Project 1: Ray Tracer

COMP30019 - Graphics and Interaction Semester 2, 2022

This project is **individual** work (30 marks).

Due: 4th September 2022, 23:59 AEST

Assignment Brief

You are tasked with building a ray tracer. Your ray tracer will output a single static PNG image, based on an input 'scene' file and command line arguments. We have provided you with a template C# implementation that you will need to complete. We are not using the Unity engine in this project, however, you may find that some of the theory in this assignment will be transferable to Unity development (particularly the naths). The assignment is broken down into numerous stages and steps. Our expectations for each stage and the respectively allocated marks are outlined in detail below. You should aim to complete each step in sequence since this will make the process less overwhelming.

There are various approaches to collect the lateracts with surfaces in a scene. Almost always, the choice of approach comes down to a trade-off between computational complexity and realism. A ray tracing based approach can produce very realistic images, however this comes with a significant computational cost that generally makes it unsuitable for real-time randering. Were Athera and polarism frequirements, we still have to approximate and optimise the ray tracing process, since simulating all rays in a scene is computationally intractable.

Template code

You will be given a GitHub repository to work on your project that is already preinitialised with the template code. This is a **private** repository, so you may commit/push to it without worry of other students having access to your work. You are expected to use GitHub from the start through to the end of the project, and should commit and push frequently. **We won't accept** submissions not hosted in your private repository.



A link to accept the assignment and automatically create your template repository is provided on the Canvas project page (where you found this specification document). Note that you may submit the assignment as many times as you wish – only the **latest** will be marked.

Stage 1 - Basic ray tracer (9 marks)

You will first implement the **basic** functionality of a ray tracer. At its core, ray tracing is an application of geometry and basic linear algebra (vector maths will become your bread and butter!). For example, a ray of light can be modelled by two three-dimensional vectors: a starting **position** and **direction**. Surfaces, light sources, and other entities in the environment can also be defined using vectors. Using geometry, it is possible to calculate how a ray reflects off a surface, or perhaps even refracts through it. Ultimately we are interested in simulating rays of light propagating throughout the environment, interacting with various surfaces, before finally reaching the viewer as pixels on their screen. If we are clever in utilising 'real-life' physical models for these interactions, we can generate incredibly realistic scenes.

In this first stage you will implement some basic vector functionality, and figure out how to shoot a ray for each pixel in a rendered image. We won't yet be worrying about materials, lighting, shading, etc. Such fancy stuff will come later in the assignment.

Stage 1.1 - Familiarise yourself with the template

Before writing any code, try to understand how the template provided to you works. We have already taken care of quite a few details for you, such as input and output handling. A sample input scene is provided to you in a text file (tests/sample_scene_1.txt), and a pars for Sil Elin 131 en litter 16 y len coss Xi a 13 and resources directly within the Scene class (src/scene/Scene.cs). The core ray tracing logic (which you will write) should be implemented inside the Render() method in Scene.cs. This method takes an Image object for which you can set the individual colour of each pixel, as well as derive properties such as its well as the program is run, this image will automatically be outputted as a PNG image file.

Try running the project so that you can see this in action. Open up the terminal in Visual Studio CoA de dur Weler de la imprementation de la destruction de la destruct

Although this looks like a bit of a mouthful at first, all it is doing is running the project with two command line arguments: an input text file (-f) and an output image file (-o). The input file will be read and parsed, and the output image written accordingly. Open the generated output file, and you will notice the entire image is black, since no ray tracing has been implemented yet. Before continuing, test your understanding by modifying the project code to output the image entirely in white instead.



Hint: Try using some loops inside the Render() method. The Image class has Width and Height properties which should be handy for determining the loop bounds. These properties are already determined by the command line arguments -w and -h, if specified.

¹Note that you may need to install the .NET SDK if you haven't already, otherwise dotnet run won't be available. Make sure you install version 6.0. You can find it at https://aka.ms/dotnet-download.

Now take a look at the main Program.cs file. In the OptionsConf class, you can see all of the potential command line arguments and their default values (these are the values used if that argument is not specified at runtime – e.g., not entered on the command line). Don't change these default values, instead, pass values using the appropriate flags on the command line, if you want to change parameters. At this point it's worth stressing that you should not modify the Program.cs file at all. Doing so risks our automated test suites breaking when running your project during marking (see the 'Submission' section for details).

