

# Data Mining and Machine Learning

## Assignment Project Exam Help

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Statistical Modelling of Sequences (2)  
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# Objectives

- So far, we introduced Markov models
- Hidden Markov models (HMMs)
- Calculating the probability of an observation sequence <https://powcoder.com>
- The Forward Probability calculation
- HMM training



# Hidden Markov Models (HMMs)

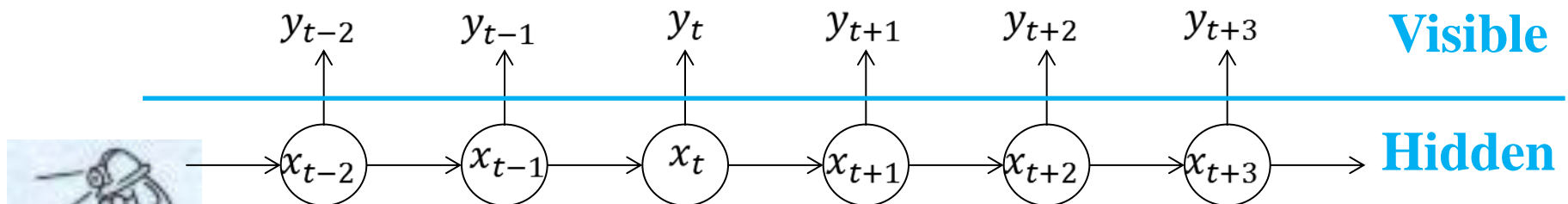
- Let's go back to our original shopping example
- Suppose that when a shopper visits a shop he or she makes a single purchase from a set of  $M$  possible items  $I_1, \dots, I_M$
- Suppose that, instead of observing the sequence of shops, we observe the sequence of purchases
- Because different shops may sell the same item it is in general not possible to know the shop sequence unambiguously from the purchase sequence

