

# Planning assumptions - vacuum world example

State<sub>1</sub>      Action      State<sub>2</sub>



In State<sub>2</sub>:  $\neg In(B)$  holds

# Assignment Project Exam Help

<https://powcoder.com>

**What can you say about Action? State<sub>1</sub>?**

## Add WeChat powcoder

- Action is not a move into B
- Action is a move from B or the vacuum cleaner is not in B in State1