Stage 1.2 - Implement vector mathematics

We have provided you with a C# struct template for representing a three-dimensional vector (src/math/Vector3.cs). Write code to complete the missing operations which are currently empty methods. Note that for convenience we have overloaded operators² such as +, *, /. This is a handy language feature that allows us to perform vector arithmetic concisely:

```
Vector3 a = new Vector3(0, 1, 0);

Vector3 b = new Vector3(1, 1, 0);

Vector3 c = a + b; // We overloaded '+' so c = (1, 2, 0)
```

As versus gratuated and cross product (at least). The dot product will tell you how much two vectors point in the same direction, and the cross product of two vectors will give you the vector which is retreated both of them the crossing the x- and y-axes would give you the z-axis).



It is **strongly** recommended that you test your implementations here thorough the transfer of the can lead to a major headache down the line.

Stage 1.3 - Fire a ray for each pixel

We have already provided you with a 'ray' structure (src/math/Ray.cs). Notice that it is simply a position (origin) and a direction, both represented as vectors. While it is possible to trace rays forwards from light sources in the scene, it is far more efficient to trace rays backwards from the camera. This is because most rays in the scene will never be seen by the viewer, and computing these would be a waste of resources.

Inside the Render() method, write code to iterate through each pixel and construct a corresponding ray that fires into the world. The biggest challenge here will be converting from a two-dimensional pixel coordinate to a three-dimensional ray. You might find it useful to consult external resources about the maths here.

²https://docs.microsoft.com/en-us/dotnet/csharp/language-reference/operators/ operator-overloading

In this project we want you to use a left-handed coordinate system. The camera should be situated at the origin of the scene - (0, 0, 0) - looking forward along the positive z-axis ('into the screen'), with the positive x-axis pointing 'right', and the positive y-axis pointing 'up'. You should ensure that there is a horizontal field-of-view (FOV) of 60° . As a sanity check, a ray at the very center of the rendered image should point in the direction (0, 0, 1). Rays at the corners of the image should have directions $(\pm i, \pm j, k)$, where i = j if the image is square. You should ensure that your solution works when different output image widths/heights are specified. For non-square images the vertical FOV should vary to maintain the correct aspect ratio.

Stage 1.4 - Calculate ray-entity intersections

In this project a scene can contain three types of primitive entities – planes, triangles and spheres. If you haven't already, open the template classes provided in the src/primitives folder:

- Plane.cs Represented by a point (center), and a vector representing the direction it faces (normal i.e., perpendicular to the actual surface of the plane). Note this defines an 'infinite' plane.
- Triangle.cs Represented by three points (vo. v1, v2). A clockwise winding constitution of the constant of
- Sphere.cs Represented by a point (center) and a radius.

All of these classes in planent to intuite content to intuite content in the content a method called Intersect(), which takes a Ray as its input and returns a RayHit as its output. The returned RayHit structure contains important information used during ray tracing: the incident ray direction, the position of the hit, and the normal of the surface at that position It is also possible that pleed to the Clear, in which case, null should be returned instead of a RayHit instance. Your job is to implement the Intersect() method for all three primitive entities. Again, you may find it helpful to research common mathematical approaches to these problems if you are stuck.

Stage 1.5 - Output primitives as solid colours

You are finally ready to generate some graphical output! Earlier you computed a ray for each pixel in the image. Extend this code to check for intersections with primitives in the scene. You will need to make further additions to the Render() method. For each ray, iterate through every entity in the scene and check whether there is an intersection between the ray and the entity. If so, you should set the corresponding pixel colour to the colour of the object. Ensure you correctly handle cases where there is more than one entity that coincides with a ray.

In case your object-oriented programming is rusty, here is a template for looping through all primitives/entities in the scene and checking if ray intersects with them:

```
foreach (SceneEntity entity in this.entities)
{
    RayHit hit = entity.Intersect(ray);
    if (hit != null)
    {
            // We got a hit with this entity!
            // The colour of the entity is entity.Material.Color
    }
}
```

Note that entity is an interface, so we don't know exactly which type of primitive it is (plane, triangle or sphere), but that does not matter since we are only interested in the intersection itself.



