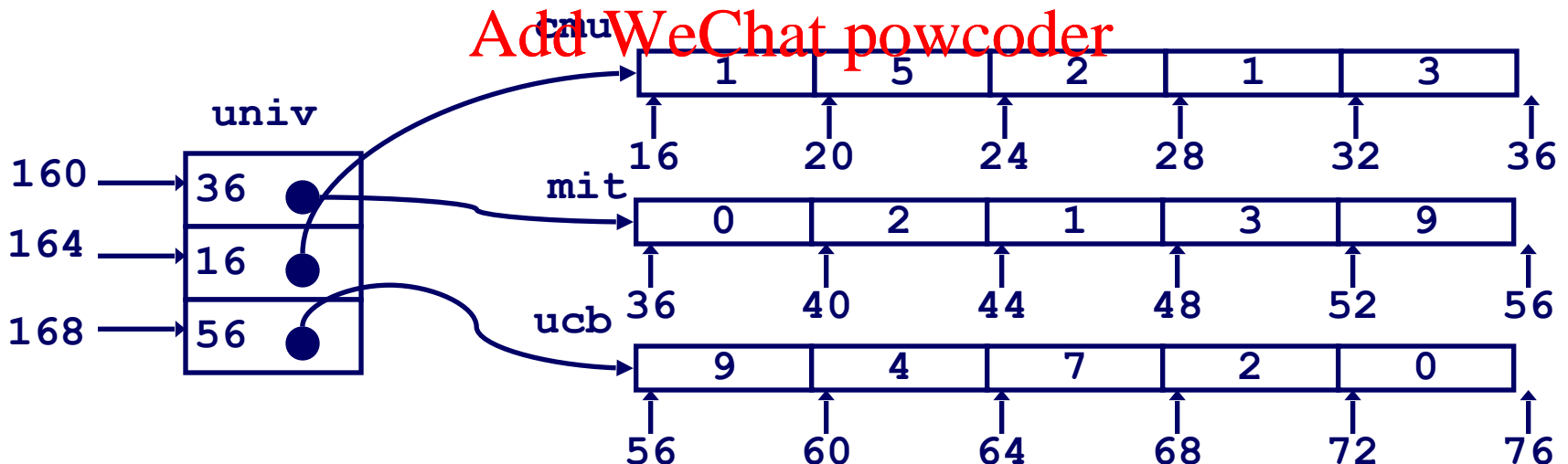
```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

```
#define UCOUNT 3  
int *univ[UCOUNT] = {mit, cmu, ucb};
```

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Element Access in Multi-Level Array

```
int get_univ_digit
(int index, int dig)
{
    return univ[index][dig];
}
```

Computation

- Element access

`Mem[Mem[univ+4*index]+4*dig]`

- Must do two memory reads

- First get pointer to row array
- Then access element within array

```
# %ecx = index
# %eax = dig
leal 0(,%ecx,4),%edx      # 4*index
movl univ(%edx),%edx      # Mem[univ+4*index]
movl (%edx,%eax,4),%eax   # Mem[...+4*dig]
```

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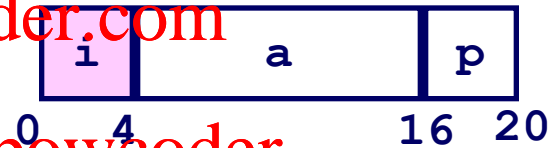
Structures

Concept

- Contiguously-allocated region of memory
- Refer to members within structure by names
- Members may be of different types

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```

Memory Layout



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Accessing Structure Member

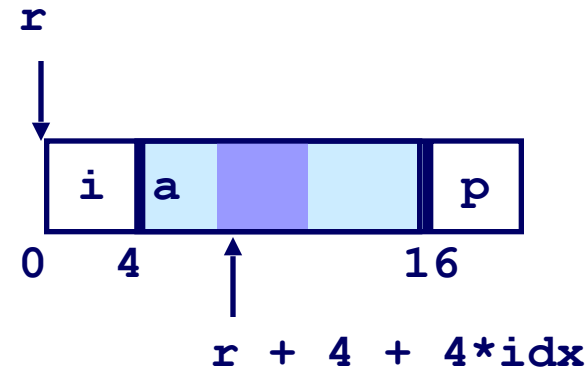
```
void  
set_i(struct rec *r,  
      int val)  
{  
    r->i = val;  
}
```

Assembly

```
# %eax = val  
# %edx = r  
movl %eax, (%edx)    # Mem[r] = val
```

Generating Pointer to Struct. Member

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```



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Generating Pointer to Array Element

- Offset of each structure member determined at compile time