■ This is an example of a Hidden Markov process

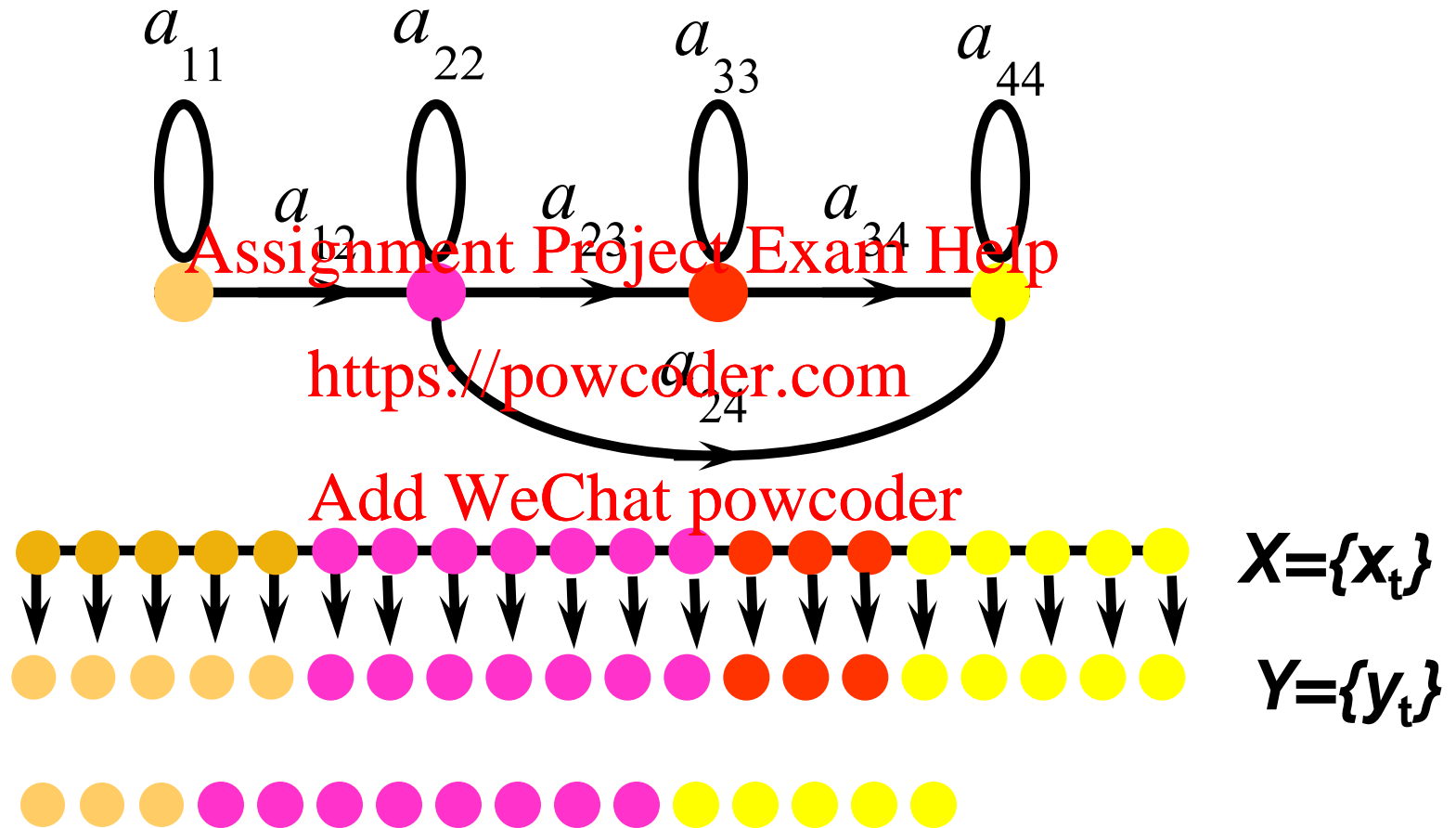


# HMMs (continued)

- In a HMM we assume that the current item purchased depends only on the current state (shop) and not on items previously purchased or shops previously visited
- Suppose  $x_t$  is the state and  $y_t$  is the item purchased at time  $t$
- The diagram indicates the dependencies:

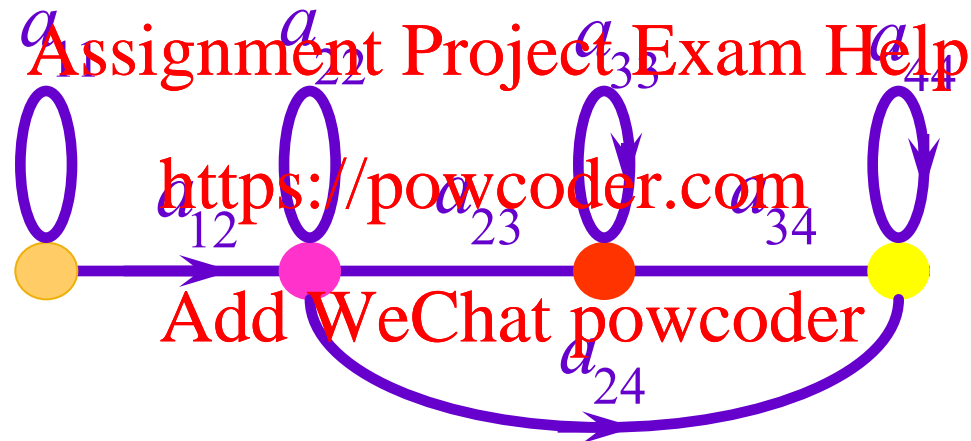


# Markov Model



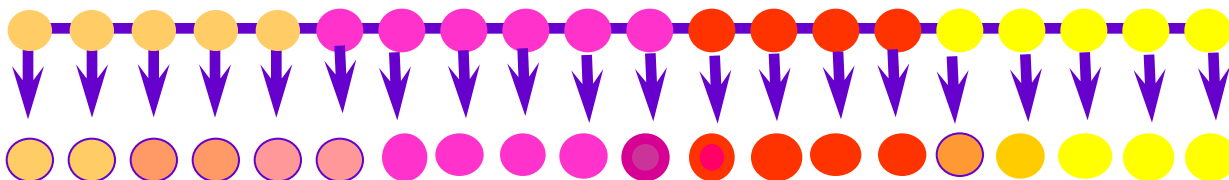
# Hidden Markov Model

- In a **hidden** Markov model, the relationship between the observation sequence and the state sequence is ambiguous.