We have provided you with sample outputs in the images folder, so you have an indication of how your output should look for stages 1 and 2 respectively.

Stage 2 - Lighting and materials (9 marks)

In this stage you will extend the ray tracer to handle lighting, and model different types of materials. Some materials are more trivial to compute that there, and this complexity Shingly Bild to the Wight Cotinerax at the heart of the complexity of the complexity

Note that every entity is assigned a *material*. The material contains properties that allow us to calculate how light interacts with the entity – for example, its colour, whether it is opaque, reflective, transparent etc. Open are core/Material cs to see our representation of a material in this project. Note that you already used the Color property in the previous stage.

Stage 2.1 - DiffyeriaWeChat powcoder

We will first consider the case where a ray coincides with a diffuse surface which is directly illuminated by a light source. When light hits an 'ideal' diffuse material, it scatters uniformly in all directions. This means it is viewer-independent, and the intensity only varies depending on the angle of incidence between the light source and the surface. Diffuse lighting is so trivial to compute that it is regularly used in real-time rendering techniques (not just ray tracing).

In this stage you need to extend the ray tracer to handle materials with the Diffuse type. Objects should be smoothly lit when this is implemented correctly. As a starting point, take note of where you set the colour of a pixel currently. Instead of outputting the material colour directly, you should compute it based on the following function:

$$C = (\hat{N} \cdot \hat{L}) C_m C_l$$

...where \hat{N} is the normal of the surface at the hit point, \hat{L} is the direction to the light source from the hit point, C_m is the material colour, C_l is the light colour and C is the

resultant output colour. Note that all light sources are available in the Scene class, so you will likely have to iterate through these. You should sum the outputs of multiple light sources into the final pixel colour (if there is more than one).

Stage 2.2 - Shadow rays

Consider the fact that light rays may be blocked by objects in the scene. This should lead to visible shadows. Extend your implementation to check whether a hit point is in fact in a shadow. You can do this by firing another ray towards the light source from that point, and checking if it hits a (closer) surface along the way. If there is a hit, then that light source should not contribute to illumination at that point.



Be careful when firing a ray away from the surface of an object. Numerical error could lead to a 'premature' hit with that same object! One solution is to offset the origin of the ray slightly away from the surface.

Stage 2.3 - Reflective materials

This is where ray tracing really starts to shine – no pun intended! Extend the ray tracer to handle materials with the Reflective type. When a ray hits a reflective material, another ray should be recursively traced to determine the colour at that point. To do this your Stockhold in the contract of the track of the lit with surface normal and the incident ray direction. This should be pure reflection – the colour of the material plays no role in the calculations. Note that if there are a lot of reflective surfaces in a scene, computational costs can blow but significantly, so you may wish to place a hard limit of depth of rearrance. On the large new reflection, rays you are willing to 'fire').

Stage 2.4 - Refractive date We Chat powcoder

Some materials are transparent, and allow light to transmit through them. Glass is an example of such a material. Unfortunately, simulating this effect in a realistic manner is not as simple as allowing an incident ray to pass directly through the object. Indeed, you may have observed that light can 'bend' through transparent mediums (take a look at any curved glass object). This phenomenon is known as refraction. Extend the ray tracer once again to handle materials with the Refractive type. In a similar way to how you handled reflection, upon a ray hitting a surface, you should recursively trace a ray through the object according to physical laws of refraction. The colour of the material should not play any role in the calculations at this stage. Note that materials have an additional RefractiveIndex property, which will come in handy here.

Stage 2.5 - The Fresnel effect

In the real world, refraction does not really occur in total isolation from reflection. When light hits a refractive surface, some proportion of it is reflected, while another proportion is refracted (these proportions sum to 1 since energy is conserved). This proportion is not uniform for all rays which hit the surface. As a ray's angle of incidence decreases, there is greater reflection versus refraction. If you look at a sheet of glass from front on, and you will see that most of the light is refracted (transmits through). However, if you look at it almost side-on, it looks a lot more reflective!