```
int *  
find_a  
(struct rec *r, int idx)  
{  
    return &r->a[idx];  
}
```

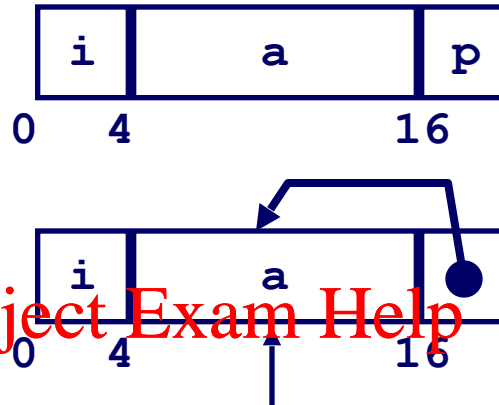
```
# %ecx = idx  
# %edx = r  
leal 0(,%ecx,4),%eax # 4*idx  
leal 4(%eax,%edx),%eax # r+4*idx+4
```

Structure Referencing (Cont.)

C Code

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```

```
void  
set_p(struct rec *r)  
{  
    r->p =  
        &r->a[r->i];  
}
```



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```
# %edx = r  
movl (%edx), %ecx          # r->i  
leal 0(, %ecx, 4), %eax     # 4*(r->i)  
leal 4(%edx, %eax), %eax    # r+4+4*(r->i)  
movl %eax, 16(%edx)        # Update r->p
```

Alignment

Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K
- Required on some architectures, advised on IA32
 - treated differently by Linux and Windows!

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Motivation for Aligning Data

- Memory accessed by (aligned) double or quad-words
 - Inefficient to load or store datum that spans quad word boundaries

Compiler

- Inserts gaps in structure to ensure correct alignment of fields

Specific Cases of Alignment

Size of Primitive Data Type:

- 1 byte (e.g., `char`)
 - no restrictions on address
- 2 bytes (e.g., `short`)
 - lowest 1 bit of address must be 0_2
- 4 bytes (e.g., `int`, `float`, `char *`, etc.)
 - lowest 2 bits of address must be 00_2
- 8 bytes (e.g., `double`)
 - Windows (and most other OS's & instruction sets):
 - » lowest 3 bits of address must be 000_2
 - Linux:
 - » lowest 2 bits of address must be 00_2
 - » i.e., treated the same as a 4-byte primitive data type
- 12 bytes (`long double`)
 - Linux:
 - » lowest 2 bits of address must be 00_2
 - » i.e., treated the same as a 4-byte primitive data type

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Satisfying Alignment with Structures

Offsets Within Structure

- Must satisfy element's alignment requirement

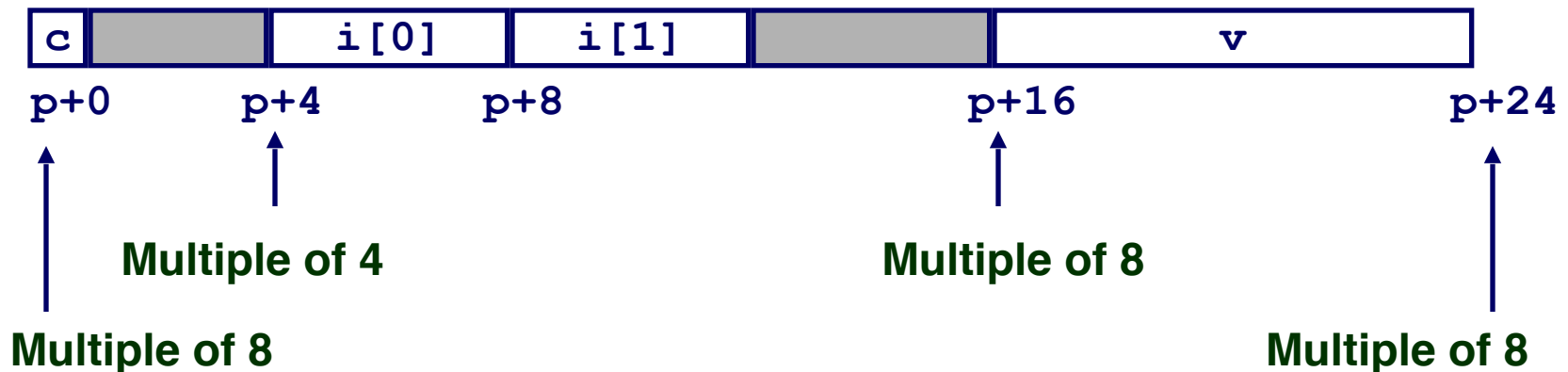
Overall Structure Placement

- Each structure has alignment requirement K
 - Largest alignment of any element
- Initial address & structure length must be multiples of K

```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

Example (under Windows):

- $K = 8$, due to double element



Linux vs. Windows