$$X = \{x_t\}$$

$$Y = \{y_t\}$$



# HMMs Continued

- Let  $B_n$  be the probability distribution for items bought in shop  $S_n$  ( $n=1, \dots, N$ )
- Then  $B_n = [B_n(1), \dots, B_n(m), \dots, B_n(M)]$ , where  $B_n(m)$  is the probability of buying item  $I_m$  in shop  $S_n$
- Or (better),  $B_n(m) = P(y_t = I_m | x_t = S_n)$ . Note that this is independent of  $t$ .
- We can write all of these probabilities as a  $N \times M$  matrix  $B$  whose  $n^{th}$  row is  $B_n$ .



# Formal definition of a HMM

- An  $N$  state HMM with observations  $\{I_1, \dots, I_M\}$  comprises:
- An underlying  $N$  state Markov model defined by an initial state probability vector  $P_0$  and  $N \times N$  state transition probability matrix  $A$ , where:
  - $P_0(n) = P(x_1 = S_n)$
  - $A_{nm} = P(x_t = S_m \mid x_{t-1} = S_n)$
- An  $N \times M$  state output probability matrix  $B$  where
  - $B_{nm} = B_n(m) = P(y_t = I_m \mid x_t = S_n)$





# Example HMM Probability Calculation

- Let's start with our simple 3 state Markov model

$$A = \begin{bmatrix} 0.5 & 0.2 & 0.3 \\ 0.2 & 0.1 & 0.8 \\ 0.3 & 0.4 & 0.6 \end{bmatrix}$$

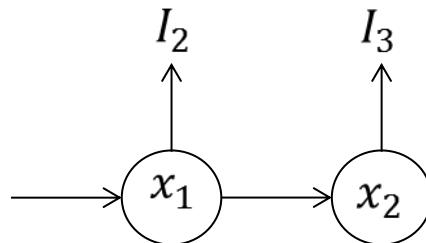
- In addition let's suppose that there are 4 possible items  $I_1, \dots, I_4$  that can be purchased. We need to specify the probabilities  $B_n(m)$  for  $n = 1, 2, 3$  and  $m = 1, 2, 3, 4$ . Suppose

$$B = \begin{bmatrix} 0.6 & 0.1 & 0.1 & 0.2 \\ 0.1 & 0.1 & 0.1 & 0.7 \\ 0.2 & 0.2 & 0.3 & 0.3 \end{bmatrix}$$



# Example (Continued)

- What is the probability of observing the sequence  $I = I_2 I_3$ ?
- This sequence must correspond to an underlying state sequence  $x = x_1 x_2$ . Suppose  $x_1 = S_1, x_2 = S_2$
- Then  $P(I, x) = P(I|x)P(x)$   
 $= P(I_2|x_1) \times P(I_3|x_2) \times P_0(x_1) \times P(x_2|x_1)$   
 $= B_1(2) \times B_2(3) \times P_0(1) \times a_{12}$   
 $= 0.1 \times 0.1 \times 0.5 \times 0.2 = 0.001$



# Example (Continued)

- So,  $P(I, x) = 0.001$
- But  $S_1S_2$  is just one of the state sequences that could have generated  $I$ . It could also have arisen from  $S_1S_1$  or  $S_1S_3$  or  $S_2S_1$  or  $S_2S_2$  or  $S_2S_3$  or  $S_3S_1$  or  $S_3S_2$  or  $S_3S_3$ !
- As always, when calculating the probability of an event  $I$  which may have arisen through a number of ways  $x$ , we have to sum the joint probability  $P(I, x)$  over all possible values of  $x$ . In other words:



# Example (Continued)

■ So,

–  $P(I, S_1 S_1) = 0.0025$

–  $P(I, S_1 S_2) = 0.0010$

–  $P(I, S_1 S_3) = 0.0045$

–  $P(I, S_2 S_1) = 0.0002$

–  $P(I, S_2 S_2) = 0.0002$

–  $P(I, S_2 S_3) = 0.0048$

–  $P(I, S_3 S_1) = 0.0024$

–  $P(I, S_3 S_2) = 0$

–  $P(I, S_3 S_3) = 0.0108$

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Hence  $P(I) = 0.0264$

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# Calculating the probability of an observed sequence

- Even in our simple example with 3 states and 2 observations there are 9 terms in the summation
- In general, if the Markov model is fully connected and has  $N$  states, and we have  $T$  observations, then the number of state sequences (and therefore the number of terms in the summation) is  $N^T$ . This makes direct calculation of  $P(I)$  computationally impractical.
- However, there is an efficient solution....