This phenomenon is known as the *Fresnel effect*. Your next task is to improve refractive materials so that reflection is *mixed* into the corresponding lighting calculations according to the Fresnel equations. Note that this means that *two* rays need to be traced for every one ray that coincides with a refractive material. If this process repeats itself multiple times, the computational burden increases exponentially, so keep this in mind when coding your solution.

Stage 2.6 - Anti-aliasing

You may have noticed that the images being produced so far contain somewhat jagged edges. This is because details in the scene can differ at the sub-pixel level when they are projected onto the final image. This is a common problem in computer graphics generally, and is called *aliasing*. Aliasing is usually quite visible where there are curved edges, or edges that are not aligned horizontally or vertically with the screen (think about why). We can use various techniques to mitigate this problem, and this process is called apticalization.

Modify your ray tracer to incorporate optional anti-aliasing during rendering. You should do this by firing more rays per pixel and then averaging the outputs for the final colour. There is another command-line argument accessible within your program which specifies the anti-aliasing shalf interpretable are the colour. Here is an example:

dotnet run -- -f tests/sample_scene.txt -o output.png -x 2

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The argument -x specifies this multiplier, which in this example is 2. This means you

The argument -x specifies this multiplier, which in this example is 2. This means you should fire twice as many rays both horizontally and vertically (4x rays per pixel). If the multiplier is 3, then you should fire three times as many rays in both directions (9x rays per pixel). And so on. Note that we have already parsed this command-line argument for you! It is accessible within the Scene class as options. AAMultiplier, so you don't need to worry about how to read it into your program.

Stage 3 - Advanced add-ons (9 marks)

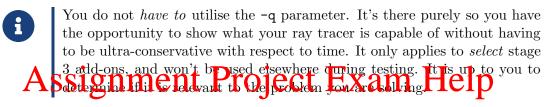
In this stage you are given the opportunity to implement some advanced add-on effects of your choosing. Some are more trivial to implement than others, and the allocated marks reflect their approximate difficulty and/or time commitment. In completing these questions to a high standard, we expect that you research various approaches, and make informed decisions to maximise the outcomes of the intended effects. You should write some detailed comments in your README.md file which describe the approach you have taken. It is not possible to receive more than the allocated marks for this section (9)

marks maximum), so if you complete more add-ons than required, clearly state which ones you want to contribute to your mark!

N.B.: Regardless of whether you complete this stage or not, you are still encouraged to show off your work by submitting a custom scene (see below).

Render quality

For a few of these add-ons, it may be useful to have a render quality parameter, which allows the user to 'trade' between computation time and output image quality. We have provided an additional command line argument -q that you are free to utilise for this. For add-ons where it's relevant, our test suite may increment the quality level and re-render a test output (starting at the default quality level of 0). This will be repeated until some reasonable time limit is reached, or the image does not change. The exact details of this process will depend on available resources during marking, however all submissions will be tested in the same environment, and with the same time limits, in order to ensure fairness.



Stage 3, Option A - Emissive materials (+6)

Up until this point to posidered by the Cornel Sucal Quits. This is an approximation, and not how lighting typically works in the real world. Consider a fluorescent bulb which is a long cylindrical shape. It would be inappropriate to model this using a singular point. Avea a station dight plotet which comes close to being modelled by a 'point', is still a physical object with a surface area that emits light. We call such surfaces emissive.

For this add-on you need to extend the ray tracer to handle emissive materials. As a consequence there should also be 'soft shadows' present in the scene (have a think about why). Note that the MaterialType enum has an Emissive type, which will be used to specify whether the material should be emissive. The colour of the material can be interpreted to be the colour of the emitted rays. You may assume only spheres and triangles will be given emissive materials (not infinite planes).

Stage 3, Option B - Ambient lighting/occlusion (+6)

The current ray tracer only simulates a very small subset of rays in a scene. Consider how the illumination of a point on a diffuse object is currently calculated. We test if there is a *direct* ray originating from a light source. If there isn't, or there is an object in-between, then the point isn't illuminated at all. However, in reality, there may still be some illumination that comes from indirect rays of light (e.g. bouncing off

other surfaces in the scene). This is called *ambient lighting*. When ambient lighting is computed, we consequently compute *ambient occlusion* in the scene, since indirect light will not illuminate all surfaces equally. For example, surfaces inside crevices and cracks tend to be a lot darker since they are less 'exposed' to the other surfaces in the scene.