```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

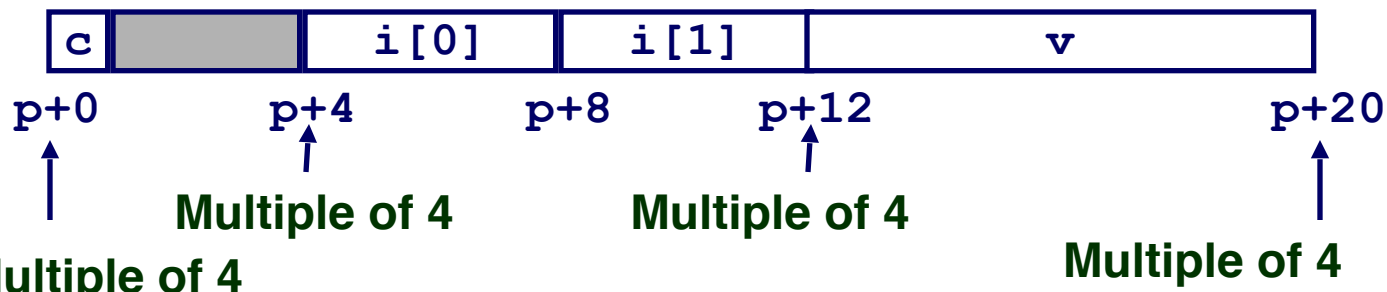
Windows (including Cygwin):

- $K = 8$, due to double element



Linux:

- $K = 4$; double treated like a 4-byte data type



Overall Alignment Requirement

```
struct S2 {  
    double x;  
    int i[2];  
    char c;  
} *p;
```

p must be multiple of:
8 for Windows
4 for Linux

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p+0

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Windows: p+24

Linux: p+20

```
struct S3 {  
    float x[2];  
    int i[2];  
    char c;  
} *p;
```

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p must be multiple of 4 (in either OS)



p+0

p+4

p+8

p+12

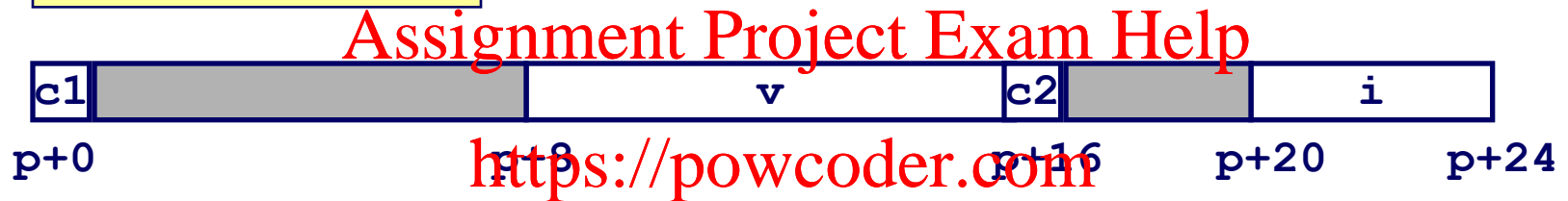
p+16

p+20

Ordering Elements Within Structure

```
struct S4 {  
    char c1;  
    double v;  
    char c2;  
    int i;  
} *p;
```

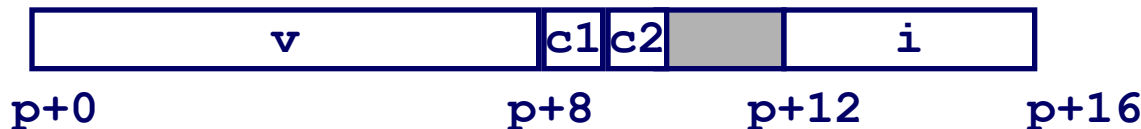
10 bytes wasted space in Windows



```
struct S5 {  
    double v;  
    char c1;  
    char c2;  
    int i;  
} *p;
```