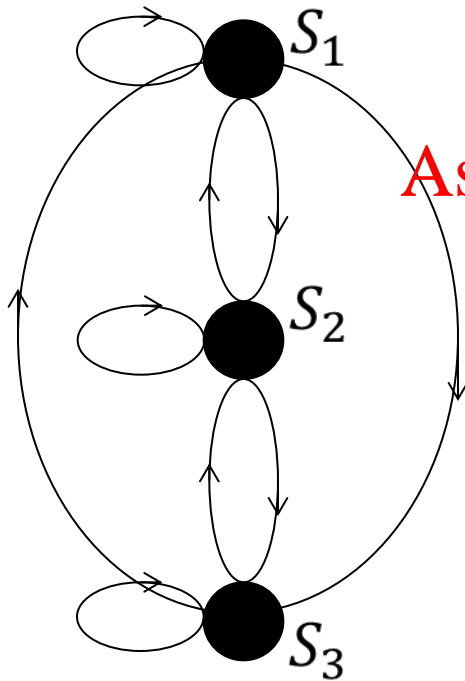
# The Forward Probability calculation

- This is very similar to Dynamic Programming
- Given a sequence of observations  $y_1, y_2, \dots, y_T$ , for each  $t$  and  $i$  define  $\alpha_t(i) = P(y_1, y_2, \dots, y_t, x_t = S_i)$
- In words,  $\alpha_t(i)$  is the probability that the subsequence  $y_1, y_2, \dots, y_t$  is observed and the Markov process is in state  $S_i$  at time  $t$ .
- This is easier to understand with a picture...



# Graphical interpretation of $\alpha_t(i)$

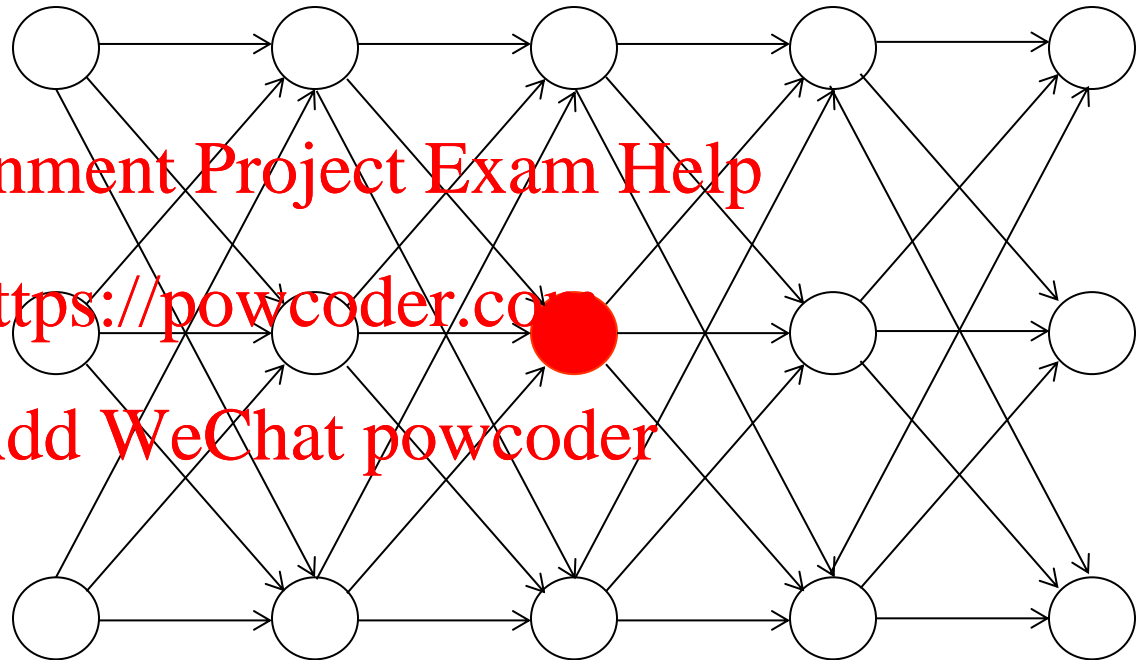
$y_1$        $y_2$        $y_3$        $y_4$        $y_5$