Extend the ray tracer so that it is possible to optionally compute ambient lighting in a rendered image. You should utilise the -1 command line flag which is available as options.AmbientLightingEnabled in the Scene class. In other words, if and only if -1 is passed to your program, ambient lighting should be enabled.



It is infeasible to compute *every* ray in a scene, so you may end up using some sort of randomised or 'Monte Carlo' method to assist with this.

Stage 3, Option C - OBJ models (+6)

Extend the ray tracer to read simple 3D models in the form of .obj files. Research how the .obj file format is structured. We only expect that you handle files with vertex, normal and face definitions (v, vn, f), and faces may be assumed to be triangles (exactly three vertices). Be sure to consider how more complex models could impact the *performance* of your ray tracer, and optimise relevant data structures accordingly. If you do implement optimisations, ensure these are discussed in your README.md.

We have provided you with a template class in the street street called ObjModel and Intersect () method that needs to be implemented. You should read/parse the .obj file in the constructor, and use this data when computing intersections.

We have provided you with a sample scene (tests/sample_scene_obj.txt) that con-

We have provided you with a sample scene (tests/sample_scene_obj.txt) that contains an OBJ, so you should examine this file first to see exactly how OBJ models are defined. In particular, observe there is a string that is the path to the .obj file itself. Also notice that we openly at offset yellow and contains a model. These parameters allow us to adjust the size and position of the model to fit the scene appropriately. The scale should be applied first, then the offset, as these are order dependent operations.

Stage 3, Option D - Glossy materials (+3)

At the moment we can model a few common materials, but there are still many material types which cannot be adequately simulated. Add support for 'glossy' materials to your ray tracer. The MaterialType enum has a Glossy type, which you should add functionality for. Unlike refractive materials, no light should transmit through the object. However, the object should not be completely reflective either. Instead, the object should be coloured based on the material's Color property, but also appear to reflect some light. Exactly how you achieve this effect is up to you, but you should aim to make it convincing. If there are parameters that need to be tuned to determine the amount of 'glossiness', choose suitable defaults that demonstrate the effect.

Stage 3, Option E - Custom camera orientation (+3)

Currently the camera is assumed to be at the origin (0, 0, 0) looking along the z-axis (with the y-axis oriented 'up'). Allow the user to apply a custom camera position and orientation to the camera based on the following parameters: a position vector (x, y, z), an axis of rotation vector (x, y, z) and an angle (in degrees). Note that this is an axis of rotation, **not** the 'direction' or local z-axis of the camera. The axis and angle are specified via the following command-line parameters where # denotes a floating point number:

- --cam-pos #,#,# Available as options. Camera Position
- --cam-axis #,#,# Available as options. CameraAxis
- --cam-angle # Available as options.CameraAngle (in degrees)

These parameters are automatically parsed for you by the template code, and so all you need to do is utilise the respective variables within the Scene class (e.g., as options.CameraPosition).

Stage 3, Option F - Beer's law (+3)

We currently Sansder halfurship in Ight Itrougi a mexical file intected by that medium, other than its refractive index. Beer's law states that light intensity should drop as light passes through a medium, and that drop is proportional to the distance traveled. Additionally, some wavelengths of light may be absorbed faster than others, giving rise to 'coloured semi-transparent objects."

Modify the ray tracer to obey Beer's law for Refractive materials. Currently the colour of refractive materials has no effect in lighting calculations, but now it should be utilised. You should in critical feet the restriction of the colour channel. For example the RGB value of (4, 1, 1) means that red light will be absorbed at a faster rate than blue and green light.

Stage 3, Option G - Depth of field (+3)

The camera is currently modelled assuming an infinitely small 'pinhole' aperture. If you think about it, a physical camera cannot function like this, since no light can pass through an infinitely small hole! We may introduce additional parameters to our ray tracer that allow us to more accurately model how a real camera works. This allows us to generate a 'depth of field' effect in our rendered images, which means some parts of the scene are in focus, and other parts are blurry depending on a given 'focal length'.