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2 bytes wasted space



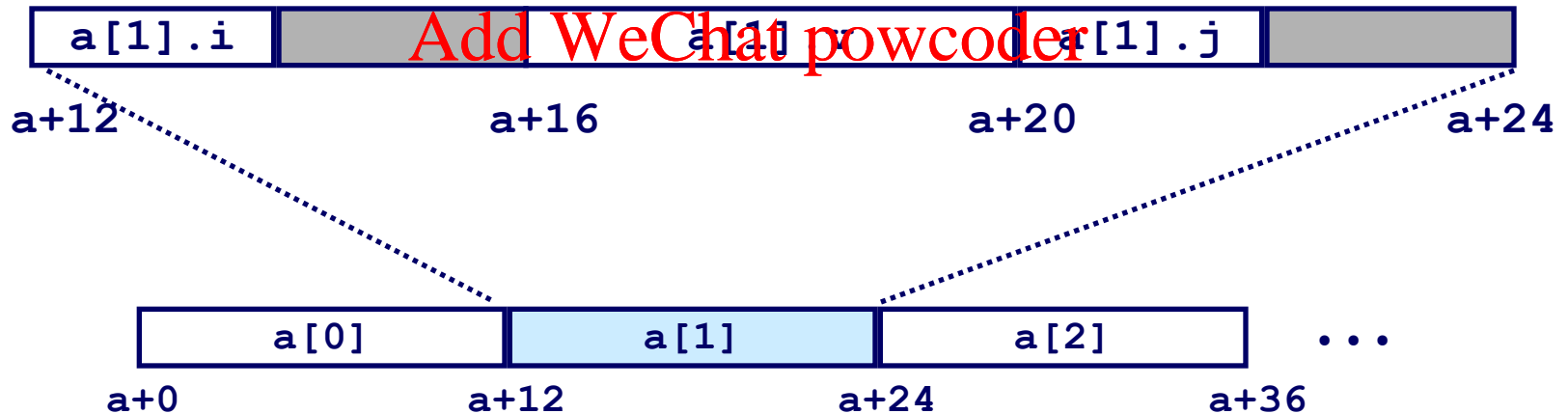
Arrays of Structures

Principle

- Allocated by repeating allocation for array type
- In general, may nest arrays & structures to arbitrary depth

```
struct S6 {  
    short i;  
    float v;  
    short j;  
} a[10];
```

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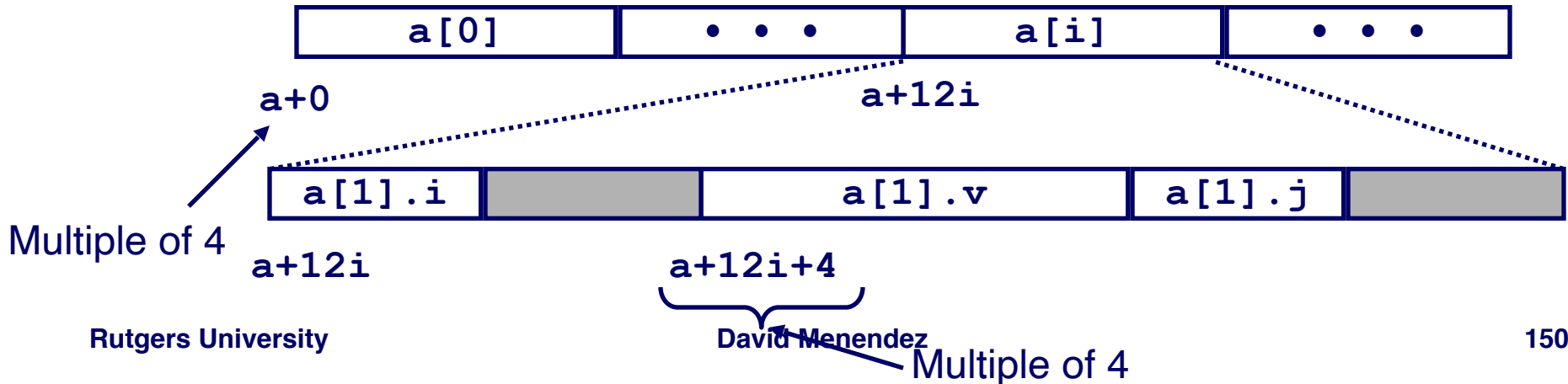


Satisfying Alignment within Structure

Achieving Alignment

- Starting address of structure array must be multiple of worst-case alignment for any element
 - a must be multiple of 4
- Offset of element within structure must be multiple of element's alignment requirement
 - v 's offset of 4 is a multiple of 4
- Overall size of structure must be multiple of worst-case alignment for any element
 - Structure padded with unused space to be 12 bytes

```
struct S6 {  
    short i;  
    float v;  
    short j;  
    a[10];  
};
```



Summary

Arrays in C

- Contiguous allocation of memory
- Pointer to first element
- No bounds checking

Compiler Optimizations

- Compiler often turns array code into pointer code (`zd2int`)
- Uses addressing modes to scale array indices
- Lots of tricks to improve array indexing in loops

Structures

- Allocate bytes in order declared
- Pad in middle and at end to satisfy alignment

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