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● Corresponds to  $\alpha_3(2)$



# Recursive equation for $\alpha_t(i)$

- From the diagram,

$$\alpha_t(i) = \sum_{j=1}^N \alpha_{t-1}(j) a_{ji} B_i(y_t)$$

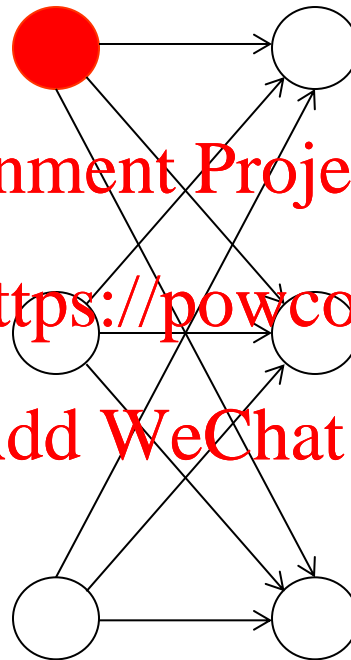
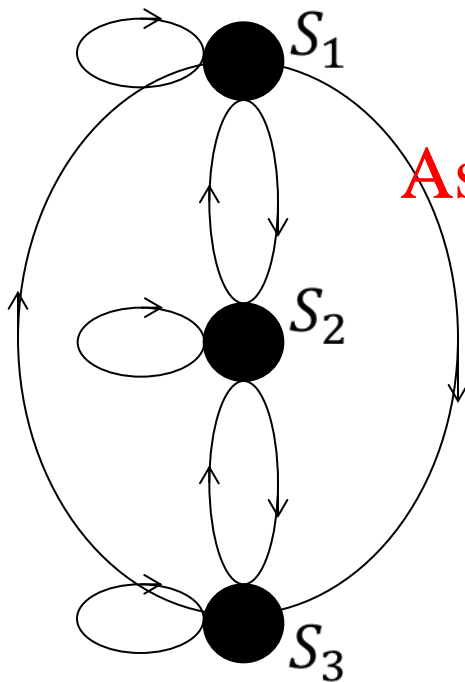
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# Example

$$y_1 = I_2 \quad y_2 = I_3$$



$$\alpha_1(1) = P_0(1) \times B_1(2) = 0.05$$

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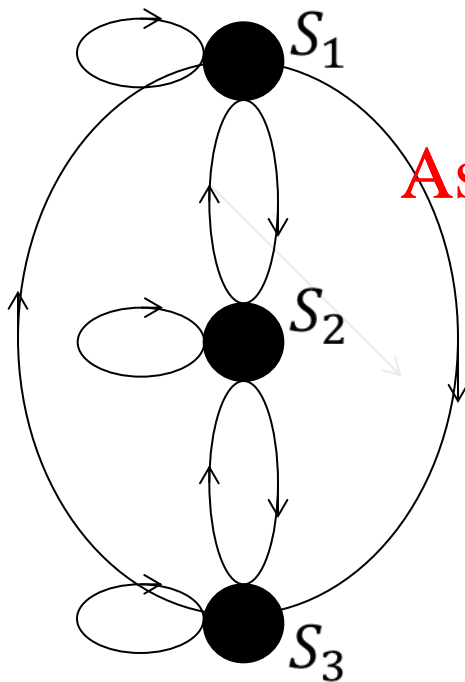
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# Example