Extend your ray tracer to account for two additional parameters: a **focal length**, and an **aperture radius**. These will be passed via the following command-line parameters where # denotes a floating point number:

• --aperture-radius # - Available as options. Aperture Radius

• --focal-length # - Available as options. FocalLength

We have already parsed these parameters for you and you can access them in the Scene class (e.g. as options.FocalLength). The aperture radius parameter has a default value of 0, which reflects the idealised pinhole model we have used up until this point. However, if this value is larger than 0, then a circular pinhole should be simulated with the corresponding radius. Surfaces at a distance equal to the focal length (away from the camera) should be in focus.

Finally - Show off your work! (3 marks)

Congrats! At this point, your ray tracer should be able to generate some pretty impressive images. Now is your chance to show off what it can do. The tests/final_scene.txt file is currently empty. You should populate this scene in order to demonstrate all the core features of the ray tracer, as well as your chosen add-ons. Choose suitable settings to render your final image, and replace the images/final_scene.png placeholder image with it. Notice that this image is already embedded in the README.md.

Also record how long it takes to render the image on your PC and include that in the README.md (see the template provided). In case we need to verify your image, you must also include the exact command line used to generate it. We might use lower resolution/anti-aliasing/quality settings to speed up the verification in tests.

resolution/anti-aliasing/quality settings to speed up the verification in resolution and the perification in the perification

Verify that your image is visible on GitHub (instead of the placeholder image) to ensure that you receive credit for it.

https://powcoder.com

Assessment

Unless explicitly stated, grading of your submission will be exclusively based on outputs produced by your includer, not cour child be will use a culturated process to pass hidden test scenes and/or specific command line arguments to your program. Failing tests won't receive credit! Therefore, you must ensure that you do not change the inputs or outputs of the provided template. Furthermore, don't rely on just the provided test scenes – think about possible edge cases and write your own! We will run your ray-tracer with both the provided test scene, and some hidden test scenes.

Ray tracers are resource intensive by nature, so we don't expect test scenes to be rendered 'instantly'. However, you should take necessary steps to optimise the process where it is sensible. For practical reasons, time limits will apply, but they will be chosen based on our sample solution to very comfortably allow your project to generate correct output images if implemented reasonably. Occasionally the time taken to generate images may be part of your assessment (e.g., if specific optimisations are applicable to an add-on you have implemented). You are encouraged to discuss any time related dilemmas you faced in your README.md.

Finally, feel free to ask questions about the specification on the discussion forum (Ed). However, before doing so, please refer to our live FAQ which will be pinned for

the duration of the project. This is based on questions from previous years, and will be updated further as new questions roll in!

Submission

You must submit the project via the respective project details page on Canvas (where you found this specification). There is an embedded Gradescope interface on that page that allows you to link your GitHub account, as well as the private repository containing your work. You may re-submit your project as many times as you wish, and only the final submission will be marked, so you are **strongly encouraged** to attempt a test run of this process comfortably before the deadline.

Your submission must conform to the *exact* scene and command line specification that is provided with the template, since our testing system is semi-automated. If you do not modify the core template code, then this should not be an issue. Additionally, external libraries, dependencies, or packages are **not** allowed. Make it clear in your git README.md which add-ons you wish to be marked, and briefly describe your approach for these. Remember, you should frequently commit your work to GitHub while working on the project. Even though you are working solo, this serves as a backup and proof of your work on the project.

Signification generally Dowcoder.com

Academic honesty

Your submission Aust of your worldshapp wein of estudents is not allowed for this assignment, although you may discuss the project with classmates at a conceptual level. We will use a sophisticated code similarity checker between all student submissions, and previous years' ones. You are welcome to utilise external resources for research purposes, however, you must attribute any sources you use both in your code and your README.md. You should minimise blindly copying and paste code, even if referenced, and deductions may apply if there is little evidence of understanding due to an over-reliance on external resources. Feel free to clarify this with your tutor if you are unsure.