$$y_1 = I_2 \quad y_2 = I_3$$

$$\alpha_1(1) = 0.05$$

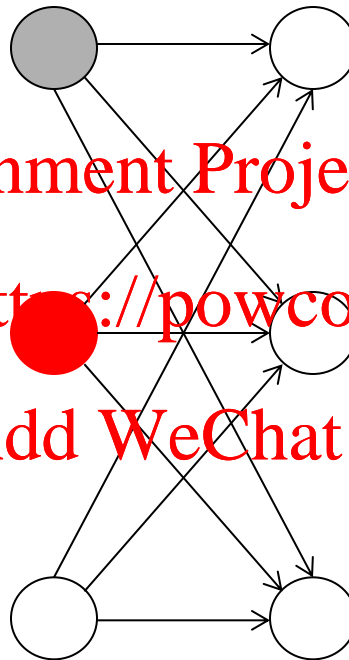


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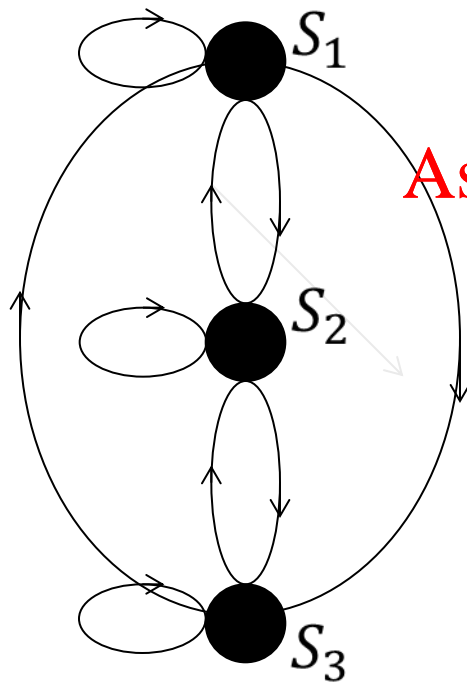
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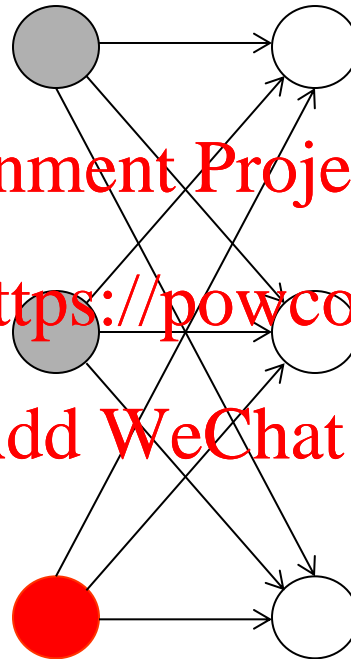
$$\alpha_1(2) = P_0(2) \times B_2(2) = 0.02$$



# Example



$$y_1 = I_2 \quad y_2 = I_3$$



$$\alpha_1(1) = B_1(2) = 0.05$$

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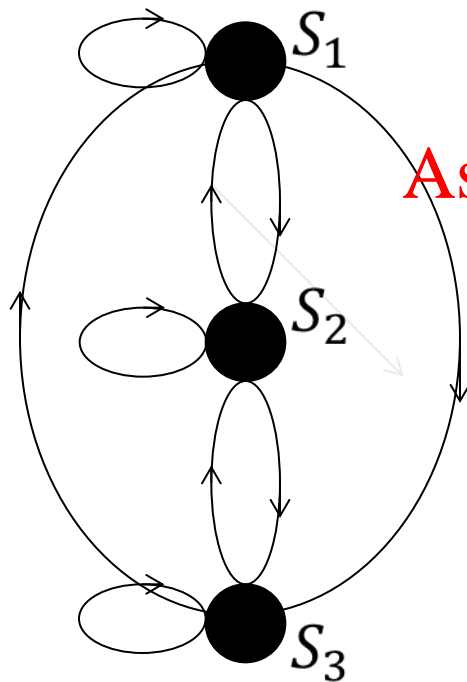
$$\alpha_1(2) = B_2(2) = 0.02$$

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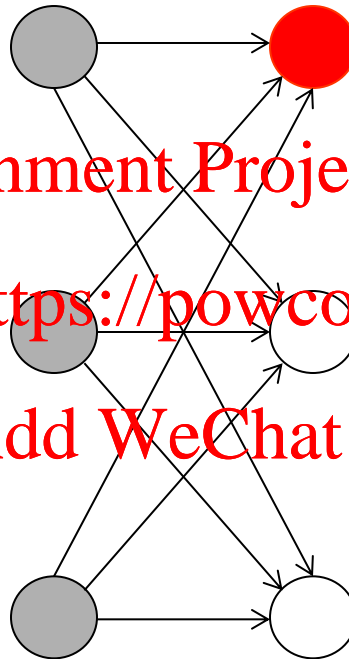
$$\alpha_1(3) = P_0(3)B_3(2) = 0.06$$



# Example



$$y_1 = I_2 \quad y_2 = I_3$$



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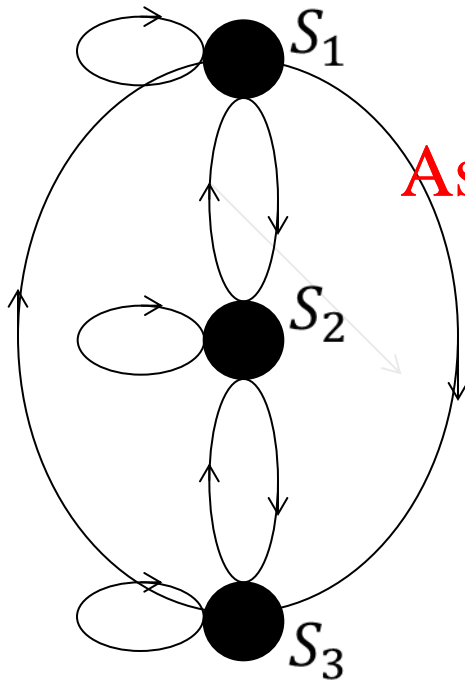
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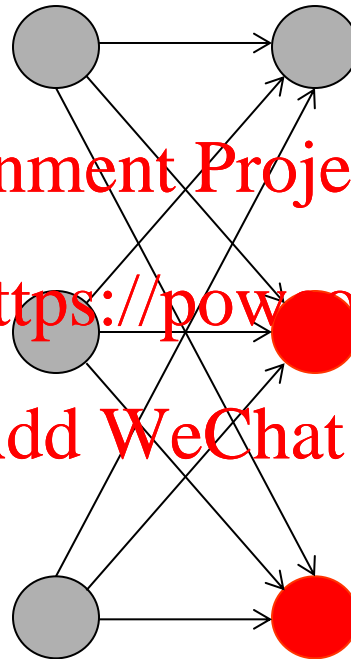
$$\begin{aligned} \alpha_2(1) = & \alpha_1(1) \times a_{11} \times B_1(3) \\ & + \alpha_1(2) \times a_{21} \times B_1(3) \\ & + \alpha_1(3) \times a_{31} \times B_1(3) = \\ & 0.05 \times 0.5 \times 0.1 \\ & + 0.02 \times 0.1 \times 0.1 \\ & + 0.06 \times 0.4 \times 0.1 = \\ & 0.0025 + 0.0002 + 0.0024 = \\ & \underline{0.0051} \end{aligned}$$



# Example



$$y_1 = I_2 \quad y_2 = I_3$$



Similarly:

$$\alpha_2(2) = 0.0012,$$

$$\alpha_2(3) = 0.0201$$

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$$P(y_1 y_2) =$$

$$P(y_1, y_2, x_2 = S_1) +$$

$$P(y_1, y_2, x_2 = S_2) +$$

$$P(y_1, y_2, x_2 = S_3) =$$

$$\alpha_2(1) + \alpha_2(2) + \alpha_2(3) =$$

$$0.0051 + 0.0012 + 0.0201$$

$$\underline{\underline{= 0.0264}}$$



# HMM Parameter Estimation

- Given a HMM and a sequence  $y$  we can calculate  $P(y)$
- But where does the HMM come from? In other words how do we estimate the HMM's parameters?
- This is done from data, using an algorithm similar to the E-M algorithm for estimating the parameters of a GMM
- The HMM training algorithm is called the Baum-Welch algorithm
- Like the E-M algorithm, it involves making an initial estimate and then iteratively improving the estimate until convergence. Hence it is only locally optimal

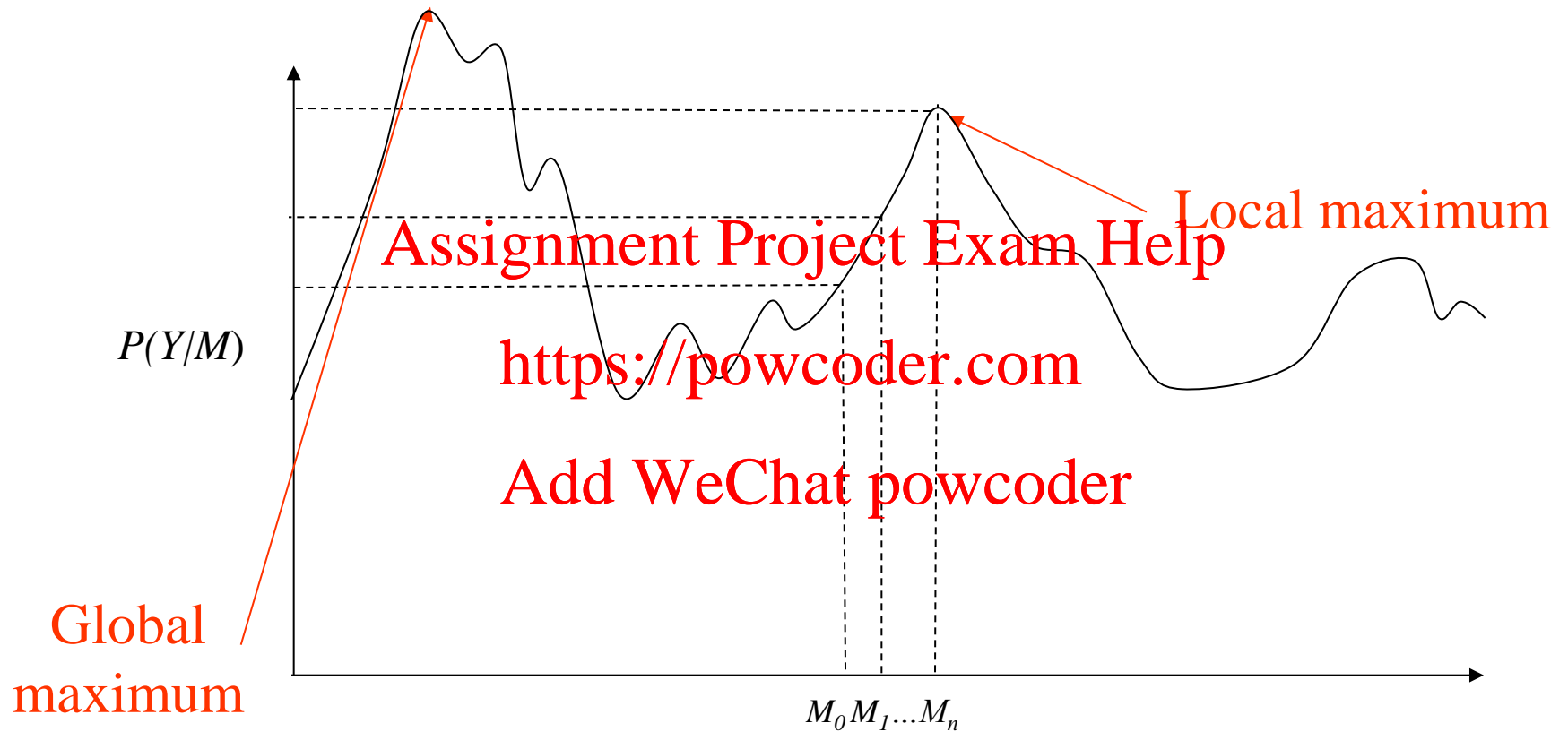


# HMM training

1. Make an initial estimate of the HMM –  $M_0$
2. Obtain a large set of training data  $Y$
3. Set  $i=1$
4. Apply the Baum-Welch algorithm to  $Y$  and  $M_{i-1}$  to get a new model  $M_i$  such that  $P(Y|M_i) \geq P(Y|M_{i-1})$
5. If  $|P(Y|M_i) - P(Y|M_{i-1})| \leq \varepsilon$  then stop, else
  1.  $i = i+1$
  2. Go back to step 4.



# Local optimality





# Summary

- Hidden Markov Models
- Calculating the probability of an observation sequence
- The forward probability calculation
- HMM training

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